



Connected Drivers & Real-Time Maps

Stephen T'Siobbel

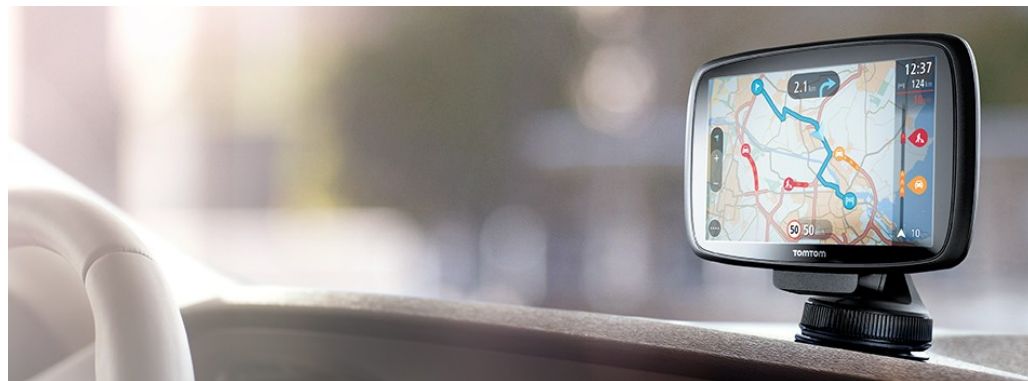
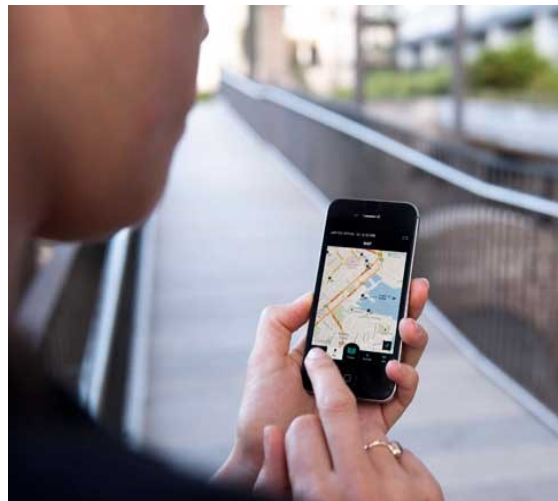
Sr. Project Manager – TomTom Maps - Advanced Driving

You have reached
your destination !



YESTERDAY – THE NOT CONNECTED EXPERIENCE

TODAY'S CONNECTED EXPERIENCE





EVERYTHING BECOMING CONNECTED

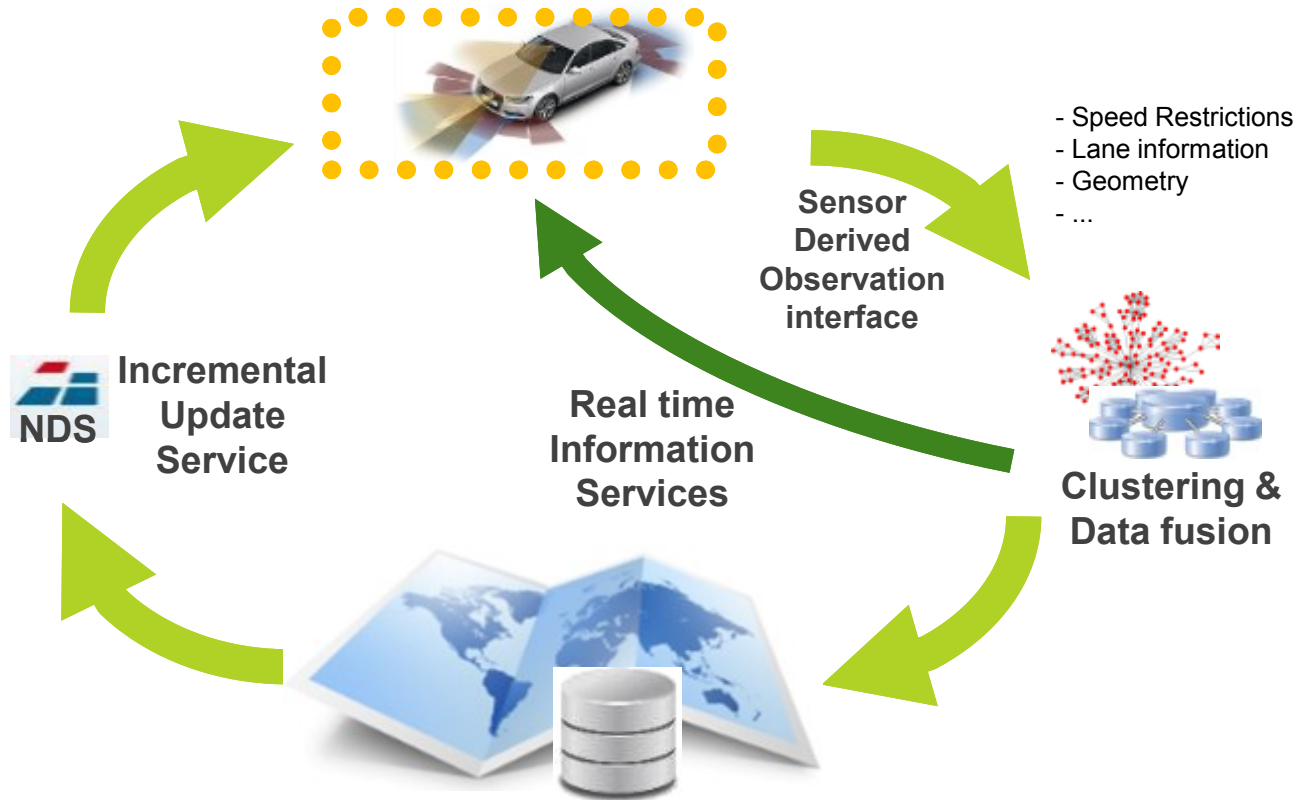
THE FUTURE CONNECTED DRIVER EXPERIENCE

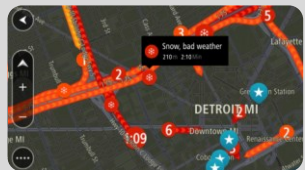




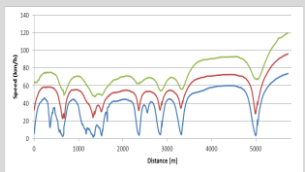
CONNECTED CAR IS AN INTELLIGENT DATA HUB WITH SENSORS

Real-Time Maps and the 'Closed Loop'

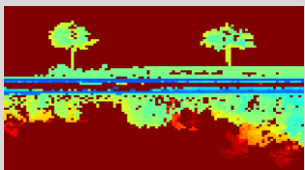




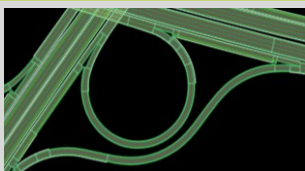
Dynamic data



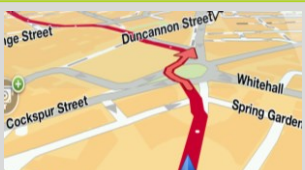
Behavioral data



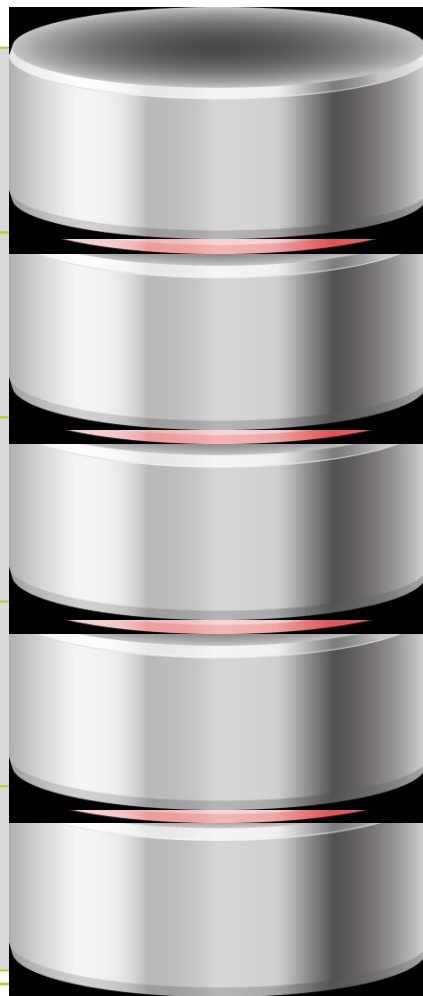
Positioning data



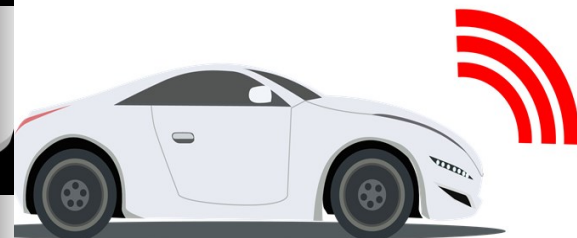
Planning data



Navigation data



MAP CONTENT IN THE CONNECTED CAR



Trends in Location Referencing

- Maturing level in standardisation
- Code & Map-Id based methods will remain important
- Map agnostic LR methods are becoming more and more main stream



Key messages

- Connected vehicles will consume and produce increasingly more spatial information
- TomTom Real-Time Maps will deliver the content & quality required for Connected & Highly Automated Driving
- Location referencing methods are maturing and will play an important role in the years to come

Questions ?