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Title: Proposal for modified syntax, semantics and decoding process for spatial scalability  
Purpose: Proposal

*This document describes the syntax, semantics and decoding process used for successful bitstream exchange for spatial scalability. It is proposed that this text replace the corresponding text in the Working Draft.*

Section 6.2.2

sequence_scalable_extension() {	No. of bits	Mnemonic
extension_start_code	32	bslbf
extension_start_code_identifier	4	uimsbf
scalable_mode	2	uimsbf
layer_id	4	uimsbf
if (scalable_mode == spatial_scalable) {		
lower_layer_prediction_horizontal_size	14	uimsbf
marker_bit	1	"1"
lower_layer_prediction_vertical_size	14	uimsbf
horizontal_subsampling_factor_m	5	uimsbf
horizontal_subsampling_factor_n	5	uimsbf
vertical_subsampling_factor_m	5	uimsbf
vertical_subsampling_factor_n	5	uimsbf
}		
if (scalable_mode == "temporal scalability")		
picture_mux_enable	1	uimsbf
picture_mux_order	3	uimsbf
picture_mux_factor	4	uimsbf
}		
next_start_code()		
}		

6.3.7 Sequence scalable extension

lower\_layer\_prediction\_horizontal\_size -- this a 14 bit unsigned integer indicating the horizontal size of the lower layer picture which is used for spatial prediction.

**lower\_layer\_prediction\_vertical\_size** – this a 14 bit unsigned integer indicating the vertical size of the lower layer picture which is used for spatial prediction.

**scalable\_mode** - The **scalable\_mode** indicates the type of scalability used for the picture. If no picture extension data is present for a picture, no scalability is used for that picture. It also indicates the macroblock\_type tables to be used. If no picture extension data is present for a picture, tables B.2-1, B.2-2 and B.2-3 should be used.

Table 6-?. Definition of **scalable\_mode**

codeword	scalable_mode	macroblock_type tables
00	data partitioning	B.2-1, B.2-2 and B.2-3
01	spatial scalability	B.2-5, B.2-6 and B.2-7
10	snr scalability	?
11	temporal scalability	B.2-1, B.2-2 and B.2-3

**horizontal\_subsampling\_factor\_m** – This affects the spatial scalable upsampling process, as defined in section 7.7. The value should be non-zero.

**horizontal\_subsampling\_factor\_n** – This affects the spatial scalable upsampling process, as defined in section 7.7. The value should be non-zero.

**vertical\_subsampling\_factor** -- This affects the spatial scalable upsampling process, as defined in section 7.7. The value should be non-zero.

**vertical\_subsampling\_factor\_n** – This affects the spatial scalable upsampling process, as defined in section 7.7. The value should be non-zero.

#### Section 6.2.4

picture_spatial_scalable_extension() {	No. of bits	Mnemonic
extension_start_code	32	bslbf
extension_start_code_identifier	4	uimsbf
lower_layer_temporal_reference	10	uimsbf
lower_layer_horizontal_offset	15	simsbf
marker_bit	1	"1"
lower_layer_vertical_offset	15	simsbf
spatial_temporal_weight_code_table_index	2	uimsbf
lower_layer_progressive_frame	1	uimsbf
lower_layer_deinterlaced_field_select	1	uimsbf
next_start_code()		
}		

#### 6.3.12 Picture spatial scalable extension

**lower\_layer\_temporal\_reference** - An unsigned integer value which indicates the temporal reference of the lower layer picture to be used to provide the prediction. If the lower layer indicates the temporal reference with more than 10 bits, the least significant bits are indicated here. If the lower layer indicates the temporal reference with less than 10 bits, all bits are indicated here, with the extra most significant bits being set to zero.

**lower\_layer\_horizontal\_offset** - This affects the spatial scalable upsampling process, as in section 7.7.

**lower\_layer\_vertical\_offset** - This affects the spatial scalable upsampling process, as in section 7.7.

**spatial\_temporal\_weight\_code\_table\_index** -- this indicates which table of spatial temporal weight codes is to be used as defined in section 7.7. **spatial\_temporal\_weight\_code\_table\_index** must be "00" when **picture\_structure** is **top\_field** or **bottom\_field** and when **progressive\_frame** is 0.

**lower\_layer\_progressive\_frame** -- this flag is set to 0 if the lower layer picture is an interlaced frame and to "1" if the lower layer picture is a progressive frame. The use of this flag in the spatial scalable upsampling process is defined in section 7.7.

**lower\_layer\_deinterlaced\_field\_select** -- This affects the spatial scalable upsampling process, as defined in section 7.7.

## 7.7 Spatial Scalability

This clause specifies the additional decoding process required for the spatial scalable extensions.

Figure 7.2 is a diagram of the video decoding process with spatial scalability. The diagram is simplified for clarity.

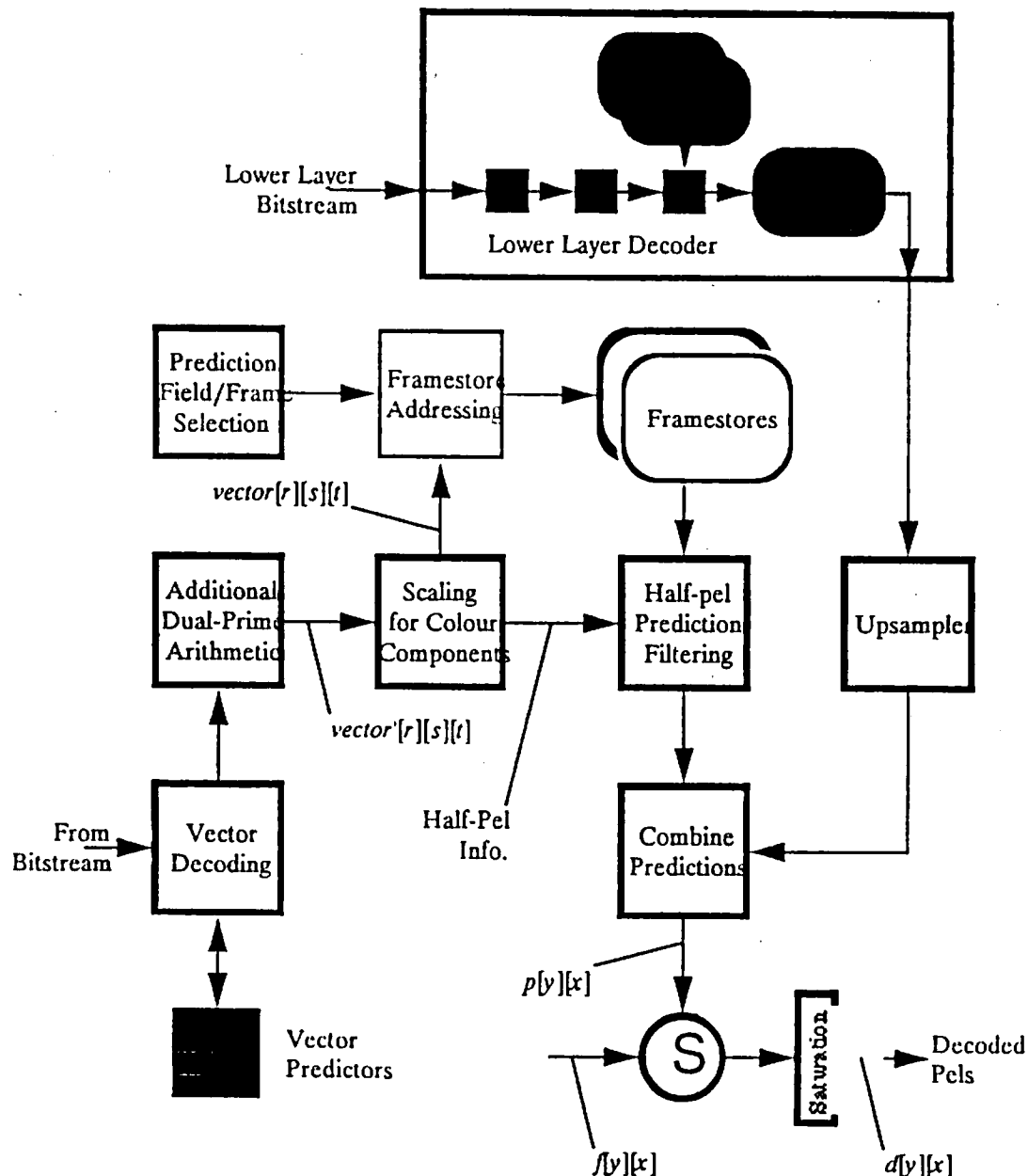


Figure 7.2. Simplified motion compensation process for spatial scalability

### 7.7.1 Prediction in scalable layer

A motion compensated 'temporal' prediction is made from previously decoded pictures in the current layer as described in section 7.6. In addition, a 'spatial' prediction is formed, which is an upsampled

version of the lower layer decoded picture, as described in section 7.7.2. These predictions are selected individually or combined to form the actual prediction.

In general up to four separate predictions are formed for each block which are combined together to form the final prediction block  $p[y][x]$ .

In the case where a block is not coded, either because the entire macroblock is skipped or the specific block is not coded as there is no coefficient data. In this case  $f[y][x]$  is zero and the decoded pels are simply the prediction,  $p[y][x]$ .

### 7.7.2 Formation of 'spatial' prediction

The spatial prediction is made from the decoded picture of the lower layer referenced by the `lower_layer_temporal_reference`. This prediction is made by scaling the lower layer to the same pel grid as the current layer. A 16x16 region is chosen, which corresponds to the position of the current macroblock which is being decoded.

This interpolation process is described in this section illustrated in figure 7-(?+1).

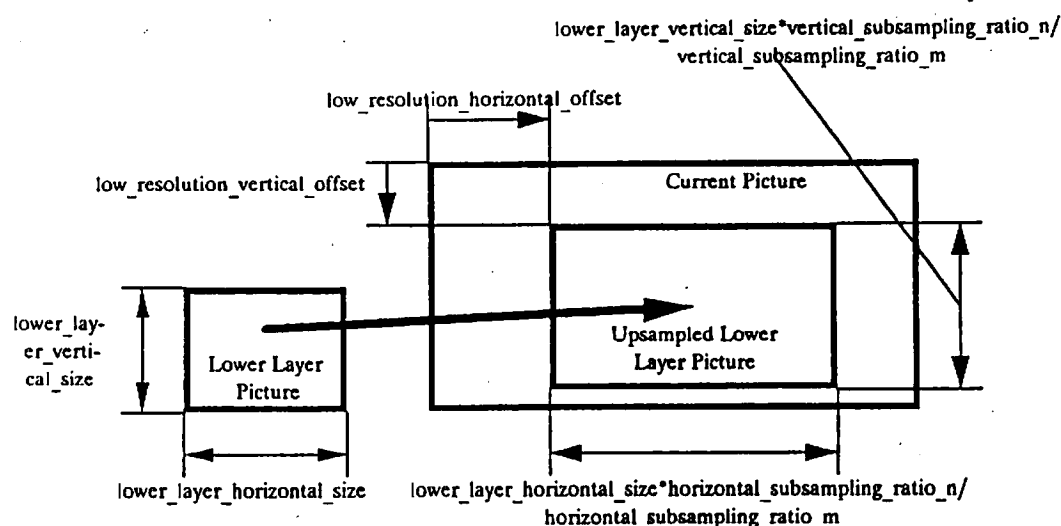


Figure 7-?. Formation of the 'spatial' prediction by interpolation of the lower layer picture

#### 7.7.2.1 General

The process for resampling depends on whether the lower layer is interlaced or progressive, as indicated by `lower_layer_progressive_frame` and whether the current layer is interlaced or progressive, as indicated by `progressive_frame`.

When `lower_layer_progressive_frame` is "1", the lower layer picture is resampled vertically as described in section 7.7.2.3. The resulting frame is considered to be progressive if `progressive_frame` is "1" and interlaced if `progressive_frame` is "0". The resulting frame is resampled horizontally as described in section 7.7.2.4. `Lower_layer_deinterlaced_field_select` should have the value "1".

When `lower_layer_progressive_frame` is "0" and `progressive_frame` is "0", the lower layer picture is deinterlaced as described in section 7.7.2.2, to produce two progressive fields. Both of these fields are resampled vertically as described in section 7.7.2.3. The resulting fields are subsampled to produce two interlaced fields: the even lines are taken from the first to make the top field and the odd lines are taken from the second to make the bottom field (counting lines from 0). The resulting frame is resampled horizontally as described in section 7.7.2.4. `Lower_layer_deinterlaced_field_select` should have the value "1".

When `lower_layer_progressive_frame` is "0" and `progressive_frame` is "1", the lower layer picture is deinterlaced as described in section 7.7.2.2, to produce two progressive fields. Only one of these fields

is required. When `lower_layer_deinterlaced_field_select` is "0" the first is used, otherwise the second is used. The one that is used is resampled vertically as described in section 7.7.2.3. The resulting frame is resampled horizontally as described in section 7.7.2.4.

In all three cases, the resulting frame is offset by `low_resolution_horizontal_offset` and `low_resolution_vertical_offset` to produce the spatial prediction.

The upsampling process is summarised in the table below.

Lower_layer_field_select	Lower_layer_progressive_frame	Progressive_frame	spatial_temporal_weight_code_table_index	Apply deinterlace process	Entity used for prediction
0	0	1	00	yes	top field
1	0	1	00	yes	bottom field
1	1	1	00	no	frame
1	1	0	00,01,10,11	no	frame
1	0	0	00,01,10,11	yes	both fields

### 7.7.2.2 Deinterlacing

First, the lower layer frame is padded with zeros to form a progressive grid at a picture rate equal to the field rate of the lower layer, and with the same number of lines and pels per line as the lower layer frame. It is then filtered using the relevant two field aperture filter from the table below. The temporal and vertical columns of the table indicate the relative spatial and temporal coordinates of the pels to which the filter taps defined in the other two columns apply. An intermediate sum is formed by adding the multiplied coefficients together.

Temporal	Vertical	Filter for first field	Filter for second field
-1	-2	0	-1
-1	0	0	2
-1	2	0	-1
0	-1	8	8
0	0	16	16
0	1	8	8
1	-2	-1	0
1	0	2	0
1	+2	-1	0

The output of the filter (sum) is then scaled according to the following formula:

$$\text{prog\_field}[x][y] = \text{sum} // 16$$

The filter aperture can extend outside the active picture area. In this case the pels of the lines outside the active picture should take the value of the closest neighbouring existing pel (below or above) of the same field as defined below.

For all pels `[y][x]`:

if `(y < 0 && (y & 1 == 1))` `y = 1`

if `(y < 0 && (y & 1 == 0))` `y = 0`

if `(y >= lower_layer_vertical_size && (y & 1 == 1))` `y = lower_layer_vertical_size - 1`

if `(y >= lower_layer_vertical_size && (y & 1 == 0))` `y = lower_layer_vertical_size - 2`

### 7.7.2.3 Vertical resampling

The frame subject to vertical resampling, `input_field`, is resampled to the current layer vertical sampling grid using linear interpolation between the sample sites according to the following formula, where `output_field` is the resulting field:

$$\text{output\_field}[x][y_h] = (16 - \text{phase}) * \text{input\_field}[x][y_1] + \text{phase} * \text{input\_field}[x][y_2]$$

where

$y_h$	=	output sample co-ordinate in output field
$y_1$	=	$(y_h * m) / n$
$y_2$	=	$y_1 + 1$ if $y_1 < \text{lower\_layer\_vertical\_size} - 1$ $y_1$ otherwise
$\text{phase}$	=	$16 * ((y_h * m) \% n) // n$
$m$	=	<code>vertical_upsampling_factor_m</code>
$n$	=	<code>vertical_upsampling_factor_n</code>

### 7.7.2.4 Horizontal resampling

The frame subject to horizontal resampling, `input_field`, is resampled to the current layer horizontal sampling grid using linear interpolation between the sample sites according to the following formula, where `output_field` is the resulting field:

$$\text{output\_field}[x_h][y_h] = ((16 - \text{phase}) * \text{input\_field}[x_1][y_h] + \text{phase} * \text{input\_field}[x_2][y_h]) / 256$$

where

$x_h$	=	output sample co-ordinate in output field
$x_1$	=	$(x_h * m) / n$
$x_2$	=	$x_1 + 1$ if $x_1 < \text{lower\_layer\_horizontal\_size} - 1$ $x_1$ otherwise
$\text{phase}$	=	$16 * ((x_h * m) \% n) // n$
$m$	=	<code>horizontal_upsampling_factor_m</code>
$n$	=	<code>horizontal_upsampling_factor_n</code>

## 7.7.3 Selection and combination of spatial and temporal predictions

The spatial and temporal predictions can be selected or combined to form the actual prediction. The `macroblock_type` (tables B.2-5, B.2-6 and B.2-7) indicates, by use of the `spatial_temporal_weight_class`, which can take the values 0, 1, 2, 3, 4, whether the prediction is temporal-only, spatial-only or a weighted combination of temporal and spatial predictions. A fuller description of `spatial_temporal_weight_class` is given in Section 7.7.4.

In intra pictures, if `spatial_temporal_weight_class` is 0, normal intra coding is performed, otherwise the prediction is spatial-only. In predicted and interpolated pictures, if the `spatial_temporal_weight_class` is 0, prediction is temporal-only, if the `spatial_temporal_weight_class` is 4, prediction is spatial-only, otherwise one or a pair of prediction weights is used to combine the spatial and temporal predictions.

The possible prediction weights are given in a weight table which is selected in the picture scalable extension. Up to four different weight tables are available for use depending on whether the current and lower layers are interlaced or progressive. At the macroblock layer, a one or two bit code, `spatial_temporal_weight_code`, is used to describe the prediction for each field (or frame), as shown in the table below.

Table showing spatial\_temporal\_weights and spatial\_temporal\_weight\_classes for the lower layer picture formats and spatial temporal weight codes

spatial_temporal_weight_code table index	spatial_temporal_weight bits	spatial_temporal_weight code	spatial_temporal_weight (s)	spatial_temporal_weight class	spatial_temporal_integer_weight
00	1	0	RESERVED		
	1	1	0.5	1	0
01	2	00	0, 1	3	1
	2	01	0, 0.5	1	0
	2	10	0.5, 1	3	0
	2	11	0.5, 0.5	1	0
10	2	00	1, 0	2	1
	2	01	0.5, 0	1	0
	2	10	1, 0.5	2	0
	2	11	0.5, 0.5	1	0
11	2	00	1, 0	2	1
	2	01	1, 0.5	2	0
	2	10	0.5, 1	3	0
	2	11	0.5, 0.5	1	0

When the prediction weight combination is given in the form (a,b), "a" gives the proportion of the prediction for the top field which is derived from the spatial prediction and "b" gives the proportion of the prediction for the bottom field which is derived from the spatial prediction for that field.

When the prediction weight combination is given in the form (a), "a" gives the proportion of the prediction for the frame which is derived from the spatial prediction for that frame. The precise method for predictor calculation is as follows:

If  $pel\_pred\_temp[y][x]$  is used to denote the temporal prediction (formed within the current layer) as defined for  $pel\_pred[y][x]$  in clause 7.6.  $pel\_pred\_lower[y][x]$  is used to denote the prediction formed from the lower layer, then:

If the weight code is zero then no prediction is made from the lower layer. Therefore;

$$pel\_pred[y][x] = pel\_pred\_temp[y][x];$$

If the weight code is one then no prediction is made from the current layer. Therefore;

$$pel\_pred[y][x] = pel\_pred\_lower[y][x];$$

If the weight code is one half then the prediction is the average of the temporal and spatial predictions. Therefore;

$$pel\_pred[y][x] = (pel\_pred\_temp[y][x] + pel\_pred\_lower[y][x]) / 2;$$

When chrominance is sampled 4:2:0, it is treated as interlaced, in accordance with the other prediction modes, that is, the first weight code is used for the top field chrominance lines and the second weight is used for the bottom field chrominance lines.

Note Each field has its own weight code.

It is intended that the different weight tables are used in the following circumstances (although this is not mandatory):

Lower layer format	Current layer format	spatial_temporal_weight code table index
Progressive or interlaced	Progressive	00
Progressive coincident with current layer top fields	Interlaced	10
Progressive coincident with current layer from bottom fields	Interlaced	01
Interlaced	Interlaced	00 or 11

#### 7.7.4 Updating motion vector predictors and Motion vector selection

In frame pictures where field prediction is used the possibility exists that one of the fields is predicted using spatial-only prediction. In this case no motion vector is present in the bit stream for the field which has spatial-only prediction. For the case where both fields of a frame have spatial-only prediction, the macroblock\_type is such that no motion vectors are present in the bit stream for that macroblock.

The class also indicates the number of motion vectors which are present in the coded bit stream and how the prediction vectors are updated and this is described in the Table below. Classes are defined in the following way:

Class 0 indicates temporal-only prediction

Class 1 indicates that neither field has spatial-only prediction

Class 2 indicates that the top field is spatial-only prediction

Class 3 indicates that the bottom field is spatial-only prediction

Class 4 indicates spatial-only prediction.

Table showing updating of motion vector predictors in Field pictures

field motion type	F	B	I	WC	Predictions to update
Field-based	-	-	1	0	$PMV[1][0][1:0] = PMV[0][0][1:0]$
Field-based	1	1	0	0	$PMV[1][0][1:0] = PMV[0][0][1:0]$ $PMV[1][1][1:0] = PMV[0][1][1:0]$
Field-based	1	0	0	0,1	$PMV[1][0][1:0] = PMV[0][0][1:0]$
Field-based	0	1	0	0,1	$PMV[1][1][1:0] = PMV[0][1][1:0]$
Field-based	0	0	0	0,1,4	$PMV[r][s][t] = 0$ §
16x8 MC	1	1	0	0,1	(none)
16x8 MC	1	0	0	0,1	(none)
16x8 MC	0	1	0	0,1	(none)
Dual prime	1	0	0	0	$PMV[1][0][1:0] = PMV[0][0][1:0]$

Note:  $PMV[r][s][1:0] = PMV[u][v][1:0]$  means that;

$PMV[r][s][1] = PMV[u][v][1]$  and  $PMV[r][s][0] = PMV[u][v][0]$

- If concealment\_motion\_vectors is zero then  $PMV[r][s][t]$  is set to zero (for all  $r, s$  and  $t$ ).

Field\_motion\_type is not present in the bitstream but is assumed to be Field-based

§ In P-pictures,  $PMV[r][s][t]$  is set to zero (for all  $r, s$  and  $t$ ). See clause 7.6.3.4. The  $PMV[r][s][t]$  is not reset in B-pictures



*Comment:* WC means spatial\_temporal\_weight\_class. This table is valid for non-scalable coding and for spatial scalability.

**Table showing updating of motion vector predictors in Frame pictures**

frame motion type	F	B	I	WC	Predictions to update
Frame-based❏	-	-	1	0	$PMV[1][0][1:0] = PMV[0][0][1:0]$
Frame-based	1	1	0	0	$PMV[1][0][1:0] = PMV[0][0][1:0]$ $PMV[1][1][1:0] = PMV[0][1][1:0]$
Frame-based	1	0	0	0,1,2,3	$PMV[1][0][1:0] = PMV[0][0][1:0]$
Frame-based	0	1	0	0,1,2,3	$PMV[1][1][1:0] = PMV[0][1][1:0]$
Frame-based❏	0	0	0	0,1,2,3,4	$PMV[r][s][t] = 0^{\S}$
Field-based	1	1	0	0	(none)
Field-based	1	0	0	0,1	(none)
Field-based	1	0	0	2	$PMV[0][0][1:0] = PMV[1][0][1:0]$
Field-based	1	0	0	3	$PMV[1][0][1:0] = PMV[0][0][1:0]$
Field-based	0	1	0	0,1	(none)
Field-based	0	1	0	2	$PMV[0][1][1:0] = PMV[1][1][1:0]$
Field-based	0	1	0	3	$PMV[1][1][1:0] = PMV[0][1][1:0]$
Dual prime@	1	0	0	0,2,3	$PMV[1][0][1:0] = PMV[0][0][1:0]$

Note:  $PMV[r][s][1:0] = PMV[u][v][1:0]$  means that;

$PMV[r][s][1] = PMV[u][v][1]$  and  $PMV[r][s][0] = PMV[u][v][0]$

- If concealment\_motion\_vectors is zero then  $PMV[r][s][t]$  is set to zero (for all  $r, s$  and  $t$ ).

❏ frame\_motion\_type is not present in the bitstream but is assumed to be Frame-based

§ In P-pictures  $PMV[r][s][t]$  is set to zero (for all  $r, s$  and  $t$ ). See clause 7.6.3.4. The  $PMV[r][s][t]$  is not reset in B-pictures

@ Dual prime can not be used when spatial\_temporal\_integer\_weight = "0".

*Comment:* WC means spatial\_temporal\_weight\_class. This table is valid for non-scalable coding and for spatial scalability.

Table showing predictions and vectors in Field pictures

field motion type	F	B	I	WC	Vector	Prediction formed for
Field-based	-	-	1	0	$vector[0][0][1:0]$ -	None (vector is for concealment)
Field-based	1	1	0	0	$vector[0][0][1:0]$ $vector[0][1][1:0]$	whole field, forward whole field, backward
Field-based	1	0	0	0,1	$vector[0][0][1:0]$	whole field, forward
Field-based	0	1	0	0,1	$vector[0][1][1:0]$	whole field, backward
Field-based	0	0	0	0,1,4	$vector[0][0][1:0]$ * §	whole field, forward
16x8 MC	1	1	0	0,1	$vector[0][0][1:0]$ $vector[1][0][1:0]$ $vector[0][1][1:0]$ $vector[1][1][1:0]$	upper 16x8 field, forward lower 16x8 field, forward upper 16x8 field, backward lower 16x8 field, backward
16x8 MC	1	0	0	0,1	$vector[0][0][1:0]$ $vector[1][0][1:0]$	upper 16x8 field, forward lower 16x8 field, forward
16x8 MC	0	1	0	0,1	$vector[0][1][1:0]$ $vector[1][1][1:0]$	upper 16x8 field, backward lower 16x8 field, backward
Dual prime	1	0	0	0	$vector[0][0][1:0]$  $vector[2][0][1:0]$ * ❏	same parity whole field, forward  opposite parity whole field, forward

Note: Vectors are listed in the order they appear in the bitstream

- the vector is only present if `concealment_motion_vectors` is one

❏ `field_motion_type` is not present in the bitstream but is assumed to be Field-based

\* These vectors are not present in the bitstream

❏ These vectors are derived from  $vector[0][0][1:0]$  as described in clause 7-?

§ The vector is taken to be (zero, zero) as explained in clause 7-?

*Comment:* WC means `spatial_temporal_weight_class`. This table is valid for non-scalable coding and for spatial scalability.

Table showing predictions and vectors in Frame pictures

frame motion type	F	B	I	WC	Vector	Prediction formed for
Frame-based	-	-	1	0	$vector[0][0][1:0]$ -	None (vector is for concealment)
Frame-based	1	1	0	0	$vector[0][0][1:0]$ $vector[0][1][1:0]$	frame, forward frame, backward
Frame-based	1	0	0	0,1,2,3	$vector[0][0][1:0]$	frame, forward
Frame-based	0	1	0	0,1,2,3	$vector[0][1][1:0]$	frame, backward
Frame-based	0	0	0	0,1,2,3,4	$vector[0][0][1:0]^{\$}$	frame, forward
Field-based	1	1	0	0	$vector[0][0][1:0]$ $vector[1][0][1:0]$ $vector[0][1][1:0]$ $vector[1][1][1:0]$	top field, forward bottom field, forward top field, backward bottom field, backward
Field-based	1	0	0	0,1	$vector[0][0][1:0]$ $vector[1][0][1:0]$	top field, forward bottom field, forward
Field-based	1	0	0	2	$vector[1][0][1:0]$	top field, spatial bottom field, forward
Field-based	1	0	0	3	$vector[0][0][1:0]$	top field, forward bottom field, spatial
Field-based	0	1	0	0,1	$vector[0][1][1:0]$ $vector[1][1][1:0]$	top field, backward bottom field, backward
Field-based	0	1	0	2	$vector[1][1][1:0]$	top field, spatial bottom field, backward
Field-based	0	1	0	3	$vector[0][1][1:0]$	top field, backward bottom field, spatial
Dual prime@	1	0	0	0,2,3	$vector[0][0][1:0]$ $vector[0][0][1:0]^*$ $vector[2][0][1:0]^{\otimes}$ $vector[3][0][1:0]^{\otimes}$	same parity top field, forward same parity bottom field, forward opposite parity top field, forward opposite parity bottom field, forward

Note: Vectors are listed in the order they appear in the bitstream

- the vector is only present if concealment\_motion\_vectors is one

$\otimes$  frame\_motion\_type is not present in the bitstream but is assumed to be Frame-based

\* These vectors are not present in the bitstream

$\otimes$  These vectors are derived from  $vector[0][0][1:0]$  as described in clause 7-?

$\$$  The vector is taken to be (zero, zero) as explained in clause 7-?

@ Dual prime can not be used when spatial\_temporal\_integer\_weight = "0".

Comment: WC means spatial\_temporal\_weight\_class. This table is valid for non-scalable coding and for spatial scalability.

### 7.7.5 Skipped macroblocks

In all cases, a skipped macroblock is only the result of a prediction, and all the DCT coefficients are considered to be zero.

The following rules apply for non-scalable bit streams; i.e. if `sequence_scalable_extension` is not present.

In I-frame pictures or field pictures, if `sequence_scalable_extension` is not present, then all macroblocks are coded and there are no skipped macroblocks; i.e. The syntax element *macroblock\_address\_increment* is always equal to "1", except for the first macroblock of a slice, in which case it indicates the horizontal position of the slice.

In P-frame pictures a skipped macroblock is defined to be a frame-based predicted macroblock with a reconstructed frame motion vector equal to zero.

In P-field pictures, a skipped macroblock is defined to be a field-based predicted macroblock with a reconstructed field motion vector equal to zero. The reference field for the prediction is the same parity field.

In B frame pictures, a skipped macroblock is defined to be a frame-based predicted macroblock with differential frame motion vector(s) equal to zero. The type of prediction (forward, backward or averaged) is the same as the prior macroblock.

In B field pictures, a skipped macroblock is defined to be a field-based predicted macroblock with differential field motion vector(s) equal to zero. The type of prediction (forward, backward or averaged) is the same as the prior macroblock. A reference field(s) for the prediction is (are) the same parity field(s).

In B-frame or B-field pictures, a skipped macroblock shall not follow an intra-coded macroblock.

If `sequence_scalable_extension` is present and `scalable_mode` = `spatial_scalability`, the following rules apply in addition to those given above.

In I-frame or I-field pictures, skipped macroblocks are allowed. These are defined as spatial-only predicted.

In P-pictures and B-pictures, the skipped macroblock is temporal-only predicted.

Table for B.2-5

Macroblock type table for intra pictures in spatial scalability

MB_type VLC code	Q	F M V	B M V	C B P	I n t r a	spatial_temporal_weight_code _flag	Description	spatial_temporal_weight_classes allowed
1	0	0	0	1	0	0	Coded, Compatible	4
01	1	0	0	1	0	0	Coded, Compatible, Quant	4
0011	0	0	0	0	1	0	Intra	0
0010	1	0	0	0	1	0	Intra, Quant	0
0001	0	0	0	0	0	0	Not Coded, Compatible	4

*Information:* spatial\_temporal\_weight\_codes are not present in the bitstream in intra pictures. Skipped macroblocks are spatial-only predicted.

Table for B.2-6

Macroblock type table for predicted pictures in spatial scalability

MB_type VLC code	Q	F M V	B M V	C B P	I n t r a	spatial_temporal_weight_code _flag	Description	spatial_temporal_weight_classes allowed
10	Q	1	0	1	0	0	MC, Coded	0
011	0	1	0	1	0	1	MC, Coded, Compatible	1,2,3
0000 100	0	0	0	1	0	0	No MC, Coded	0
0001 11	0	0	0	1	0	1	No MC, Coded, Compatible	1,2,3
0010	0	1	0	0	0	0	MC, Not Coded	0
0000 111	0	0	0	0	1	0	Intra	0
0011	0	1	0	0	0	1	MC, Not coded, Compatible	1,2,3
010	1	1	0	1	0	0	MC, Coded, Quant	0
0001 00	1	0	0	1	0	0	No MC, Coded, Quant	0
0000 110	1	0	0	0	1	0	Intra, Quant	0
11	1	1	0	1	0	1	MC, Coded, Compatible, Quant	1,2,3
0001 01	1	0	0	1	0	1	No MC, Coded, Compatible, Quant	1,2,3
0001 10	0	0	0	0	0	1	No MC, Not Coded, Compatible	1,2,3
0000 101	0	0	0	1	0	0	Coded, Compatible	4
0000 010	1	0	0	1	0	0	Coded, Compatible, Quant	4
0000 011	0	0	0	0	0	0	Not Coded, Compatible	4

*Information:* spatial\_temporal\_weight\_codes are only present in the bitstream when the spatial\_temporal\_weight\_class is non zero. Skipped macroblocks are temporal-only predicted.

Table for B.2-7

Macroblock type table for interpolated pictures in spatial scalability

MB_type VLC code	Q	F M V	B M V	C B P	I n t r a	spatial_temporal _weight_code _flag	Description	spatial_ temporal_ weight_ classes allowed
10	0	1	1	0	0	0	Interp, Not coded	0
11	0	1	1	1	0	0	Interp, Coded	0
010	0	0	1	0	0	0	Back, Not coded	0
011	0	0	1	1	0	0	Back, Coded	0
0010	0	1	0	0	0	0	For, Not coded	0
0011	0	1	0	1	0	0	For, Coded	0
0001 10	0	0	1	0	0	1	Back, Not Coded, Compatible	1,2,3
0001 11	0	0	1	1	0	1	Back, Coded, Compatible	1,2,3
0001 00	0	1	0	0	0	1	For, Not Coded, Compatible	1,2,3
0001 01	0	1	0	1	0	1	For, Coded, Compatible	1,2,3
0000 110	0	0	0	0	1	0	Intra	0
0000 111	1	1	1	1	0	0	Interp, Coded, Quant	0
0000 100	1	1	0	1	0	0	For, Coded, Quant	0
0000 101	1	0	1	1	0	0	Back, Coded, Quant	0
0000 0100	1	0	0	0	1	0	Intra, Quant	0
0000 0101	1	1	0	1	0	1	For, Coded, Compatible, Quant	1,2,3
0000 0110 0	1	0	1	1	0	1	Back, Coded, Compatible, Quant	1,2,3
0000 0111 0	0	0	0	0	0	0	Not Coded, Compatible	4
0000 0110 1	1	0	0	1	0	0	Coded, Compatible, Quant	4
0000 0111 1	0	0	0	1	0	0	Coded, Compatible	4

*Information:* spatial\_temporal\_weight\_codes are only present in the bitstream when the spatial\_temporal\_weight\_class is non zero. Skipped macroblocks are temporal-only predicted.

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