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THE INTERNATIONAL TELEGRAPH AND TELEPHONE CONSULTATIVE COMMITTEE

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CCITT HIGH LEVEL LANGUAGE (CHILL)

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NOTES

- 1 CCITT Recommendation Z.200 was published in Fascicle X.6 of the *Blue Book*. This file is an extract from the *Blue Book*. While the presentation and layout of the text might be slightly different from the *Blue Book* version, the contents of the file are identical to the *Blue Book* version and copyright conditions remain unchanged (see below).
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CCITT HIGH LEVEL LANGUAGE (CHILL)

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1 INTRODUCTION

This recommendation defines the CCITT high level programming language CHILL. CHILL stands for CCITT High Level Language.

The following sub-sections in this chapter introduce some of the motivations behind the language design and provide an overview of the language features.

For information concerning the variety of introductory and training material on this subject, the reader is referred to the CCITT Manuals, "Introduction to CHILL" and "CHILL user's manual".

An alternative definition of CHILL, in a strict mathematical form (based on the VDM notation), is available in the CCITT Manual entitled "Formal definition of CHILL".

1.1 GENERAL

CHILL is a strongly typed, block structured language designed primarily for the implementation of large and complex embedded systems.

CHILL was designed to:

- enhance reliability and run time efficiency by means of extensive compile-time checking;
- be sufficiently flexible and powerful to encompass the required range of applications and to exploit a variety of hardware;
- provide facilities that encourage piecewise and modular development of large systems;
- cater for real-time implementations by providing built-in concurrency and time supervision primitives;
- · permit the generation of highly efficient object code;
- be easy to learn and use.

The expressive power inherent in the language design allow engineers to select the appropriate constructs from a rich set of facilities such that the resulting implementation can match the original specification more precisely.

Because CHILL is careful to distinguish between static and dynamic objects, nearly all the semantic checking can be achieved at compile time. This has obvious run time benefits. Violation of CHILL dynamic rules results in run-time exceptions which can be intercepted by an appropriate exception handler (however, generation of such implicit checks is optional, unless a user defined handler is explicitly specified).

CHILL permits programs to be written in a machine independent manner. The language itself is machine independent; however, particular compilation systems may require the provision of specific implementation defined objects. It should be noted that programs containing such objects will not, in general, be portable.

1.2 LANGUAGE SURVEY

A CHILL program consists essentially of three parts:

- a description of data objects;
- a description of actions which are to be performed upon the data objects;
- a description of the program structure.

Data objects are described by data statements (declaration and definition statements), actions are described by action statements and the program structure is determined by program structuring statements.

The manipulatable data objects of CHILL are values and locations where values can be stored. The actions define the operations to be performed upon the data objects and the order in which values are stored into and retrieved from locations. The program structure determines the lifetime and visibility of data objects.

CHILL provides for extensive static checking of the use of data objects in a given context.

In the following sections, a summary of the various CHILL concepts is given. Each section is an introduction to a chapter with the same title, describing the concept in detail.

1.3 MODES AND CLASSES

A location has a mode attached to it. The mode of a location defines the set of values which may reside in that location and other properties associated with it (note that not all properties of a location are determinable by its mode alone). Properties of locations are: size, internal structure, read-onliness, referability, etc. Properties of values are: internal representation, ordering, applicable operations, etc.

A value has a class attached to it. The class of a value determines the modes of the locations that may contain the value.

CHILL provides the following categories of modes:

discrete modes integer, character, boolean, set (symbolic) modes and ranges thereof;
powerset modes sets of elements of some discrete mode;
bound references, free references and rows used as references to locations;
composite modes string, array and structure modes;
procedure modes procedures considered as manipulatable data objects;

instance modes identifications for processes;

synchronisation modes event and buffer modes for process synchronisation and communication;

input-output modes association, access and text modes for input-output operations;

timing modes duration and absolute time modes for time supervision.

CHILL provides denotations for a set of standard modes. Program defined modes can be introduced by means of mode definitions. Some language constructs have a so-called dynamic mode attached. A dynamic mode is a mode of which some properties can be determined only dynamically. Dynamic modes are always parameterised modes with run-time parameters. A mode that is not dynamic is called a static mode.

Classes have no denotation in CHILL. They are introduced in the metalanguage only to describe static and dynamic context conditions.

1.4 LOCATIONS AND THEIR ACCESSES

Locations are (abstract) places where values can be stored or from which values can be obtained. In order to store or obtain a value, a location has to be accessed.

Declaration statements define names to be used for accessing a location. There are:

- 1. location declarations;
- 2. loc-identity declarations.

The first one creates locations and establishes access names to the newly created locations. The latter one establishes new access names for locations created elsewhere.

Apart from location declarations, new locations can be created by means of a GETSTACK or ALLOCATE built-in routine calls yielding reference values (see below) to the newly created location.

A location may be referable. This means that a corresponding reference value exists for the location. This reference value is obtained as the result of the referencing operation, applied to the referable location. By dereferencing a reference value, the referred location is obtained. CHILL requires certain locations to be referable and others to be not referable, but for other locations it is left to the implementation to decide whether or not they are referable. Referability must be a statically determinable property of locations.

A location may have a read-only mode, which means that it can only be accessed to obtain a value and not to store a new value into it (except when initialising).

A location may be composite, which means that it has sub-locations which can be accessed separately. A sub-location is not necessarily referable. A location containing at least one read-only sub-location is said to have the read-only property. The accessing methods delivering sub-locations (or sub-values) are indexing and slicing for strings and for arrays, and selection for structures.

A location has a mode attached. If this mode is dynamic, the location is called a dynamic mode location.

The following properties of a location, although statically determinable, are not part of the mode:

referability: whether or not a reference value exists for the location;

storage class: whether or not it is statically allocated;

regionality: whether or not the location is declared within a region.

1.5 VALUES AND THEIR OPERATIONS

Values are basic objects on which specific operations are defined. A value is either a (CHILL) defined value or an undefined value (in the CHILL sense). The usage of an undefined value in specified contexts results in an undefined situation (in the CHILL sense) and the program is considered to be incorrect.

CHILL allows locations to be used in contexts where values are required. In this case, the location is accessed to obtain the value contained in it.

A value has a class attached. Strong values are values that besides their class also have a mode attached. In that case the value is always one of the values defined by the mode. The class is used for compatibility checking and the mode for describing properties of the value. Some contexts require those properties to be known and a strong value will then be required.

A value may be literal, in which case it denotes an implementation independent discrete value, known at compile time. A value may be constant, in which case it always delivers the same value, i.e. it need only be evaluated once. When the context requires a literal or constant value, the value is assumed to be evaluated before run-time and therefore cannot generate a run-time exception. A value may be intra-regional, in which case it can refer somehow to locations declared within a region. A value may be composite, i.e. contain sub-values.

Synonym definition statements establish new names to denote constant values.

1.6 ACTIONS

Actions constitute the algorithmic part of a CHILL program.

The assignment action stores a (computed) value into one or more locations. The procedure call invokes a procedure, a built-in routine call invokes a built-in routine (a built-in routine is a procedure whose definition need not be written in CHILL and whose parameter and result mechanism may be more general). To return from and/or establish the result of a procedure call, the return and result actions are used.

To control the sequential action flow, CHILL provides the following flow of control actions:

if action for a two-way branch;

case action for a multiple branch. The selection of the branch may be based upon several values,

similarly to a decision table;

do action for iteration or bracketing;

exit action for leaving a bracketed action or a module in a structured manner;

cause action to cause a specific exception;

goto action for unconditional transfer to a labelled program point.

Action and data statements can be grouped together to form a module or begin-end block, which form a (compound) action.

To control the concurrent action flow, CHILL provides the start, stop, delay, continue, send, delay case, and receive case actions, and receive and start expressions.

1.7 INPUT AND OUTPUT

The input and output facilities of CHILL provide the means to communicate with a variety of devices in the outside world.

The input-output reference model knows three states. In the free state there is no interaction with the outside world.

Through an ASSOCIATE operation the file handling state is entered. In the file handling state there are locations of association mode, which denote outside world objects. It is possible via built-in routines to read and modify the language defined attributes of associations, i.e. existing, readable, writeable, indexable, sequencible and variable. File creation and deletion are also done in the file handling state.

Through the CONNECT operation, a location of access mode is connected to a location of an association mode, and the data transfer state is entered. The CONNECT operation allows positioning of a base index in a file. In the data transfer state various attributes of locations of access mode can be inspected and the data transfer operations READRECORD and WRITERECORD can be applied.

Through the text transfer operations, CHILL values can be represented in a human-readable form which can be transferred to or from a file or a CHILL location.

1.8 EXCEPTION HANDLING

The dynamic semantic conditions of CHILL are those (non context-free) conditions that, in general, cannot be statically determined. (It is left to the implementation to decide whether or not to generate code to test the dynamic conditions at run time, unless an appropriate handler is explicitly specified.) The violation of a dynamic semantic rule causes a run-time exception; however, if an implementation can determine statically that a dynamic condition will be violated, it may reject the program.

Exceptions can also be caused by the execution of a cause action or, conditionally, by the execution of an assert action. When, at a given program point, an exception occurs, control is transferred to the associated handler for that exception, if it is specifiable (i.e. it has a name) and is specified. Whether or not a handler is specified for an exception at a given point can be statically determined. If no explicit handler is specified, control may be transferred to an implementation defined exception handler.

Exceptions have a name, which is either a CHILL defined exception name, an implementation defined exception name, or a program defined exception name. Note that when a handler is specified for an exception name, the associated dynamic condition must be checked.

1.9 TIME SUPERVISION

Time supervision facilities of CHILL provide the means to react to the elapse of time in the external world. CHILL processes may be interrupted only at precise timeoutable points during execution. When this happens, control is transferred to an appropriate handler.

Programs may detect the elapsing of a period of time or may synchronise to an absolute point of time or at precise intervals without cumulated drifts. Built-in routines for time are provided to convert time and duration values into integer values, to put a process in a waiting state and to detect the expiration of a time supervision.

1.10 PROGRAM STRUCTURE

The program structuring statements are the begin-end block, module, procedure, process and region. The program structuring statements provide the means of controlling the lifetime of locations and the visibility of names.

The lifetime of a location is the time during which a location exists within the program. Locations can be explicitly declared (in a location declaration) or generated (GETSTACK or ALLOCATE built-in routine call), or they can be implicitly declared or generated as the result of the use of language constructs.

A name is said to be visible at a certain point in the program if it may be used at that point. The scope of a name encompasses all the points where it is visible, i.e. where the denoted object is identified by that name.

Begin-end blocks determine both visibility of names and lifetime of locations.

Modules are provided to restrict the visibility of names to protect against unauthorised usage. By means of visibility statements, it is possible to exercise control over the visibility of names in various program parts.

A procedure is a (possibly parameterised) sub-program that may be invoked (called) at different places within a program. It may return a value (value procedure) or a location (location procedure), or deliver no result. In the latter case the procedure can only be called in a procedure call action.

Processes and regions provide the means by which a structure of concurrent executions can be achieved.

A complete CHILL program is a list of modules or regions that is considered to be surrounded by an (imaginary) process definition. This outermost process is started by the system under whose control the program is executed.

Constructs are provided to facilitate various ways of piecewise development of programs. A spec module and spec region are used to define the static properties of a program piece, a context is used to define the static properties of seized names. In addition it is possible to specify that the text of a program piece is to be found somewhere else through the remote facility.

1.11 CONCURRENT EXECUTION

CHILL allows for the concurrent execution of program units. A process is the unit of concurrent execution. The evaluation of a start expression causes the creation of a new process of the indicated process definition. The process is then considered to be executed concurrently with the starting process. CHILL allows for one or more processes with the same or different definition to be active at one time. The stop action, executed by a process, causes its termination.

A process is always in one of two states; it can be active or delayed. The transition from active to delayed is called the delaying of the process; the transition from delayed to active is called the re-activation of the process. The execution of delaying actions on events, or receiving actions on buffers or signals, or sending actions on buffers, can cause the executing process to become delayed. The execution of a continue action on events, or sending actions on buffers or signals, or receiving actions on buffers can cause a delayed process to become active again.

Buffers and events are locations with restricted use. The operations send, receive and receive case are defined on buffers; the operations delay, delay case and continue are defined on events. Buffers are a means of synchronising and transmitting information between processes. Events are used only for synchronisation. Signals are defined in signal definition statements. They denote functions for composing and decomposing lists of values transmitted between processes. Send actions and receive case actions provide for communication of a list of values and for synchronisation.

A region is a special kind of module. Its use is to provide for mutually exclusive access to data structures that are shared by several processes.

1.12 GENERAL SEMANTIC PROPERTIES

The semantic (non context-free) conditions of CHILL are the mode and class compatibility conditions (mode checking) and the visibility conditions (scope checking). The mode rules determine how names may be used; the scope rules determine where names may be used.

The mode rules are formulated in terms of compatibility requirements between modes, between classes and between modes and classes. The compatibility requirements between modes and classes and between classes themselves are defined in terms of equivalence relations between modes. If dynamic modes are involved, mode checking is partly dynamic.

The scope rules determine the visibility of names through the program structure and explicit visibility statements. The explicit visibility statements influence the scope of the mentioned names and also of possibly implied names of the mentioned names. Names introduced in a program have a place where they are defined or declared. This place is called the defining occurrence of the name. The places where the name is used are called applied occurrences of the name. The name binding rules associate a unique defining occurrence with each applied occurrence of the name.

1.13 IMPLEMENTATION OPTIONS

CHILL allows for implementation defined integer modes, implementation defined built-in routines, implementation defined process names, implementation defined exception handlers and implementation defined exception names.

An implementation defined integer mode must be denoted by an implementation defined mode name. This name is considered to be defined in a newmode definition statement that is not specified in CHILL. Extending the existing CHILL-defined arithmetic operations to the implementation defined integer modes is allowed within the framework of the CHILL syntactic and semantic rules. Examples of implementation defined integer modes are long integers, and short integers.

A built-in routine is a procedure whose definition need not be written in CHILL and that may have a more general parameter passing and result transmission scheme than CHILL procedures.

A built-in process name is a process name whose definition need not be written in CHILL and that may have a more general parameter passing scheme than CHILL processes. A CHILL process may cooperate with built-in processes or start such processes.

An implementation defined exception handler is a handler appended to a process definition. If this handler receives control after the occurrence of an exception, the implementation decides which actions are to be taken. An implementation defined exception is caused if an implementation defined dynamic condition is violated.

NOTE

Recommendation Z.200 was prepared by the International Telegraph and Telephone Consultative Committee (CCITT) of the International Telecommunication Union (ITU) and was adopted, under a special "fast-track procedure", as International Standard ISO/IEC 9496 by ISO (the International Organization for Standardization) and IEC (the International Electrotechnical Commission) through their Joint Technical Committee ISO/IEC JTC 1, Information technology.

The text of CCITT Recommendation Z.200 serves as ISO/IEC 9496.

2 PRELIMINARIES

2.1 THE METALANGUAGE

The CHILL description consists of two parts:

- the description of the context-free syntax;
- the description of the semantic conditions.

2.1.1 The context-free syntax description

The context-free syntax is described using an extension of the Backus-Naur Form. Syntactic categories are indicated by one or more English words, written in slanted characters, enclosed between angular brackets (< and >). This indicator is called a non-terminal symbol. For each non-terminal symbol, a production rule is given in an appropriate syntax section. A production rule for a non-terminal symbol consists of the non-terminal symbol at the lefthand side of the symbol ::=, and one or more constructs, consisting of non-terminal and/or terminal symbols at the righthand side. These constructs are separated by a vertical bar (|) to denote alternative productions for the non-terminal symbol.

Sometimes the non-terminal symbol includes an underlined part. This underlined part does not form part of the context-free description but defines a semantic category (see section 2.1.2).

Syntactic elements may be grouped together by using curly brackets ($\{$ and $\}$). Repetition of curly bracketed groups is indicated by an asterisk (*) or plus ($^+$). An asterisk indicates that the group is optional and can be further repeated any number of times; a plus indicates that the group must be present and can be further repeated any number of times. For example, $\{A\}^*$ stands for any sequence of A's, including zero, while $\{A\}^*$ stands for any sequence of at least one A. If syntactic elements are grouped using square brackets ($\{and\}$), then the group is optional. A curly or square bracketed group may contain one or more vertical bars, indicating alternative syntactic elements.

A distinction is made between strict syntax, for which the semantic conditions are given directly, and derived syntax. The derived syntax is considered to be an extension of the strict syntax and the semantics for the derived syntax is indirectly explained in terms of the associated strict syntax.

It is to be noted that the context-free syntax description is chosen to suit the semantic description in this document and is not made to suit any particular parsing algorithm (e.g. there are some context-free ambiguities introduced in the interest of clarity). The ambiguities are resolved using the semantic category of the syntactic elements.

2.1.2 The semantic description

Each syntactic category (non-terminal symbol) is described in sub-sections semantics, static properties, dynamic properties, static conditions and dynamic conditions.

The section semantics describes the concepts denoted by the syntactic categories (i.e. their meaning and behaviour).

The section static properties defines statically determinable semantic properties of the syntactic category. These properties are used in the formulation of static and/or dynamic conditions in the sections where the syntactic category is used.

The section dynamic properties defines the properties of the syntactic category, which are known only dynamically.

The section static conditions describes the context-dependent, statically checkable conditions which must be fulfilled when the syntactic category is used. Some static conditions are expressed in the syntax by means of an underlined part in the non-terminal symbol (see section 2.1.1). This use requires the non-terminal to be of a specific semantic category. E.g. < boolean expression > is identical to < expression > in the context free sense, but semantically it requires the expression to be of a boolean class.

The section dynamic conditions describes the context-dependent conditions that must be fulfilled during execution. In some cases, conditions are static if no dynamic modes are involved. In those cases, the condition is mentioned under static conditions and referred to under dynamic conditions. In other cases, dynamic conditions can be checked statically; an implementation may treat this as a violation of a static condition.

In the semantic description, different fonts are used in the following ways: slanted font (without < and >) is used to indicate syntactic objects; corresponding terms in roman font indicate corresponding semantic objects (e.g. a location denotes a location). Bolding is used to name semantic properties; sometimes a property can be expressed syntactically as well as semantically (e.g. the sentence "the expression is constant" means the same as "the expression is a <u>constant</u> expression").

Unless otherwise specified, the semantics, properties and conditions described in the sub-section of a syntactic category hold regardless of the context in which in other sections that syntactic category may appear.

The properties of a syntactic category A that has a production rule of the form A := B, where B is a syntactic category, are the same as B unless otherwise specified.

2.1.3 The examples

For most syntax sections, there is a section examples giving one or more examples of the defined syntactic categories. These examples are extracted from a set of program examples contained in Appendix D. References indicate via which syntax rule each example is produced and from which example it is taken.

E.g. 6.20 (d+5)/5 (1.2) indicates an example of the terminal string (d+5)/5, produced via rule (1.2) of the appropriate syntax section, taken from program example no. 6 line 20.

2.1.4 The binding rules in the metalanguage

Sometimes the semantic description mentions CHILL special simple name strings (see Appendix C). These special simple name strings are always used with their CHILL meaning and are therefore not influenced by the binding rules of an actual CHILL program.

2.2 VOCABULARY

Programs are represented using the CHILL character set (see Appendix A). The alphabet is represented by the syntactic category <character>, from which any character that is in the CHILL character set can be derived as terminal production.

The lexical elements of CHILL are:

- special symbols
- simple name strings
- · literals.

Apart from the lexical elements there are also special character combinations. The special symbols and special character combinations are listed in Appendix B.

Simple name strings are formed according to the following syntax:

syntax:

8

$$\langle letter \rangle ::=$$

$$A \mid B \mid C \mid D \mid E \mid F \mid G \mid H \mid I \mid J \mid K \mid L \mid M$$

$$(2.1)$$

$$| N | O | P | Q | R | S | T | U | V | W | X | Y | Z$$
 (2.2)

$$<$$
digit $> ::=$ (3) $0 \mid 1 \mid 2 \mid 3 \mid 4 \mid 5 \mid 6 \mid 7 \mid 8 \mid 9$ (3.1)

semantics: The underline character (_) forms part of the simple name string; e.g. the simple name string life_time is different from the simple name string lifetime. Lower case and upper case letters are different, e.g. Status and status are two different simple name strings.

The language has a number of special simple name strings with predetermined meanings (see Appendix C). Some of them are reserved, i.e. they cannot be used for other purposes.

The special simple name strings in a piece must either all be in upper case representation or all be in lower case representation. The reserved simple name strings are only reserved in the chosen representation (e.g. if the lower case fashion is chosen, row is reserved, ROW is not).

static conditions: A simple name string can not be one of the reserved simple name strings (see Appendix C.1).

2.3 THE USE OF SPACES

A space terminates any lexical element or special character combination. Lexical elements are also terminated by the first character that cannot be part of the lexical element. For instance, *IFBTHEN* will be considered a *simple name string* and not as the beginning of an action **IF** B **THEN**, //* will be considered as the concatenation symbol (//) followed by an asterisk (*) and not as a divide symbol (/) followed by a comment opening bracket (/*).

2.4 COMMENTS

syntax:

N.B. end-of-line denotes the end of the line in which the comment occurs.

semantics: A comment conveys information to the reader of a program. It has no influence on the program semantics.

A comment may be inserted at all places where spaces are allowed as delimiters.

A bracketed comment is terminated by the first occurrence of the special sequence: */. A line-end comment is terminated by the first occurrence of the end of the line.

examples:

2.5 FORMAT EFFECTORS

The format effectors BS (Backspace), CR (Carriage return), FF (Form feed), HT (Horizontal tabulation), LF (Line feed), and VT (Vertical tabulation) of the CHILL character set (see Appendix A, positions FE₀ to FE₅) are not mentioned in the CHILL context-free syntax description. When used, they have the same delimiting effect as a space. Spaces and format effectors may not occur within lexical elements (except character string literals).

COMPILER DIRECTIVES

syntax:

<implementation directive> (2.1)

semantics: A directive clause conveys information to the compiler. This information is specified in an implementation defined format.

An implementation directive must not influence the program semantics, i.e. a program with implementation directives is correct, in the CHILL sense, if and only if it is correct without these directives.

A directive clause is terminated by the first occurrence of the directive ending symbol (<>). A directive may contain any character of the character set (see Appendix A).

static properties: A directive clause may be inserted at any place where spaces are allowed. It has the same delimiting effect as a space. The names used in a directive clause follow an implementation defined name binding scheme which does not influence the CHILL name binding rules (see section 12.2).

NAMES AND THEIR DEFINING OCCURRENCES

syn

ntax:		
	<name> ::=</name>	(1)
	<name string=""></name>	(1.1)
	<name string=""> ::=</name>	(2)
	<simple name="" string=""></simple>	(2.1)
	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(2.2)
	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(3)
	<pre><prefix> ! <simple name="" string=""></simple></prefix></pre>	(3.1)
	<pre><prefix> ::=</prefix></pre>	(4)
	<simple prefix=""> { ! <simple prefix=""> }*</simple></simple>	(4.1)
	<simple prefix=""> ::=</simple>	(5)
	<simple name="" string=""></simple>	(5.1)
	<defining occurrence=""> ::=</defining>	(6)
	<simple name="" string=""></simple>	(6.1)
	<defining list="" occurrence=""> ::=</defining>	(7)
	<defining occurrence=""> { , <defining occurrence=""> }*</defining></defining>	(7.1)
	<field name=""> ::=</field>	(8)
	<simple name="" string=""></simple>	(8.1)
	< field name defining occurrence > ::=	(9)
	<simple name="" string=""></simple>	(9.1)
	< field name defining occurrence list> ::=	(10)
	<field defining="" name="" occurrence=""> { , <field defining="" name="" occurrence=""> }*</field></field>	(10.1)
	<exception name=""> ::=</exception>	(11)
	<simple name="" string=""></simple>	(11.1)
	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(11.2)
	<text name="" reference=""> ::=</text>	(12)
	<simple name="" string=""></simple>	(12.1)

(12.2)

| < prefixed name string>

semantics: Names in a program denote objects. Given an occurrence of a name (formally: an occurrence of a terminal production of name) in a program, the binding rules of section 12.2 provide defining occurrences (formally: occurrences of terminal productions of defining occurrence) to which that (occurrence of) name is bound. The name then denotes the object defined or declared by the defining occurrences. (There can be more than one defining occurrence for a name only in the case of set element names or of names with quasi defining occurrences.) Defining occurrences are said to define the name. A name is said to be an applied occurrence of the name created by the defining occurrence to which it is bound. The name has its rightmost simple name string equal to that of the name.

Similarly, field names are bound to field name defining occurrences and denote the fields (of a structure mode) defined by those field name defining occurrences.

Exception names are used to identify exception handlers according to the rules stated in Chapter 8.

Text reference names are used to identify descriptions of pieces of source text in an implementation defined way, subject to the rules in section 10.10.1.

When a name is bound to more than one defining occurrence, each of the defining occurrences to which the name is bound defines or declares the same object (see 10.10 and 12.2.2 for precise rules).

definition of notation: Given a name string NS, and a string of characters P, which is either a prefix or is empty, the result of prefixing NS with P, written P! NS, is defined as follows:

- if P is empty, then P! NS is NS;
- otherwise P! NS is the name string obtained by concatenating all the characters in P, a prefixing operator and all the characters in NS.

For example, if P is "q!r" and NS is "s!n" then P!NS is "q!r!s!n".

static properties: Each simple name string has a canonical name string attached which is the simple name string itself. A name string has a canonical name string attached which is:

- if the name string is a simple name string, then the canonical name string of that simple name string;
- if the name string is a prefixed name string, then the concatenation in left to right order of all simple name strings in the name string, separated by prefixing operators, i.e. interspersed spaces, comments and format effectors (if any) are left out.

In the rest of this document:

- the name string of a name, exception name or text reference name is used to denote the canonical name string of the name string in that name, exception name or text reference name, respectively;
- the name string of a defining occurrence, field name or field name defining occurrence is used to denote the canonical name string of the simple name string in that defining occurrence, field name or field name defining occurrence, respectively.

The binding rules are such that:

- names with a simple name string are bound to defining occurrences with the same name string;
- names with a prefixed name string are bound to defining occurrences with the same name string as the rightmost simple name string in the prefixed name string of the name;
- field names are bound to field name defining occurrences with the same name string as the field names.

A name inherits all the static properties attached to the name defined by the defining occurrence to which it is bound. A field name inherits all static properties attached to the field name defined by the field name defining occurrence to which it is bound.

3 MODES AND CLASSES

3.1 GENERAL

A location has a mode attached to it; a value has a class attached to it. The mode attached to a location defines the set of values that may be contained in the location, the access methods of the location and the allowed operations on the values. The class attached to a value is a means of determining the modes of the locations that may contain the value. Some values are strong. A strong value has a class and a mode attached. Strong values are required in those value contexts where mode information is needed.

3.1.1 Modes

CHILL has static modes (i.e. modes for which all properties are statically determinable) and dynamic modes (i.e. modes for which some properties are only known at run time). Dynamic modes are always parameterised modes with run-time parameters.

Static modes are terminal productions of the syntactic category mode.

In this document, virtual mode names are introduced to describe modes which are not denoted explicitly in the program text. In such cases the mode name is preceded by an ampersand symbol (&).

Modes are also parameterised by values not explicitly denoted in the program text.

3.1.2 Classes

Classes have no denotation in CHILL.

The following kinds of classes exist and any value in a CHILL program has a class of one of these kinds:

- For a mode M there exists the M-value class. All values with such a class and only those values are strong and the mode attached to the value is M.
- For a mode M there exists the M-derived class.
- For any mode M there exists the M-reference class.
- The null class.
- · The all class.

The last two classes are constant classes, i.e. they do not depend on a mode M. A class is said to be dynamic if and only if it is an M-value class, an M-derived class, or an M-reference class, where M is a dynamic mode.

3.1.3 Properties of, and relations between, modes and classes

Modes in CHILL have properties. These may be hereditary or non-hereditary properties. A hereditary property is inherited from a defining mode to a mode name defined by it. Below a summary is given of the properties that apply to all modes (except for the first, they are all defined in section 12.1):

- A mode has a novelty (defined in sections 3.2.2, 3.2.3 and 3.3).
- A mode can have the read-only property.
- A mode can be parameterisable.
- A mode can have the referencing property.
- · A mode can have the tagged parameterised property.
- A mode can have the non-value property.

Classes in CHILL may have the following properties (defined in section 12.1):

- · A class can have a root mode.
- One or more classes may have a resulting class.

Operations in CHILL are determined by the modes and classes of locations and values. This is expressed by the mode checking rules which are defined in section 12.1 as a number of relations between modes and classes. There exists the following relations:

- Two modes can be similar.
- Two modes can be v-equivalent.
- Two modes can be equivalent.
- Two modes can be l-equivalent.
- · Two modes can be alike.
- Two modes can be novelty bound.
- Two modes can be read-compatible.
- Two modes can be dynamic read-compatible.
- Two modes can be dynamic equivalent.
- A mode can be restrictable to a mode.
- A mode can be compatible with a class.
- A class can be compatible with a class.

3.2 MODE DEFINITIONS

3.2.1 General

syntax:

$$<$$
 defining mode $>$::= $<$ mode $>$ (2)

derived syntax: A mode definition where the defining occurrence list consists of more than one defining occurrence is derived from several mode definitions, one for each defining occurrence, separated by commas, with the same defining mode. For example:

NEWMODE dollar, pound = INT;

is derived from:

NEWMODE dollar = INT, pound = INT;

semantics: A mode definition defines a name that denotes the specified mode. Mode definitions occur in synmode and newmode definition statements. A synmode is synonymous with its defining mode. A newmode is not synonymous with its defining mode. The difference is defined in terms of the property novelty, that is used in the mode checking (see section 12.1).

static properties: A defining occurrence in a mode definition defines a mode name.

Predefined mode names and implementation defined integer mode names (if any, see section 3.4.2) are also mode names.

A mode name has a defining mode which is the defining mode in the mode definition which defines it. (For predefined and implementation defined mode names this defining mode is a virtual mode). The hereditary properties of a mode name are those of its defining mode.

A set of recursive definitions is a set of mode definitions or synonym definitions (see section 5.1) such that the defining mode in each mode definition or <u>constant</u> value or mode in each synonym definition is, or directly contains, a mode name or a synonym name defined by a definition in the set.

A set of recursive mode definitions is a set of recursive definitions having only mode definitions. (Any set of recursive definitions must be a set of recursive mode definitions; see section 5.1).

Any mode being or containing a mode name defined in a set of recursive mode definitions is said to denote a recursive mode. A path in a set of recursive mode definitions is a list of mode names, each name indexed with a marker such that:

- · all names in the path have a different definition;
- for each name, its successor is or directly occurs in its defining mode (the successor of the last name is the first name);
- the marker indicates uniquely the position of the name in the defining mode of its predecessor (the predecessor of the first name is the last name).

(Example: NEWMODE M = STRUCT (i M, n REF M); contains two paths: $\{M_i\}$ and $\{M_n\}$.)

A path is safe if and only if at least one of its names is contained in a reference mode, a row mode, or a procedure mode at the marked place.

static conditions: For any set of recursive mode definitions, all its paths must be safe. (The first path of the example above is not safe).

examples:

1.15 operand_mode =
$$INT$$
 (1.1)
3.3 complex = $STRUCT$ (re,im INT) (1.1)

3.2.2 Synmode definitions

syntax:

semantics: A synmode definition statement defines mode names which are synonymous with their defining mode.

static properties: A defining occurrence in a mode definition in a symmode definition statement defines a symmode name (which is also a mode name). A symmode name is said to be synonymous with a mode M (conversely, M is said to be synonymous with the symmode name) if and only if:

- either M is the defining mode of the synmode name;
- or the defining mode of the synmode name is itself a synmode name synonymous with M.

The novelty of a symmode name is that of its defining mode.

If the defining mode is a range mode, then the parent mode of the synonym name is that of its defining mode. If the defining mode is a varying string mode, then the component mode of the synonym name is that of its defining mode.

examples:

3.2.3 Newmode definitions

syntax:

semantics: A newmode definition statement defines mode names which are not synonymous with their defining mode.

static properties: A defining occurrence in a mode definition in a newmode definition statement defines a newmode name (which is also a mode name).

The novelty of the newmode name is the defining occurrence which defines it. If the defining mode of the newmode name is a range mode, then the virtual mode &name is introduced as the parent mode of the newmode name. The defining mode of &name is the parent mode of the range mode, and the novelty of &name is that of the newmode name.

If the defining mode is a varying string mode, then the virtual mode &name is introduced as the component mode of the newmode name. The defining mode of &name is the component mode of the varying string mode, and the novelty of &name is that of the newmode name.

If the defining occurrence of the mode definition is a quasi defining occurrence, then the novelty is a quasi novelty, otherwise it is a real novelty.

static conditions: If the novelty is a quasi novelty, then at most one real novelty must be novelty bound to it.

examples:

3.3 MODE CLASSIFICATION

syntax:

<mode> ::=</mode>	(1)
$[\ \mathbf{READ} \] < non-composite \ mode >$	(1.1)
[READ] <composite mode=""></composite>	(1.2)
<non-composite mode=""> ::=</non-composite>	(2)
<discrete mode=""></discrete>	(2.1)
<powerset mode=""></powerset>	(2.2)
<pre><reference mode=""></reference></pre>	(2.3)
<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(2.4)
<instance mode=""></instance>	(2.5)
<synchronisation mode=""></synchronisation>	(2.6)
<pre><input-output mode=""></input-output></pre>	(2.7)
<timing mode=""></timing>	(2.8)

semantics: A mode defines a set of values and the operations which are allowed on the values. A mode may be a read-only mode, indicating that a location of that mode may not be accessed to store a value.

A mode has a novelty, indicating whether it was introduced via a newmode definition statement or not.

static properties: A mode has the following hereditary properties:

- It is a read-only mode if it is an explicit or an implicit read-only mode.
- It is an explicit read-only mode if **READ** is specified or it is a parameterised array mode, a parameterised string mode or a parameterised structure mode, where the origin array mode name, origin string mode name or origin variant structure mode name, respectively, in it is a read-only mode.

- It is an implicit read-only mode if it is not an explicit read-only mode and if:
 - it is the element mode of a read-only array mode (see section 3.12.3);
 - it is a field mode of a read-only structure mode or it is the mode of a tag field of a parameterised structure mode (see section 3.12.4).

A mode has the same properties as the non-composite mode or composite mode in it. In the following sections, the properties are defined for predefined mode names and for modes that are not mode names; the properties of mode names are defined in section 3.2. Read-only modes have the same properties as their corresponding non-read-only modes except for the read-only property (see section 12.1.1.1).

A mode has the following non-hereditary properties:

- A novelty that is either nil or the defining occurrence in a mode definition in a newmode definition statement. The novelty of a mode which is not a <u>mode</u> name (nor READ <u>mode</u> name) is defined as follows:
 - if it is a parameterised string mode, a parameterised array mode or a parameterised structure mode, its novelty is that of its origin string mode, origin array mode or origin variant structure mode, respectively;
 - if it is a range mode, its novelty is that of its parent mode;
 - otherwise its novelty is nil.

The novelty of a mode that is a <u>mode</u> name (READ <u>mode</u> name) is defined in sections 3.2.2 and 3.2.3.

• A size that is the value delivered by SIZE (&M), where &M is a virtual symmode name synonymous with the mode.

3.4 DISCRETE MODES

3.4.1 General

syntax:

<discrete mode=""> ::=</discrete>	(1)
<integer mode=""></integer>	(1.1)
<boolean mode=""></boolean>	(1.2)
<pre><character mode=""></character></pre>	(1.3)
<pre><set mode=""></set></pre>	(1.4)
<pre><range mode=""></range></pre>	(1.5)

semantics: A discrete modes defines sets and subsets of well-ordered values.

3.4.2 Integer modes

syntax:

predefined names: The name INT is predefined as an integer mode name.

semantics: An integer mode defines a set of signed integer values between implementation defined bounds over which the usual ordering and arithmetic operations are defined (see section 5.3). An implementation may define other integer modes with different bounds (e.g. LONG_INT, SHORT_INT, ...) that may also be used as parent modes for ranges (see section 13.2). The internal representation of an integer value is the integer value itself.

static properties: An integer mode has the following hereditary properties:

- An upper bound and a lower bound which are the literals denoting respectively the highest and lowest value defined by the integer mode. They are implementation defined.
- A number of values which is upper bound lower bound + 1.

examples:

$$1.5 \qquad INT \tag{1.1}$$

3.4.3 Boolean modes

syntax:

$$<$$
boolean mode> ::= (1)
 $<$ boolean mode name> (1.1)

predefined names: The name BOOL is predefined as a boolean mode name.

semantics: A boolean mode defines the logical truth values (TRUE and FALSE), with the usual boolean operations (see section 5.3). The internal representations of FALSE and TRUE are the integer values 0 and 1, respectively. This representation defines the ordering of the values.

static properties: A boolean mode has the following hereditary properties:

- An upper bound which is TRUE, and a lower bound which is FALSE.
- A number of values which is 2.

examples:

$$5.4 \quad BOOL$$
 (1.1)

3.4.4 Character modes

syntax:

predefined names: The name CHAR is predefined as a character mode name.

semantics: A character mode defines the character values as described by the CHILL character set (see Appendix A). This alphabet defines the ordering of the characters and the integer values which are their internal representations.

static properties: A character mode has the following hereditary properties:

- An upper bound and a lower bound which are the character literals denoting respectively the highest and lowest value defined by CHAR.
- A number of values which is 256.

examples:

$$CHAR$$
 (1.1)

3.4.5 Set modes

syntax:

(3.1)

<numbered set element> { , <numbered set element> }*

semantics: A set mode defines a set of named and unnamed values. The named values are denoted by the names defined by defining occurrences in the set list; the unnamed values are the other values. The internal representation of the named values is the integer value associated with them. This representation defines the ordering of the values.

static properties: A defining occurrence in a set list defines a set element name. A set element name has a set mode attached, which is the set mode.

A set mode has the following hereditary properties:

- A set of set element names which is the set of names defined by defining occurrences in its set list.
- Each set element name of a set mode has an internal representation value attached which is, in the case of a numbered set element, the value delivered by the <u>integer literal</u> expression in it; otherwise one of the values 0, 1, 2, etc., according to its position in the unnumbered set list. For example in: SET (a,b), a has representation value 0, and b has representation value 1 attached.
- An upper bound and a lower bound which are its set element names with the highest and lowest representation values, respectively.
- A number of values which is the highest of the values attached to the set element names
 plus 1.
- It is a numbered set mode if the set list in it is a numbered set list; otherwise it is an unnumbered set mode.

static conditions: For each pair of <u>integer literal</u> expressions e_1 , e_2 in the set list NUM (e_1) and NUM (e_2) must deliver different non-negative results.

examples:

3.4.6 Range modes

<range mode> ::=

syntax:

derived syntax: The notation BIN (n) is derived from INT (0: 2^n-1), e.g. BIN (2+1) stands for INT (0: 7).

semantics: A range mode defines the set of values ranging between the bounds specified (bounds included) by the *literal range*. The range is taken from a specific parent mode that determines the operations on and ordering of the range values.

static properties: A range mode has the following non-hereditary property: it has a parent mode, defined as follows:

• If the range mode is of the form:

```
< discrete mode name> ( < literal range> )
```

then if the <u>discrete mode</u> name is not a range mode, the <u>parent</u> mode is the <u>discrete mode</u> name; otherwise it is the <u>parent</u> mode of the <u>discrete mode</u> name.

• If the range mode is of the form:

```
RANGE ( < literal range > )
```

then the parent mode is the root mode of the resulting class of the classes of the upper bound and lower bound in the literal range.

• If the range mode is a <u>range mode</u> name which is a synmode name, then its parent mode is that of the defining mode of the synmode name; otherwise it is a newmode name and then its parent mode is the virtually introduced parent mode (see section 3.2.3).

A range mode has the following hereditary properties:

- An upper bound and a lower bound which are the literals denoting the values delivered by lower bound and upper bound, respectively, in the literal range.
- A number of values which is the value delivered by NUM(U) NUM(L) + 1, where U and L denote respectively the upper bound and lower bound of the range mode.
- It is a numbered range mode if its parent mode is a numbered set mode.

(1)

static conditions: The classes of upper bound and lower bound must be compatible and both must be compatible with the <u>discrete mode</u> name, if specified.

Lower bound must deliver a value that is less than or equal to the value delivered by upper bound, and both values must belong to the set of values defined by <u>discrete mode</u> name, if specified.

The integer literal expression in case of BIN must deliver a non-negative value.

examples:

3.5 POWERSET MODES

syntax:

$$<$$
member mode $> ::=$ (2)
 $<$ discrete mode $>$ (2.1)

semantics: A powerset mode defines values that are sets of values of its member mode. Powerset values range over all subsets of the member mode. The usual set-theoretic operators are defined on powerset values (see section 5.3).

static properties: A powerset mode has the following hereditary property:

• A member mode which is the member mode.

examples:

3.6 REFERENCE MODES

3.6.1 General

syntax:

semantics: A reference mode defines references (addresses or descriptors) to referable locations. By definition, bound references refer to locations of a given static mode; free references may refer to locations of any static mode; rows refer to locations of a dynamic mode.

The dereferencing operation is defined on reference values (see sections 4.2.3, 4.2.4 and 4.2.5), delivering the location that is referenced.

Two reference values are equal if and only if they both refer to the same location, or both do not refer to a location (i.e. they are the value NULL).

3.6.2 Bound reference modes

syntax:

$$<$$
referenced mode $> ::=$ (2)
 $<$ mode $>$ (2.1)

semantics: A bound reference mode defines reference values to locations of the specified referenced mode.

static properties: A bound reference mode has the following hereditary property:

A referenced mode which is the referenced mode.

examples:

3.6.3 Free reference modes

syntax:

predefined names: The name PTR is predefined as a free reference mode name.

semantics: A free reference mode defines reference values to locations of any static mode.

examples:

$$19.8 \qquad PTR \tag{1.1}$$

3.6.4 Row modes

syntax:

semantics: A row mode defines reference values to locations of dynamic mode (which are locations of some parameterised mode with statically unknown parameters).

A row value may refer to:

- · string locations with statically unknown string length,
- array locations with statically unknown upper bound,
- parameterised structure locations with statically unknown parameters.

static properties: A row mode has the following hereditary property:

• A referenced origin mode which is the <u>string</u> mode, the <u>array</u> mode, or the <u>variant structure</u> mode, respectively.

static condition: The variant structure mode must be parameterisable.

examples:

8.6 ROW CHARS
$$(max)$$
 (1.1)

3.7 PROCEDURE MODES

syntax:

$$<$$
parameter spec> $\{$, $<$ parameter spec> $\}^*$ (2.1)

$$<$$
parameter attribute $> ::=$ (4)

RETURNS (
$$< mode > [< result attribute >]$$
) (5.1)

$$\langle exception \ list \rangle ::=$$
 (7)

semantics: A procedure mode defines (general) procedure values, i.e. the objects denoted by general procedure names that are names defined in procedure definition statements. Procedure values indicate pieces of code in a dynamic context. Procedure modes allow for manipulating a procedure dynamically, e.g. passing it as a parameter to other procedures, sending it as message value to a buffer, storing it into a location, etc.

Procedure values can be called (see section 6.7).

Two procedure values are equal if and only if they denote the same procedure in the same dynamic context, or if they both denote no procedure (i.e. they are the value NULL).

static properties: A procedure mode has the following hereditary properties:

- A list of parameter specs, each consisting of a mode and possibly a parameter attribute. The parameter specs are defined by the parameter list.
- An optional result spec, consisting of a mode and an optional result attribute. The result spec is defined by the result spec.
- A possibly empty list of exception names which are those mentioned in the exception list.
- A recursivity which is recursive if RECURSIVE is specified; otherwise an implementation defined default specifies either recursive or non-recursive.

static conditions: All names mentioned in exception list must be different.

Only if LOC is specified in the parameter spec or result spec may the mode in it have the non-value property.

If DYNAMIC is specified in the parameter spec or the result spec, the mode in it must be parameterisable.

3.8 INSTANCE MODES

syntax:

predefined names: The name INSTANCE is predefined as an instance mode name.

semantics: An instance mode defines values which identify processes. The creation of a new process (see sections 5.2.14, 6.13 and 11.1) yields a unique instance value as identification for the created process.

Two instance values are equal if and only if they identify the same process, or they both identify no process (i.e. they are the value NULL).

examples:

3.9 SYNCHRONISATION MODES

3.9.1 General

syntax:

semantics: A synchronisation mode provides a means for synchronisation and communication between processes (see chapter 11). There exists no expression in CHILL denoting a value defined by a synchronisation mode. As a consequence, there are no operations defined on the values.

3.9.2 Event modes

syntax:

$$\langle event \ mode \rangle ::=$$
 (1)

$$|<$$
 event mode name $>$ (1.2)

$$\langle event \ length \rangle ::=$$
 (2)

$$\langle \underline{integer\ literal}\ expression \rangle$$
 (2.1)

semantics: An event mode location provides a means for synchronisation between processes. The operations defined on event mode locations are the continue action, the delay action and the delay case action, which are described in section 6.15, 6.16 and 6.17, respectively.

The event length specifies the maximum number of processes that may become delayed on an event location; that number is unlimited if no event length is specified.

static properties: An event mode has the following hereditary property:

• An optional event length which is the value delivered by event length.

static conditions: The event length must deliver a positive value.

examples:

$$14.10 \quad \mathbf{EVENT} \tag{1.1}$$

3.9.3 Buffer modes

syntax:

$$<$$
buffer mode $> ::=$ (1)

$$|<$$
 buffer mode name $>$ (1.2)

$$<$$
buffer length $> ::=$ (2)

$$<$$
integer literal expression $>$ (2.1)

$$<$$
buffer element mode $> ::=$ (3)

$$< mode>$$
 (3.1)

semantics: A buffer mode location provides a means for synchronisation and communication between processes. The operations defined on buffer locations are the send action, the receive case action and the receive expression, described in section 6.18, 6.19 and 5.3.9, respectively.

The buffer length specifies the maximum number of values that can be stored in an event location; that number is unlimited if no buffer length is specified.

static properties: A buffer mode has the following hereditary properties:

- An optional buffer length which is the value delivered by buffer length.
- A buffer element mode which is the buffer element mode.

static conditions: The buffer length must deliver a non-negative value.

The buffer element mode must not have the non-value property.

examples:

3.10 INPUT-OUTPUT MODES

3.10.1General

syntax:

semantics: An input-output mode provides a means for input-output operations as defined in chapter 7. There exists no expression in CHILL denoting a value defined by an input-output mode. As a consequence, there are no operations defined on the values.

examples:

3.10.2 Association modes

syntax:

predefined names: The name ASSOCIATION is predefined as an association mode name.

semantics: An association mode location provides a means for representing a relation to an outside world object. Such a relation is called an association in CHILL; associations can be created by the built-in routine ASSOCIATE and be ended by DISSOCIATE.

3.10.3 Access modes

syntax:

(3.2)

derived syntax: The index mode notation literal range is derived from the discrete mode RANGE (literal range).

semantics: An access mode location provides a means for positioning a file and for transferring values from a CHILL program to a file in the outside world, and vice versa.

An access mode may define a record mode; this record mode defines the root mode of the class of the values that can be transferred via a location of that access mode to or from a file. The mode of the transferred value may be dynamic, i.e. the size of the record may vary, when the attribute DYNAMIC is specified in the access mode denotation or when record mode is a varying string mode. In the latter case DYNAMIC need not be specified.

An access mode may also define an index mode; such an index mode defines the size of a "window" to (a part of) the file, from which it is possible to read (or write) records randomly. Such a window can be positioned in an (indexable) file by the connect operation. If no index mode is specified, then it is possible to transfer records only sequentially.

static properties: An access mode has the following hereditary properties:

- An optional record mode which is the record mode if present. It is a dynamic record
 mode if DYNAMIC is specified or if record mode is a varying string mode, otherwise it is
 a static record mode.
- An optional index mode which is the index mode.

ACCESS (index_set) record_type

static conditions: The optional record mode must not have the non-value property.

If DYNAMIC is specified, the record mode must be parameterisable and must not be a tagless structure mode.

The index mode must neither be a numbered set mode nor a numbered range mode.

examples:

(1.1)

$$20.18 \qquad index_set \tag{3.1}$$

3.10.4 Text modes

20.18

syntax:

$$<$$
text mode $>$::= (1)

TEXT
$$(< text \ length>) [< index \ mode>] [DYNAMIC] (1.1)$$

$$\langle text \ length \rangle ::=$$
 (2)

< integer literal expression > (2.1)

semantics: A text mode location provides a means for transferring values represented in human-readable form from a CHILL program to a file in the outside world, and vice versa. A text mode location has a text record and an access sub-locations. The text record sub-location is initialised with an empty string.

A text mode has a text length, which defines the maximum length of the records that can be transferred, and possibly an index mode that has the same meaning as for access modes.

static properties: A text mode has the following hereditary properties:

- A text length which is the value delivered by text length.
- A text record mode which is CHARS (<text length>) VARYING.
- It has an access mode which is ACCESS [(<index mode>)] CHARS (<text length>) [DYNAMIC] (<index mode> and DYNAMIC are part of the mode only if they are specified).

examples:

(1.1)

3.11 TIMING MODES

3.11.1 General

syntax:

semantics: A timing mode provides a means for time supervision of processes as described in chapter 9.

Timing values are created by a set of built-in routines. The relational operators are defined on timing values.

3.11.2 Duration modes

syntax:

$$< duration mode > ::=$$

$$< \underline{duration mode name}$$

$$(1.1)$$

predefined names: The name DURATION is predefined as a duration mode name.

semantics: A duration mode defines values which represent periods of time. The set of values defined by the duration mode is implementation defined. An implementation may choose to represent duration values as pairs of precision and value. Duration values are ordered in the intuitive way.

3.11.3 Absolute time modes

syntax:

$$\langle absolute\ time\ mode \rangle ::=$$
 (1)
 $\langle absolute\ time\ mode\ name \rangle$ (1.1)

predefined names: The name TIME is predefined as an absolute time mode name.

semantics: An absolute time mode defines values which represent points in time. The set of values defined by the absolute time mode is implementation defined. Absolute time values are ordered in the intuitive way.

3.12 COMPOSITE MODES

3.12.1 General

syntax:

(1)

(5.1)

semantics: A composite mode defines composite values, i.e. values consisting of sub-components which can be accessed or obtained (see sections 4.2.6-4.2.10 and 5.2.6-5.2.10).

3.12.2 String modes

<string mode> ::=

syntax:

semantics: A fixed string mode defines bit or character string values of a length indicated or implied by the string mode. A varying string mode defines bit or character string values whose actual length can vary dynamically from 0 to the string length. The length is known only at runtime from the value of the attribute actual length. For a fixed string mode the actual length is always equal to the string length. Character strings are sequences of character values; bit strings are sequences of boolean values.

String values are either empty or have string elements which are numbered from 0 upward.

The string values of a given string mode are well-ordered in accordance with the ordering of the component values and the following definition.

Two strings s and t are equal if and only if they are empty or have the same length l and s(i) = t(i) for all $0 \le i < l$. A string s precedes t when either:

- there exists an index j such that s(j) < t(j) and s(0:j-1) = t(0:j-1), or
- LENGTH (s) < LENGTH(t) and s = t(0 UP LENGTH(s)).

The concatenation operator is defined on string values. The usual logical operators are defined on bit string values and operate between their corresponding elements (see section 5.3).

<integer literal expression>

static properties: A string mode has the following hereditary properties:

- A string length which is the value delivered by string length.
- An upper bound and a lower bound which are the values delivered by string length -1 and 0, respectively.
- It is a bit string mode or a character string mode, depending on whether string type specifies BOOLS or CHARS, or whether origin string mode name is a bit or character string mode.
- It is a varying string mode if VARYING is specified or if the origin string mode name is a varying string mode; otherwise it is a fixed string mode.

A string mode is parameterised if and only if it is a parameterised string mode.

A parameterised string mode has an origin string mode which is the mode denoted by origin string mode name.

A varying string mode has the following non-hereditary property: it has a component mode, defined as follows:

• If the varying string mode is of the form:

<string type> (<string length>) VARYING

then it is <string type> (<string length>).

• If the varying string mode is of the form:

<origin string mode name> (<string length>)

then the component mode is &name (string length), where &name is a virtually introduced synmode name synonymous with the component mode of the origin string mode name.

• If the varying string mode is a <u>string mode</u> name which is a synmode name, then its component mode is that of the defining mode of the synmode name; otherwise it is a newmode name and then its component mode is the virtually introduced component mode (see section 3.2.3).

static conditions: The string length must deliver a non-negative value.

The value delivered by the string length directly contained in a parameterised string mode must be less than or equal to the string length of the origin string mode name. This condition applies only to the parameterised string modes that are not introduced virtually.

examples:

3.12.3 Array modes

syntax:

<array mode=""> ::= APRAY (sinday mode> [sinday mode>]*)</array>	(1)
ARRAY (<index mode=""> { , <index mode=""> }*) <element mode=""> { <element layout=""> }* <parameterised array="" mode=""> <array mode="" name=""></array></parameterised></element></element></index></index>	(1.1) (1.2) (1.3)
<pre><parameterised array="" mode=""> ::=</parameterised></pre>	(2) (2.1) (2.2)
<origin array="" mode="" name=""> ::= <<u>array mode</u> name></origin>	(3) (3.1)
<upper index=""> ::= < discrete literal expression></upper>	(4) (4.1)
<pre><element mode=""> ::= <mode></mode></element></pre>	(5) (5.1)

derived syntax: An array mode with more than one index mode (denoting a multi-dimensional array), is derived syntax for an array mode with an element mode that is an array mode. For example:

is derived from:

Only if this derived syntax is used, is more than one element layout occurrence allowed. The number of element layout occurrences must be less than or equal to the number of index mode occurrences. In that case, the leftmost element layout is associated with the innermost element mode, etc.

semantics: An array mode defines composite values, which are lists of values defined by its element mode. The physical layout of an array location or value can be controlled by element layout specification (see section 3.12.5). Two array values are equal if and only if all corresponding element values are equal.

static properties: An array mode has the following hereditary properties:

• An index mode which is the index mode if it is not a parameterised array mode, otherwise the index mode is the range mode constructed as:

&name (lower bound: upper bound)

where &name is a virtual synmode name synonymous with the index mode of origin array mode name, lower bound is the lower bound of the index mode of the origin array mode name and upper bound is the upper index.

- An upper bound and a lower bound which are the upper bound and the lower bound of its index mode, respectively.
- An element mode which is either M or READ M, where M is the element mode, or the element mode of the origin array mode name, respectively. The element mode will be READ M if and only if M is not a read-only mode and the array mode is a read-only mode. The element mode is an implicit read-only mode if it is READ M.
- An element layout which, if it is a parameterised array mode, is the element layout of its origin array mode name; otherwise it is either the specified element layout, or the implementation default, which is either PACK or NOPACK.
- A number of elements which is the value delivered by:

$$NUM$$
 (upper bound) - NUM (lower bound) + 1

where upper bound and lower bound are respectively the upper bound and the lower bound of its index mode.

• It is a mapped mode if element layout is specified and is a step.

An array mode is parameterised if and only if it is a parameterised array mode.

A parameterised array mode has an origin array mode which is the mode denoted by origin array mode name.

static conditions: The class of upper index must be compatible with the index mode of the origin array mode name and the value delivered by it must lie in the range defined by that index mode.

examples:

5.29 ARRAY (1:16) STRUCT (c4, c2, c1 BOOL)
$$(1.1)$$

3.12.4 Structure modes

syntax:

```
(1)
<structure mode> ::=
                                                                                               (1.1)
        STRUCT ( < field > { , < field > }* )
                                                                                               (1.2)
       | | parameterised structure mode>
                                                                                               (1.3)
         <structure mode name>
                                                                                                 (2)
<field> ::=
         <fixed field>
                                                                                               (2.1)
                                                                                               (2.2)
       | <alternative field>
                                                                                                 (3)
<fixed field> ::=
         < field name defining occurrence list> < mode> [ < field layout> ]
                                                                                               (3.1)
                                                                                                 (4)
<alternative field> ::=
         CASE [ < tag \ list > ] OF
         <variant alternative> { , <variant alternative> }*
         [ ELSE [ < variant field> { , < variant field> }* ] ] ESAC
                                                                                               (4.1)
                                                                                                 (5)
<variant alternative> ::=
         [ <case label specification> ] : [ <variant field> { , <variant field> } ^* ]
                                                                                               (5.1)
                                                                                                 (6)
< tag\ list> ::=
         <tag field name> \{ , <tag field name> \}*
                                                                                               (6.1)
                                                                                                 (7)
<variant field> ::=
         < field name defining occurrence list> < mode> [ < field layout> ]
                                                                                               (7.1)
                                                                                                 (8)
cparameterised structure mode> ::=
         <origin variant structure mode name> ( teral expression list> )
                                                                                                (8.1)
                                                                                               (8.2)
        parameterised structure mode name>
                                                                                                 (9)
<origin variant structure mode name> ::=
                                                                                               (9.1)
         <variant structure mode name>
                                                                                                (10)
literal expression list> ::=
         < discrete literal expression> { , < discrete literal expression> }*
                                                                                              (10.1)
```

derived syntax: A fixed field occurrence or variant field occurrence, where field name defining occurrence list consists of more than one field name defining occurrence, is derived syntax for several fixed field occurrences or variant field occurrences with one field name defining occurrence respectively, each with the specified mode and optional field layout. In the case of field layout, this field layout must not be pos. For example:

STRUCT (I,J BOOL PACK)

is derived from:

STRUCT (I BOOL PACK, J BOOL PACK)

semantics: Structure modes define composite values consisting of a list of values, selectable by a component name. Each value is defined by a mode that is attached to the component name. Structure values may reside in (composite) structure locations, where the component name serves as an access to the sub-location. The components of a structure value or location are called fields and their names field names.

There are fixed structures, variant structures and parameterised structures.

Fixed structures consist only of fixed fields, i.e. fields that are always present and that can be accessed without any dynamic check.

Variant structures have variant fields, i.e. fields that are not always present. For tagged variant structures, the presence of these fields is known only at run time from the value(s) of certain associated fixed field(s) called tag fields. Tag-less variant structures do not have tag fields. Because the composition of a variant structure may change during run time, the size of a variant structure location is based upon the largest choice (worst case) of variant alternatives.

In an alternative field the variant alternative chosen is that for which values give in the case label specification match; if no value match, the variant alternative following ELSE (which will be present) is chosen.

A parameterised structure is determined from a variant structure mode for which the choice of variant alternatives is statically specified by means of literal expressions. The composition is fixed from the point of the creation of the parameterised structure and may not change during run time. The tag fields, if present, are read-only and automatically initialised with the specified values. For a parameterised structure location, a precise amount of storage can be allocated at the point of declaration or generation. Note that dynamic parameterised structure modes also exist; their semantics are defined in section 3.13.4.

The layout of a structure location or value can be controlled by means of a field layout specification (see section 3.12.5).

Two structure values are equal if and only if the corresponding component values are equal. However, if the structure values are tag-less variant structure values, the result of comparison is implementation defined.

static properties:

general:

A structure mode has the following hereditary properties:

- It is a fixed structure mode if it is a structure mode that does not directly contain an alternative field occurrence.
- It is a variant structure mode if it is a structure mode and contains at least one alternative field occurrence.
- It is a parameterised structure mode if it is a parameterised structure mode.
- It has a set of field names. This set is defined below for the different cases. A name is said to be a field name if and only if it is defined in a field name defining occurrence list in fixed fields or variant fields in a structure mode.

Each fixed field, variant field and therefore each field name of a structure mode has a field mode attached that is either M or READ M, where M is the mode in the fixed field or variant field. The field mode is READ M if M is not a read-only mode and either the structure mode is a read-only mode, or the field is a tag field of a parameterised structure mode. The field mode is an implicit read-only mode if it is READ M.

A fixed field, variant field and therefore a field name of a given structure mode has a field layout attached to it that is the field layout in the fixed field or variant field, if present; otherwise it is the default field layout, which is either PACK or NOPACK.

It is a mapped mode if its field names have a field layout that is pos.

fixed structures:

A fixed structure mode has the following hereditary property:

• A set of field names which is the set of names defined by any field name defining occurrence list in fixed fields. These field names are fixed field names.

variant structures:

A variant structure mode has the following hereditary properties:

• A set of field names which is the union of the set of names defined by any field name defining occurrence list in fixed fields and the set of names defined by any field name defining occurrence list in alternative fields. Field names defined by a field name defining occurrence list in fixed fields are the fixed field names of the variant structure mode; its other field names are the variant field names.

A field name of a variant structure mode is a tag field name if and only if it occurs in any tag list of an alternative field. Alternative fields in which no tag list are specified are tag-less alternative fields.

- A variant structure mode is a tag-less variant structure mode if all its alternative field occurrences are tag-less. Otherwise it is a tagged variant structure mode.
- A variant structure mode is a parameterisable variant structure mode if it is either a tagged variant structure mode or a tag-less variant structure mode where for each of the alternative field occurrences a case label specification is given for all the variant alternative occurrences in it.
- A parameterisable variant structure mode has a list of classes attached, determined as follows:
 - if it is a tagged variant structure mode, the list of M_i -value classes, where M_i are the modes of the tag field names in the order that they are defined in fixed fields;
 - if it is a tag-less variant structure mode, the list is built up from the individual resulting lists of classes of each alternative field by concatenating them in the order as the alternative fields occur. The resulting list of classes of an alternative field occurrence is the resulting list of classes of the list of case label specification occurrences in it (see section 12.3).

parameterised structures:

A parameterised structure mode has the following hereditary properties:

- An origin variant structure mode which is the mode denoted by origin variant structure mode name.
- A set of field names which is the union of the set of fixed field names of its origin variant structure mode and the set of those variant field names of its origin variant structure mode that are defined in variant alternative occurrences that are selected by the list of values defined by literal expression list.

The set of tag field names of a parameterised structure mode is the set of tag field names of its origin variant structure mode.

- · A list of values attached, defined by literal expression list.
- It is a tagged parameterised structure mode if its origin variant structure mode is a tagged variant structure mode; otherwise the parameterised structure mode is tag-less.

For dynamic parameterized structure modes see section 3.13.4.

static conditions:

general:

All field names of a structure mode must be different.

If any field has a field layout which is pos, all the fields must have a field layout which must be pos.

variant structures:

A tag field name must be a fixed field name and must be textually defined before all the alternative field occurrences in whose tag list it is mentioned. (As a consequence, a tag field precedes all the variant fields that depend upon it). The mode of a tag field name must be a discrete mode.

The mode of variant field may have neither the non-value property nor the tagged parameterised property.

In a variant structure mode the alternative field occurrences must be either all tagged or all tagless. For tag-less alternative fields, case label specification may be omitted in all variant alternative occurrences together, or must be specified for each variant alternative occurrence.

If, for a tag-less variant structure mode, any of its alternative fields has case label specification given, all its alternative fields must have case label specification.

For alternative fields, the case selection conditions must be fulfilled (see section 12.3), and the same completeness, consistency and compatibility requirements must hold as for the case action (see section 6.4). Each of the tag field names of tag list (if present) serves as a case selector with the M-value class, where M is the mode of the tag field name. In the case of tag-less alternative fields, the checks involving the case selector are ignored.

For a parameterisable variant structure mode none of the classes of its attached list of classes may be the all class. (This condition is automatically fulfilled by a tagged variant structure mode.)

parameterised structures:

The origin variant structure mode name must be parameterisable.

There must be as many literal expressions in the literal expression list as there are classes in the list of classes of the origin variant structure mode name. The class of each literal expression must be compatible with the corresponding (by position) class of the list of classes. If the latter class is an M-value class, the value delivered by the literal expression must be one of the values defined by M.

examples:

3.3	STRUCT (re, im INT)	(1.1)
11.7	STRUCT (status SET (occupied, free),	, ,
	CASE status OF	
	(occupied): p piece,	
	(free):	
	ESAC)	(1.1)
2.6	fraction	(1.3)
11.7	status SET (occupied, free)	(3.1)
11.8	status	(6.1)
11.9	p piece	(7.1)

3.12.5 Layout description for array modes and structure modes

syntax:

<integer literal expression> (9.1)
semantics: It is possible to control the layout of an array or a structure by giving packing or mapping information in its mode. Packing information is either PACK or NOPACK, mapping information is either step in the case of array modes, or pos in the case of structure modes. The absence of

If PACK is specified for elements of an array or fields of a structure, it means that the use of memory space is optimised for the array elements or structure fields, whereas NOPACK implies that the access time for the array elements or the structure fields is optimised. NOPACK also implies referable.

element layout or field layout in an array or structure mode will always be interpreted as packing

(8)

(9)

(8.1)

< integer literal expression>

information, i.e. either as PACK or as NOPACK.

<end bit> ::=

< length> ::=

The PACK, NOPACK information is applied only for one level, i.e. it is applied to the elements of the array or fields of the structure, not for possible components of the array element or structure field. The layout information is always attached to the nearest mode to which it may apply and which does not already have layout attached. For example, if the default packing is NOPACK:

is equivalent to:

It is also possible to control the precise layout of an array or a structure by specifying positioning information for its components in the mode. This positioning information is given in the following ways:

- For array modes, the positioning information is given for all elements together, in the form of a step following the array mode.
- For structure modes, the positioning information is given for each field individually, in the form of a pos, following the mode of the field.

Mapping information with pos is given in terms of word and bit-offsets. A pos of the form:

defines a bit-offset of

and a length of NUM (length) bits, where WIDTH is the (implementation defined) number of bits in a word, and word is an <u>integer literal</u> expression.

When pos is specified in field layout it defines that the corresponding field starts at the given bit-offset from the start of each location of that mode, and occupies the given length.

A step of the form:

defines a series of bit-offsets b_i for i taking values 0 to n-1 where n is the number of elements in the array and

$$b_i = i * NUM \text{ (step size)}.$$

The j-th element of the array starts at a bit-offset of $p + b_j$ from the start of each location of the array mode, where p is the bit-offset specified in pos. Each element occupies the length given in pos.

Defaults

The notation:

is semantically equivalent to:

The notation:

is semantically equivalent to:

where BSIZE is the minimum number of bits which is needed to be occupied by the component for which the pos is specified.

The notation:

is semantically equivalent to:

The notation:

is semantically equivalent to

where SSIZE is the <length> specified in pos or derivable from pos by the above rules.

static properties: For any location of an array mode the element layout of the mode determines the referability of its sub-locations (including sub-arrays, array slices) as follows:

- either all sub-locations are referable, or none of them are;
- · if the element layout is NOPACK all sub-locations are referable.

For any location of a structure mode, the referability of the structure field selected by a field name is determined by the field layout of the field name as follows:

• the field name is referable if the field layout is NOPACK.

static conditions: If the element mode of a given array mode or the field mode of a field name of a given structure mode, is itself an array or structure mode, then it must be a mapped mode if the given array or structure mode is mapped.

Each of word, start bit, end bit, length and step size must, if specified, deliver a non negative value; and the values delivered by start bit and end bit must be less than WIDTH, the number of bits in an implementation's word; and the value delivered by start bit must be less than or equal to that of end bit.

Each implementation defines for each mode a minimum number of bits its values need to occupy; call this the minimum bit occupancy. For discrete modes it is any number of bits not less than log to the base two of the number of values of the mode. For array modes it is the offset of the element of the highest index plus its occupied bits. For structure modes it is the offset of the highest bit occupied.

For each pos the length specified must not be less than the minimum bit occupancy of the mode of the associated field or array components.

For each mapped array mode the step size must not be less than the length given or implied in the

Consistency and feasibility

Consistency:

No component of a structure may be specified such that it occupies any bits occupied by another component of the same object except in the case of two variant field names defined in the same alternative field occurrence; however, in the latter case the variant field names may not both be defined in the same variant alternative nor both following ELSE.

Feasibility:

There are no language defined feasibility requirements, except for the one that can be deduced from the rule that the referability of a sub-location of any (referable or non-referable) location is determined only by the (element or field) layout, which is a property of the mode of the location. This places some restrictions on the mapping of components that themselves have referable components.

examples:

19.14 POS
$$(1,0.15)$$
 (4.2)

3.13 DYNAMIC MODES

3.13.1 General

A dynamic mode is a mode of which some properties are known only at run time. Dynamic modes are always parameterised modes with one or more run-time parameters. For description purposes, virtual denotations are introduced in this document. These virtual denotations are preceded by the ampersand symbol (&) to distinguish them from actual notations which appears in a CHILL program text.

3.13.2 Dynamic string modes

virtual denotation: & <origin string mode name > (< integer expression >)

semantics: A dynamic string mode is a parameterised string mode with statically unknown length.

static properties: Dynamic string modes have the same properties as string modes, except for the properties described below.

dynamic properties:

- A dynamic string mode has a dynamic string length which is the value delivered by <u>integer</u> expression.
- A dynamic string mode has an upper bound and a lower bound which are the values delivered by string length -1 and 0, respectively.

3.13.3 Dynamic array modes

virtual denotation: & < origin array mode name > (< discrete expression >)

semantics: A dynamic array mode is a parameterised array mode with statically unknown upper bound.

static properties: Dynamic array modes have the same properties as array modes, except for the properties described below.

dynamic properties:

• A dynamic array mode has a dynamic upper bound which is the value delivered by <u>discrete</u> expression, and a dynamic number of elements which is the value delivered by

```
NUM \ (\underline{discrete} \ expression) - NUM \ (lower \ bound) + 1
```

where lower bound is the lower bound of the origin array mode name.

3.13.4 Dynamic parameterised structure modes

virtual denotation: & < origin variant structure mode name > (< expression list >)

- semantics: A dynamic parameterised structure mode is a parameterised structure mode with statically unknown parameters.
- static properties: The static properties of a dynamic parameterised structure mode are those of a static parameterised structure mode except for the following:
 - The set of field names of a dynamic parameterised structure mode is the set of field names of its origin variant structure mode.

dynamic properties:

• A dynamic parameterised structure mode has a list of values attached that is the list of values delivered by the expressions in the expression list.

4 LOCATIONS AND THEIR ACCESSES

4.1 DECLARATIONS

4.1.1 General

syntax:

$$<$$
declaration $> ::=$ (2)

semantics: A declaration statement declares one or more names to be an access to a location.

examples:

4.1.2 Location declarations

<location declaration> ::=

syntax:

semantics: A location declaration creates as many locations as there are defining occurrences specified in the defining occurrence list.

With reach-bound initialisation, the value is evaluated each time the reach in which the declaration is placed is entered (see section 10.2) and the delivered value is assigned to the location(s). Before the value is evaluated the location(s) contain(s) the undefined value.

With lifetime-bound initialisation, the value yielded by the <u>constant</u> value is assigned to the location(s) only once at the beginning of the lifetime of the location(s) (see sections 10.2 and 10.9).

Specifying no initialisation is semantically equivalent to the specification of a lifetime-bound initialisation with the undefined value (see section 5.3.1).

The meaning of the undefined value as initialisation for a location which has attached a mode with the tagged parameterised property or the non-value property is as follows:

- tagged parameterised property: the created tag field sub-location(s) are initialised with their corresponding parameter value.
- non-value property:
 - the created event and/or buffer (sub-)location(s) are initialised to "empty", i.e. no delayed processes are attached to the event or buffer nor are there messages in the buffer;
 - the created association (sub-)location(s) are initialised to "empty", i.e. they do not contain an association;

(1)

- the created access (sub-)location(s) are initialised to "empty", i.e. they are not connected to an association;
- the created text (sub-)location(s) have a text record sub-location which is initialised with an empty string and an access sub-location which is initialised with "empty", i.e. it is not connected to an association.

The semantics of STATIC and handler can be found in section 10.9 and chapter 8, respectively.

static properties: A defining occurrence in a location declaration defines a location name. The mode attached to the location name is the mode specified in the location declaration. A location name is referable.

static conditions: The class of the value or <u>constant</u> value must be compatible with the mode and the delivered value should be one of the values defined by the mode, or the undefined value.

If the mode has the read-only property, initialisation must be specified. If the mode has the non-value property, reach-bound initialisation must not be specified.

If initialisation is specified, the value must be regionally safe for the location (see section 11.2.2).

dynamic conditions: In the case of reach-bound initialisation, the assignment conditions of value with respect to the mode apply (see section 6.2).

examples:

5.7
$$k2$$
, x, w, t, s, r $BOOL$ (1.1)

$$6.9 := julian_day_number (3.1)$$

8.4 INIT :=
$$['A':'Z']$$
 (4.1)

4.1.3 Loc-identity declarations

syntax:

semantics: A loc-identity declaration creates as many access names to the specified location as there are defining occurrences specified in the defining occurrence list. The mode of the location may be dynamic only if DYNAMIC is specified.

If the location is evaluated dynamically, this evaluation is done each time the reach in which the loc-identity declaration is placed is entered. In this case, a declared name denotes an undefined location prior to the first evaluation during the lifetime of the access denoted by the declared name (see sections 10.2 and 10.9).

static properties: A defining occurrence in a loc-identity declaration defines a loc-identity name. The mode attached to a loc-identity name is, if DYNAMIC is not specified, the mode specified in the loc-identity declaration; otherwise it is the dynamically parameterised version of it that has the same parameters as the mode of the location.

A loc-identity name is referable if and only if the specified location is referable.

static conditions: If DYNAMIC is specified in the loc-identity declaration, the mode must be parameterisable. The specified mode must be dynamic read-compatible with the mode of the location if DYNAMIC is specified and read-compatible with the mode of the location otherwise.

The location must not be a string element or string slice in which the mode of the <u>string</u> location is a varying string mode.

dynamic conditions: The RANGEFAIL or TAGFAIL exception occurs if DYNAMIC is specified, and the above-mentioned dynamic read-compatible check fails.

examples:

11.36 starting square LOC :=
$$b(m.lin_1)(m.col_1)$$
 (1.1)

4.2 LOCATIONS

4.2.1 General

syntax:

<location> ::=</location>	(1)
<access name=""></access>	(1.1)
<pre><dereferenced bound="" reference=""></dereferenced></pre>	(1.2)
<pre><dereferenced free="" reference=""></dereferenced></pre>	(1.3)
<dereferenced row=""></dereferenced>	(1.4)
<pre><string element=""></string></pre>	(1.5)
<pre><string slice=""></string></pre>	(1.6)
<pre><array element=""></array></pre>	(1.7)
<array slice=""></array>	(1.8)
<structure field=""></structure>	(1.9)
<location call="" procedure=""></location>	(1.10)
<location built-in="" call="" routine=""></location>	(1.11)
<pre><location conversion=""></location></pre>	(1.12)

semantics: A location is an object that can contain values. Locations have to be accessed to store or obtain a value.

static properties: A location has the following properties:

- A mode, as defined in the appropriate sections. This mode is either static or dynamic.
- It is static or not (see section 10.9).
- It is intra-regional or extra-regional (see section 11.2.2).
- It is referable or not. The language definition requires certain locations to be referable and
 others to be not referable as defined in the appropriate sections. An implementation may
 extend referability to other locations except when explicitly disallowed.

4.2.2 Access names

syntax:

<access name=""> ::=</access>	1	(1)
< <u>location</u> name>		(1.1)
< <u>loc-identity</u> name>		(1.2)
< location enumeration name>		(1.3)
<pre><<u>location do-with</u> name></pre>		(1.4)

semantics: An access name delivers a location. An access name is one of the following:

- a location name, i.e. a name explicitly declared in a location declaration or implicitly declared in a formal parameter without the LOC attribute;
- a loc-identity name, i.e. a name explicitly declared in a loc-identity declaration or implicitly declared in a formal parameter with the LOC attribute;
- a location enumeration name, i.e. a loop counter in a location enumeration;
- a location do-with name, i.e. a field name used as direct access in the do action with a with part.

If the location denoted by a <u>location do-with</u> name is a variant field of a tag-less variant structure location, the semantics are implementation defined.

static properties: The (possibly dynamic) mode attached to an access name is the mode of the <u>location</u> name, <u>loc-identity</u> name, <u>location enumeration</u> name or <u>location do-with</u> name, respectively.

An access name is referable if and only if it is a <u>location</u> name, a referable <u>location enumeration</u> name, or a referable <u>location do-with</u> name.

dynamic conditions: When accessing via a loc-identity name, it must not denote an undefined location.

When accessing via a <u>loc-identity</u> name a location which is a variant field, the variant field access conditions for the location must be satisfied (see section 4.2.10). Accessing via a <u>location do-with</u> name causes a TAGFAIL exception if the denoted location is a variant field and the variant field access conditions for the location are not satisfied.

examples:

4.12	a	(1.1)
11.39	starting	(1.2)
15.35	each	(1.3)
5.10	c1	(1.4)

4.2.3 Dereferenced bound references

syntax:

semantics: A dereferenced bound reference delivers the location that is referenced by the bound reference value.

static properties: The mode attached to a dereferenced bound reference is the <u>mode</u> name if specified, otherwise the referenced mode of the mode of the <u>bound reference</u> primitive value. A dereferenced bound reference is referable.

static conditions: The <u>bound reference</u> primitive value must be strong. If the optional <u>mode</u> name is specified, it must be read-compatible with the referenced mode of the <u>bound reference</u> primitive value.

dynamic conditions: The lifetime of the referenced location must not have ended.

The EMPTY exception occurs if the bound reference primitive value delivers the value NULL.

If the referenced location is a variant field, the variant field access conditions for the location must be satisfied (see section 4.2.10).

examples:

$$10.54 \quad p \rightarrow \tag{1.1}$$

4.2.4 Dereferenced free references

syntax:

semantics: A dereferenced free reference delivers the location that is referenced by the free reference value.

static properties: The mode attached to a dereferenced free reference is the <u>mode</u> name. A dereferenced free reference is referable.

static conditions: The free reference primitive value must be strong.

dynamic conditions: The lifetime of the referenced location must not have ended.

The EMPTY exception occurs if the free reference primitive value delivers the value NULL.

The mode name must be read-compatible with the mode of the referenced location.

If the referenced location is a variant field, the variant field access conditions for the location must be satisfied (see section 4.2.10).

4.2.5 Dereferenced rows

syntax:

$$<$$
 dereferenced row $> ::=$ (1)
 $<$ row primitive value $> ->$ (1.1)

semantics: A dereferenced row delivers the location that is referenced by the row value.

static properties: The dynamic mode attached to a dereferenced row is constructed as follows:

where <u>origin mode</u> name is a virtual synmode name synonymous with the referenced origin mode of the mode of the <u>row</u> primitive value and where the parameters are, depending on the referenced origin mode:

- the dynamic string length, in the case of a string mode;
- the dynamic upper bound, in the case of an array mode;
- the list of values associated with the mode of the parameterised structure location, in the case of a variant structure mode.

A dereferenced row is referable.

static conditions: The row primitive value must be strong.

dynamic conditions: The lifetime of the referenced location must not have ended.

The EMPTY exception occurs if the row primitive value delivers NULL.

If the referenced location is a variant field, the variant field access conditions for the location must be satisfied (see section 4.2.10).

examples:

8.11
$$input \rightarrow$$
 (1.1)

4.2.6 String elements

syntax:

semantics: A string element delivers a (sub-)location which is the element of the specified string location indicated by start element.

static properties: The mode attached to the string element is BOOL or CHAR depending on whether the mode of the string location is a bit string mode or a character string mode.

If the mode of the string location is a varying string mode, then the string element is not referable.

dynamic conditions: The RANGEFAIL exception occurs if the following relation does not hold:

$$0 \leq NUM \text{ (start element)} \leq L-1$$

Where L is the actual length of the string location.

examples:

$$18.16 \quad string \rightarrow (i) \tag{1.1}$$

4.2.7 String slices

syntax:

$$\langle integer \ expression \rangle$$
 (2.1)

$$<$$
right element $> ::=$ (3)

$$\langle integer | expression \rangle$$
 (3.1)

$$\langle slice \ size \rangle ::=$$
 (4)

$$\langle integer | expression \rangle$$
 (4.1)

semantics: A string slice delivers a (possibly dynamic) string location that is the part of the specified string location indicated by left element and right element or start element and slice size. The (possibly dynamic) length of the string slice is determined from the specified expressions.

A string slice in which the right element delivers a value which is less than that delivered by the left element or in which slice size delivers a non positive value denotes an empty string.

static properties: The (possibly dynamic) mode attached to a string slice is a parameterised string mode constructed as:

&name (string size)

where &name is a virtual synmode name synonymous with the (possibly dynamic) mode of the <u>string</u> location if it is a fixed string mode, otherwise with the component mode, and where string size is either

$$NUM$$
 (right element) - NUM (left element) + 1

or

NUM (slice size).

However, if an empty string is denoted, string size is 0. The mode attached to a string slice is static if string size is literal, i.e. left element and right element are literal or slice size is literal; otherwise the mode is dynamic.

If the mode of the string location is a varying string mode, then the string slice is not referable.

static conditions: The following relations must hold:

 $0 \le NUM \ (left \ element) \le L-1$

 $0 \le NUM \text{ (right element)} \le L-1$

 $0 \leq NUM \ (start \ element) \leq L-1$

NUM (start element) + NUM (slice size) $\leq L$

where L is the actual length of the <u>string</u> location. If L and the value all <u>integer</u> expressions are known statically, the relations can be checked statically.

dynamic conditions: The RANGEFAIL exception occurs if a dynamic part of the check of the relations above fails.

examples:

18.23 string
$$\rightarrow$$
 (scanstart UP 10) (1.2)

4.2.8 Array elements

syntax:

$$\langle \underline{array} | location \rangle (\langle expression | list \rangle)$$
 (1.1)

$$\langle expression \ list \rangle ::=$$
 (2)

$$\langle expression \rangle \{ , \langle expression \rangle \}^*$$
 (2.1)

derived syntax: The notation: (<expression list>) is derived syntax for:

where there are as many parenthesised expressions as there are expressions in the expression list. Thus an array element in the strict syntax has only one (index) expression.

semantics: An array element delivers a (sub-)location which is the element of the specified array location indicated by expression.

static properties: The mode attached to the array element is the element mode of the mode of the array location.

An array element is referable if the element layout of the mode of the array location is NOPACK.

static conditions: The class of the expression must be compatible with the index mode of the mode of the array location.

dynamic conditions: The RANGEFAIL exception occurs if the following relation does not hold:

$$L \leq \text{expression} \leq U$$

where L and U are the lower bound and the (possibly dynamic) upper bound of the mode of the <u>array</u> location, respectively.

examples:

$$11.36 \quad b(m.lin_1)(m.col_1)$$
 (1.1)

4.2.9 Array slices

syntax

$$\langle array \ slice \rangle ::=$$
 (1)

$$\langle first \ element \rangle ::=$$
 (4)

$$\langle expression \rangle$$
 (4.1)

semantics: An array slice delivers a (possibly dynamic) array location which is the part of the specified array location indicated by lower element and upper element or first element and slice size. The lower bound of the array slice is equal to the lower bound of the specified array; the (possibly dynamic) upper bound is determined from the specified expressions.

static properties: The (possibly dynamic) mode attached to an array slice is a parameterised array mode constructed as:

&name (upper index)

where &name is a virtual symmode name synonymous with the (possibly dynamic) mode of the <u>array</u> location and upper index is either an expression whose class is compatible with the classes of lower element and upper element and delivers a value such that:

$$NUM$$
 (upper index) = NUM (L) + NUM (upper element) - NUM (lower element)

or is an expression whose class is compatible with the class of first element and delivers a value such that:

$$NUM$$
 (upper index) = NUM (L) + NUM (slice size) - 1

where L is the lower bound of the mode of the array location.

The mode attached to an array slice is static if upper index is literal, i.e. lower element and upper element are both literal or slice size is literal; otherwise the mode is dynamic.

An array slice is referable if the element layout of the mode of the array location is NOPACK.

static conditions: The classes of lower element and upper element or the class of first element must be compatible with the index mode of the array location.

The following relations must hold:

 $L \leq lower \ element \leq upper \ element \leq U$

$$1 < NUM \text{ (slice size)} < NUM \text{ (}U\text{)} - NUM \text{ (}L\text{)} + 1$$

$$NUM(L) \leq NUM$$
 (first element) $\leq NUM$ (first element) $+ NUM$ (slice size) $-1 \leq NUM$ (U)

where L and U are respectively the lower bound and upper bound of the mode of the <u>array</u> location. If U and the value of all expressions are known statically, the relations can be checked statically.

dynamic conditions: The RANGEFAIL exception occurs if a dynamic part of the check of the relations above fails.

examples:

17.27 res
$$(0: count - 1)$$
 (1.1)

4.2.10 Structure fields

syntax:

semantics: A structure field delivers a (sub-)location which is the field of the specified structure location indicated by field name. If the <u>structure</u> location has a tag-less variant structure mode and the field name is a variant field name, the semantics are implementation defined.

static properties: The mode of the structure field is the mode of the field name.

A structure field is referable if the field layout of the field name is NOPACK.

static conditions: The field name must be a name from the set of field names of the mode of the <u>structure</u> location.

dynamic conditions: A location must not denote:

- a tagged variant structure mode location in which the associated tag field value(s) indicate(s) that the field does not exist;
- a dynamic parameterised structure mode location in which the associated list of values indicates that the field does not exist.

The above mentioned conditions are called the variant field access conditions for the location (note that the condition do not include the occurrence of an exception). The TAGFAIL exception occurs if they are not satisfied for the <u>structure</u> location.

examples:

$$10.57 \quad last \rightarrow .info \tag{1.1}$$

4.2.11 Location procedure calls

syntax:

semantics: A location procedure call delivers the location returned from the procedure.

static properties: The mode attached to a location procedure call is the mode of the result spec of the <u>location</u> procedure call if **DYNAMIC** is not specified in it; otherwise it is the dynamically parameterised version of it that has the same parameters as the mode of the delivered location.

The location procedure call is referable if NONREF is not specified in the result spec of the location procedure call.

dynamic conditions: The <u>location</u> procedure call must not deliver an undefined location and the lifetime of the delivered location must not have ended.

4.2.12 Location built-in routine calls

syntax:

semantics: A location built-in routine call delivers the location returned from the built-in routine call.

static properties: The mode attached to the location built-in routine call is the mode of the result spec of the <u>location</u> built-in routine call.

dynamic conditions: The <u>location</u> built-in routine call must not deliver an undefined location and the lifetime of the delivered location must not have ended.

4.2.13 Location conversions

syntax:

$$<$$
location conversion> ::= (1)
 $<$ mode name> ($<$ static mode location>) (1.1)

semantics: A location conversion delivers the location denoted by <u>static mode</u> location. However, it overrides the CHILL mode checking and compatibility rules and explicitly attaches a mode to the location.

The precise dynamic semantics of a location conversion are implementation defined.

static properties: The mode of a location conversion is the mode name.

A location conversion is referable.

static conditions: The static mode location must be referable.

The following relation must hold:

SIZE (mode name) = SIZE (static mode location)

5 VALUES AND THEIR OPERATIONS

5.1 SYNONYM DEFINITIONS

syntax:

derived syntax: A synonym definition, where defining occurrence list consists of more than one defining occurrence, is derived from several synonym definition occurrences, one for each defining occurrence with the same <u>constant</u> value and mode, if present. E.g. SYN i, j = 3; is derived from SYN i = 3, j = 3;

semantics: A synonym definition defines a name that denotes the specified constant value.

static properties: A defining occurrence in a synonym definition defines a synonym name.

The class of the synonym name is, if a mode is specified, the M-value class, where M is the mode, otherwise the class of the <u>constant</u> value.

A synonym name is undefined if and only if the <u>constant</u> value is an undefined value (see section 5.3.1).

A synonym name is literal if and only if the constant value is literal.

static conditions: If a mode is specified, it must be compatible with the class of the <u>constant</u> value and the value delivered by the <u>constant</u> value must be one of the values defined by the <u>mode</u>.

Synonym definitions must not be recursive nor mutually recursive via other synonym definitions or mode definitions, i.e. no set of recursive definitions may contain synonym definitions (see section 3.2.1).

examples:

5.2 PRIMITIVE VALUE

5.2.1 General

syntax:

<pre><pre><pre><pre>tive value> ::=</pre></pre></pre></pre>	(1)
< location contents>	(1.1)
<pre><value name=""></value></pre>	(1.2)
literal>	(1.3)
<tuple></tuple>	(1.4)
<pre>< value string element></pre>	(1.5)
<pre>< value string slice></pre>	(1.6)
< value array element>	(1.7)
<pre>< value array slice></pre>	(1.8)
<pre>< value structure field></pre>	(1.9)
<pre><expression conversion=""></expression></pre>	(1.10)

< value procedure call>	(1.11)
<pre>< value built-in routine call></pre>	(1.12)
<pre><start expression=""></start></pre>	(1.13)
<zero-adic operator=""></zero-adic>	(1.14)
< parenthesised expression>	(1.15)

semantics: A primitive value is the basic constituent of an expression. Some primitive values have a dynamic class, i.e. a class based on a dynamic mode. For these primitive values the compatibility checks can only be completed at run time. Check failure will then result in the TAGFAIL or RANGEFAIL exception.

static properties: The class of the primitive value is the class of the location contents, value name, etc., respectively.

A primitive value is constant if and only if it is a constant value name, a literal, a constant tuple, a constant expression conversion, a constant value built-in routine call or a constant parenthesised expression.

A primitive value is literal if and only if it is a value name that is literal, a discrete literal, or a value built-in routine call that is literal.

5.2.2 Location contents

syntax:

semantics: A location contents delivers the value contained in the specified location. The location is accessed to obtain the stored value.

static properties: The class of the location contents is the M-value class, where M is the (possibly dynamic) mode of the location.

static conditions: The mode of the location must not have the non-value property.

dynamic conditions: The delivered value must not be undefined.

examples:

$$3.7$$
 c2.im (1.1)

5.2.3 Value names

syntax:

semantics: A value name delivers a value. A value name is one of the following:

- a synonym name, i.e. a name defined in a synonym definition statement;
- a value enumeration name, i.e. a name defined by a loop counter in a value enumeration;
- a value do-with name, i.e. a field name introduced as value name in the do action with a with part;
- a value receive name, i.e. a name introduced in a receive case action;
- a general procedure name (see section 10.4).

If the value denoted by a <u>value do-with</u> name is a variant field of a tag-less variant structure value, the semantics are implementation defined.

static properties: The class of a value name is the class of the <u>synonym</u> name, <u>value enumeration</u> name, <u>value do-with</u> name, <u>value receive</u> name or the M-derived class, where M is the mode of the <u>general</u> <u>procedure</u> name, respectively.

A value name is literal if and only if it is a synonym name that is literal.

A value name is constant if it is a <u>synonym</u> name or a <u>general procedure</u> name denoting a procedure name which has attached a <u>procedure</u> definition which is not surrounded by a block.

static conditions: The synonym name must not be undefined.

dynamic conditions: Evaluating a <u>value do-with</u> name causes a TAGFAIL exception if the denoted value is a variant field and the variant field access conditions for the value are not satisfied.

examples:

5.2.4 Literals

5.2.4.1 General

syntax:

<pre><literal> ::=</literal></pre>	(1)
<integer literal=""></integer>	(1.1)
<boolean literal=""></boolean>	(1.2)
<character literal=""></character>	(1.3)
<pre><set literal=""></set></pre>	(1.4)
<emptiness literal=""></emptiness>	(1.5)
<pre><character literal="" string=""></character></pre>	(1.6)
< bit string literal>	(1.7)

semantics: A literal delivers a constant value.

static properties: The class of the literal is the class of the integer literal, boolean literal, etc., respectively.

A literal is discrete if it is either an integer literal, a boolean literal, a character literal or a set literal.

The letter together with the following apostrophe which starts an integer literal, boolean literal, and bit string literal (i.e. B', D', H', O', b', d', h', o') is a literal qualification.

5.2.4.2 Integer literals

syntax:

$$[\{ D \mid d \} '] \{ < digit > |_{-} \}^{+}$$
 (2.1)

$$\langle binary\ integer\ literal > ::=$$
 (3)
 $\{ B \mid b \}$ ' $\{ 0 \mid 1 \mid _ \}^+$ (3.1)

 ::=
$$\{ O \mid o \} ' \{ \mid _ \}^+$$

$$(4.1)$$

$$\{H \mid h\} \ '\{< \text{hexadecimal digit}> \mid _\}^+$$
 (5.1)

$$\begin{array}{l} < h \text{exadecimal digit} > ::= \\ < d \text{igit} > \mid A \mid B \mid C \mid D \mid E \mid F \mid a \mid b \mid c \mid d \mid e \mid f \end{array}$$

$$< octal \ digit > ::=$$
 (7)
0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 (7.1)

semantics: An integer literal delivers a non-negative integer value. The usual decimal (base 10) notation is provided as well as binary (base 2), octal (base 8) and hexadecimal (base 16). The underline character (...) is not significant, i.e. it serves only for readability and it does not influence the denoted value.

static properties: The class of an integer literal is the INT-derived class. An integer literal is constant and literal.

static conditions: The string following the apostrophe (') and the whole integer literal must not consist solely of underline characters.

examples:

5.2.4.3 Boolean literals

syntax:

predefined names: The names FALSE and TRUE are predefined as boolean literal names.

semantics: A boolean literal delivers a boolean value.

static properties: The class of a boolean literal is the BOOL-derived class. A boolean literal is constant and literal.

examples:

5.2.4.4 Character literals

syntax:

semantics: A character literal delivers a character value. Apart from the printable representation, the control sequence representation may be used.

static properties: The class of a character literal is the CHAR-derived class. A character literal is constant and literal.

static conditions: A control sequence in a character literal must denote only one character.

examples:

7.9
$$'M'$$
 (1.1)

5.2.4.5 Set literals

syntax:

$$\langle set \ literal \rangle ::=$$
 $\langle set \ element \ name \rangle$
(1)

semantics: A set literal delivers a set value. A set literal is a name defined in a set mode.

static properties: The class of a set literal is the M-derived class, where M is the set mode attached to the set element name. A set literal is constant and literal.

examples:

5.2.4.6 Emptiness literal

syntax:

predefined names: The name NULL is predefined as an emptiness literal name.

semantics: The emptiness literal delivers either the empty reference value, i.e. a value which does not refer to a location, the empty procedure value, i.e. a value which does not indicate a procedure, or the empty instance value, i.e. a value which does not identify a process.

static properties: The class of the emptiness literal is the null class. An emptiness literal is constant.

examples:

5.2.4.7 Character string literals

syntax:

semantics: A character string literal delivers a character string value that may be of length 0. It is a list of values for the elements of the string; the values are given for the elements in increasing order of their index from left to right. To represent the character quote (") within a character string literal, it has to be written twice ("").

Apart from the printable representation, the control sequence representation may be used. A control sequence in which the circumflex character (^) is followed by an open parenthesis denotes the sequence of characters whose representations are the <u>integer literal</u> expression in it; otherwise if it is followed by another circumflex character it denotes itself, otherwise it denotes the character whose representation is obtained by logically negating the b7 of the internal representation of the <u>non-special</u> character in it (see Appendix A).

static properties: The string length of a character string literal is the number of <u>non-reserved</u> character, quote and characters denoted by control sequence occurrences.

The class of a character string literal is the CHARS (n)-derived class, where n is the string length of the character string literal. A character string literal is constant.

static conditions: The value delivered by an <u>integer literal</u> expression in a control sequence must belong to the range of values defined by the representations of the characters in the CHILL character set (see Appendix A).

examples:

8.20 "
$$A-B < ZAA9K$$
" (1.1)

5.2.4.8 Bit string literals

syntax:

semantics: A bit string literal delivers a bit string value that may be of length 0. Binary, octal or hexadecimal notations may be used. The underline character (_) is insignificant, i.e. it serves only for readability and does not influence the indicated value.

A bit string literal is a list of values for the elements of the string; the values are given for the elements in increasing order of their index from left to right.

static properties: The string length of a bit string literal is either the number of 0 and 1 occurrences after B', three times the number of octal digit occurrences after O' or four times the number of hexadecimal digit occurrences after H'.

The class of a bit string literal is the BOOLS (n)-derived class, where n is the string length of the bit string literal. A bit string literal is constant.

examples:

5.2.5 Tuples

syntax:

(4.1)

$$<$$
case label list $>$: $<$ value $>$ { , $<$ case label list $>$: $<$ value $>$ }* (6.1)

<unlabelled array tuple>

derived syntax: The tuple opening and closing brackets, [and], are derived syntax for (: and :), respectively.

This is not indicated in the syntax to avoid confusion with the use of square brackets as meta symbols.

semantics: A tuple delivers either a powerset value, an array value or a structure value.

If it is a powerset value, it consists of a list of expressions and/or ranges denoting those member values which are in the powerset value. A range denotes those values which lie between or are one of the values delivered by the expressions in the range. If the second expression delivers a value which is less than the value delivered by the first expression, the range is empty, i.e. it denotes no values. The powerset tuple may denote the empty powerset value.

If it is an array value, it is a (possibly labelled) list of values for the elements of the array; in the unlabelled array tuple, the values are given for the elements in increasing order of their index; in the labelled array tuple, the values are given for the elements whose indices are specified in the case label list labelling the value. It can be used as a shorthand for large array tuples where many values are the same. The label ELSE denotes all the index values not mentioned explicitly. The label * denotes all index values (for further details, see section 12.3).

If it is a structure value, it is a (possibly labelled) set of values for the fields of the structure. In the unlabelled structure tuple, the values are given for the fields in the same order as they are specified in the attached structure mode. In the labelled structure tuple, the values are given for the fields whose field names are specified in the field name list for the value.

The order of evaluation of the expressions and values in a tuple is undefined and they may be considered as being evaluated in mixed order.

static properties: The class of a tuple is the M-value class, where M is the <u>mode</u> name, if specified. Otherwise M depends upon the context where the tuple occurs, according to the following list:

- if the tuple is the value or <u>constant</u> value in an initialisation in a location declaration, then M is the mode in the location declaration;
- if the tuple is the righthand side value in a single assignment action, then M is the (possibly dynamic) mode of the lefthand side location;
- if the tuple is the <u>constant</u> value in a synonym definition with a specified mode, then M is that mode;
- if the tuple is an actual parameter in a procedure call or in a start expression where DY-NAMIC is not specified in the corresponding parameter spec, then M is the mode in the corresponding parameter spec;
- if the tuple is the value in a return action or a result action, then M is the mode of the result spec of the procedure name of the result action or return action (see section 6.8);
- if the tuple is a value in a send action, then it is the associated mode specified in the signal definition of the <u>signal</u> name or the buffer element mode of the mode of the <u>buffer</u> location;
- if the tuple is an expression in an array tuple, then M is the element mode of the mode of the array tuple;
- if the tuple is an expression in an unlabelled structure tuple or a labelled structure tuple where the associated field name list consists of only one field name, then M is the mode of the field in the structure tuple for which the tuple is specified;
- If the tuple is the value in a GETSTACK or ALLOCATE built-in routine call, then M is the mode denoted by mode argument.

A tuple is constant if and only if each value or expression occurring in it is constant.

static conditions: The optional <u>mode</u> name may be deleted only in the contexts specified above. Depending on whether a powerset tuple, array tuple or structure tuple is specified, the following compatibility requirements must be fulfilled:

a. powerset tuple

- 1. The mode of the tuple must be a powerset mode.
- 2. The class of each expression must be compatible with the member mode of the mode of the tuple.
- 3. For a constant powerset tuple the value delivered by each expression must be one of the values defined by that member mode.

b. array tuple

- 1. The mode of the tuple must be an array mode.
- 2. The class of each value must be compatible with the element mode of the mode of the tuple.
- 3. In the case of an unlabelled array tuple, there must be as many occurrences of value as the number of elements of the array mode of the tuple.
- 4. In the case of a labelled array tuple, the case selection conditions must hold for the list of case label list occurrences (see section 12.3). The resulting class of the list must be compatible with the index mode of the mode of the tuple. The list of case label specifications must be complete.
- 5. In the case of a labelled array tuple, the values explicitly indicated by each case label in a case label list must be values defined by the index mode of the tuple.
- 6. In an unlabelled array tuple, at least one value occurrence must be an expression.
- 7. For a constant array tuple, where the element mode of the mode of the tuple is a discrete mode, each specified value must deliver a value defined by that element mode, unless it is an undefined value.

c. structure tuple

- The mode of the tuple must be a structure mode.
- 2. This mode must not be a structure mode which has field names which are invisible (see section 12.2.5).

In the case of an unlabelled structure tuple:

- If the mode of the tuple is neither a variant structure mode nor a parameterised structure mode, then:
 - 3. There must be as many occurrences of value as there are field names in the list of field names of the mode of the tuple.
 - 4. The class of each value must be compatible with the mode of the corresponding (by position) field name of the mode of the tuple.
- If the mode of the tuple is a tagged variant structure mode or a tagged parameterised structure mode, then:
 - 5. Each value specified for a tag field must be a discrete literal expression.
 - 6. There must be as many occurrences of value as there are field names indicated as existing by the value(s) delivered by the <u>discrete literal</u> expression occurrences specified for the tag fields.
 - 7. The class of each value must be compatible with the mode of the corresponding field name.
- If the mode of the tuple is a tag-less variant structure mode or a tag-less parameterised structure mode, then:
 - 8. No unlabelled structure tuple is allowed.

In the case of a labelled structure tuple:

- If the mode of the tuple is neither a variant structure mode nor a parameterised structure mode, then:
 - 9. Each field name of the list of field names of the mode of the tuple must be mentioned once and only once in a field name list and in the same order as in the mode of the tuple.
 - 10. The class of each value must be compatible with the mode of every field name specified in the field name list labelling that value.
- If the mode of the tuple is a tagged variant structure mode or a tagged parameterised structure mode, then:
 - 11. Each value that is specified for a tag field must be a <u>discrete literal</u> expression.
 - 12. Only field names corresponding to fields indicated as existing by the value(s) delivered by the <u>discrete literal</u> expression occurrences specified for the tag fields may be specified and all of them must be specified and must be in the same order as in the mode of the tuple.
 - 13. The class of each value must be compatible with the mode of any field name specified in the field name list labelling that value.
- If the mode of the tuple is a tag-less variant structure mode or a tag-less parameterised structure mode, then:
 - 14. Field names mentioned in field name list, which are defined in the same alternative field, must be all defined in the same variant alternative or defined after ELSE. All the field names of a selected variant alternative or defined after ELSE must be mentioned once and only once in the same order as in the mode of the tuple.
 - 15. The class of each value must be compatible with the mode of any field name specified in the field name list labelling that value.
- 16. If the mode of the tuple is a tagged parameterised structure mode, the list of values delivered by the <u>discrete literal</u> expression occurrences specified for the tag fields must be the same as the list of values of the mode of the tuple.
- 17. For a constant structure tuple, each value specified for a field with a discrete mode must deliver a value defined by the field mode, unless it is an undefined value.
- 18. At least one value occurrence must be an expression.

No tuple may have two value occurrences in it such that one is extra-regional and the other is intra-regional (see section 11.2.2).

dynamic conditions: The assignment conditions of any value with respect to the member mode, element mode or associated field mode, in the case of powerset tuple, array tuple or structure tuple, respectively (see section 6.2) apply (refer to conditions a2, b2, c4, c7, c10, c13 and c15).

If the tuple has a dynamic array mode, the RANGEFAIL exception occurs if any of the conditions b3 or b5 are not satisfied.

If the tuple has a dynamic parameterised structure mode, the TAGFAIL exception occurs if any of the conditions c14 or c16 are not satisfied.

The value delivered by a tuple must not be undefined.

examples:

9.6	number_list[]	(1.1)
9.7	[2:max]	(2.1)
8.26	[('A'):3,('B','K','Z'):1,(ELSE):0]	(6.1)
17.5	[(*):' 1	(6.1)
12.35	(:NULL,NULL,536:)	(7.1)
11.18	[.status:occupied,.p:[white,rook]]	(9.1)

5.2.6 Value string elements

syntax:

N.B. if the <u>string</u> primitive value is a <u>string</u> location, the syntactic construct is ambiguous and will be interpreted as a string element (see section 4.2.6).

semantics: A value string element delivers a value which is the element of the specified string value indicated by start element.

static properties: The class of the value string element is the BOOL-value class or CHAR-value class depending on whether the mode of the <u>string</u> primitive value is a bit string mode or a character string mode.

dynamic conditions: The value delivered by a value string element must not be undefined.

The RANGEFAIL exception occurs if the following relation does not hold:

$$0 \le NUM \text{ (start element)} \le L-1$$

Where L is the actual length of the string primitive value.

5.2.7 Value string slices

syntax:

N.B. if the <u>string</u> primitive value is a <u>string</u> location, the syntactic construct is ambiguous and will be interpreted as a <u>string</u> slice (see section 4.2.7).

semantics: A value string slice delivers a (possibly dynamic) string value which is the part of the specified string value indicated by left element and right element or start element and slice size. The (possibly dynamic) length of the string slice is determined from the specified expressions.

A string slice in which the right element delivers a value which is less than that delivered by the left element or in which slice size delivers a non positive value denotes an empty string.

static properties: The (possibly dynamic) class of a value string slice is the M-value class if the <u>string</u> primitive value is strong and otherwise the M-derived class, where M is a parameterised string mode constructed as:

```
&name (string size)
```

where &name is a virtual symmode name synonymous with the (possibly dynamic) root mode of the <u>string</u> primitive value if it is a fixed string mode, otherwise with the component mode, and where string size is either

$$NUM (right element) - NUM (left element) + 1$$

10

NUM (slice size).

However, if an empty string is denoted, string size is 0. The class of a value string slice is static if string size is literal, i.e. left element and right element are literal or slice size is literal; otherwise the class is dynamic.

static conditions: The following relations must hold:

$$0 \le NUM \ (left \ element) \le L-1$$

$$0 \leq NUM \text{ (right element)} \leq L-1$$

$$0 \leq NUM \text{ (start element)} \leq L-1$$

$$NUM$$
 (start element) + NUM (slice size) $\leq L$

where L is the actual length of the <u>string</u> primitive value. If L and the value all <u>integer</u> expressions are known statically, the relations can be checked statically.

dynamic conditions: The value delivered by a value string slice must not be undefined.

The RANGEFAIL exception occurs if a dynamic part of the check of the relations above fails.

5.2.8 Value array elements

syntax:

N.B. If the <u>array</u> primitive value is an <u>array</u> location the syntactic construct is ambiguous and will be interpreted as an array element (see section 4.2.8).

derived syntax: See section 4.2.8.

semantics: A value array element delivers a value which is the element of the specified array value indicated by expression.

static properties: The class of the value array element is the M-value class, where M is the element mode of the mode of the array primitive value.

static conditions: The class of the expression must be compatible with the index mode of the mode of the array primitive value.

dynamic conditions: The value delivered by a value array element must not be undefined.

The RANGEFAIL exception occurs if the following relation does not hold:

$$L \leq expression \leq U$$

where L and U are the lower bound and (possibly dynamic) upper bound of the mode of the <u>array</u> primitive value, respectively.

5.2.9 Value array slices

syntax:

N.B. If the <u>array primitive value</u> is an <u>array location</u>, the syntactic construct is ambiguous and will be interpreted as an array slice (see section 4.2.9).

semantics: A value array slice delivers an (possibly dynamic) array value which is the part of the specified array value indicated by lower element and upper element, or first element and slice size. The lower bound of the value array slice is equal to the lower bound of the specified array value; the (possibly dynamic) upper bound is determined from the specified expressions.

static properties: The (possibly dynamic) class of a value array slice is the M-value class, where M is a parameterised array mode constructed as:

```
&name (upper index)
```

where &name is a virtual symmode name symonymous with the (possibly dynamic) mode of the <u>array</u> primitive value and upper index is either an expression whose class is compatible with the classes of lower element and upper element and delivers a value such that:

$$NUM$$
 (upper index) = NUM (L) + NUM (upper element) - NUM (lower element)

or is an expression whose class is compatible with the class of first element and delivers a value such that:

$$NUM$$
 (upper index) = NUM (L) + NUM (slice size) - 1

where L is the lower bound of the mode of the array primitive value.

The class of a value array slice is static if upper index is literal, i.e. lower element and upper element both are literal or slice size is literal; otherwise the class is dynamic.

static conditions: The classes of lower element and upper element or the class of first element must be compatible with the index mode of the array primitive value.

The following relations must hold:

```
L < lower element < upper element < U
```

$$1 < NUM$$
 (slice size) $< NUM$ (U) $- NUM$ (L) $+ 1$

$$NUM(L) < NUM$$
 (first element) $< NUM$ (first element) $+ NUM$ (slice size) $-1 < NUM$ (U)

where L and U are, respectively, the lower bound and upper bound of the mode of the <u>array</u> primitive value. If U and the value af all expressions are known statically, the relations can be checked statically.

dynamic conditions: The value delivered by a value array slice must not be undefined.

The RANGEFAIL exception occurs if a dynamic part of the check of the relations above fails.

5.2.10 Value structure fields

syntax:

N.B. If the <u>structure</u> primitive value is a <u>structure</u> location, the syntactic construct is ambiguous and will be interpreted as a <u>structure</u> field (see section 4.2.10).

semantics: A value structure field delivers a value which is the field of the specified structure value indicated by field name. If the <u>structure</u> primitive value has a tag-less variant structure mode and the field name is a variant field name, the semantics are implementation defined.

static properties: The class of value structure field is the M-value class, where M is the mode of the field

static conditions: The field name must be a name from the set of field names of the mode of the <u>structure</u> primitive value.

dynamic conditions: The value delivered by a value structure field must not be undefined.

A value must not denote:

- a tagged variant structure mode value in which the associated tag field value(s) indicate(s) that the denoted field does not exist;
- a dynamic parameterised structure mode value in which the associated list of values indicates that the field does not exist.

The above mentioned conditions are called the variant field access conditions for the value (note that the condition do not include the occurrence of an exception). The TAGFAIL exception occurs if they are not satisfied for the <u>structure</u> primitive value.

examples:

5.2.11 Expression conversions

syntax:

$$<$$
expression conversion $>$::= (1)
 $<$ mode name $>$ ($<$ expression $>$) (1.1)

N.B. If the expression is a <u>static mode</u> location, the syntactic construct is ambiguous and will be interpreted as a location conversion (see section 4.2.13).

semantics: An expression conversion overrides the CHILL mode checking and compatibility rules. It explicitly attaches a mode to the expression. If the mode of the <u>mode</u> name is a discrete mode and the class of the value delivered by the expression is discrete, then the value delivered by the expression conversion is such that:

$$NUM \ (\underline{mode} \ name \ (expression)) = NUM \ (expression)$$

Otherwise the value delivered by the expression conversion is implementation defined and depends on the internal representation of values.

static properties: The class of the expression conversion is the M-value class, where M is the <u>mode</u> name.

An expression conversion is constant if and only if the expression is constant.

static conditions: The <u>mode</u> name must not have the non-value property. An implementation may impose additional static conditions.

dynamic conditions: If the class of the value delivered by expression is discrete and if the mode of the mode name is a discrete mode which does not define a value with an internal representation equal to NUM (expression), then the OVERFLOW exception occurs. An implementation may impose additional dynamic conditions that, when violated, result in the occurrence of an exception defined by the implementation.

5.2.12 Value procedure calls

syntax:

semantics: A value procedure call delivers the value returned from a procedure.

static properties: The class of the value procedure call is the M-value class, where M is the mode of the result spec of the <u>value</u> procedure call.

dynamic conditions: The <u>value</u> procedure call must not deliver an undefined value (see sections 5.3.1 and 6.8).

examples:

5.2.13 Value built-in routine calls

syntax:

 ::= (1)
<
$$\underline{\text{value}}$$
 built-in routine call> (1.1)

semantics: A value built-in routine call delivers the value returned by the built-in routine.

static properties: The class attached to the value built-in routine call is the class of the <u>value</u> built-in routine call.

dynamic conditions: The <u>value</u> built-in routine call must not deliver an undefined value (see sections 5.3.1 and 6.8).

5.2.14 Start expressions

syntax:

semantics: The evaluation of the start expression creates and activates a new process whose definition is indicated by the <u>process</u> name (see chapter 11). The start expression delivers the instance value identifying the created process. Parameter passing is analogous to procedure parameter passing; however, additional actual parameters may be given with an implementation defined meaning.

static properties: The class of the start expression is the INSTANCE-derived class.

static conditions: The number of actual parameter occurrences in the actual parameter list must not be less than the number of formal parameter occurrences in the formal parameter list of the process definition of the <u>process</u> name. If the number of actual parameters is m and the number of formal parameters is n ($m \ge n$), the compatibility and regionality requirements for the first n actual parameters are the same as for procedure parameter passing (see section 6.7). The static conditions for the rest of the actual parameters are implementation defined.

dynamic conditions: For parameter passing, the assignment conditions of any actual value with respect to the mode of its associated formal parameter apply (see section 6.7).

The start expression causes the SPACEFAIL exception if storage requirements cannot be satisfied.

examples:

5.2.15 Zero-adic operator

syntax:

$$<$$
zero-adic operator $> ::=$ (1)
THIS (1.1)

semantics: The zero-adic operator delivers the unique instance value identifying the process executing it. static properties: The class of the zero-adic operator is the INSTANCE-derived class.

5.2.16 Parenthesised expression

syntax:

semantics: A parenthesised expression delivers the value delivered by the evaluation of the expression.

static properties: The class of the parenthesised expression is the class of the expression.

A parenthesised expression is constant (literal) if and only if the expression is constant (literal).

examples:

5.10 (al OR b1)
$$(1.1)$$

5.3 VALUES AND EXPRESSIONS

5.3.1 General

syntax:

semantics: A value is either an undefined value or a (CHILL defined) value delivered as the result of the evaluation of an expression.

Except where explicitly indicated to the contrary, the order of evaluation of the constituents of an expression and their sub-constituents, etc., is undefined and they may be considered as being evaluated in mixed order. They need only be evaluated to the point that the value to be delivered is determined uniquely. If the context requires a constant or literal expression, the evaluation is assumed to be done prior to run time and cannot cause an exception. An implementation will define ranges of allowed values for literal and constant expressions and may reject a program if such a prior-to-run-time evaluation delivers a value out of the implementation defined bounds.

static properties: The class of a value is the class of the expression or undefined value, respectively.

The class of the undefined value is the all class if the undefined value is a *; otherwise the class is the class of the <u>undefined synonym</u> name.

A value is constant if and only if it is an undefined value or an expression which is constant. A value is literal if and only if it is an expression which is literal.

dynamic properties: A value is said to be undefined if it is denoted by the undefined value or when explicitly indicated in this document. A composite value is undefined if and only if all its sub-components (i.e. substring values, element values, field values) are undefined.

examples:

6.40
$$(146_097*c)/4+(1_461*y)/4 + (153+m+c)/5+day+1_721_119$$
 (1.1)

5.3.2 Expressions

syntax:

```
(1)
<expression> ::=
                                                                                             (1.1)
        <operand-0>
                                                                                             (1.2)
       | <conditional expression>
                                                                                              (2)
<conditional expression> ::=
       | IF < boolean expression > < then alternative >
                                                                                             (2.1)
        <else alternative> FI
       | CASE < case selector list > OF { < value case alternative > } +
        [ ELSE < sub expression> ] ESAC
                                                                                             (2.2)
                                                                                              (3)
<then alternative> ::=
                                                                                             (3.1)
        THEN < sub expression>
                                                                                              (4)
<else alternative> ::=
        ELSE < sub expression>
                                                                                             (4.1)
       | ELSIF < boolean expression>
                                                                                             (4.2)
         <then alternative> <else alternative>
                                                                                              (5)
<sub expression> ::=
                                                                                             (5.1)
         <expression>
                                                                                              (6)
<value case alternative> ::=
         <case label specification> : <sub expression> ;
                                                                                             (6.1)
```

semantics: If IF is specified, the <u>boolean</u> expression is evaluated and if it yields TRUE, the result is the value delivered by the sub expression in the then alternative, otherwise it is the value delivered by the else alternative.

The value delivered by an else alternative is the value of the sub expression if **ELSE** is specified, otherwise the <u>boolean</u> expression is evaluated and if it yields TRUE, it is the value delivered by the sub expression in the then alternative, otherwise it is the value delivered by the else alternative.

If CASE is specified, the sub expressions in the case selector list are evaluated and if a case label specification matches, the result is the value delivered by the corresponding sub expression, otherwise it is the value delivered by the sub expression following ELSE (which will be present).

Unused sub expressions in a conditional expression are not evaluated.

static properties: If an expression is an operand-0, the class of the expression is the class of the operand-0. If it is a conditional expression, the class of the expression is the M-value class, where M is the mode which depends on the context where the conditional expression occurs according to the same rules that define the mode of the class of a tuple without a <u>mode</u> name (see section 5.2.5).

An expression is constant (literal) if and only if it is either an operand-0 which is constant (literal), or a conditional expression in which all <u>boolean</u> expression or case selector list in it are constant (literal) and in which all sub expressions in it are constant (literal).

static conditions: If an expression is a conditional expression the following conditions apply:

- a conditional expression may occur only in the contexts in which a tuple without a <u>mode</u>
 name in front of it may occur;
- each sub expression must be compatible with the mode that is derived from the context
 with the same rules as for tuples. However, the dynamic part of the compatibility relation
 applies only to the selected sub expression;

- if CASE is specified, the case selection conditions must be fulfilled (see section 12.3), and the same completeness, consistency and compatibility requirements must hold as for the case action (see section 6.4);
- no conditional expression may have two sub expression occurrences in it such that one is extra-regional and the other is intra-regional (see section 11.2.2).

dynamic conditions: In the case of a conditional expression, the assignment conditions of the value delivered by the selected sub expression with respect to the mode M derived from the context apply.

5.3.3 Operand-0

syntax:

$$\langle operand-0 \rangle ::=$$
 (1)

$$\langle operand-1 \rangle$$
 (1.1)

$$| \langle sub \ operand - \theta \rangle \{ \ OR \ | \ ORIF \ | \ XOR \} \langle operand - 1 \rangle$$
 (1.2)

$$\langle \text{sub operand-0} \rangle ::=$$
 (2)
 $\langle \text{operand-0} \rangle$ (2.1)

semantics: If OR, ORIF or XOR is specified, sub operand-0 and operand-1 deliver:

- boolean values, in which case **OR** and **XOR** denote the logical operators "inclusive disjunction" and "exclusive disjunction", respectively, delivering a boolean value. If **ORIF** is specified and operand-0 delivers the boolean value TRUE, then this is the result, otherwise the result is operand-1;
- bit string values, in which case **OR** and **XOR** denote the logical operations on each element of the bit strings, delivering a bit string value;
- powerset values, in which case **OR** denotes the union of both powerset values and **XOR** denotes the powerset value consisting of those member values which are in only one of the specified powerset values (e.g. A **XOR** B = A B **OR** B A).

static properties: If an operand-0 is an operand-1, the class of operand-0 is the class of operand-1. If OR, ORIF or XOR is specified, the class of operand-0 is the resulting class of the classes of sub operand-0 and operand-1.

An operand-0 is constant (literal) if and only if it is either an operand-1 which is constant (literal), or built up from an operand-0 and an operand-1 which are both constant(literal).

static conditions: If OR, ORIF or XOR is specified, the class of sub operand-0 must be compatible with the class of operand-1. If ORIF is specified, both classes must have a boolean root mode, otherwise both classes must have a boolean, powerset or bit string root mode, in which case the actual length of sub operand-0 and operand-1 must be the same. This check is dynamic if one or both modes is (are) dynamic or varying string modes.

dynamic conditions: In the case of OR or XOR, a RANGEFAIL exception occurs if one or both operands have a dynamic class and the dynamic part of the above mentioned compatibility check fails.

examples:

10.31
$$i < \min OR i > \max$$
 (1.2)

5.3.4 Operand-1

syntax:

semantics: If AND or ANDIF is specified, sub operand-1 and operand-2 deliver:

<operand-1>

- boolean values, in which case AND denotes the logical "conjunction" operation, delivering a boolean value. If ANDIF is specified and sub operand-1 delivers the boolean value FALSE, then this is the result, otherwise the result is operand-2;
- bit string values, in which case AND denotes the logical operation on each element of the bit strings, delivering a bit string value;
- powerset values, in which case AND denotes the "intersection" operation of powerset values delivering a powerset value as a result.

static properties: If an operand-1 is an operand-2, the class of operand-1 is the class of operand-2.

If AND or ANDIF is specified, the class of operand-1 is the resulting class of the classes of sub operand-1 and operand-2.

An operand-1 is constant (literal) if and only if it is either an operand-2 which is constant (literal), or built up from an operand-1 and an operand-2 which are both constant (literal).

static conditions: If AND or ANDIF is specified, the class of sub operand-1 must be compatible with the class of operand-2. If ANDIF is specified, both classes must have a boolean root mode, otherwise both classes must have a boolean, powerset or bit string root mode, in which case the actual length of sub operand-1 and operand-2 must be the same. This check is dynamic if one or both modes is (are) dynamic or varying string modes.

dynamic conditions: In the case of AND, a RANGEFAIL exception occurs if one or both operands have a dynamic class and the dynamic part of the above mentioned compatibility check fails.

examples:

5.3.5 Operand-2

syntax:

| <powerset inclusion operator>

(3.3)

(2.1)

$$<$$
membership operator $> ::=$ (5)

IN
$$(5.1)$$

semantics: The equality (=) and inequality (/=) operators are defined between all values of a given mode. The other relational operators (less than: <, less than or equal to: <=, greater than: >, greater than or equal to: >=) are defined between values of a given discrete, timing or string mode. All the relational operators deliver a boolean value as result.

The membership operator is defined between a member value and a powerset value. The operator delivers TRUE if the member value is in the specified powerset value, otherwise FALSE.

The powerset inclusion operators are defined between powerset values and they test whether or not a powerset value is contained in: <=, is properly contained in: <, contains: >= or properly contains: > the other powerset value. A powerset inclusion operator delivers a boolean value as result.

static properties: If an operand-2 is an operand-3, the class of operand-2 is the class of operand-3. If an operator-3 is specified, the class of operand-2 is the BOOL-derived class.

An operand-2 is constant (literal) if and only if it is either an operand-3 which is constant (literal) or built up from a sub operand-2 and an operand-3 which are both constant (literal).

static conditions: If an operator-3 is specified, the following compatibility requirements between the class of sub operand-2 and the class of operand-3 must be fulfilled:

- if operator-3 is = or /=, both classes must be compatible;
- if operator-3 is a relational operator other than = or /=, both classes must be compatible and must have a discrete, timing or string root mode;
- if operator-3 is a membership operator, the class of operand-3 must have a powerset root mode and the class of sub operand-2 must be compatible with the member mode of that root mode;
- if operator-3 is a powerset inclusion operator, both classes must be compatible and must have a powerset root mode.

dynamic conditions: In the case of a relational operator, a RANGEFAIL or TAGFAIL exception occurs if one or both operands have a dynamic class and the dynamic part of the above mentioned compatibility check fails. The TAGFAIL exception occurs if and only if a dynamic class is based upon a dynamic parameterised structure mode.

examples:

$$10.50 \quad last=NULL \tag{1.2}$$

5.3.6 Operand-3

syntax

<pre><operand-3> ::=</operand-3></pre>	(1)
<pre><operand-4></operand-4></pre>	(1.1)
_{<operator-4> <operand-4></operand-4></operator-4>}	(1.2)
_{::=}	(2)
<pre><operand-3></operand-3></pre>	(2.1)
<operator-4> ::=</operator-4>	(3)
<arithmetic additive="" operator=""></arithmetic>	(3.1)
<pre><string concatenation="" operator=""></string></pre>	(3.2)
<pre><powerset difference="" operator=""></powerset></pre>	(3.3)
<arithmetic additive="" operator=""> ::=</arithmetic>	(4)
+ -	(4.1)
<string concatenation="" operator=""> ::=</string>	(5)
	(5.1)
<pre><powerset difference="" operator=""> ::=</powerset></pre>	(6)
-	(6.1)

semantics: If operator-4 is an arithmetic additive operator, both operands deliver integer values and the resulting integer value is the sum (+) or difference (-) of the two values.

If operator-4 is a string concatenation operator, both operands deliver either bit string values or character string values; the resulting value consists of the concatenation of these values. Boolean (character) values are also allowed; they are regarded as bit (character) string values of length 1.

If operator-4 is the powerset difference operator, both operands deliver powerset values and the resulting value is the powerset value consisting of those member values which are in the value delivered by sub operand-3 and not in the value delivered by operand-4.

static properties: If an operand-3 is an operand-4, the class of operand-3 is the class of operand-4. If an operator-4 is specified, the class of operand-3 is determined by operator-4 as follows:

- if operator-4 is a string concatenation operator, the class of operand-3 is dependent on the classes of operand-4 and sub operand-3, in which an operand that is a boolean or a character value is regarded as a value whose class is a BOOLS (1)-derived class or CHARS (1)-derived class, respectively:
 - if none of them is strong, the class is the BOOLS (n)-derived class or CHARS (n)-derived class, depending on whether both operands are bit or character strings, where n is the sum of the string lengths of the root modes of both classes;
 - otherwise the class is the &name(n)-value class, where &name is a virtual symmode name synonymous with the root mode of the resulting class of the classes of the operands and n is the sum of the string lengths of the root modes of both classes

(this class is dynamic if one or both operands have a dynamic class).

• if operator-4 is an arithmetic additive operator or powerset difference operator, the class of operand-3 is the resulting class of the classes of operand-4 and sub operand-3.

An operand-3 is constant (literal) if and only if it is either an operand-4 which is constant (literal), or built up from an operand-3 and an operand-4 which are both constant (literal) and operator-4 is either the arithmetic additive operator or the powerset difference operator.

If operator-4 is the string concatenation operator, an operand-3 is constant if it is built up from an operand-3 and operand-4 which are both constant.

static conditions: If an operator-4 is specified, the following compatibility requirements must be fulfilled:

- if operator-4 is the arithmetic additive operator, the classes of both operands must be compatible and they must both have an integer root mode;
- if operator-4 is the string concatenation operator then:
 - the classes of both operands must be compatible and they must both have a bit string root mode or both have a character string root mode, or
 - the classes of both operands must be compatible with the BOOL mode or both be compatible with the CHAR mode, or
 - the class of one operand must have a bit (character) string root mode and the other must be compatible with the BOOL (CHAR) mode.
- if operator-4 is the powerset difference operator, the classes of both operands must be compatible and both must have a powerset root mode.

dynamic conditions: In the case of an operand-3 that is not constant, an OVERFLOW exception occurs if an addition (+) or a subtraction (-) gives rise to a value that is not one of the values defined by the root mode of the class of operand-3.

examples:

1.6
$$j$$

1.6 $i+j$ (1.1)

5.3.7 Operand-4

syntax

$$\langle operand-4 \rangle ::=$$
 (1)

$$\langle operand-5 \rangle$$
 (1.1)

$$\langle sub\ operand-4 \rangle ::=$$
 (2)
 $\langle operand-4 \rangle$ (2.1)

semantics: If an arithmetic multiplicative operator is specified, sub operand-4 and operand-5 deliver integer values and the resulting integer value is either the product (*), the quotient (/), modulo (MOD) or division remainder (REM) of both values.

The modulo operation is defined such that i MOD j delivers the unique integer value k, $0 \le k < j$ such that there is an integer value n such that i = n * j + k; j must be greater than 0.

The quotient operation is defined such that all relations:

$$ABS(x/y) = ABS(x)/ABS(y)$$
 and $sign(x/y) = sign(x)/sign(y)$ and $ABS(x) - (ABS(x)/ABS(y)) * ABS(y) = ABS(x)$ MOD $ABS(y)$

yield TRUE for all integer values x and y, where sign(x) = -1 if x < 0, otherwise sign(x) = 1.

The remainder operation is defined such that x REM y = x - (x/y) * y yields TRUE for all integer values x and y.

static properties: If operand-4 is an operand-5, the class of operand-4 is the class of operand-5; otherwise the class of operand-4 is the resulting class of the classes of sub operand-4 and operand-5.

An operand-4 is constant (literal) if and only if it is either an operand-5 which is constant (literal), or built up from an operand-4 and an operand-5 which are both constant (literal).

static conditions: If an arithmetic multiplicative operator is specified, the classes of operand-5 and sub operand-4 must be compatible and both must have an integer root mode.

dynamic conditions: In the case of an operand-4 that is not constant, an OVERFLOW exception occurs if a multiplication (*), a division (/), a modulo (MOD), or a remainder (REM) operation gives rise to a value that is not one of the values defined by the root mode of the class of operand-4 or is performed on operand values for which the operator is mathematically not defined, i.e. division or remainder with an operand-5 delivering 0 or a modulo operation with an operand-5 delivering a non-positive integer value.

examples:

5.3.8 Operand-5

syntax

semantics: If the monadic operator is a change-sign operator (-), operand-6 delivers an integer value and the resulting integer value is the previous integer value with its sign changed.

If the monadic operator is NOT, operand-6 delivers a boolean value, a bit string value, or a powerset value. In the first two cases the logical negation of the boolean value or of the elements of the bit string value is delivered. In the latter case, the set complement value, i.e. the set of those member values which are not in the operand powerset value, is delivered.

If the monadic operator is a string repetition operator, operand-6 is a character string literal or a bit string literal. If the <u>integer literal</u> expression delivers 0, the result is the empty string value; otherwise the result is the string value formed by concatenating the string with itself as many times as specified by the value delivered by the literal expression minus 1.

static properties: If operand-5 is an operand-6, the class of operand-5 is the class of operand-6.

If a monadic operator is specified, the class of operand-5 is:

- if the monadic operator is or NOT then the resulting class of operand-6;
- if the monadic operator is the string repetition operator, then it is the **CHARS** (n)- or **BOOLS** (n)-derived class (depending on whether the literal was a character string literal or bit string literal) where n = r * l, where r is the value delivered by the <u>integer literal</u> expression and l is the string length of the string literal.

An operand-5 is constant if and only if the operand-6 is constant. An operand-5 is literal if and only if the operand-6 is literal and the monadic operator is – or NOT.

static conditions: If monadic operator is -, the class of operand-6 must have an integer root mode.

If monadic operator is NOT, the class of operand-6 must have a boolean, bit string or powerset root mode.

If monadic operator is the string repetition operator, operand-6 must be a character string literal or a bit string literal. The <u>integer literal</u> expression must deliver a non-negative integer-value.

dynamic conditions: If operand-5 is not constant, an OVERFLOW exception occurs if a change sign (-) operation gives rise to a value which is not one of the values defined by the root mode of the class of the operand-5.

examples:

5.10	NOT RZ	(1.1)
7.54	(6)' '	(1.1)
7.54	(6)	(2.2)

5.3.9 Operand-6

syntax:

$$<$$
receive expression $> ::=$ (3)
RECEIVE $<$ buffer location $>$ (3.1)

semantics: A referenced location delivers a reference to the specified location.

The receive expression receives a value from the <u>buffer</u> location. The executing process may become delayed and may re-activate another process, delayed on sending to the specified buffer location (see section 6.19.3 for details).

static properties: The class of an operand-6 is the class of the referenced location, receive expression or primitive value, respectively. The class of the referenced location is the M-reference class where M is the mode of the location. The class of the receive expression is the M-value class, where M is the buffer element mode of the mode of the <u>buffer</u> location.

An operand-6 is constant if and only if the primitive value is constant or the referenced location is constant. A referenced location is constant if and only if the location is static. An operand-6 is literal if and only if the primitive value is literal.

static conditions: The location must be referable.

dynamic conditions: The lifetime of the <u>buffer</u> location must not end while the executing process is delayed on it.

examples:

6 ACTIONS

6.1 GENERAL

syntax:

<action statement=""> ::=</action>	(1)
[<defining occurrence=""> :] <action> [<handler>] [<simple name="" string="">];</simple></handler></action></defining>	(1.1)
<module></module>	(1.2)
<pre><spec module=""></spec></pre>	(1.3)
<context module=""></context>	(1.4)
<action> ::=</action>	(2)
<pre><bracketed action=""></bracketed></pre>	(2.1)
<assignment action=""></assignment>	(2.2)
< call action >	(2.3)
<exit action=""></exit>	(2.4)
<return action=""></return>	(2.5)
<result action=""></result>	(2.6)
<pre><goto action=""></goto></pre>	(2.7)
<assert action=""></assert>	(2.8)
<pre><empty action=""></empty></pre>	(2.9)
<pre><start action=""></start></pre>	(2.10)
<pre><stop action=""></stop></pre>	(2.11)
<pre><delay action=""></delay></pre>	(2.12)
<pre><continue action=""></continue></pre>	(2.13)
<pre><send action=""></send></pre>	(2.14)
<pre><cause action=""></cause></pre>	(2.15)
<pre><bracketed action=""> ::=</bracketed></pre>	(3)
<if action=""></if>	(3.1)
<pre><case action=""></case></pre>	(3.2)
<pre><do action=""></do></pre>	(3.3)
< begin-end block>	(3.4)
<delay action="" case=""></delay>	(3.5)
<receive action="" case=""></receive>	(3.6)
<pre><timing action=""></timing></pre>	(3.7)

semantics: Action statements constitute the algorithmic part of a CHILL program. Any action statement may be labelled. Those actions that may never cause an exception may not have a handler appended.

static properties: A defining occurrence in an action statement defines a label name.

static conditions: The simple name string may only be given after an action which is a bracketed action or if a handler is specified, and only if a defining occurrence is specified. The simple name string must be the same name string as the defining occurrence.

6.2 ASSIGNMENT ACTION

syntax:

```
<assignment action> ::=
                                                                                           (1)
         <single assignment action>
                                                                                          (1.1)
                                                                                          (1.2)
       | < multiple assignment action>
<single assignment action> ::=
                                                                                           (2)
         <location> <assignment symbol> <value>
                                                                                          (2.1)
                                                                                          (2.2)
       | <location> <assigning operator> <expression>
< multiple assignment action> ::=
                                                                                           (3)
         <location> { , <location> }+ <assignment symbol> <value>
                                                                                          (3.1)
```

<pre><closed dyadic="" operator=""> <assignment symbol=""></assignment></closed></pre>	(4.1)
<closed dyadic="" operator=""> ::=</closed>	(5)
OR XOR AND	(5.1)
<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(5.2)
<pre><arithmetic additive="" operator=""></arithmetic></pre>	(5.3)
<pre><arithmetic multiplicative="" operator=""></arithmetic></pre>	(5.4)
<pre><string concatenation="" operator=""></string></pre>	(5.5)
<assignment symbol=""> ::=</assignment>	
;=	(6.1)

(4)

semantics: An assignment action stores a value into one or more locations.

<assigning operator> ::=

If an assignment symbol is used, the value yielded by the right hand side is stored into the location(s) specified at the left hand side.

If an assigning operator is used, the value contained in the location is combined with the right hand side value (in that order) according to the semantics of the specified closed dyadic operator, and the result is stored back into the same location.

The evaluation of the left hand side location(s), of the right hand side value, and of the assignment themselves are performed in an unspecified and possibly mixed order. Any assignment may be performed as soon as the value and a location have been evaluated.

If the location (or any of the locations) is the tag field of a variant structure, the semantics for the variant fields that depend on it are implementation defined.

static conditions: The modes of all location occurrences must be equivalent and they must have neither the read-only property nor the non-value property. Each mode must be compatible with the class of the value. The checks are dynamic in the case where dynamic mode locations and/or a value with a dynamic class are involved.

The value must be regionally safe for every location (see section 11.2.2).

If any location has a fixed string mode, then the string length of the mode and the actual length of the value must be the same; otherwise, if it has a varying string mode, then the string length of the mode must not be less than the actual length of the value. This check is dynamic if one or both modes is (are) dynamic or varying string modes. This condition is called the string assignment condition.

dynamic conditions: The RANGEFAIL or TAGFAIL exception occurs if the mode of the location and/or that of the value are dynamic modes and the dynamic part of the above mentioned compatibility checks fails.

The RANGEFAIL exception occurs if the mode of the location and/or that of the value are varying string modes and the dynamic part of the above mentioned compatibility checks fails.

The RANGEFAIL exception occurs if any location has a range mode and the value delivered by the evaluation of value is neither one of the values defined by the range mode nor the undefined value.

The above mentioned dynamic conditions together with the string assignment condition are called the assignment conditions of a value with respect to a mode.

In the case of an assigning operator, the same exceptions are caused as if the expression:

were evaluated and the delivered value stored into the specified location (note that the location is evaluated once only).

examples:

4.12
$$a := b + c$$
 (1.1)

$$10.25 \quad stackindex - := 1 \tag{2.1}$$

19.19
$$x \rightarrow .prex, x \rightarrow .next := NULL$$
 (3.1)

$$10.25 \quad -:= \tag{4.1}$$

6.3 IF ACTION

syntax:

examples:

$$\langle \text{if action} \rangle ::=$$
 (1)

$$\langle then\ clause \rangle ::=$$
 (2)

derived syntax: The notation:

is derived syntax for:

semantics: An if action is a conditional two-way branch. If the <u>boolean</u> expression yields TRUE, the action statement list following THEN is entered; otherwise the action statement list following ELSE, if present, is entered.

dynamic conditions: The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

7.22 IF
$$n >= 50$$
 THEN $rn(r) := 'L'$;

$$n-:=50;$$

 $r+:=1;$

FI

10.50 IF last = NULL

THEN first, last := p;

ELSE last->.succ := p;

p->.pred := last;

last := p;

 $\mathbf{FI} \tag{1.1}$

(1.1)

syntax:

$$\langle case \ action \rangle ::=$$
 (1)

$$< \underline{\text{discrete}} \text{ expression} > \{ , < \underline{\text{discrete}} \text{ expression} > \}^*$$
 (2.1)

$$< \underline{\text{discrete mode}} \text{ name} > \{ , < \underline{\text{discrete mode}} \text{ name} > \}^*$$
 (3.1)

semantics: A case action is a multiple branch. It consists of the specification of one or more discrete expressions (the case selector list) and a number of labelled action statement lists (case alternatives). Each action statement list is labelled with a case label specification which consists of a list of case label list specifications (one for each case selector). Each case label list defines a set of values. The use of a list of discrete expressions in the case selector list allows selection of an alternative based on multiple conditions.

The case action enters that action statement list for which values given in the case label specification match the values in the case selector list; if no value match, the action statement list following ELSE is entered.

The expressions in the case selector list are evaluated in an undefined and possibly mixed order. They need be evaluated only up to the point where a case alternative is uniquely determined.

static conditions: For the list of case label specification occurrences, the case selection conditions apply (see section 12.3).

The number of <u>discrete</u> expression occurrences in the case selector list must be equal to the number of classes in the resulting list of classes of the list of case label list occurrences and, if present, to the number of <u>discrete mode</u> name occurrences in the range list.

The class of any <u>discrete</u> expression in the case selector list must be compatible with the corresponding (by position) class of the resulting list of classes of the case label list occurrences and, if present, compatible with the corresponding (by position) <u>discrete mode</u> name in the range list. The latter mode must also be compatible with the corresponding class of the resulting list of classes.

Any value delivered by a <u>discrete literal</u> expression or defined by a <u>literal range</u> or by a <u>discrete mode</u> name in a case label (see section 12.3) must lie in the range of the corresponding <u>discrete mode</u> name of the range list, if present, and also in the range defined by the mode of the corresponding <u>discrete</u> expression in the case selector list, if it is a strong <u>discrete</u> expression. In the latter case, the values defined by the corresponding <u>discrete mode</u> name of the range list, if present, must also lie in that range.

The optional ELSE part according to the syntax may only be omitted if the list of case label list occurrences is complete (see section 12.3).

dynamic conditions: The RANGEFAIL exception occurs if a range list is specified and the value delivered by a <u>discrete</u> expression in the case selector list does not lie within the bounds specified by the corresponding <u>discrete mode</u> name in the range list.

The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

examples:

```
4.11
        CASE order OF
            (1): a := b+c;
                RETURN;
            (2): d := 0:
            (ELSE): d := 1;
                                                                                        (1.1)
        ESAC
        starting.p.kind, starting.p.color
                                                                                        (2.1)
11.43
11.58
        (rook),(*):
            IF NOT ok_rook(b,m)
                 THEN
                   CAUSE illegal;
                                                                                        (4.1)
            FI;
```

6.5 DO ACTION

6.5.1 General

syntax:

semantics: A do action has one out of three different forms: the do-for and the do-while versions, both for looping, and the do-with version as a convenient short hand notation for accessing structure fields in an efficient way. If no control part is specified, the action statement list is entered once, each time the do action is entered.

When the do-for and the do-while versions are combined, the while control is evaluated after the for control, and only if the do action is not terminated by the for control.

If the specified control part is a for control and/or while control, then for as long as control stays inside the reach of the do action, the action statement list is entered according to the control part, but the do reach is not re-entered for each execution of the action statement list.

dynamic conditions: The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

examples:

6.5.2 For control

syntax:

<for control=""> ::= FOR { <iteration> { , <iteration> }* EVER }</iteration></iteration></for>	(1) (1.1)
<pre><iteration> ::= <value enumeration=""></value></iteration></pre>	(2) (2.1) (2.2)
<pre><value enumeration=""> ::=</value></pre>	(3) (3.1) (3.2) (3.3)
<pre><step enumeration=""> ::= <loop counter=""> <assignment symbol=""> <start value=""> [<step value="">] [DOWN] <end value=""></end></step></start></assignment></loop></step></pre>	(4) (4.1)
cloop counter> ::= defining occurrence>	(5) (5.1)
<start value=""> ::= <<u>discrete</u> expression></start>	(6) (6.1)
<step value=""> ::= BY < integer expression></step>	(7) (7.1)
<pre><end value=""> ::= TO < discrete expression></end></pre>	(8) (8.1)
<pre><range enumeration=""> ::= <loop counter=""> [DOWN] IN < discrete mode name></loop></range></pre>	(9) (9.1)
<pre><pre><pre><pre><pre><pre><pre>cloop counter> [DOWN] IN <pre><pre>powerset</pre> expression></pre></pre></pre></pre></pre></pre></pre></pre>	(10) (10.1)
<pre><location enumeration=""> ::= <loop counter=""> [DOWN] IN <composite object=""></composite></loop></location></pre>	(11) (11.1)
<composite object=""> ::= <array location=""> <array expression=""> <string location=""> <string expression=""></string></string></array></array></composite>	(12) (12.1) (12.2) (12.3) (12.4)

N.B. If the composite object is a (<u>string</u>, <u>array</u>) location, the syntactic ambiguity is resolved by interpreting composite object as a location rather than an expression.

semantics: The for control may mention several loop counters. The loop counters are evaluated each time in an unspecified order, before entering the action statement list, and they need be evaluated only up to the point that it can be decided to terminate the do action. The do action is terminated if at least one of the loop counters indicates termination.

1. do for ever:

The action list is indefinitely repeated. The do action can only terminate by a transfer of control out of it.

2. value enumeration:

The action statement list is repeatedly entered for the set of specified values of the loop counters. The set of values is either specified by a <u>discrete mode</u> name (range enumeration), or by a powerset value (powerset enumeration), or by a start value, step value and end value (step enumeration).

The loop counter implicitly defines a name which denotes its value or location inside the action statement list.

range enumeration:

In the case of range enumeration without (with) **DOWN** specification, the initial value of the loop counter is the smallest (greatest) value in the set of values defined by the <u>discrete mode</u> name. For subsequent executions of the action statement list, the next value will be evaluated as:

```
SUCC (previous value) (PRED (previous value)).
```

Termination occurs if the action statement list has been executed for the greatest (smallest) value defined by the <u>discrete mode</u> name.

powerset enumeration:

In the case of powerset enumeration without (with) **DOWN** specification, the initial value of the loop counter is the smallest (highest) member value in the denoted powerset value. If the powerset value is empty, the action statement list will not be executed. For subsequent executions of the action statement list, the next value will be the next greater (smaller) member value in the powerset value. Termination occurs if the action statement list has been executed for the greatest (smallest) value. When the do action is executed, the **powerset** expression is evaluated only once.

step enumeration:

In the case of step enumeration without (with) **DOWN** specification, the set of values of the loop counter is determined by a start value, an end value, and possibly a step value. When the do action is executed, these expressions are evaluated only once in an unspecified and possibly mixed order. The step value is always positive. The test for termination is made before each execution of the action statement list. Initially, a test is made to determine whether the start value of the loop counter is greater (smaller) than the end value. For subsequent executions, next value will be evaluated as:

```
previous value + step value (previous value - step value)
```

in the case of step value specification; otherwise as:

```
SUCC (previous value) (PRED (previous value)).
```

Termination occurs if the evaluation yields a value which is greater (smaller) than the end value or would have caused an OVERFLOW exception.

3. location enumeration:

In the case of a location enumeration without (with) **DOWN** specification, the action statement list is repeatedly entered for a set of locations which are the elements of the array location denoted by <u>array location</u> or the components of the string location denoted by <u>string</u> location. If an <u>array</u> or <u>string</u> expression is specified that is not a location, a location containing the specified value will be implicitly created. The lifetime of the created location is the do action. The mode of the created location is dynamic if the value has a dynamic class. The semantics are as if before each execution of the action statement list the loc-identity declaration:

```
DCL <loop counter> <mode> LOC := <composite object> (<index>);
```

were encountered, where mode is the element mode of the array location or &name(1) such that &name is a virtual symmode name synonymous with the mode of the string location if it is a fixed string mode, otherwise with the component mode, and where index is initially set to the lower bound (upper bound) of the mode of location and index before each subsequent execution of the action statement list is set to SUCC (index) (PRED (index)). The action statement list will not be executed if the actual length of the string location equals 0. The do action is terminated if index just after an execution of the action statement list is equal to the upper bound (lower bound) of the mode of location. When the do action is executed, the composite object is evaluated only once.

static properties: A loop counter has a name string attached which is the name string of its defining occurrence.

value enumeration:

The name defined by the loop counter is a value enumeration name.

step enumeration:

The class of the name defined by a loop counter is the resulting class of the classes of the start value, the step value, if present, and the end value.

range enumeration:

The class of the name defined by the loop counter is the M-value class, where M is the <u>discrete mode</u> name.

powerset enumeration:

The class of the name defined by the loop counter is the M-value class, where M is the member mode of the mode of the (strong) powerset expression.

location enumeration:

The name defined by the loop counter is a location enumeration name. Its mode is the element mode of the mode of the <u>array</u> location or <u>array</u> expression or the string mode &name(1), where &name is a virtual synmode name synonymous with the mode of <u>string</u> location or the root mode of the <u>string</u> expression.

A location enumeration name is referable if the element layout of the mode of the <u>array</u> location is NOPACK.

static conditions: The classes of start value, end value and step value, if present, must be pairwise compatible.

The root mode of the class of a loop counter in a value enumeration must not be a numbered set mode.

dynamic conditions: A RANGEFAIL exception occurs if the value delivered by step value is not greater than 0. This exception occurs outside the block of the do action.

examples:

4.17
 FOR
$$i := 1$$
 TO c
 (1.1)

 15.37
 FOR EVER
 (1.1)

 4.17
 $i := 1$ TO c
 (3.1)

 9.12
 $j := MIN$ (sieve) BY MIN (sieve) TO max
 (3.1)

 14.28
 i IN INT (1:100)
 (3.2)

6.5.3 While control

syntax:

$$<$$
while control $> ::=$ (1)
$$WHILE < \underline{boolean} \text{ expression}>$$
 (1.1)

semantics: The boolean expression is evaluated just before entering the action statement list (after the evaluation of the for control, if present). If it yields TRUE, the action statement list is entered; otherwise the do action is terminated.

examples:

7.35 WHILE
$$n >= 1$$
 (1.1)

6.5.4 With part

syntax:

$$<$$
with part $> ::=$ (1)

WITH
$$<$$
 with control $>$ { , $<$ with control $>$ }* (1.1)

$$<$$
with control $> ::=$ (2)

$$\langle \underline{structure} | location \rangle$$
 (2.1)

$$|<$$
 structure primitive value> (2.2)

N.B. If the with control is a <u>structure</u> location, the syntactic ambiguity is resolved by interpreting with control as a location rather than a primitive value.

semantics: The (visible) field names of the mode of the structure locations or structure value specified in each with control are made available as direct accesses to the fields.

The visibility rules are as if a field name defining occurrence were introduced for each field name attached to the mode of the location or primitive value and with the same name string as the field name.

If a <u>structure</u> location is specified, access names with the same name string as the field names of the mode of the <u>structure</u> location are implicitly declared, denoting the sub-locations of the structure location.

If a <u>structure</u> primitive value is specified, value names with the same name string as the field names of the mode of the (strong) <u>structure</u> primitive value are implicitly defined, denoting the sub-values of the structure value.

When the do action is entered, the specified structure locations and/or structure values are evaluated once only on entering the do action, in an unspecified, possibly mixed order.

static properties: The (virtual) defining occurrence introduced for a field name has the same name string as the field name defining occurrence of that field name.

If a <u>structure</u> primitive value is specified, a (virtual) defining occurrence in a with part defines a value do-with name. Its class is the M-value class, where M is the mode of that field name of the structure mode of the <u>structure</u> primitive value which is made available as value do-with name.

If a <u>structure</u> location is specified, a (virtual) defining occurrence in a with part defines a location do-with name. Its mode is the mode of that field name of the mode of the <u>structure</u> location which is made available as location do-with name. A location do-with name is referable if the field layout of the associated field name is **NOPACK**.

examples:

6.6 EXIT ACTION

syntax:

$$\langle \text{exit action} \rangle ::=$$

$$\text{EXIT } \langle \underline{\text{label name}} \rangle \tag{1.1}$$

semantics: An exit action is used to leave a bracketed action statement or a module. Execution is resumed immediately after the closest surrounding bracketed action statement or module labelled with the

<u>label</u> name.

static conditions: The exit action must lie within the bracketed action statement or module of which the defining occurrence in front has the same name string as <u>label</u> name.

If the exit action is placed within a procedure or process definition, the exited bracketed action statement or module must also lie within the same procedure or process definition (i.e. the exit action cannot be used to leave procedures or processes).

No handler may be appended to an exit action.

examples:

6.7 CALL ACTION

syntax:

```
<call action> ::=
                                                                                                   (1)
         call>
                                                                                                  (1.1)
       | <built-in routine call>
                                                                                                  (1.2)
cedure call> ::=
                                                                                                   (2)
         { < procedure name > | < procedure primitive value > }
         ([ <actual parameter list> ])
                                                                                                  (2.1)
<actual parameter list> ::=
                                                                                                   (3)
         <actual parameter> { , <actual parameter> }*
                                                                                                  (3.1)
<actual parameter> ::=
                                                                                                   (4)
         <value>
                                                                                                  (4.1)
        | <location>
                                                                                                  (4.2)
<br/>
<br/>
built-in routine call> ::=
                                                                                                   (5)
         < built-in routine name> ( [ < built-in routine parameter list> ] )
                                                                                                  (5.1)
<br/>
<br/>
built-in routine parameter list> ::=
                                                                                                   (6)
         <built-in routine parameter> { , <built-in routine parameter> }*
                                                                                                  (6.1)
<br/>
<br/>
built-in routine parameter> ::=
                                                                                                   (7)
         <value>
                                                                                                  (7.1)
                                                                                                  (7.2)
        | <location>
```

N.B. If the actual parameter or built-in routine parameter is a location, the syntactic ambiguity is resolved by interpreting it as a location rather than a value.

(7.3)

semantics: A call action causes the call of either a procedure or a built-in routine. A procedure call causes a call of the general procedure indicated by the value delivered by the <u>procedure</u> primitive value or the procedure indicated by the <u>procedure</u> name. The actual values and locations specified in the actual parameter list are passed to the procedure.

| < non-reserved name > [(< built-in routine parameter list >)]

A built-in routine call is either a CHILL built-in routine call or an implementation built-in routine call (see sections 6.20 and 13.1, respectively).

A value, a location, or any program defined name that is not a reserved simple name string may be passed as built-in routine parameter. The built-in routine call may return a value or a location.

A built-in routine may be generic, i.e. its class (if it is a value built-in routine call) or its mode (if it is a location built-in routine call) may depend not only on the <u>built-in routine</u> name but also on the static properties of the actual parameters passed and the static context of the call.

static properties: A procedure call has the following properties attached: a list of parameter specs, possibly a result spec, a possibly empty set of exception names, a generality, a recursivity, and possibly it is intra-regional (the latter is only possible with a <u>procedure</u> name, see section 11.2.2). These properties are inherited from the <u>procedure</u> name or any mode compatible with the class of the <u>procedure</u> primitive value (in the latter case, the generality is always general).

A procedure call with a result spec is a <u>location</u> procedure call if and only if LOC is specified in the result spec; otherwise it is a <u>value</u> procedure call.

A <u>built-in routine</u> name is a CHILL or an implementation defined name that is considered to be defined in the reach of the imaginary outermost process definition or in any context (see section 10.8).

A built-in routine call is a location built-in routine call if it delivers a location; it is a value built-in routine call if it delivers a value.

static conditions: The number of actual parameter occurrences in the procedure call must be the same as the number of its parameter specs. The compatibility requirements for the actual parameter and corresponding (by position) parameter spec of the procedure call are:

- If the parameter spec has the IN attribute (default), the actual parameter must be a value whose class is compatible with the mode in the corresponding parameter spec. The latter mode must not have the non-value property. The actual parameter is a value which must be regionally safe for the procedure call.
- If the parameter spec has the INOUT or OUT attribute, the actual parameter must be a location, whose mode must be compatible with the M-value class, where M is the mode in the corresponding parameter spec. The mode of the (actual) location must be static and must not have the read-only property nor the non-value property. The actual parameter is a location. It can be viewed as a value which must be regionally safe for the procedure call.
- If the parameter spec has the INOUT attribute, the mode in the parameter spec must be compatible with the M-value class where M is the mode of the location.
- If the parameter spec has the LOC attribute specified without DYNAMIC, the actual parameter must be a location which is both referable and such that the mode in the parameter spec is read-compatible with the mode of the (actual) location, or the actual parameter must be a value which is not a location but whose class is compatible with the mode in the parameter spec.
- If the parameter spec has the LOC attribute with DYNAMIC specified, the actual parameter must be a location which is both referable and such that the mode in the parameter spec is dynamic read-compatible with the mode of the (actual) location, or the actual parameter must be a value which is not a location but whose class is compatible with a parameterised version of this mode.
- If the parameter spec has the LOC attribute then
 - if the actual parameter is a location it must have the same regionality as the procedure call;
 - if the actual parameter is a value then it must be regionally safe for the procedure

dynamic conditions: A procedure call or built-in routine call can cause any of the exceptions from the attached set of exception names. A procedure call causes the EMPTY exception if the procedure primitive value delivers NULL; it causes the SPACEFAIL exception if storage requirements cannot be satisfied. If the recursivity of the procedure is non-recursive, then the procedure must not call itself either directly or indirectly.

Parameter passing can cause the following exceptions:

- If the parameter spec has the IN or INOUT attribute, the assignment conditions of the (actual) value with respect to the mode of the parameter spec apply at the point of the call (see section 6.2) and the possible exceptions are caused before the procedure is called.
- If the parameter spec has the INOUT or OUT attribute, the assignment conditions of the local value of the formal parameter with respect to the mode of the (actual) location apply at the point of return (see section 6.2) and possible exceptions are caused after the procedure has returned.

• If the parameter spec has the LOC attribute and the actual parameter is a value which is not a location, the assignment conditions of the (actual) value with respect to the mode of the parameter spec apply at the point of the call and the possible exceptions are caused before the procedure is called (see section 6.2).

The <u>procedure</u> primitive value must not deliver a procedure defined within a process definition whose activation is not the same as the activation of the process executing the procedure call (other than the imaginary outermost process) and the lifetime of the denoted procedure must not have ended.

examples:

4.18
$$op(a,b,d,order-1)$$
 (1.1)

6.8 RESULT AND RETURN ACTION

syntax:

$$RESULT < result >$$
 (2.1)

derived syntax: The return action with result is derived from DO RESULT < result> ; RETURN; OD.

semantics: A result action serves to establish the result to be delivered by a procedure call. This result may be a location or a value. A return action causes the return from the invocation of the procedure within whose definition it is placed. If the procedure returns a result, this result is determined by the latest executed result action. If no result action has been executed, the procedure call delivers an undefined location or undefined value, respectively.

static properties: A result action and a return action have a procedure name attached, which is the name of the closest surrounding procedure definition.

static conditions: A return action and a result action must be textually surrounded by a procedure definition.

A result action may only be specified if its procedure name has a result spec.

A handler must not be appended to a return action (without result).

If LOC (LOC DYNAMIC) is specified in the result spec of the procedure name of the result action, the result must be a location, such that the mode in the result spec is read-compatible (dynamic read-compatible) with the mode of the location. The location must be referable if NONREF is not specified in the result spec. The result is a location which must have the same regionality as the procedure name attached to the result action.

If LOC is not specified in the result spec of the procedure name of the result action, the result must be a value, whose class is compatible with the mode in the result spec. The result is a value which must be regionally safe for the procedure name attached to the result action.

dynamic conditions: If LOC is not specified in the result spec of the procedure name, the assignment conditions of the value in the result action with respect to the mode in the result spec of its procedure name apply.

examples:

4.21 RETURN (1.1)
1.6 RESULT
$$i+j$$
 (2.1)
5.19 c (3.1)

6.9 GOTO ACTION

syntax:

semantics: A goto action causes a transfer of control. Execution is resumed with the action statement labelled with the <u>label</u> name.

static conditions: If a goto action is placed within a procedure or process definition, the label indicated by the <u>label</u> name must also be defined within the definition (i.e. it is not possible to jump outside a procedure or process invocation).

A handler must not be appended to a goto action.

6.10 ASSERT ACTION

syntax:

semantics: An assert action provides a means of testing a condition.

dynamic conditions: The ASSERTFAIL exception occurs if the <u>boolean</u> expression delivers FALSE. examples:

4.7 ASSERT
$$b>0$$
 AND $c>0$ AND order>0 (1.1)

6.11 EMPTY ACTION

syntax:

$$\langle empty \ action \rangle ::=$$
 $\langle empty \rangle$
(1)

$$\langle empty \rangle ::=$$
 (2)

semantics: An empty action causes no action.

static conditions: A handler must not be appended to an empty action.

6.12 CAUSE ACTION

syntax:

CAUSE < exception name >

(1.1)

semantics: A cause action causes the exception whose name is indicated by exception name to occur.

static conditions: A handler must not be appended to a cause action.

examples:

6.13 START ACTION

syntax:

semantics: A start action evaluates the start expression (see section 5.2.14) without using the resulting instance value.

examples:

6.14 STOP ACTION

syntax:

semantics: A stop action terminates the process executing it (see section 11.1).

static conditions: A handler must not be appended to a stop action.

6.15 CONTINUE ACTION

syntax:

semantics: A continue action evaluates the event location.

If the event location has a non-empty set of delayed processes attached, one of these, with the highest priority, will be be re-activated. If there are several such processes, one will be selected in an implementation defined way. If there are no such processes, the continue action has no further effect.

If a process becomes re-activated, it is removed from all sets of delayed processes of which it was a member.

examples:

6.16 DELAY ACTION

syntax:

semantics: A delay action evaluates the event location.

Then a DELAYFAIL exception occurs (see below) or the executing process becomes delayed.

If the executing process becomes delayed, it becomes a member with a priority of the set of delayed processes attached to the specified event location. The priority is the one specified, if any, otherwise 0 (lowest).

dynamic properties: A process executing a delay action becomes timeoutable when it reaches the point of execution where it may become delayed. It ceases to be timeoutable when it leaves that point.

static conditions: The integer literal expression must not deliver a negative value.

dynamic conditions: The DELAYFAIL exception occurs if the <u>event</u> location has a mode with an event length attached which is equal to the number of processes already delayed on the event location.

The lifetime of the event location must not end while the executing process is delayed on it.

examples:

6.17 DELAY CASE ACTION

syntax:

$$\langle event \ list \rangle ::=$$
 (3)

< <u>event</u> location> $\{$, < <u>event</u> location> $\}$ *

semantics: A delay case action evaluates, in an unspecified and possibly mixed order, the <u>instance</u> location, if present, and all <u>event</u> locations specified in a delay alternative.

Then a DELAYFAIL exception occurs (see below) or the executing process becomes delayed.

If the executing process becomes delayed, it becomes a member with a priority of the set of delayed processes attached to each of the specified event locations. The priority is the one specified, if any, otherwise 0 (lowest).

If the delayed process becomes re-activated by another process executing a continue action on an event location, the corresponding action statement list is entered. If several delay alternatives specify the same event location, the choice between them is not specified. Prior to entering, if an <u>instance</u> location is specified, the instance value identifying the process that has executed the continue action is stored in it.

dynamic properties: A process executing a delay case action becomes timeoutable when it reaches the point of execution where it may become delayed. It ceases to be timeoutable when it leaves that point.

static conditions: The mode of the <u>instance</u> location must not have the read-only property. The <u>integer literal</u> expression in priority must not deliver a negative value.

dynamic conditions: The DELAYFAIL exception occurs if any <u>event</u> location has a mode with an event length attached which is equal to the number of processes already delayed on that event location.

The lifetime of none of the event locations must end while the executing process is delayed on them.

The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

examples:

14.26 DELAY CASE

```
(operator_is_ready): /* some actions */
(switch_is_closed): DO FOR i IN INT (1:100);

CONTINUE operator_is_ready;
/* empty the queue */
OD;

ESAC
```

(1.1)

6.18.1 General

syntax:

semantics: A send action initiates the transfer of synchronisation information from a sending process. The detailed semantics depend on whether the synchronisation object is a signal or a buffer.

6.18.2 Send signal action

syntax:

semantics: A send signal action evaluates, in an unspecified and possibly mixed order, the list of values, if present, and the <u>instance</u> primitive value, if present.

The signal specified by <u>signal</u> name is composed for transmission from the specified values and a priority. The priority is the one specified, if any, otherwise 0 (lowest).

If the signal name has a process name attached, only processes with that name may receive the signal; if an <u>instance</u> primitive value is specified, only that process may receive the signal. Otherwise any process may receive the signal.

If the signal has a non-empty set of delayed processes attached, in which one or more may receive the signal, one of these will be re-activated. If there are several such processes, one will be selected in an implementation defined way. If there are no such processes, the signal becomes pending.

If a process becomes re-activated, it is removed from all sets of delayed processes of which it was a member.

static conditions: The number of value occurrences must be equal to the number of modes of the <u>signal</u> name. The class of each value must be compatible with the corresponding mode of the <u>signal</u> name. No value occurrence may be intra-regional (see section 11.2.2). The <u>integer literal</u> expression in priority must not deliver a negative value.

dynamic conditions: The assignment conditions of each value with respect to its corresponding mode of the <u>signal</u> name apply.

The EMPTY exception occurs if the instance primitive value delivers NULL.

The lifetime of the process indicated by the value delivered by the <u>instance</u> primitive value must not have ended at the point of the execution of the send signal action.

The SENDFAIL exception occurs if the <u>signal</u> name has a process name attached which is not the name of the process indicated by the value delivered by the <u>instance</u> primitive value.

examples:

6.18.3 Send buffer action

syntax:

semantics: A send buffer action evaluates the buffer location and the value in any order.

If the buffer location has a non-empty set of delayed processes attached, one of these will be reactivated. If there are several such processes, one will be selected in an implementation defined way. If there are no such processes and the capacity of the buffer location is exceeded, the executing process becomes delayed with a priority. Otherwise the value is stored with a priority. The priority is the one specified, if any, otherwise 0 (lowest). The capacity of the buffer is exceeded if the buffer location has a mode with a buffer length attached which is equal to the number of values already stored in the buffer location.

If the executing process becomes delayed, it becomes a member of the set of delayed sending processes attached to the buffer location. If a process becomes re-activated, it is removed from all sets of delayed processes of which it was a member.

dynamic properties: A process executing a send buffer action becomes timeoutable when it reaches the point of execution where it may become delayed. It ceases to be timeoutable when it leaves that point.

static conditions: The class of the value must be compatible with the buffer element mode of the mode of the buffer location. The value must not be intra-regional (see section 11.2.2). The integer literal expression in priority must not deliver a negative value.

dynamic conditions: The assignment conditions of the value with respect to the buffer element mode of the mode of the buffer location apply; the possible exceptions occur before the process may become delayed.

The lifetime of the buffer location must not end while the executing process is delayed on it.

examples:

6.19 RECEIVE CASE ACTION

6.19.1General

syntax:

| <receive buffer case action> (1.2)

semantics: A receive case action receives synchronisation information transmitted by a send action. The detailed semantics depend on the synchronisation object used, which is either a signal or a buffer. Entering a receive case action does not necessarily result in a delaying of the executing process (see chapter 11 for further details).

6.19.2 Receive signal case action

syntax:

semantics: A receive signal case action evaluates the instance location, if present.

Then the executing process: (immediately) receives a signal or, if **ELSE** is specified, enters the corresponding action statement list, otherwise becomes delayed. The executing process immediately receives a signal if one of a <u>signal</u> name specified in a <u>signal</u> receive alternative is pending and may be received by the process. If more than one signal may be received, one with the highest priority will be selected in an implementation defined way.

If the executing process becomes delayed, it becomes a member of the set of delayed processes attached to each of the specified signals. If the delayed process becomes re-activated by another process executing a send signal action, it receives a signal.

If the executing process receives a signal, the corresponding action statement list is entered. Prior to entering, if an <u>instance</u> location is specified, the instance value identifying the process that has sent the received signal is stored in it. If the signal name of the received signal has a list of modes attached, a list of value receive names is specified; the signal carries a list of values, and the value receive names denote their corresponding value in the entered action statement list.

static properties: A defining occurrence in the defining occurrence list of a signal receive alternative defines a value receive name. Its class is the M-value class, where M is the corresponding mode in the list of modes attached to the <u>signal</u> name in front of it.

dynamic properties: A process executing a receive signal case action becomes timeoutable when it reaches the point of execution where it may become delayed. It ceases to be timeoutable when it leaves that point.

static conditions: The mode of the instance location must not have the read-only property.

All signal name occurrences must be different.

The optional IN and the defining occurrence list in the signal receive alternative must be specified if and only if the <u>signal</u> name has a non-empty set of modes. The number of names in the defining occurrence list must be equal to the number of modes of the <u>signal</u> name.

dynamic conditions: The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

15.83 RECEIVE CASE

```
(advance): count + := 1;
  (terminate):
    SEND readout(count) TO user;
    EXIT work_loop;
ESAC
(1.1)
```

6.19.3 Receive buffer case action

syntax:

semantics: A receive buffer case action evaluates, in an unspecified and possibly mixed order, the <u>instance</u> location, if present, and all <u>buffer</u> locations specified in a buffer receive alternative.

Then the executing process: (immediately) receives a value or, if ELSE is specified, enters the corresponding action statement list, otherwise becomes delayed. The executing process immediately receives a value if one is stored in, or a sending process delayed on, one of the specified buffer locations. If more than one value may be received, one with the highest priority will be selected in an implementation defined way.

If the executing process becomes delayed, it becomes a member of the set of delayed processes attached to each of the specified buffer locations. If the delayed process becomes re-activated by another process executing a send buffer action, it receives a value.

If the executing process receives a value, the corresponding action statement list is entered. If several buffer receive alternatives specify the same buffer location, the choice between them is not specified. Prior to entering, if an <u>instance</u> location is specified, the instance value identifying the process that has sent the received value is stored in it. The specified value receive name denotes the received value in the entered action statement list.

Another process becomes re-activated if the executing process receives a value from a buffer location, the attached set of delayed sending processes of which is not empty. The re-activated process is one with the highest priority attached, if the received value was stored in the buffer location, otherwise the one sending the received value. In the former case, the value to be sent by the re-activated process is stored in the buffer location (the capacity of which remains exceeded), and if more than one process may be re-activated, one will be selected in an implementation defined way. The re-activated process is removed from the set of delayed sending processes attached to the buffer location.

static properties: A defining occurrence in a buffer receive alternative defines a value receive name. Its class is the M-value class, where M is the buffer element mode of the mode of the <u>buffer</u> location labelling the buffer receive alternative.

dynamic properties: A process executing a receive buffer case action becomes timeoutable when it reaches the point of execution where it may become delayed. It ceases to be timeoutable when it leaves that point.

static conditions: The mode of the instance location must not have the read-only property.

dynamic conditions: The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

The lifetime of none of the buffer locations must end while the executing process is delayed on them.

6.20 CHILL BUILT-IN ROUTINE CALLS

syntax:

predefined names: The CHILL built-in routine names are predefined as built-in routine names (see section 6.7).

semantics: A CHILL built-in routine call is either a CHILL simple built-in routine call, which delivers no results (see section 6.20.1), a CHILL location built-in routine call, which delivers a location (see section 6.20.2), or a CHILL value built-in routine call, which delivers a value (see section 6.20.3).

static properties: A CHILL built-in routine call is a location built-in routine call if it is a CHILL location built-in routine call; it is a value built-in routine call if it is a CHILL value built-in routine call.

6.20.1 CHILL simple built-in routine calls

syntax:

semantics: A CHILL simple built-in routine call is a built-in routine call which delivers neither a value nor a location. The simple built-in routines for input output are defined in Chapter 7. The simple built-in routines for timing are defined in Chapter 9.

6.20.2 CHILL location built-in routine calls

syntax:

semantics: A CHILL location built-in routine call is a built-in routine call that delivers a location. The location built-in routines for input output are defined in Chapter 7.

6.20.3 CHILL value built-in routine calls

syntax:

```
< CHILL value built-in routine call> ::=
                                                                                              (1)
         NUM ( < discrete expression > )
                                                                                            (1.1)
        | PRED ( < discrete expression > )
                                                                                            (1.2)
         SUCC ( < discrete expression> )
                                                                                            (1.3)
        ABS ( < integer expression > )
                                                                                            (1.4)
        CARD ( < powerset expression > )
                                                                                            (1.5)
       | MAX ( < powerset expression > )
                                                                                            (1.6)
        MIN (< powerset expression>)
                                                                                            (1.7)
       | SIZE ( { <location> | <mode argument> } )
                                                                                            (1.8)
        | UPPER ( <upper lower argument> )
                                                                                            (1.9)
        | LOWER ( <upper lower argument> )
                                                                                           (1.10)
       | LENGTH ( < length argument> )
                                                                                           (1.11)
        | <allocate built-in routine call>
                                                                                           (1.12)
         <io value built-in routine call>
                                                                                           (1.13)
       <time value built-in routine call>
                                                                                           (1.14)
<mode argument> ::=
                                                                                             (2)
         <mode name>
                                                                                            (2.1)
       <array mode name> ( <expression> )
                                                                                            (2.2)
       | <string mode name> ( <integer expression> )
                                                                                            (2.3)
       < variant structure mode name> ( <expression list> )
                                                                                            (2.4)
<upper lower argument> ::=
                                                                                             (3)
         <array location>
                                                                                            (3.1)
       | <array expression>
                                                                                            (3.2)
       | <array mode name>
                                                                                            (3.3)
        <string location>
                                                                                            (3.4)
       | < string expression>
                                                                                           (3.5)
        <string mode name>
                                                                                            (3.6)
        < discrete location>
                                                                                           (3.7)
        < discrete expression>
                                                                                           (3.8)
       | < discrete mode name>
                                                                                           (3.9)
<length argument> ::=
                                                                                             (4)
         <string location>
                                                                                           (4.1)
       <string expression>
                                                                                           (4.2)
```

N.B. If the upper lower argument is an (<u>array, string, discrete</u>) location, the syntactic ambiguity is resolved by interpreting upper lower argument as a location rather than an expression or primitive value. If the length argument is a <u>string</u> location, the syntactic ambiguity is resolved by interpreting length argument as a location rather than an expression.

semantics: A CHILL value built-in routine call is a built-in routine call that delivers a value.

NUM delivers an integer value with the same internal representation as the value delivered by its argument.

PRED and SUCC deliver respectively the next lower and higher discrete value of their argument.

ABS delivers the absolute value of its argument.

CARD, MAX and MIN are defined on powerset values. CARD delivers the number of element values in its argument.

MAX and MIN deliver respectively the greatest and smallest element value in their argument.

SIZE is defined on referable locations and (possibly dynamic) modes. In the first case, it delivers the number of addressable memory units occupied by that location; in the second case, the number of addressable memory units that a referable location of that mode will occupy. The mode is static if the mode argument is a <u>mode</u> name, otherwise it is a dynamically parameterised version of it, with parameters as specified in the mode argument. In the first case, the location will not be evaluated at run time.

UPPER and LOWER are defined on (possibly dynamic):

- array, string and discrete locations, delivering the upper bound and lower bound of the mode of the location,
- array and string expressions, delivering the upper bound and lower bound of the mode
 of the value's class,
- strong discrete expressions, delivering the upper bound and lower bound of the mode of the value's class,
- array, string and discrete mode names, delivering the upper bound and lower bound of the mode.

LENGTH delivers the actual length of its argument.

static properties: The class of a NUM built-in routine call is the INT-derived class. The built-in routine call is constant if and only if the argument is either constant or literal.

The class of a *PRED* or *SUCC* built-in routine call is the resulting class of the argument. The built-in routine call is constant (literal) if and only if the argument is constant (literal).

The class of an ABS built-in routine call is the resulting class of the argument. The built-in routine call is constant (literal) if and only if the argument is constant (literal).

The class of a CARD built-in routine call is the INT-derived class. The built-in routine call is constant if and only if the argument is constant.

The class of a MAX or MIN built-in routine call is the M-value class, where M is the member mode of the mode of the <u>powerset</u> expression. The built-in routine call is constant if and only if the argument is constant.

The class of a SIZE built-in routine call is the INT-derived class. The built-in routine call is constant if the mode of the argument is static.

The class of an UPPER and LOWER built-in routine call is

- the M-value class if upper lower argument is an <u>array</u> location, <u>array</u> expression or <u>array mode</u> name, where M is the index mode of <u>array</u> location, <u>array</u> expression or <u>array mode</u> name, respectively;
- the INT-derived class if upper lower argument is a <u>string</u> location, <u>string</u> expression or <u>string mode</u> name;
- the M-value class if upper lower argument is a <u>discrete</u> location, <u>discrete</u> expression or <u>discrete mode</u> name, where M is the mode of <u>discrete</u> location, or <u>discrete</u> expression, or <u>discrete mode</u> name, respectively.

An UPPER or LOWER built-in routine call is constant if the upper lower argument is an (array, string or discrete) mode name, if the mode of the array or string location is static, if the array or string expression has a static class, or if upper lower argument is a discrete expression or a discrete location.

The class of a LENGTH built-in routine call is the INT-derived class.

static conditions: If the argument of a PRED or SUCC built-in routine call is constant, it must not deliver, respectively, the smallest or greatest discrete value defined by the root mode of the class of the argument. The root mode of the <u>discrete</u> expression argument of PRED and SUCC must not be an unnumbered set mode.

If the argument of a MAX or MIN built-in routine call is constant, it must not deliver the empty powerset value.

The location argument of SIZE must be referable.

The discrete expression as an argument of UPPER and LOWER must be strong.

The following compatibility requirements hold for a mode argument which is not a single <u>mode</u> name:

- The class of the expression must be compatible with the index mode of the <u>array mode</u> name.
- The <u>variant structure mode</u> name must be parameterisable and there must be as many expressions in the expression list as there are classes in its list of classes and the class of each expression must be compatible with the corresponding class in the list of classes.

dynamic conditions: PRED and SUCC cause the OVERFLOW exception if they are applied to the smallest or greatest discrete value defined by the root mode of the class of the argument.

NUM and CARD cause the OVERFLOW exception if the resulting value is outside the set of values defined by INT.

MAX and MIN cause the EMPTY exception if they are applied to empty powerset values.

ABS causes the OVERFLOW exception if the resulting value is outside the bounds defined by the root mode of the class of the argument.

The RANGEFAIL exception occurs if in the mode argument:

- the expression delivers a value which is outside the set of values defined by the index mode of the <u>array mode</u> name;
- the <u>integer</u> expression delivers a negative value or a value which is greater than the string length of the <u>string mode</u> name;
- any expression in the expression list for which the corresponding class in the list of classes of the <u>variant structure mode</u> name is an M-value class (i.e. is strong) delivers a value which is outside the set of values defined by M.

examples:

6.20.4 Dynamic storage handling built-in routines

syntax:

semantics: GETSTACK and ALLOCATE create a location of the specified mode and deliver a reference value for the created location. GETSTACK creates this location on the stack (see section 10.9). A location whose mode is that of the mode argument is created and a value referring to it is delivered. The created location is initialised with the value of value, if present; otherwise with the undefined value (see section 4.1.2).

TERMINATE ends the lifetime of the location referred to by the value delivered by <u>reference</u> primitive value. An implementation might as a consequence release the storage occupied by this location.

static properties: The class of a GETSTACK or ALLOCATE built-in routine call is the M-reference class, where M is the mode of mode argument. M is either the <u>mode</u> name or a parameterised mode constructed as:

&<array mode name> (<expression>) or

&<string mode name> (<integer expression>) or

& < variant structure mode name > (< expression list >),

respectively.

A GETSTACK or ALLOCATE built-in routine call is intra-regional if it is surrounded by a region, otherwise it is extra-regional.

static conditions: The class of the value, if present, in the GETSTACK and ALLOCATE built-in routine call must be compatible with the mode of mode argument; this check is dynamic in case the mode of mode argument is a dynamic mode.

If the first argument of GETSTACK or ALLOCATE has the read-only property, the second argument must be present.

The value, if present, in the GETSTACK and ALLOCATE built-in routine call, must be regionally safe for the created location.

- dynamic properties: A reference value is an allocated reference value if and only if it is returned by an ALLOCATE built-in routine call.
- dynamic conditions: GETSTACK causes the SPACEFAIL exception if storage requirements cannot be satisfied.

ALLOCATE causes the ALLOCATEFAIL exception if storage requirements cannot be satisfied.

For GETSTACK and ALLOCATE the assignment conditions of the value delivered by value with respect to the mode of mode argument apply.

TERMINATE causes the EMPTY exception if the <u>reference</u> primitive value delivers the value NULL.

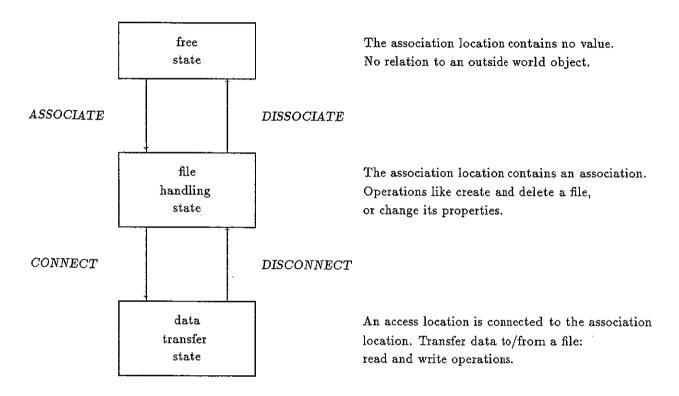
The <u>reference</u> primitive value must deliver an allocated reference value. The lifetime of the referenced location must not have ended.

7 INPUT AND OUTPUT

7.1 I/O REFERENCE MODEL

A model is used for the description of the input/output facilities in an implementation independent way; it distinguishes three states for a given association location: a free state, a file handling state and a data transfer state.

The diagram shows the three states and the possible transitions between the states.



The model assumes that objects, in implementations often referred to as datasets, files or devices, exist in the outside world, i.e. the external environment of a CHILL program. Such an outside world object is called a file in the model. A file can be a physical device, a communication line or just a file in a file management system; in general, a file is an object that can produce and/or consume data.

Manipulating a file in CHILL requires an association; an association is created by the associate operation and it identifies a file. An association has attributes; these attributes describe the properties of a file that is or could be attached to the association.

In the free state, there is no interaction or relation between the CHILL program and outside world objects. The associate operation changes the state of the model from the free state into the file handling state. This operation takes as one argument an association location and an implementation defined denotation for an outside world object for which an association must be created; additional arguments may be used to indicate the kind of association for the object and the initial values for the attributes of the association. A particular association also implies an (implementation dependent) set of operations that may be applied on the file that is attached to that association.

In the file handling state, it is possible to manipulate a file and its properties via an association, provided that the association enables the particular operation; for operations that change the properties of a file, an exclusive association for the file will be necessary in general.

The model assumes associations in general are exclusive, i.e. only one association exists at the same time for a given outside world object. However, implementations may allow the creation of more associations for the same object, provided that the object can be shared among different users (programs) and/or among different associations within the same program. All operations in the file handling state take an association as an argument.

The dissociate operation is used to end an association for an outside world object; this operation causes transition from the file handling state back to the free state.

Transferring data to or from a file is possible only in the data transfer state; transfer operations require an access location to be connected to an association for that file. The connect operation connects an access location to an association and changes the state of the model into the data transfer state. The operation takes an association location and an access location as arguments; the association location contains an association for the file to, or from, which data can be transferred via the access location. Additional arguments of the connect operation denote for which type of transfer operations the access location must be connected, and to which record the file must be positioned. At most one access location can be connected to an association location at any one time.

The disconnect operation takes an access location as argument and disconnects it from the association it is connected to; it changes the state of the model back to the file handling state.

In the data transfer state, an access location must be used as an argument of a transfer operation; there are two transfer operations provided, namely, a read operation to transfer data from a file to the program and a write operation to transfer data from the program to a file. The transfer operations use the record mode of the access location to transform CHILL values into records of the file, and vice versa.

A file is viewed in the model as an array of values; each element of this array relates to a record of the file. The element mode of this array is determined by the connect operation to be the record mode of the access location being connected. An index value is assigned to each record of the file; this value uniquely identifies each record of the file. In the description of the connect and transfer operations, three special index values will be used, namely, a base index, a current index and a transfer index. The base index is set by the connect operation and remains unchanged until a subsequent connect operation; it is used to calculate the transfer index in transfer operations and the current index in a connect operation. The transfer index denotes the position in the file where a transfer will take place; the current index denotes the record to which the file currently is positioned.

7.2 ASSOCIATION VALUES

7.2.1 General

An association value reflects the properties of a file that is or could be attached to it. A particular association value also implies an (implementation dependent) set of operations on the file that is possibly attached to it.

Association values have no denotation but are contained in locations of association mode; there exists no expression denoting a value of association mode. Association values can only be manipulated by built-in routines that take an association location as parameter.

7.2.2 Attributes of association values

An association value has attributes; the attributes describe the properties of the association and the file that may or could be attached to it.

The following attributes are language defined:

- existing: indicating that a (possibly empty) file is attached to the association;
- readable: indicating that read operations are possible for the file when it is attached to the association;
- writeable: indicating that write operations are possible for the file when it is attached to the association;
- indexable: indicating that the file, when it is attached to the association, allows for random access to its records;
- sequencible: indicating that the file, when it is attached to the association, allows for sequential access to its records;
- variable: indicating that the size of the records of the file, when it is attached to the association, may vary within the file.

These attributes have a boolean value; the attributes are initialized when the association is created and may be updated as a consequence of particular operations on the association. This list comprises the language defined attributes only; implementations may add attributes according to their own needs.

7.3 ACCESS VALUES

7.3.1 General

Access values are contained in locations of access mode. An access location is necessary to transfer data from or to a file in the outside world.

Access values have no denotation but are contained in locations of access mode; there exists no expression denoting a value of access mode. Access values can only be manipulated by built-in routines that take an access location as parameter.

7.3.2 Attributes of access values

Access values have attributes that describe their dynamic properties, the semantics of transfer operations, and the conditions under which exceptions can occur.

CHILL defines the following attributes:

- usage: indicating for which transfer operation(s) the access location is connected to an association; the attribute is set by the connect operation.
- outoffile: indicating whether or not the transfer index calculated by the last read operation was in the file; the attribute is initialized to FALSE by the connect operation and is set by every read operation.

7.4 BUILT-IN ROUTINES FOR INPUT OUTPUT

7.4.1 General

Language defined built-in routines are defined for operations on association locations and access locations, and for inspecting and changing the attributes of their values.

The built-in routines will be described in the following sections.

syntax:

<pre><io built-in="" call="" routine="" value=""> ::=</io></pre>	(1)
<association attr="" built-in="" call="" routine=""></association>	(1.1)
<pre><isassociated built-in="" call="" routine=""></isassociated></pre>	(1.2)
<access attr="" built-in="" call="" routine=""></access>	(1.3)
< readrecord built-in routine call>	(1.4)
<gettext built-in="" call="" routine=""></gettext>	(1.5)
<io built-in="" call="" routine="" simple=""> ::=</io>	(2)
<dissociate built-in="" call="" routine=""></dissociate>	(2.1)
< modification built-in routine call>	(2.2)
<pre><connect built-in="" call="" routine=""></connect></pre>	(2.3)
< disconnect built-in routine call>	(2.4)
<pre><writerecord built-in="" call="" routine=""></writerecord></pre>	(2.5)
<pre><text built-in="" call="" routine=""></text></pre>	(2.6)
<settext built-in="" call="" routine=""></settext>	(2.7)
<io built-in="" call="" location="" routine=""> ::=</io>	(3)
<associate built-in="" call="" routine=""></associate>	(3.1)

static conditions: A built-in routine parameter in an io built-in routine that is an <u>association</u>, <u>access</u> or <u>text</u> location must be referable.

7.4.2 Associating an outside world object

syntax:

$$ISASSOCIATED (< \underline{association} \ location>) \tag{2.1}$$

$$<$$
location $>$ (4.1)

semantics: ASSOCIATE creates an association to an outside world object. It initializes the <u>association</u> location with the created association. It initializes the attributes of the created association. The association location is also returned as a result of the call. The particular association that is created is determined by the locations and/or values occurring in the associate parameter list; the modes (classes) and the semantics of these locations (values) are implementation defined.

ISASSOCIATED returns TRUE if <u>association</u> location contains an association and FALSE otherwise.

static properties: The class of an ISASSOCIATED built-in routine call is the BOOL-derived class. The mode of an ASSOCIATE built-in routine call is the mode of the <u>association</u> location.

The regionality of an ASSOCIATION built-in routine call is that of the association location.

static conditions: The mode and the class of each associate parameter is implementation defined.

dynamic conditions: ASSOCIATE causes the ASSOCIATEFAIL exception if the <u>association</u> location already contains an association or if the association cannot be created due to implementation defined reasons.

examples:

7.4.3 Dissociating an outside world object

syntax:

DISSOCIATE (
$$<$$
association location $>$) (1.1)

semantics: DISSOCIATE terminates an association to an outside world object. An access location that is still connected to the association contained in an association location is disconnected before the association is terminated.

dynamic conditions: DISSOCIATE causes the NOTASSOCIATED exception if <u>association</u> location does not contain an association.

examples:

7.4.4 Accessing association attributes

syntax:

<association attr="" built-in="" call="" routine=""> ::=</association>	(1)	
EXISTING (<association location="">)</association>	(1.1)	
READABLE (< association location>)	(1.2)	
WRITEABLE (< association location>)	(1.3)	
INDEXABLE (< association location >)	(1.4)	
SEQUENCIBLE (< association location >)	(1.5)	
VARIABLE (< association location >)	(1.6)	

semantics: EXISTING, READABLE, WRITEABLE, INDEXABLE, SEQUENCIBLE and VARIABLE return respectively the value of the existing-, readable-, writeable-, indexable-, sequencible- and variable-attribute of the association contained in <u>association</u> location.

static properties: The class of an association attr built-in routine call is the BOOL-derived class.

dynamic conditions: The association attr built-in routine call causes the NOTASSOCIATED exception if association location does not contain an association.

7.4.5 Modifying association attributes

syntax:

semantics: CREATE creates an empty file and attaches it to the association denoted by the <u>association</u> location. The existing-attribute of the indicated association is set to TRUE if the operation succeeds.

DELETE detaches a file from the association denoted by <u>association</u> location and deletes the file. The existing-attribute of the indicated association is set to FALSE if the operation succeeds.

MODIFY provides the means of changing properties of an outside world object for which an association exists and that is denoted by <u>association</u> location; the locations and/or values that occur in modify parameter list describe how the properties must be modified. The modes (classes) and the semantics of these locations (values) are implementation defined.

dynamic conditions: CREATE, DELETE and MODIFY cause the NOTASSOCIATED exception if the <u>association</u> location does not contain an association.

CREATE causes the CREATEFAIL exception if one of the following conditions occurs:

- the existing-attribute of the association is TRUE;
- the creation of the file fails (implementation defined).

DELETE causes the DELETEFAIL exception if one of the following conditions occurs:

- the existing-attribute of the association is FALSE;
- the deletion of the file fails (implementation defined).

MODIFY causes the MODIFYFAIL exception if the properties, defined by modify parameter list cannot or may not be modified; the conditions under which this exception can occur are implementation defined.

examples:

7.4.6 Connecting an access location

syntax:

predefined names: To control the connect operation, performed by the built-in routine CONNECT, two symmode names are predefined in the language, namely, USAGE and WHERE; their defining modes are SET (READONLY, WRITEONLY, READWRITE) and SET (FIRST, SAME, LAST), respectively.

Values of the mode *USAGE* indicate for which type of transfer operations the access location must be connected to an association, while values of the mode *WHERE* indicate how the file that is attached to an association must be positioned by the connect operation.

semantics: CONNECT connects the access location denoted by transfer location to the association that is contained in <u>association</u> location; there must be a file attached to the denoted association; i.e. the association's existing-attribute must be TRUE.

The access location denoted by transfer location is the location itself if it is an <u>access</u> location; otherwise the <u>access</u> sub-location of the <u>text</u> location.

The value that is delivered by usage expression indicates for which type of transfer operations the access location must be connected to the file. If the expression delivers READONLY, the connection is prepared for read operations only; if it delivers WRITEONLY, the connection is set up for write operations only; if it delivers READWRITE, the connection is prepared for both read and write operations.

The indexable-attribute of the denoted association must be TRUE if the access location has an index mode, while the sequencible-attribute must be TRUE if the location has no index mode.

CONNECT (re)positions the file that is attached to the denoted association; i.e. it establishes a (new) base index and current index in the file. The (new) base index depends upon the value that is delivered by where expression:

- if where expression delivers FIRST or is not specified, the base index is set to 0; i.e. the file is positioned before the first record;
- if where expression delivers SAME, the base index is set to the current index in the file; i.e. the file position is not changed;
- if where expression delivers LAST, the base index is set to N, where N denotes the number of records in the file; i.e. the file is positioned after the last record.

After a base index is set, a current index will be established by CONNECT. This current index depends upon the optional specification of an index expression:

- if no index expression is specified, the current index is set to the (new) base index;
- · if an index expression is specified, the current index is set to

base index
$$+NUM(v) - NUM(l)$$

where l denotes the lower bound of the access location's index mode and v denotes the value that is delivered by index expression.

If the access location is being connected for sequential write operations (i.e. the access location has no index mode and the usage expression delivers WRITEONLY), then those records in the file that have an index greater than the (new) current index will be removed from the file; i.e. the file may be truncated or emptied by CONNECT.

An access location that has no index mode cannot be connected to an association for read and write operations at the same time.

Any access location to which the denoted association may be connected will be disconnected implicitly before the association is connected to the location that is denoted by transfer location.

CONNECT initializes the outoffile-attribute of the access location to FALSE and sets the usage-attribute according to the value that is delivered by usage expression.

static properties: The mode attached to a transfer location is the mode of the <u>access</u> location or the access mode of the <u>text</u> location, respectively.

static conditions: The mode of transfer location must have an index mode if an index expression is specified; the class of the value delivered by index expression must be compatible with that index mode. The transfer location must have the same regionality as the association location.

The class of the value delivered by usage expression must be compatible with the USAGE-derived class.

The class of the value delivered by where expression must be compatible with the WHERE-derived class.

dynamic conditions: CONNECT causes the NOTASSOCIATED exception if <u>association</u> location does not contain an association.

CONNECT causes the CONNECTFAIL exception if one of the following conditions occurs:

- the association's existing-attribute is FALSE;
- the association's readable-attribute is FALSE and usage expression delivers READONLY or READWRITE;
- the association's writeable-attribute is FALSE and usage expression delivers WRITEONLY or READWRITE;
- the association's indexable-attribute is FALSE and access location has an index mode;
- the association's sequencible-attribute is FALSE and access location has no index mode;
- where expression delivers SAME, while the association contained in <u>association</u> location is not connected to an access location;
- the association's variable-attribute is FALSE and the access location has a dynamic record mode, while usage expression delivers WRITEONLY or READWRITE;

- the association's variable-attribute is TRUE and the access location has a static record mode, while usage expression delivers READONLY or READWRITE;
- the access location has no index mode, while usage expression delivers READWRITE;
- the association contained in <u>association</u> location cannot be connected to the access location, due to implementation defined conditions.

CONNECT causes the RANGEFAIL exception if the index mode of access location is a range mode and the index expression delivers a value which lies outside the bounds of that range mode.

The EMPTY exception occurs if the access reference of the text location delivers the value NULL.

examples:

7.4.7 Disconnecting an access location

syntax:

semantics: DISCONNECT disconnects the access location denoted by transfer location from the association it is connected to.

dynamic conditions: DISCONNECT causes the NOTCONNECTED exception if the access location denoted by transfer location is not connected to an association.

7.4.8 Accessing attributes of access locations

syntax:

semantics: GETASSOCIATION returns a reference value to the association location that the access location denoted by transfer location is connected to; it returns NULL if the access location is not connected to an association.

GETUSAGE returns the value of the usage-attribute; i.e. READONLY (WRITEONLY) if the access location is connected only for read (write) operations, or READWRITE if the access location is connected for both read and write operations.

OUTOFFILE returns the value of the outoffile-attribute of access location; i.e. TRUE if the last read operation calculated a transfer index that was not in the file, FALSE otherwise.

static properties: The class of a GETASSOCIATION built-in routine call is the ASSOCIATION-reference class. The regionality of an GETASSOCIATION built-in routine call is that of the transfer location.

The class of an OUTOFFILE built-in routine call is the BOOL-derived class.

The class of a GETUSAGE built-in routine call is the USAGE-derived class.

dynamic conditions: GETUSAGE and OUTOFFILE cause the NOTCONNECTED exception if the access location is not connected to an association.

examples:

7.4.9 Data transfer operations

syntax:

$$\langle static\ mode\ location \rangle$$
 (3.1)

N.B. If the <u>access</u> location has an index mode, the syntactic ambiguity is resolved by interpreting the second argument as an index expression rather than a store location.

semantics: For the transfer of data to or from a file, the built-in routines WRITERECORD and READ-RECORD are defined. The <u>access</u> location must have a record mode, and it must be connected to an association in order to transfer data to or from the file that is attached to that association. The transfer direction must not be in contradiction with the value of the <u>access</u> location's usage-attribute.

Before a transfer takes place, the transfer index, i.e. the position in the file of the record to be transferred, is calculated. If the <u>access</u> location has no index mode, the transfer index is the current index incremented by 1; if the <u>access</u> location has an index mode, the transfer index is calculated as follows:

```
transfer index := base index + NUM(v) - NUM(l) + 1
```

where l is the lower bound of the mode of the <u>access</u> location's index mode and v denotes the value that is delivered by index expression. If the transfer of the record with the calculated transfer index has been performed successfully, the current index becomes the transfer index.

The read operation:

READRECORD transfers data from a file in the outside world to the CHILL program.

If the calculated transfer index is not in the file, the outoffile-attribute is set to TRUE; otherwise the file is positioned, the record is read, and the outoffile-attribute is set to FALSE.

The record that is read must not deliver an undefined value; the effect of the read operation is implementation defined if the record being read from the file is not a legal value according to the record mode of the <u>access location</u>.

If a store location is specified, then the value of the record that was read is assigned to this location. If no store location is specified, the value will be assigned to an implicitly created location; the lifetime of this location ends when the <u>access</u> location is disconnected or reconnected. Whether the referenced location is created only once by the connect operation, or every time a read operation is performed, is not defined.

READRECORD returns in both cases a reference value that refers to the (possibly dynamic mode) location to which the value was assigned.

If the outoffile-attribute is set to TRUE as a result of the built-in routine call, then the NULL value is returned as a result of the call.

The write operation:

WRITERECORD transfers data from the CHILL program to a file in the outside world. The file is positioned to the record with the calculated index and the record is written.

After the record has been written successfully, the number of records is set to the transfer index, if the latter is greater than the actual number of records.

The record written by WRITERECORD is the value delivered by write expression.

static properties: The class of the value that was read by READRECORD is the M-value class, where M is the record mode of the <u>access location</u>, if it has a static record mode, or a dynamically parameterised version of it, if the location has a dynamic record mode; the parameters of such a dynamically parameterised record mode are:

- the dynamic string length of the string value that was read in case of a string mode;
- the dynamic upper bound of the array value that was read in case of an array mode;
- the list of (tag) values associated with the mode of the structure value that was read in case of a variant structure.

The class of the READRECORD built-in routine call is the M-reference class if store location is not specified, otherwise it is the S-reference class, where S is the mode of the store location.

The regionality of a READRECORD built-in routine call is that of the store location if it is specified, otherwise it is that of the <u>access</u> location.

static conditions: The access location must have a record mode.

An index expression may not be specified if <u>access</u> location has no index mode and must be specified if <u>access</u> location has an index mode; the class of the value delivered by index expression must be compatible with that index mode.

The store location must be referable.

The mode of store location must not have the read-only property.

If store location is specified, then the mode of store location must be equivalent with the record mode of the <u>access</u> location, if it has a static record mode or a varying string record mode, otherwise a dynamically parameterised version of it; the parameters of such a dynamically parameterised mode are those of the value that has been read.

The class of the value delivered by write expression must be compatible with the record mode of the <u>access</u> location, if it has a static record mode or a varying string record mode; otherwise there should exist a dynamically parameterised version of record mode that is compatible with the class of write expression. The assignment conditions of the value of write expression with respect to the above mentioned mode apply.

dynamic conditions: The RANGEFAIL or TAGFAIL exceptions occur if the dynamic part of the above mentioned compatibility check fails.

The READRECORD and WRITERECORD built-in routine call cause the NOTCONNECTED exception if the <u>access</u> location is not connected to an association.

The READRECORD or WRITERECORD built-in routine call cause the RANGEFAIL exception if the index mode of <u>access</u> location is a range mode and the index expression delivers a value that lies outside the bounds of that range mode.

The READRECORD built-in routine call causes the READFAIL exception if one of the following conditions occurs:

- the value of the usage-attribute is WRITEONLY;
- the value of the outoffile-attribute is TRUE and the <u>access</u> location is connected for sequential read operations;
- the reading of the record with the calculated index fails, due to outside world conditions.

The WRITERECORD built-in routine call causes the WRITEFAIL exception if one of the following conditions occurs:

- the value of the usage-attribute is READONLY;
- the writing of the record with the calculated index fails, due to outside world conditions.

If the RANGEFAIL exception or the NOTCONNECTED exception occur then it occurs before the value of any attribute is changed and before the file is positioned.

examples:

20.24	READRECORD (record_file, curindex, record_buffer);	(1.1)
22.25	READRECORD (fileaccess);	(1.1)
20.32	WRITERECORD (record_file, curindex, record_buffer);	(2.1)
21.61	WRITERECORD (outfile, buffers(flag));	(2.1)
20.24	record_buffer	(3.1)
21.61	buffers(flag)	(4.1)

7.5 TEXT INPUT OUTPUT

7.5.1 General

Text output operations allow the representation of CHILL values in a human-readable form; text input operations perform the opposite transformation.

Text transfer operations are defined on top of the basic CHILL input/output model and operate on files that may be accessed either sequentially or randomly and whose records may have a fixed or variable length.

The model assumes that every record has a (possibly empty) positioning information attached, in implementations often referred to as carriage control or control characters.

Manipulating a text file in CHILL requires an association; transferring data to or from a text file requires a text location to be connected to an association for that file.

Text transfer operations can be applied to CHILL values that may become records of some text file, as well as to CHILL locations that are not necessarily related to any i/o activity of the program.

The possibility to recover from a piece of text the same CHILL values that originated it cannot be guaranteed in general, but rather it depends on the specific representation that has been used.

Text values are contained in locations of text mode. A text location is necessary to transfer data in human-readable form.

Text values have no denotation but are contained in locations of text mode; there exists no expression denoting a value of text mode. Text values can only be manipulated by built-in routines that take a text location as parameter.

7.5.2 Attributes of text values

Text values have attributes that describe their dynamic properties. The following attributes are defined:

- actual index: indicating the next character position of the text record to be read or written. It has a mode which is *INT* (0:L), where L is the text length of the value's mode. It is initialised to 0 when a text location is created.
- text record reference: indicating a reference value to the text record sub-location of the text location. It has a mode which is REF M, where M is the text record mode of the value's mode.
- access reference: indicating a reference value to the access sub-location of the text location. It has a mode which is REF M, where M is the access mode of the value's mode.

7.5.3 Text transfer operations

syntax:

<text built-in="" call="" routine=""> ::=</text>	(1)
READTEXT (< text io argument list>)	(1.1)
WRITETEXT (< text io argument list>)	(1.2)
that 's assumed I' do as	(9)
<text argument="" io="" list=""> ::=</text>	(2)
<pre><text argument=""> [, <index expression="">] ,</index></text></pre>	(0.1)
<format argument=""> [, <io list="">]</io></format>	(2.1)
<text argument=""> ::=</text>	(3)
< text location>	(3.1)
< character string location>	(3.2)
< character string expression>	(3.3)
)	()
<format argument=""> ::=</format>	(4)
< character string expression>	(4.1)
, -	• •
<io list=""> ::=</io>	(5)
<pre><io list=""> ::= <io element="" list=""> { , <io element="" list=""> }*</io></io></io></pre>	(5) (5.1)
<io element="" list=""> { , <io element="" list=""> }*</io></io>	(5.1)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7) (7.1)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7) (7.1)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7) (7.1) (7.2)
<pre><io element="" list=""> { , <io element="" list=""> }* <io element="" list=""> ::=</io></io></io></pre>	(5.1) (6) (6.1) (6.2) (7) (7.1) (7.2)

N.B. If the io list element is a location, the syntactic ambiguity is resolved by interpreting the io list element as a location argument rather than a value argument.

semantics: READTEXT applies the conversion, editing and i/o control functions contained in the format argument to the text record denoted by the text argument; this (possibly) produces a list of values that are assigned to the elements of the io list in the sequence in which they are specified.

WRITETEXT performs the opposite operation. No implicit i/o operations are performed.

If the text argument is a <u>character string</u> location or a <u>character string</u> expression, then the conversion and editing functions are applied without any relation with the external world. In this case the actual index denotes a location that is implicitly created at the beginning of the built-in routine call and initialised to 0. The text record is the character string denoted by <u>character string</u> location or <u>character string</u> expression and the text length its string length.

The elements of the io list may be either:

- · value arguments and location arguments, or
- variable clause widths as described below.

Relationships between a format argument and an io list

The value delivered by a format argument must have the form of a format control string (see 7.5.4.)

During the execution of a text i/o built-in routine call the format control string (see 7.5.4) denoted by the format argument and the io list are scanned from left to right. Each occurrence of a format text and format specification is interpreted and the appropriate action is taken as follows:

a. format text:

In READTEXT the text record should contain at the actual index position a string slice which is equal to the string delivered by format text. In WRITETEXT, the string delivered by format text is transferred to the text record. The semantics are the same as if a format specification which is %C and an io list element that delivers the same string value as that delivered by format text were encountered.

b. format specification:

If the format specification contains a repetition factor, then it is equivalent to a sequence of as many format element occurrences as the number denoted by repetition factor.

If the format specification is a format clause, then it contains a control code. If the control code is a conversion clause, then an io list element is taken from the io list and the conversion function selected by the conversion code, conversion qualifiers and clause width is applied to it (see section 7.5.5). If the control code is an editing clause or an io clause, then the editing or io function selected by the editing code or io code and clause width is applied to the text argument without reference to the io list (see sections 7.5.6 and 7.5.7).

If the clause width is variable, then a value is taken from the list, which denotes the width parameter of the conversion or editing control function.

If the format specification is a parenthesised clause, then the format control string that is contained in it is scanned.

The interpretation of the format control string terminates when the end of the string delivered by format control string has been reached.

The io list elements of the io list are scanned in the order that they are specified.

static conditions: If the text argument is a string location, its mode must be a varying string mode.

An index expression may not be specified if the text argument is not a <u>text</u> location or if it is and its access mode has no index mode and must be specified if the access mode has an index mode; the class of the value delivered by index expression must be compatible with that index mode.

A text argument in a WRITETEXT built-in routine call must be a location.

A string location in a text argument must be referable.

dynamic conditions: The TEXTFAIL exception occurs if:

- the string value delivered by the format argument cannot be derived as a terminal production
 of the format control string, or
- an attempt to assign to the actual index a value which is less than 0 or greater than text length is made, or
- during the interpretation, the end of the format control string has been reached and the io list is not completely scanned, or no more elements can be taken from the io list and the format control string contains more conversion codes or variable clause widths, or
- an io clause is encountered and the text argument is not a text location, or
- a format text is encountered in READTEXT and the text record does not contain at the actual index position a string which is equal to the string delivered by format text.

Any exception defined for the READRECORD and WRITERECORD built-in routine call can occur if an i/o control function is executed and any one of the dynamic conditions defined is violated.

examples:

7.5.4 Format control string

syntax:

N.B. A format specification is terminated by the first character that cannot be part of the format element. Spaces and format effectors may not be used within format elements. A period (.) may be used to terminate a format clause. It belongs to the format clause and it has only a delimiting effect. To represent the character percent (%) within a format text, it has to be written twice (%%).

semantics: A format control string specifies the external form of the values being transferred and the layout of data within the records. A format control string is composed of format text occurrences, which denote fixed parts of the records and of format specification occurrences, which denote the external representations of CHILL values, allowing the editing of the text record or controlling the actual i/o operations.

A format specification that contains a repetition factor and a format clause is equivalent to as many identical format specification occurrences for the format clause as the repetition factor. A repetition factor can be 0, in which case the format specification is not considered. E.g. "%3D4" is equivalent to "%D4%D4%D4".

The decimal notation is assumed for the digits in a repetition factor.

A format control string in a parenthesised clause is repeatedly scanned according to the repetition factor. If none is specified, 1 is assumed by default.

26.20 size = %C%/ (1.1)

7.5.5 Conversion

syntax:

$$B \mid O \mid H \mid C$$
 (2.1)

$$L \mid E \mid P < \text{character} >$$
 (3.1)

$$<$$
clause $width> ::=$ (4) $\{<$ digit $>$ $\}^+ \mid V$ (4.1)

derived syntax: A conversion clause in which a clause width is not present is derived syntax for a conversion clause in which a clause width that is 0 is specified.

semantics: A conversion in a READTEXT built-in routine call transforms a string which is an external representation into a CHILL value. A conversion in a WRITETEXT built-in routine call performs the opposite transformation. The conversion code together with the conversion qualifier specifiy the type of the conversion and the details of the requested operation such as justification, overflow handling and padding.

The external representation is a string whose length usually depends on the value being converted. That string may contain the minimum number of characters that are necessary to represent the CHILL value (free format) or may have a given length (fixed format).

In the fixed format a slice of width size starting from the actual index position is read from or written into the text record according to the justification and padding selected by conversion qualifiers, as follows:

- in READTEXT: all padding characters (to the left or to the right according to the justification), if any, are removed. However, when characters or fixed character strings are being read, the maximum number N of padding characters that are removed is width -L, where L is 1 or string length, respectively. No characters are removed if N < 0. The remaining characters are taken as the external representation;
- in WRITETEXT: if the length of the external representation is less than or equal to width, then the characters are justified to the left or to the right in the slice (according to the justification). The unused string elements, if any, are filled with the padding character. Otherwise the string is truncated (on the left if the justification to the right is selected, otherwise on the right), or width "overflow" indicator characters (*) are transferred, if the qualifier E is present. The truncation is applied to the external representation, including the minus sign, if any.

In the free format the following holds:

- in READTEXT: padding characters, if any, are skipped except when a character or a character string is being read and the conversion qualifier P is not specified. Then, the external representation is taken as the longest slice of characters that starts at the actual index and is made of all the subsequent characters that may lexically belong to it as defined below.
- in WRITETEXT: the string delivered by the conversion is inserted starting from the actual index position.

In WRITETEXT the string which is the external representation is transferred to the text record without regard to its actual length. After the transfer, the actual index is automatically advanced to the next available character position and the actual length is set to the maximum value between the actual index and the (old) actual length.

A clause width is constant if it is made of digits. The decimal notation is assumed. Otherwise it is variable.

If the width is zero, then the free format is chosen, otherwise the width is the length of the fixed format.

If the width is too small to contain the string, the appropriate action is taken depending on the conversion qualifier.

In a READTEXT the external representation that is applied is the one defined below for the mode of the location argument.

In a WRITETEXT the external representation that is applied is the one defined below for the mode M of the M-value or M-derived class of the value delivered by the value argument.

Conversion codes

Conversion codes are represented as single letters. The following conversion codes are defined:

- B: binary representation;
- O: octal representation;
- H: hexadecimal representation;
- C: conversion: indicates the default external representation of CHILL values, which depends on the mode of the value being converted (see below).

The external representation depends on the conversion code and the mode of the value being converted.

Conversion qualifiers

Conversion qualifiers are represented as single letters. The following conversion qualifiers are defined:

- L: left justification. Right justification is assumed if it is not present. In the free format the qualifier has no effect.
- E: overflow evidence. In WRITETEXT the overflow indication is selected; if the qualifier is not present, then truncation is performed. In READTEXT or in the free format this qualifier has no effect.
- P: padding. The character that follows the qualifier specifies the padding character. If P is not present, then the padding character is assumed to be space by default. In READTEXT if the free format is selected, then spaces and HT (Horizontal Tabulation) are considered as the same character for skipping purposes, either when specified after the qualifier or when applied by default.

External representation

The external representation of CHILL values is defined as follows:

a. integers

Integer values are lexically represented as one or more digits in a decimal default base without leading zeroes and with a leading sign if negative. A leading plus sign and leading zeroes are discarded in READTEXT. The following conversion codes are available: B, O, C and H. The conversion code C selects the decimal representation. The digits that may belong to the representation are only those that are selected by the conversion code.

b. booleans

Boolean values are lexically represented as simple name string, that are TRUE and FALSE (in upper-case (e.g. TRUE) or lower case (e.g. true) depending on the representation chosen by the implementation for the special simple name strings). The following conversion code is available: C.

c. characters

Character values are lexically represented as strings of length 1. The following conversion code is available: C.

d. sets

Set mode values are lexically represented as simple name strings, that are the set literals. The following conversion code is available: C.

e. ranges

Range values have the same representation as the values of their root mode. However, only the representations of the values defined by the range mode belong to the set of external representations associated to the range mode.

f. character strings

Character string values are lexically represented as strings of characters of length L. In WRITETEXT L is the actual length. In READTEXT L is the string length if the string is a fixed string, otherwise it is a varying string and L is the string length, unless there are less characters available in the (slice of) text record at the actual index position, in which case L is the number of available characters. The following conversion code is available: C.

g. bit strings

Bit string values are lexically represented as strings of binary digits. The same rules as for character strings apply to determine the number of digits. The following conversion code is available: C.

dynamic properties: A clause width has a width, which is the value delivered by digits or by a value from the io list if the clause width is variable.

dynamic conditions: The TEXTFAIL exception occurs if:

- in READTEXT, the text record does not contain a string slice starting at the actual index that (after the removal or skipping of padding characters, see above) can be interpreted as an external representation of one of the values of the mode of the current location argument (including an attempt to read a non-empty external representation from a text record when actual index = actual length), or
- in WRITETEXT, a string slice that is the external representation of the current value argument can not be transferred to the text record starting at the actual index, or
- in READTEXT a conversion code is encountered and the current element in the io list is not a location, or the mode of the location has the read-only property, or
- a variable clause width is encountered and the corresponding io list element in the io list does not have an integer class or it is less than 0.

examples:

$$26.21 CL6$$
 (1.1)

7.5.6 Editing

syntax:

derived syntax: An editing clause in which a clause width is not present is derived syntax for an editing clause in which a clause width that is 1 is specified if the editing code is not T, otherwise 0, respectively.

semantics: The following editing functions are defined:

X: space: width space characters are inserted or skipped.

>: skip right: the actual index is moved rightward for width positions.

<: skip left: the actual index is moved leftward for width positions.

T: tabulation: the actual index is moved to the position width.

In WRITETEXT, if the actual index is moved to a position which is greater than the actual length, then a string of N space characters, where N is the difference between the actual index and the (old) actual length is appended to the text record. The actual length is set to the maximum value between the actual index and the (old) actual length.

dynamic conditions: The TEXTFAIL exception occurs if:

- the actual index is moved to a position which is less than 0 or greater than text length,
 or
- in READTEXT the actual index is moved to a position which is greater than the actual length, or
- in READTEXT the editing code X is specified and a string of width space or HT (Horizontal Tabulation) characters is not present in the text record at the actual index position.

examples:

$$26.22 X$$
 (1.1)

7.5.7 I/O control

syntax:

$$\langle io \ clause \rangle ::=$$
 (1) $\langle io \ code \rangle$ (1.1)

$$< io \ code> ::=$$
 (2)
 $/ |-|+|?|!=$ (2.1)

semantics: The i/o control functions (except %=) perform an i/o operation. They allow precise control over the transfer of the text record. In READTEXT, all the functions have the same effect, to read the next record from the file. In WRITETEXT, the text record and the appropriate representation of the carriage control information are transferred. The initial position of the carriage at the time the text location is connected is such that the first character of the first text record is printed at the beginning of the first unoccupied line (regardless of any positioning information attached to the text record).

The carriage placement is described by means of the following abstract operations on the current column, line and page (x, y, z) considering columns as being numbered from zero starting at the left margin, and lines from zero starting at the top margin.

nl(w): the carriage is moved w lines downward, at the beginning of the line (new position: $(0, (y+w) \mod p, z + (y+w)/p$, where p is the number of lines per page));

np(w): the carriage is moved w pages downward at the beginning of the line (new position: (0,0,z+w)).

The following control functions are provided:

- /: next record: the record is printed on the next line (nl(1), print record, nl(0));
- +: next page: the record is printed on the top of the next page (np(1), print record, nl(0));
- -: current line: the record is printed on the current line (print record, nl(0));
- ?: prompt: the record is printed on the next line. The carriage is left at the end of the line (nl(1), print record);
- !: emit: no carriage control is performed (print record);
- =: end page: defines the positioning of the next record, if any, to be at the top of the next page (this overrides the positioning performed before the printing of the record). It does not cause any i/o operation.

The I/O transfer is performed as follows:

- in READTEXT, the semantics are as if a READRECORD (A,I,R), where A is the access sub-location of the <u>text</u> location, I is the index expression (if any) and R denotes the text record, were executed. After the I/O transfer actual index is set to 0 and actual length to the string length of the string value that was read;
- in WRITETEXT, the semantics are as if a WRITERECORD (A,I,R), where A is the access sub-location of the <u>text</u> location, I is the index expression (if any) and R denotes the text record, were executed. The associated positioning information is also transferred. If the record mode of the access is not dynamic, then the text record is filled at the end with space characters and its actual length is set to text length before the transfer takes place. After the I/O transfer actual index and actual length are set to 0.

examples:

7.5.8 Accessing the attributes of a text location

<gettext built-in routine call> ::=

syntax:

$$| GETTEXTINDEX (< \underline{text} | location >)$$

$$| GETTEXTACCESS (< \underline{text} | location >)$$

$$| EOLN (< \underline{text} | location >)$$

$$(1.2)$$

(1)

(1.1)

 ::= (2)
$$SETTEXTRECORD (< \underline{text} | location>, < \underline{character string} | location>) (2.1)$$

$$| SETTEXTINDEX (< \underline{text} | location>, < \underline{integer} | expression>) (2.2)$$

$$| SETTEXTACCESS (< \underline{text} | location>, < \underline{access} | location>) (2.3)$$

semantics: GETTEXTRECORD returns the text record reference of text location.

GETTEXTINDEX returns the actual index of text location.

GETTEXTRECORD (< text location >)

GETTEXTACCESS returns the access reference of text location.

EOLN delivers TRUE if no more characters are available in the text record (i.e. if the actual index equals the actual length).

SETTEXTRECORD stores a reference to the location delivered by <u>character string</u> location into the text record reference of the <u>text</u> location.

SETTEXTINDEX has the same semantics as an editing clause in WRITETEXT in which editing code is T and clause width delivers the same value as <u>integer</u> expression, applied to the text record denoted by <u>text</u> location.

SETTEXTACCESS stores a reference to the location delivered by <u>access</u> location into the access reference of the <u>text</u> location.

static properties: The class of the GETTEXTRECORD built-in routine call is the M-reference class, where M is the text record mode of the <u>text</u> location.

The class of the GETTEXTINDEX built-in routine call is the INT-derived class.

The class of the GETTEXTACCESS built-in routine call is the M-reference class, where M is the access mode of the <u>text</u> location.

The class of the EOLN built-in routine call is the BOOL-derived class.

A GETTEXTRECORD or GETTEXTACCESS built-in routine call has the same regionality as the <u>text</u> location.

static conditions: The mode of the <u>character string</u> location argument of SETTEXTRECORD must be read-compatible with the text record mode of the <u>text</u> location.

The mode of the <u>access</u> location argument of SETTEXTACCESS must be read-compatible with the access mode of the <u>text</u> location.

The location argument in SETTEXTRECORD and SETTEXTACCESS must have the same regionality as the <u>text</u> location.

dynamic conditions: The TEXTFAIL exception occurs if the <u>integer</u> expression argument of SETTEXTIN-DEX delivers a value that is less than 0 or greater than the text length of the <u>text</u> location.

examples:

26.23 GETTEXTINDEX (output)

(1.2)

8 EXCEPTION HANDLING

8.1 GENERAL

An exception is either a language defined exception, in which case it has a language defined exception name, a user defined exception, or an implementation defined exception. A language defined exception will be caused by the dynamic violation of a dynamic condition. Any exception can be caused by the execution of a cause action.

When an exception is caused, it may be handled, i.e. an action statement list of an appropriate handler will be executed.

Exception handling is defined such that at any statement it is statically known which exceptions might occur (i.e. it is statically known which exceptions cannot occur) and for which exceptions an appropriate handler can be found or which exceptions may be passed to the calling point of a procedure. If an exception occurs and no handler for it can be found, the program is in error.

When an exception occurs at an action statement or a declaration statement, the execution of the statement is performed up to an unspecified extent, unless stated otherwise in the appropriate section.

8.2 HANDLERS

syntax:

semantics: A handler is entered if it is appropriate for an exception E according to section 8.3. If E is mentioned in an exception list in an on-alternative in the handler, the corresponding action statement list is entered; otherwise ELSE is specified and the corresponding action statement list is entered.

> When the end of the chosen action statement list is reached, the handler and the construct to which the handler is appended are terminated.

static conditions: All the exception names in all the exception list occurrences must be different.

dynamic conditions: The SPACEFAIL exception occurs if an action statement list is entered and storage requirements cannot be satisfied.

examples:

HANDLER IDENTIFICATION

When an exception E occurs at an action or module A, or a data statement or region D, the exception may be handled by an appropriate handler; i.e. an action statement list in the handler will be executed or the exception may be passed to the calling point of a procedure; or, if neither is possible, the program is in error.

For any action or module A, or data statement or region D, it can be statically determined whether for a given exception E at A or D an appropriate handler can be found or whether the exception may be passed to the calling point.

An appropriate handler for A or D with respect to an exception with exception name E is determined as follows:

- 1. if a handler which mentions E in an exception list or which specifies ELSE is appended to or included in A or D, and E occurs in the reach directly enclosing the handler, then that handler is the appropriate one with respect to E:
- 2. otherwise, if A or D is directly enclosed by a bracketed action, a module or a region, the appropriate handler (if present) is the appropriate handler for the bracketed action, module or region with respect to E;
- 3. otherwise, if A or D is placed in the reach of a procedure definition then:
 - if a handler which mentions E in an exception list or specifies **ELSE** is appended to the procedure definition, then that handler is the appropriate handler,
 - otherwise, if E is mentioned in the exception list of the procedure definition, then E is caused at the calling point,
 - otherwise there is no handler;
- 4. otherwise, if A or D is placed in the reach of a process definition, then:
 - if a handler which mentions E in an exception list or specifies **ELSE** is appended to the process definition, then that handler is the appropriate handler,
 - otherwise there is no handler; however, in this situation an implementation defined handler may be appropriate (see section 13.4);
- 5. otherwise, if A is an action of an action statement list in a handler, then the appropriate handler is the appropriate handler for the action A' or data statement or region D' with respect to E which the handler is appended to or included in but considered as if that handler were not specified.

If an exception is caused and the transfer of control to the appropriate handler implies exiting from blocks, local storage will be released when exiting from the block.

9 TIME SUPERVISION

9.1 GENERAL

It is assumed that a concept of time exists externally to a CHILL program (system). CHILL does not specify the precise properties of time, but provides mechanisms to enable a program to interact with the external world's view of time.

TIMEOUTABLE PROCESSES

The concept of a timeoutable process exists in order to identify the precise points during program execution where a time interrupt may occur, that is, when a time supervision may interfere with the normal execution of

A process becomes timeoutable when it reaches a well-defined point in the execution of certain actions. CHILL defines a process to become timeoutable during the execution of specific actions; an implementation may define a process to become timeoutable during the execution of further actions.

TIMING ACTIONS 9.3

syntax:

(1.3)

semantics: A timing action specifies time supervisions of the executing process. A time supervision may be initiated, it may expire and it may cease to exist. Because of the cyclic timing action and because of the nesting of timing actions, several time supervisions may be associated with the same process.

> A time interrupt occurs when a process is timeoutable and at least one of its associated time supervisions has expired. The occurrence of a time interrupt implies that the first expired time supervision ceases to exist; furthermore, it leads to the transfer of control associated with that time supervision in the supervised process. If the supervised process was delayed, it becomes re-activated.

Time supervisions also cease to exist when control leaves the timing action that initiated them.

9.3.1 Relative timing action

syntax:

semantics: The duration primitive value is evaluated, a time supervision is initiated, and then the action statement list is entered.

> If DELAY is not specified, the time supervision is initiated before the action statement list is entered, otherwise it is initiated when the executing process becomes timeoutable at the point of execution specified by the action statement in the action statement list.

> If DELAY is specified, the time supervision ceases to exist if it has been initiated and the executing process ceases to be timeoutable.

The time supervision expires if it has not ceased to exist when the specified period of time has elapsed since initiation.

The transfer of control associated with the time supervision is to the action statement list of the timing handler.

static conditions: If DELAY is specified the action statement list must consist of precisely one action statement that may itself cause the executing process to become timeoutable.

dynamic conditions: The TIMERFAIL exception occurs if the initiation of the time supervision fails for an implementation defined reason.

9.3.2 Absolute timing action

syntax:

semantics: The <u>absolute time</u> primitive value is evaluated, a time supervision is initiated, and then the action statement list is entered.

The time supervision expires if it has not ceased to exist at (or after) the specified point in time.

The transfer of control associated with the time supervision is to the action statement list of the timing handler.

dynamic condition: The TIMERFAIL exception occurs if the initiation of the time supervision fails for an implementation defined reason.

9.3.3 Cyclic timing action

syntax:

semantics: The cyclic timing action is intended to ensure that the executing process enters the action statement list at precise intervals without cumulated drifts (this implies that the execution time for the action statement list on average should be less than the specified duration value). The <u>duration</u> primitive value is evaluated, a relative time supervision is initiated, and then the action statement list is entered.

The time supervision expires if it has not ceased to exist when the specified period of time has elapsed since initiation. Indivisibly with the expiration a new time supervision with the same duration value is initiated.

The transfer of control associated with the time supervision is to the beginning of the action statement list.

Note that the cyclic timing action can only terminate by a transfer of control out of it.

dynamic properties: The executing process becomes timeoutable if and when control reaches the end of the action statement list.

dynamic conditions: The TIMERFAIL exception occurs if any initiation of a time supervision fails for an implementation defined reason.

9.4 BUILT-IN ROUTINES FOR TIME

syntax:

semantics: Implementations are likely to have quite different requirements and capabilities in terms of precision and range of time values. The built-in routines defined below are intended to accommodate these differences in a portable manner.

9.4.1 Duration built-in routines

syntax:

```
      <duration built-in routine call> ::=
      (1)

      MILLISECS (<integer expression>)
      (1.1)

      | SECS (<integer expression>)
      (1.2)

      | MINUTES (<integer expression>)
      (1.3)

      | HOURS (<integer expression>)
      (1.4)

      | DAYS (<integer expression>)
      (1.5)
```

semantics: A duration built-in routine call delivers a duration value with implementation defined and possibly varying precision (i.e. MILLISECS (1000) and SECS (1) may deliver different duration values); this value is the closest approximation in the chosen precision to the indicated period of time.

static properties: The class of a duration built-in routine call is the DURATION-derived class.

dynamic conditions: The RANGEFAIL exception occurs if the implementation cannot deliver a duration value denoting the indicated period of time.

9.4.2 Absolute time built-in routine

syntax:

semantics: The ABSTIME built-in routine call delivers an absolute time value denoting the point in time in the Gregorian calendar indicated in the parameter list. When higher order parameters are omitted, the point in time indicated is the next one that matches the low order parameters present (e.g. ABSTIME (15,12,00,00) denotes noon on the 15th in this or the next month.

When no parameters are specified, an absolute time value denoting the present point in time is delivered.

static properties: The class of the absolute time built-in routine call is the TIME-derived class.

dynamic conditions: The RANGEFAIL exception is caused if the implementation cannot deliver an absolute time value denoting the indicated point in time.

9.4.3 Timing built-in routine call

syntax:

<pre><timing built-in="" call="" routine="" simple=""> ::= WAIT () EXPIRED () INTTIME (<absolute primitive="" time="" value=""> , [[[(year location> < month location> ,] < day location> ,] <hour location=""> ,] <minute location=""> ,]</minute></hour></absolute></timing></pre>	(1) (1.1) (1.2)
<second location="">)</second>	(1.3)
<pre><year location=""> ::= <iinteger location=""></iinteger></year></pre>	(2) (2.1)
<month location=""> ::= <integer location=""></integer></month>	(3) (3.1)
<day location=""> ::= < integer location></day>	(4) (4.1)
<hour location=""> ::= <integer location=""></integer></hour>	(5) (5.1)
<minute location=""> ::= <integer location=""></integer></minute>	(6) (6.1)
<pre><second location=""> ::= <integer location=""></integer></second></pre>	(7) (7.1)

semantics: WAIT unconditionally makes the executing process timeoutable: its execution can only terminate by a time interrupt.

EXPIRED makes the executing process timeoutable if one of its associated time supervision has expired; otherwise it has no effect.

INTTIME assigns to the specified integer locations an integer representation of the point in time in the Gregorian calendar specified by the <u>absolute time</u> primitive value.

static conditions: All specified integer locations must be referable and their modes may not have the read-only property.

dynamic properties: WAIT makes the executing process timeoutable.

EXPIRED makes the executing process timeoutable if there is an expired time supervision associated with it.

10 PROGRAM STRUCTURE

10.1 GENERAL

The if action, case action, do action, delay case action, begin-end block, module, region, spec module, spec region, context, receive case action, procedure definition and process definition determine the program structure; i.e. they determine the scope of names and the lifetime of locations created in them.

- The word block will be used to denote:
 - the action statement list in a do action including any loop counter and while control;
 - the action statement list in a then clause in an if action;
 - the action statement list in a case alternative in a case action:
 - the action statement list in a delay alternative in a delay case action;
 - the begin-end block;
 - the procedure definition excluding the result spec and parameter spec of all formal parameters of the formal parameter list;
 - the process definition excluding the parameter spec of all formal parameters of the formal parameter list:
 - the action statement list in a buffer receive alternative or in a signal receive alternative, including any defining occurrences in a defining occurrence list after IN;
 - the action statement list after ELSE in an if action or case action or a receive case action or handler;
 - the on-alternative in a handler:
 - the action statement list in a relative timing action, an absolute timing action, a cyclic timing action or in a timing handler.
- The word modulion will be used to denote:
 - a module or region, excluding the context list and defining occurrence, if any;
 - a spec module or spec region, excluding the context list, if any;
 - a context.
- The word group will denote either a block or a modulion.
- The word reach or reach of a group will denote that part of the group that is not surrounded (see section 10.2) by an inner group.

A group influences the scope of each name created in its reach. Names are created by defining occurrences:

- A defining occurrence in the defining occurrence list of a declaration, mode definition or synonym definition or appearing in a signal definition creates a name in the reach where the declaration, mode definition, synonym definition or signal definition, respectively, is placed.
- A defining occurrence in a set mode creates a name in the reach directly enclosing the set mode.
- A defining occurrence appearing in the defining occurrence list in a formal parameter list creates a name in the reach of the associated procedure definition or process definition.
- A defining occurrence in front of a colon followed by an action, region, procedure definition, or process definition creates a name in the reach where the action, region, procedure definition, process definition, respectively, is placed.
- A (virtual) defining occurrence introduced by a with part or in a loop counter creates a name in the reach of the block of the associated do action.
- A defining occurrence in the defining occurrence list of a buffer receive alternative or a signal receive alternative creates a name in the reach of the block of the associated buffer receive alternative or signal receive alternative, respectively.
- A (virtual) defining occurrence for a language predefined or an implementation defined name creates a name in the reach of the imaginary outermost process (see section 10.8).

The places where a name is used are called applied occurrences of the name. The name binding rules associate a defining occurrence with each applied occurrence of the name (see section 12.2.2).

A name has a certain scope, i.e. that part of the program where its definition or declarations can be seen and, as a consequence, where it may be freely used. The name is said to be visible in that part. Locations and procedures have a certain lifetime, i.e. that part of the program where they exist. Blocks determine both visibility of names and the lifetime of the locations created in them. Modulions determine only visibility; the lifetime of locations created in the reach of a modulion will be the same as if they were created in the reach of the first surrounding block. Modulions allow for restricting the visibility of names. For instance, a name created in the reach of a module will not automatically be visible in inner or outer modules, although the lifetime might allow for it.

10.2 REACHES AND NESTING

syntax:

```
<br/>
<br/>
begin-end body> ::=
                                                                                             (1)
         <data statement list> <action statement list>
                                                                                           (1.1)
c body> ::=
                                                                                             (2)
         <data statement list> <action statement list>
                                                                                           (2.1)
cess body> ::=
                                                                                             (3)
         <data statement list> <action statement list>
                                                                                           (3.1)
<module body> ::=
                                                                                             (4)
         { <data statement> | <visibility statement> | <region> |
         <spec region> }* <action statement list>
                                                                                           (4.1)
<region body> ::=
                                                                                             (5)
        { <data statement> | <visibility statement> }*
                                                                                           (5.1)
<spec module body> ::=
                                                                                             (6)
        { <quasi data statement> | <visibility statement> |
         <spec module> | <spec region> }*
                                                                                           (6.1)
<spec region body> ::=
        { <quasi data statement> | < visibility statement> }*
                                                                                           (7.1)
<context body> ::=
                                                                                             (8)
        { <quasi data statement> | <visibility statement> |
        <spec module> | <spec region> }*
                                                                                           (8.1)
<action statement list> ::=
                                                                                             (9)
        { <action statement> }*
                                                                                           (9.1)
<data statement list> ::=
                                                                                           (10)
        { <data statement> }*
                                                                                          (10.1)
<data statement> ::=
                                                                                           (11)
         <declaration statement>
                                                                                          (11.1)
       | <definition statement>
                                                                                          (11.2)
<definition statement> ::=
                                                                                           (12)
         <synmode definition statement>
                                                                                          (12.1)
        <newmode definition statement>
                                                                                          (12.2)
        <synonym definition statement>
                                                                                          (12.3)
        cprocedure definition statement>
                                                                                          (12.4)
        cess definition statement>
                                                                                          (12.5)
        <signal definition statement>
                                                                                          (12.6)
        < empty > ;
                                                                                          (12.7)
```

semantics: When a reach of a block is entered, all the lifetime-bound initialisations of the locations created when entering the block are performed. Subsequently, the reach-bound initialisations in the block reach, the possibly dynamic evaluations in the loc-identity declarations, the reach-bound initialisations in the regions and the actions are performed in the order they are textually specified.

When a reach of a modulion is entered, the reach-bound initialisations, the possibly dynamic evaluations in the loc-identity declarations, the reach-bound initialisations in the regions and the actions (if the modulion is a module) that are in the modulion reach are performed in the order they are textually specified.

A data statement, action, module or region, is terminated either by completing it, or by terminating a handler appended to it.

When a reach-bound initialisation, loc-identity declaration, action, module, region, procedure or process is terminated, execution is resumed as follows, depending on the statement or the kind of termination:

- if the statement is terminated by completing the execution of a handler, then the execution is resumed with the subsequent statement;
- otherwise, if it is an action that implies a transfer of control, the execution is resumed with the statement defined for that action (see sections 6.5, 6.6, 6.8, 6.9);
- otherwise, if it is a procedure, control is returned to the calling point (see section 10.4).
- otherwise, if it is a process, the execution of that process (or the program, if it is the outermost process) ends (see section 11.1) and execution is (possibly) resumed with another process;
- · otherwise control will be given to the subsequent statement.

static properties: Any reach is directly enclosed in zero or more groups as follows:

- If the reach is the reach of a do action, begin-end block, procedure definition, process definition, then it is directly enclosed in the group in whose reach the do action, begin-end block, procedure definition or process definition, respectively, is placed, and only in that group.
- If the reach is the action statement list of a timing action or timing handler, or one of the action statement lists of an if action, case action or delay case action, then it is directly enclosed in the group in whose reach the timing action, timing handler, if action, case action or delay case action is placed, and only in that group.
- If the reach is the action statement list, or a buffer receive alternative, or signal receive alternative, or the action statement list following ELSE in a receive buffer case action or receive signal case action, then it is directly enclosed in the group in whose reach the receive buffer case action or receive signal case action is placed, and only in that group.
- If the reach is the action statement list in an on-alternative or the action statement list following ELSE in a handler which is not appended to a group, then it is directly enclosed in the group in whose reach the statement to which the handler is appended is placed, and only in that group.
- If the reach is an on-alternative or action statement list after ELSE of a handler which is appended to a group, then it is directly enclosed in the group to which the handler is appended, and only in that group.
- If the reach is a module, region, spec module or spec region, then it is directly enclosed in the group in whose reach it is placed, and also directly enclosed in the context directly in front of the module, region, spec module or spec region, if any. This is the only case where a reach has more than one directly enclosing group.
- If the reach is a context, then it is directly enclosed in the context directly in front of it. If there is no such context, it has no directly enclosing group.

A reach has directly enclosing reaches that are the reaches of the directly enclosing groups. A statement has a unique directly enclosing group, namely, the group in which the statement is placed. A reach is said to directly enclose a group (reach) if and only if the reach is a directly enclosing reach of the group (reach).

A statement (reach) is said to be surrounded by a group if and only if either the group is the directly enclosing group of the statement (reach) or a directly enclosing reach is surrounded by the group.

A reach is said to be entered when:

- Module reach: the module is executed as an action (e.g. the module is not said to be entered
 when a goto action transfers control to a label name defined inside the module).
- Begin-end reach: the begin-end block is executed as an action.
- Region reach: the region is encountered (e.g. the region is not said to be entered when one of its critical procedures is called).
- Procedure reach: the procedure is entered via a procedure call.
- Process reach: the process is activated via the evaluation of a start expression.
- Do reach: the do action is executed as an action after the evaluation of the expressions or locations in the control part.
- Buffer-receive alternative reach, signal receive alternative reach: the alternative is executed on reception of a buffer value or signal.
- On-alternative reach: the on-alternative is executed on the cause of an exception.
- Other block reaches: the action statement list is entered.

An action statement list is said to be entered when and only when its first action, if present, receives control from outside the action statement list.

A reach is a quasi reach if it is the one of a spec module, spec region or context, otherwise it is a real reach.

A defining occurrence is a quasi defining occurrence if:

- it is surrounded by a context and not by a module or region, or
- it is surrounded by a simple spec module or a simple spec region, or
- it is not surrounded by one of the above mentioned groups and it is surrounded by a module spec or a region spec and it is contained in a quasi declaration, a quasi procedure definition statement or a quasi process definition statement, and it is not the defining occurrence of a set element name,

otherwise it is a real defining occurrence.

10.3 BEGIN-END BLOCKS

syntax:

semantics: A begin-end block is an action, possibly containing local declarations and definitions. It determines both visibility of locally created names and the lifetimes of locally created locations (see sections 10.9 and 12.2).

dynamic conditions: The SPACEFAIL exception occurs if storage requirements cannot be satisfied.

examples: see 15.73 - 15.90

10.4 PROCEDURE DEFINITIONS

syntax:

<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	(1)
<pre><defining occurrence=""> : <pre><pre>cedure definition> [<handler>] [<simple name="" string="">] ;</simple></handler></pre></pre></defining></pre>	(1.1)
<pre><pre><pre><pre><pre>PROC ([<formal list="" parameter="">]) [<result spec="">]</result></formal></pre></pre></pre></pre></pre>	(2)
[EXCEPTIONS (< exception list>)] <pre>procedure attribute list> <pre>cproc body> END</pre></pre>	(2.1)
<formal list="" parameter=""> ::=</formal>	(3) (3.1)
<formal parameter=""> ::=</formal>	(4) (4.1)
<pre><pre><pre><pre><pre><pre><pre> [<generality>] [RECURSIVE]</generality></pre></pre></pre></pre></pre></pre></pre>	(5) (5.1)
<pre><generality> ::= GENERAL SIMPLE INLINE</generality></pre>	(6) (6.1) (6.2) (6.3)

derived syntax: A formal parameter, where defining occurrence list consists of more than one defining occurrence, is derived from several formal parameter occurrences, separated by commas, one for each defining occurrence and each with the same parameter spec. E.g. i, j INT LOC is derived from i INT LOC, j INT LOC.

semantics: A procedure definition statement defines a (possibly) parameterised sequence of actions that may be called from different places in the program. The procedure is terminated and control is returned to the calling point either by executing a return action or by reaching the end of the procedure by terminating a handler appended to the procedure definition (falling through). Different degrees of complexity of procedures may be specified as follows:

- a. simple procedures (SIMPLE) are procedures that cannot be manipulated dynamically. They are not treated as values, i.e. they cannot be stored in a procedure location nor can they be passed as parameters to or returned as result from a procedure call.
- b. general procedures (GENERAL) do not have the restrictions of simple procedures and may be treated as procedure values.
- c. inline procedures (INLINE) have the same restrictions as simple procedures and they cannot be recursive. They have the same semantics as normal procedures, but the compiler will insert the generated object code at the point of invocation rather than generating code for actually calling the procedure.

Only simple and general procedures may be specified to be (mutually) recursive. When no procedure attributes are specified, an implementation default will apply.

A procedure may return a value or it may return a location (indicated by the LOC attribute in the result spec).

The defining occurrence in front of the procedure definition defines the name of the procedure.

parameter passing:

There are basically two parameter passing mechanisms: the "pass by value" (IN, OUT and IN-OUT) and the "pass by location" (LOC).

pass by value

In pass by value parameter passing, a value is passed as a parameter to the procedure and stored in a local location of the specified parameter mode. The effect is as if, at the beginning of the procedure call, the location declaration:

```
DCL <defining occurrence> <mode> := <actual parameter>;
```

were encountered for the defining occurrences of the formal parameter. However the procedure is entered after the actual parameters have been evaluated. Optionally, the keyword IN may be specified to indicate pass by value explicitly.

If the attribute INOUT is specified, the actual parameter value is obtained from a location and just before returning the current value of the formal parameter is restored in the actual location.

The effect of OUT is the same as for INOUT with the exception that the initial value of the actual location is not copied into the formal parameter location upon procedure entry; therefore, the formal parameter has an undefined initial value. The store-back operation need not be performed if the procedure causes an exception at the calling point.

pass by location

In pass by location parameter passing, a (possibly dynamic mode) location is passed as a parameter to the procedure body. Only referable locations can be passed in this way. The effect is as if at the entry point of the procedure the loc-identity declaration statement:

```
DCL <defining occurrence> <mode>
LOC [DYNAMIC] := <actual parameter>;
```

were encountered for the defining occurrences of the formal parameter. However the procedure is entered after the actual parameters have been evaluated.

If a value is specified that is not a location, a location containing the specified value will be implicitly created and passed at the point of the call. The lifetime of the created location is the procedure call. The mode of the created location is dynamic if the value has a dynamic class.

result transmission:

Both a value and a location may be returned from the procedure. In the first case, a value is specified in any result action, in the latter case, a location (see section 6.8). If the attribute NONREF is not given in the result spec, the location must be referable. The returned value or location is determined by the most recently executed result action before returning. If a procedure with a result spec returns without having executed a result action, the procedure returns an undefined value or an undefined location. In this case the procedure call may not be used as a location procedure call (see section 4.2.11) nor as a value procedure call (see section 5.2.12), but only as a call action (section 6.7).

static properties: A defining occurrence in a procedure definition statement defines a procedure name.

A procedure name has a procedure definition attached that is the procedure definition in the statement in which the procedure name is defined.

A procedure name has the following properties attached, as defined by its procedure definition:

- It has a list of parameter specs that are defined by the parameter spec occurrences in the formal parameter list, each parameter consisting of a mode and possibly a parameter attribute.
- It has possibly a result spec, consisting of a mode and an optional result attribute.
- It has a possibly empty list of exception names, which are the names mentioned in exception list.
- It has a generality that is, if generality is specified, either general or simple or inline, depending on whether GENERAL, SIMPLE or INLINE is specified; otherwise an implementation default specifies general or simple. If the procedure name is defined inside a region, its generality is simple.
- It has a recursivity which is recursive if RECURSIVE is specified; otherwise an implementation default specifies either recursive or non-recursive. However, if the generality is inline or if the procedure name is critical (see section 11.2.1) the recursivity is non-recursive.

A procedure name that is general is a general procedure name. A general procedure name has a procedure mode attached, formed as:

```
PROC ([<parameter list>])[<result spec>]
[EXCEPTIONS (<exception list>)][RECURSIVE]
```

where <result spec>, if present, and <exception list> are the same as in its procedure definition and and cparameter list> is the sequence of cparameter spec> occurrences in the formal parameter list, separated by commas.

A name defined in a defining occurrence list in the formal parameter is a location name if and only if the parameter spec in the formal parameter does not contain the LOC attribute. If it does contain the LOC attribute, it is a loc-identity name. Any such a location name or loc-identity name is referable.

static conditions: If a procedure name is intra-regional (see section 11.2.2), its procedure definition must not specify GENERAL.

If a procedure name is critical (see section 11.2.1), its definition may specify neither GENERAL nor RECURSIVE.

No procedure definition may specify both INLINE and RECURSIVE.

If specified, the simple name string must be equal to the name string of the defining occurrence in front of the procedure definition.

Only if LOC is specified in the parameter spec or result spec may the mode in it have the non-value property.

All exception names mentioned in exception list must be different.

examples:

10.5 PROCESS DEFINITIONS

syntax:

PROCESS ([
$$<$$
formal parameter list $>$]) $<$ process body $>$ END (2.1)

semantics: A process definition statement defines a possibly parameterised sequence of actions that may be started for concurrent execution from different places in the program (see chapter 11).

static properties: A defining occurrence in a process definition statement defines a process name.

A process name has the following property attached, as defined by its process definition:

• It has a list of parameter specs that are defined by the parameter spec occurrences in the formal parameter list, each parameter consisting of a mode and possibly a parameter attribute.

static conditions: If specified, the simple name string must be equal to the name string of the defining occurrence in front of the process definition.

A process definition statement must not be surrounded by a region or by a block other than the imaginary outermost process definition (see section 10.8).

The parameter attributes in the formal parameter list must not be INOUT nor OUT.

Only if LOC is specified in the parameter spec in a formal parameter in the formal parameter list may the mode in it have the non-value property.

examples:

```
14.13 PROCESS ();

wait:

PROC (x INT);

/*some wait action*/

END wait;

DO FOR EVER;

wait(10 /* seconds */ );

CONTINUE operator_is_ready;

OD;

END (2.1)
```

10.6 MODULES

syntax:

```
<module> ::=

[ <context list> ] [ <defining occurrence> : ]

MODULE [ BODY ] <module body> END

[ <handler> ] [ <simple name string> ] ; (1.1)
| <remote modulion> (1.2)
```

semantics: A module is an action statement possibly containing local declarations and definitions. A module is a means of restricting the visibility of name strings; it does not influence the lifetime of the locally declared locations.

The detailed visibility rules for modules are given in section 12.2.

static properties: A defining occurrence in a module defines a module name as well as a label name. The name has the module (seen as a modulion, i.e. excluding the context list and defining occurrence, if any) attached.

A module is developed piecewisely if and only if a context list is specified.

A module is a module body if and only if BODY is specified.

static conditions: If specified, the simple name string must be equal to the name string of the defining occurrence.

A remote modulion in a module must refer to a module.

examples:

7.48 MODULE SEIZE convert; DCL n INT INIT := 1979; DCL rn CHARS (20) INIT := (20)''; GRANT n,rn; convert(); ASSERT rn = "MDCCCCLXXVIIII"//(6)''; END (1.1)

10.7 REGIONS

syntax:

semantics: A region is a means of providing mutually exclusive access to its locally declared data objects for the concurrent executions of processes (see chapter 11). It determines visibility of locally created names in the same way as a module.

static properties: A defining occurrence in a region defines a region name. It has the region (seen as a modulion, i.e. excluding the context list and defining occurrence, if any) attached.

A region is developed piecewisely if and only if a context list is specified.

A region is a region body if and only if BODY is specified.

static conditions: If specified, the simple name string must be equal to the name string of the defining occurrence.

A region must not be surrounded by a block other than the imaginary outermost process definition.

A remote modulion in a region must refer to a region.

examples: see 13.1 - 13.28

10.8 PROGRAM

syntax:

$$<$$
program $> ::=$ (1)
 $\{<$ module $> \mid <$ spec module $> \mid <$ region $> \mid <$ spec region $> \}^+$ (1.1)

semantics: Programs consist of a list of modules or regions surrounded by an imaginary outermost process definition.

The definitions of the CHILL pre-defined names (see Appendix C.2) and the implementation defined built-in routines and integer modes are considered, for lifetime purposes, to be defined in the reach of the imaginary outermost process definition. For their visibility see section 12.2.

10.9 STORAGE ALLOCATION AND LIFETIME

The time during which a location or procedure exists within its program is its lifetime.

A location is created by a declaration or by the execution of a GETSTACK or an ALLOCATE built-in routine call.

The lifetime of a location declared in the reach of a block is the time during which control lies in that block or in a procedure whose call originated from that block, unless it is declared with the attribute STATIC. The lifetime of a location declared in the reach of a modulion is the same as if it were declared in the reach of the closest surrounding block of the modulion. The lifetime of a location declared with the attribute STATIC is the same as if it were declared in the reach of the imaginary outermost process definition. This implies that for a location declaration with the attribute STATIC storage allocation is made only once, namely, when starting the imaginary outermost process. If such a declaration appears inside a procedure definition or process definition, only one location will exist for all invocations or activations.

The lifetime of a location created by executing a GETSTACK built-in routine call ends when the directly enclosing block terminates.

The lifetime of a location created by an ALLOCATE built-in routine call is the time starting from the ALLO-CATE call until the time that the location cannot be accessed anymore by any CHILL program. The latter is always the case if a TERMINATE built-in routine is applied to an allocated reference value that references the location.

The lifetime of an access created in a loc-identity declaration is the directly enclosing block of the loc-identity declaration.

The lifetime of a procedure is the directly enclosing block of the procedure definition.

static properties: A location is said to be static if and only if it is a <u>static mode</u> location of one of the following kinds:

- A <u>location</u> name that is declared with the attribute STATIC or whose definition is not surrounded by a block other than the imaginary outermost process definition.
- A string element or string slice where the <u>string</u> location is static and either the left element and right element, or start element and slice size are constant.
- An array element where the array location is static and the expression is constant.
- An array slice where the <u>array</u> location is static and either the lower element and upper element or the first element and slice size are constant.
- A structure field where the structure location is static.
- A location conversion where the location occurring in it is static.

10.10 CONSTRUCTS FOR PIECEWISE PROGRAMMING

Modules and regions are the elementary units (pieces) in which a complete CHILL program that is developed piecewisely can be subdivided. The text of such pieces is indicated by remote constructs (see section 10.10.1). CHILL defines the syntax and semantics of complete programs, in which all occurrences of remote pieces have been virtually replaced by the referred text.

10.10.1 Remote pieces

syntax:

<remote context=""> ::=</remote>	(3)
CONTEXT REMOTE < piece designator > [< context body >] FOR	(3.1)
<pre><context module=""> ::= CONTEXT MODULE REMOTE < piece designator> ;</context></pre>	(4) $ (4.1)$
<pre><piece designator=""> ::=</piece></pre>	(5)
<pre><character literal="" string=""></character></pre>	(5.1)
<pre><text name="" reference=""></text></pre>	(5.2)
<empty></empty>	(5.3)

derived syntax: The notation:

CONTEXT MODULE REMOTE < piece designator>

is derived syntax for:

CONTEXT REMOTE < piece designator > FOR MODULE SEIZE ALL; END;

N.B. This construct is redundant but can be used for consistence checking.

semantics: Remote modulions, remote specs, remote contexts and context modules are means to represent the source text of a program as a set of (interconnected) files.

A piece designator refers in an implementation defined way to a description of a piece of CHILL source text, as follows:

- If the piece designator is empty, the source text is retrieved from a place determined by the structure of the program.
- If the piece designator contains a character string literal, the character string literal is used to retrieve the source text.
- If the piece designator contains a text reference name, the text reference name is interpreted in an implementation defined way to retrieve the source text.

A program with 1. remote modulions, 2. remote specs, is equivalent to the program built by replacing each 1. remote modulions, 2. remote specs, by the piece of CHILL text referred to by its piece designator.

A program with remote contexts is equivalent to the program built by replacing each remote context by the piece of CHILL text referred to by its piece designator in which the context body has been virtually inserted immediately after the last occurrence of context body in the context list referred to by the piece designator.

If the designated piece is not available as CHILL text, then the piece designator in it is considered to refer to an equivalent piece of CHILL text which is introduced virtually.

Although the semantics of a remote piece is defined in terms of replacement, CHILL does not imply any textual substitution.

static conditions: The piece designator in a 1. remote modulion, 2. remote spec, 3. remote context, 4. context module, must refer to a description of a piece of source text which is a terminal production of a 1. module or region that is not a remote modulion, 2. spec module or spec region that is not a remote spec, 3.,4. context list which is not a remote context.

When the source text referred to by the piece designator in a remote modulion starts with a defining occurrence, then the remote modulion must start with a simple name string which is the name string of that defining occurrence.

When the source text referred to by the piece designator in a remote spec starts with a simple name string, then the remote spec must start with the same simple name string.

example		
example	25.9 stack: REMOTE "example 27 or 28";	(1.1)
	25.9 "example 27 or 28"	(5.1)
10.10.2	Spec modules, spec regions and contexts	
syntax:		
_	<spec module=""> ::=</spec>	(1)
	<simple module="" spec=""></simple>	(1.1)
	<module spec=""></module>	(1.2)
	<pre><remote spec=""></remote></pre>	(1.3)
	<simple module="" spec=""> ::=</simple>	(2)
	[<context list="">] [<simple name="" string=""> :] SPEC MODULE</simple></context>	(2)
	<pre><spec body="" module=""> END [<simple name="" string="">];</simple></spec></pre>	(2.1)
	<module spec=""> ::=</module>	(3)
	[<context list="">] <simple name="" string=""> : MODULE SPEC</simple></context>	(0)
	<pre><spec body="" module=""> END [<simple name="" string="">];</simple></spec></pre>	(3.1)
	<pre><spec region=""> ::=</spec></pre>	(4)
	<simple region="" spec=""></simple>	(4.1)
	<pre><region spec=""></region></pre>	(4.2)
	<pre><remote spec=""></remote></pre>	(4.3)
	<simple region="" spec=""> ::=</simple>	(5)
	[<context list="">] [<simple name="" string=""> :] SPEC REGION</simple></context>	(*)
	<pre><spec body="" region=""> END [<simple name="" string="">];</simple></spec></pre>	(5.1)
	<region spec=""> ::=</region>	(6)
	[<context list="">] <simple name="" string=""> : REGION SPEC</simple></context>	(*)
	<pre><spec body="" region=""> END [<simple name="" string="">];</simple></spec></pre>	(6.1)

semantics: Simple spec modules, simple spec regions and contexts are used to specify static properties of names. They are redundant but they can be used for piecewise programming.

Simple name strings in spec modules and spec regions are not names, they are not bound, and they have no visibility rules.

(7)

(7.1)

(7.2)

(8)

(8.1)

1. spec modules, 2. spec regions in a real reach indicate the properties of one or more 1. modules, 2. regions that are piecewisely compiled and that are considered to be enclosed in that reach. The texts of such 1. modules, 2. regions are indicated by occurrences of remote modulions. A context list indicates the surrounding reaches (note that a modulion that is developed piecewisely always has a context list in front of it).

For each name string OP! NS visible in the reach of a 1. module spec, 2. region spec and linked there to a quasi defining occurrence and that is granted into a real reach as NP! NS, a (virtual) grant statement with the same old name string OP! NS and new name string NP! NS is considered to be introduced in the reach of the corresponding 1. module body, 2. region body.

<context list> ::=

<context> ::=

<context> { <context> }*

CONTEXT < context body > FOR

<remote context>

static conditions: In a spec module or a spec region, the optional simple name string following END may only be present if the optional simple name string before SPEC is present. When both are present, they must have equal name strings.

A context which has no directly enclosing group may not contain visibility statements.

A real reach that contains a 1. spec module, 2. spec region must also contain at least a remote modulion and vice-versa.

If a real reach contains a 1. module which is a module body, 2. region which is a region body, then it must contain also a 1. module spec, 2. region spec such that the simple name strings in front of them have equal name strings. The 1. module spec, 2. region spec is said to have a corresponding 1. module body, 2. region body.

A remote spec in a 1. spec module, 2. spec region must refer to a 1. spec module, 2. spec region.

examples:

example:	s:		•
	23.2	<pre>letter_count: SPEC MODULE SEIZE max; count: PROC (input ROW CHARS (max) IN, output ARRAY ('A':'Z') INT OUT) END; GRANT count; END letter_count;</pre>	(1.1)
	24.1	CONTEXT count: PROC (ROW CHARS (max) IN, ARRAY ('A':'Z') INT OUT) END; FOR	(8.1)
10.10.3	Quasi	statements	
syntax:	<qua:< td=""><td>si data statement> ::= <quasi declaration="" statement=""> <quasi definition="" statement=""></quasi></quasi></td><td>(1) (1.1) (1.2)</td></qua:<>	si data statement> ::= <quasi declaration="" statement=""> <quasi definition="" statement=""></quasi></quasi>	(1) (1.1) (1.2)
	<qua< td=""><td>si declaration statement> ::= DCL <quasi declaration=""> { , <quasi declaration=""> }*;</quasi></quasi></td><td>(2) (2.1)</td></qua<>	si declaration statement> ::= DCL <quasi declaration=""> { , <quasi declaration=""> }*;</quasi></quasi>	(2) (2.1)
	<qua< td=""><td>si declaration> ::= <quasi declaration="" location=""> <quasi declaration="" loc-identity=""></quasi></quasi></td><td>(3) (3.1) (3.2)</td></qua<>	si declaration> ::= <quasi declaration="" location=""> <quasi declaration="" loc-identity=""></quasi></quasi>	(3) (3.1) (3.2)
	<qua	si location declaration> ::=	(4) (4.1)
	<qua< td=""><td>si loc-identity declaration> ::=</td><td>(5) (5.1)</td></qua<>	si loc-identity declaration> ::=	(5) (5.1)
	<qua< td=""><td>asi definition statement> ::= <synmode definition="" statement=""> <newmode definition="" statement=""> <synonym definition="" statement=""> <quasi definition="" statement="" synonym=""> <quasi definition="" procedure="" statement=""> <quasi definition="" process="" statement=""> <quasi definition="" process="" statement=""> <quasi definition="" signal="" statement=""></quasi></quasi></quasi></quasi></quasi></quasi></quasi></quasi></quasi></synonym></newmode></synmode></td><td>(6) (6.1) (6.2) (6.3) (6.4) (6.5) (6.6) (6.7) (6.8)</td></qua<>	asi definition statement> ::= <synmode definition="" statement=""> <newmode definition="" statement=""> <synonym definition="" statement=""> <quasi definition="" statement="" synonym=""> <quasi definition="" procedure="" statement=""> <quasi definition="" process="" statement=""> <quasi definition="" process="" statement=""> <quasi definition="" signal="" statement=""></quasi></quasi></quasi></quasi></quasi></quasi></quasi></quasi></quasi></synonym></newmode></synmode>	(6) (6.1) (6.2) (6.3) (6.4) (6.5) (6.6) (6.7) (6.8)

```
<quasi synonym definition statement> ::=
                                                                                             (7)
         SYN <quasi synonym definition> { , <quasi synonym definition> }*;
                                                                                           (7.1)
<quasi synonym definition> ::=
                                                                                             (8)
         <defining occurrence list> { <mode> = [ <constant value> ] |
         [< mode>] = < \underline{literal} | expression> 
                                                                                           (8.1)
<quasi procedure definition statement> ::=
                                                                                             (9)
         < defining occurrence> : PROC ([ < quasi formal parameter list> ] )
         [ <result spec> ] [ EXCEPTIONS ( <exception list> ) ]
         cedure attribute list> END [ <simple name string> ];
                                                                                           (9.1)
<quasi formal parameter list> ::=
                                                                                           (10)
         <quasi formal parameter> { , <quasi formal parameter> }*
                                                                                          (10.1)
<quasi formal parameter> ::=
                                                                                           (11)
         <simple name string> \{ , <simple name string> \}^* <parameter spec>
                                                                                          (11.1)
<quasi process definition statement> ::=
                                                                                           (12)
        <defining occurrence>: PROCESS ( [ <quasi formal parameter list> ] )
         END [ < simple name string > ];
                                                                                         (12.1)
<quasi signal definition statement> ::=
                                                                                           (13)
        SIGNAL <quasi signal definition> { ,<quasi signal definition> }*;
                                                                                         (13.1)
<quasi signal definition> ::=
                                                                                           (14)
        <defining occurrence> [ = (<mode> { , <mode> }* ) ] [ TO ]
                                                                                         (14.1)
```

semantics: Quasi statements are used in spec modules, spec regions and contexts to specify static properties of names. These specifications are redundant, but quasi statements can be used for piecewise programming.

An implementation that can not guarantee the equality of the values between quasi constant synonym names and the corresponding real ones may disallow the indication of the <u>constant</u> value.

Note that in CHILL no quasi defining occurrences exist for label names.

static properties: Quasi statements are restricted forms of the corresponding statements, and have the same static properties.

The name defined by a defining occurrence in a quasi loc-identity declaration is referable if NON-REF is not specified.

static conditions: Quasi statements are restricted forms of the corresponding statements and are subject to their static conditions.

A quasi synonym definition statement may only be directly enclosed in a simple spec module, simple spec region or context. A synonym definition statement in a quasi definition statement may only be directly enclosed in a module spec or region spec.

10.10.4 Matching between quasi defining occurrences and defining occurrences

Two defining occurrences are said to match if they have identical semantic categories and:

- If they are synonym names, then they must have the same regionality and value, the root mode of their classes must be alike, they must both have an M-value, M-derived, M-reference, null or all class, and if the one which is quasi is literal, then so the other one must be.
- If they are set element names, then the attached set modes must be alike.
- If they are newmode names or synmode names, then their modes must be alike.
- If they are location names or loc-identity names, then they must have the same regionality, they
 both must be or both not be referable, they both must be or both not be static, and their modes must
 be alike.

- If they are procedure names, then they must have the same regionality and generality, they both must be or both not be critical, they must satisfy the same conditions of alikeness as procedure modes, and corresponding (by position) simple name strings in the formal parameter list and quasi formal parameter list must be the same.
- If they are process names, then the parameters of their process definitions must satisfy the same conditions of matching and alikeness as the parameters of procedure names.
- If they are signal names, then they must both specify or both not specify TO, their lists of modes must have the same number of modes, and corresponding modes must be alike.

If two structure modes are novelty bound in a reach R, then they must have the same set of visible field names in R.

The following rules apply:

- If a name string in a reach that is not the reach of a spec module, spec region or context is bound to a quasi defining occurrence, then it must also be bound to a defining occurrence which is not a quasi defining occurrence, and further:
 - Let a name string be bound to a quasi defining occurrence QD and be bound also to a real defining occurrence RD in reach R, then:
 - 1. QD and RD must match as defined above, and
 - 2. RD and QD must both be enclosed in an enclosed group of R or both not be enclosed in the group of R or, if R is the reach of a module or region which is a module body or region body, then QD must be enclosed in the group of the corresponding module spec or region spec and RD must be enclosed in the group of R.
 - If a name string in a real reach R is bound to a quasi defining occurrence that is enclosed in the group of R (i.e. surrounded by a spec modulion), then it must also be bound to a real defining occurrence that is surrounded by the group of a module or region that are indicated by a remote modulion directly enclosed in R (informally, if the interface grants, so must the implementation). If the quasi defining occurrence is enclosed in the group of a module spec or a region spec, then the real one must be enclosed in the group of the corresponding modulion.
 - If a name string in a real reach R is bound to a real defining occurrence that is enclosed in the group of a module or region that are indicated by a remote modulion directly enclosed in R, then it must also be bound to a quasi defining occurrence that is enclosed into the group of R (i.e. surrounded by a spec modulion. Informally, if the implementation grants, so must the interface).
 - For each name string in the reach Q of a spec module or spec region directly enclosed in a real reach R that is bound to a defining occurrence not surrounded by Q, there must be an identical name string in the reach of a module or region that is indicated by a remote modulion directly enclosed in R that is bound to the same defining occurrence (informally, if the interface seizes, so must the implementation).
- If two name strings are bound to the same 1. real, 2. quasi defining occurrence in a reach, then both name strings must be bound to the same 1. quasi, 2. real defining occurrence, or both not be further bound.
- A real novelty may not be novelty bound to two quasi novelties in any reach.
 - Let a quasi novelty QN and a real novelty RN be novelty bound to each other in a reach R; then RN and QN must both be enclosed in an enclosed group of R or both not be enclosed in the group of R, or if R is the reach of a module or region which is a module body or region body, then RN must be enclosed in the group of R and QN must be enclosed in the group of the corresponding module spec or region spec.

11 CONCURRENT EXECUTION

11.1 PROCESSES AND THEIR DEFINITIONS

A process is the sequential execution of a series of statements. It may be executed concurrently with other processes. The behaviour of a process is described by a process definition (see section 10.5), that describes the objects local to a process and the series of action statements to be executed sequentially.

A process is created by the evaluation of a start expression (see section 5.2.14). It becomes active (i.e. under execution) and is considered to be executed concurrently with other processes. The created process is an activation of the definition indicated by the process name of the process definition. An unspecified number of processes with the same definition may be created and may be executed concurrently. Each process is uniquely identified by an instance value, yielded as the result of the start expression or the evaluation of the **THIS** operator. The creation of a process causes the creation of its locally declared locations, except those declared with the attribute **STATIC** (see section 10.9), and of locally defined values and procedures. The locally declared locations, values and procedures are said to have the same activation as the created process to which they belong. The imaginary outermost process (see section 10.8), which is the whole CHILL program under execution, is considered to be created by a start expression executed by the system under whose control the program is executing. At the creation of a process, its formal parameters, if present, denote the values and locations as delivered by the corresponding actual parameters in the start expression.

A process is terminated by the execution of a stop action, by reaching the end of the process body or by terminating a handler specified at the end of the process definition (falling through). If the imaginary outermost process executes a stop action or falls through, the termination will be completed when and only when all other processes in the program are terminated.

A process is, at the CHILL programming level, always in one of two states: it is either active (i.e. under execution) or delayed (i.e. waiting for a condition to be fulfilled). The transition from active to delayed is called the delaying of the process; the transition from delayed to active is called the re-activation of the process.

11.2 MUTUAL EXCLUSION AND REGIONS

11.2.1 General

Regions (see section 10.7) are a means of providing processes with mutually exclusive access to locations declared in them. Static context conditions (see section 11.2.2) are made such that accesses by a process (which is not the imaginary outermost process) to locations declared in a region can be made only by calling procedures that are defined inside the region and granted by the region.

A procedure name is said to denote a critical procedure (and it is a critical procedure name) if it is defined inside a region and granted by the region.

A region is said to be free if and only if control lies in none of its critical procedures or in the region itself performing reach-bound initialisations.

The region will be locked (to prevent concurrent execution) if:

- The region is entered (note that because regions are not surrounded by a block, no concurrent attempts can be made to enter the region).
- A critical procedure of the region is called.
- A process, delayed in the region, is re-activated.

The region will be released, becoming free again, if:

- The region is left.
- The critical procedure returns.
- The critical procedure executes an action that causes the executing process to become delayed (see section 11.3). In the case of dynamically nested critical procedure calls, only the latest locked region will be released.
- The process executing the critical procedure terminates. In the case of dynamically nested critical procedure calls, all the regions locked by the process will be released.

If, while the region is locked, a process attempts to call one of its critical procedures or a process delayed in the region is re-activated, the process is suspended until the region is released. (Note that the process remains active in the CHILL sense).

When a region is released and more than one process has been suspended while attempting to call one of its critical procedures or to be re-activated in one of its critical procedures, only one process will be selected to lock the region according to an implementation defined scheduling algorithm.

11.2.2 Regionality

To allow for checking statically that a location declared in a region can only be accessed by calling critical procedures or by entering the region for performing reach-bound initialisations, the following static context conditions are enforced:

- the regionality requirements mentioned in the appropriate sections (assignment action, procedure call, send action, result action, etc.);
- intra-regional procedures are not general (see section 10.4);
- critical procedures are neither general nor recursive (see section 10.4).

A location and procedure call have a regionality which is intra-regional or extra-regional. A value has a regionality which is intra-regional or extra-regional or nil. These properties are defined as follows:

1. Location

A location is intra-regional if and only if any of the following conditions are fulfilled:

- It is an access name that is either:
 - a <u>location</u> name declared textually inside a region or spec region and not defined in a formal parameter of a critical procedure,
 - a <u>loc-identity</u> name, where the location in its declaration is intra-regional or that is defined in a formal parameter of an intra-regional procedure,
 - a <u>location enumeration</u> name, where the <u>array</u> location or <u>string</u> location in the associated do action is intra-regional,
 - a <u>location do-with</u> name, where the <u>structure</u> location in the associated do action is intraregional.
- It is a dereferenced bound reference, where the <u>bound reference</u> primitive value in it is intraregional.
- It is a dereferenced free reference, where the <u>free reference</u> primitive value in it is intra-regional.
- It is a dereferenced row, where the <u>row</u> primitive value in it is intra-regional.
- It is an array element or array slice, where the array location in it is intra-regional.
- It is a string element or string slice, where the string location in it is intra-regional.
- It is a structure field, where the structure location in it is intra-regional.
- It is a location procedure call, where in the <u>location</u> procedure call a <u>procedure</u> name is specified which is intra-regional.
- It is a <u>location</u> built-in routine call, that the CHILL definition or the implementation specifies to be intra-regional.
- It is a location conversion, where the <u>static mode</u> location in it is intra-regional.

A location which is not intra-regional is extra-regional.

2. Value

A value has a regionality depending on its class. If it has the M-derived class or the all class or the null class then it has regionality nil. Otherwise it has the M-value class or the M reference class and it has a regionality depending on the mode M as follows:

If the value has the M-value class and M does not have the referencing property then the regionality is nil; otherwise the value is an operand-6 (and has the referencing property) or a conditional expression:

If it is a primitive value then:

- If it is a location contents that is a location, then it is that of the location.
- If it is a value name, then:
 - if it is a synonym name then it is that of the constant value in its definition;
 - if it is a <u>value do-with</u> name then it is that of the <u>structure</u> primitive value in the associated do action:
 - if it is a value receive name then it is extra-regional.
- If it is a tuple then if one of the value occurrences in it has regionality not nil, then it is that of that value (it does not matter which choice is made, see section 5.2.5 static conditions); otherwise it is nil.
- If it is a value array element or a value array slice then it is that of the array primitive value in it.
- If it is a value structure field then it is that of the structure primitive value in it.
- If it is an expression conversion then it is that of the expression in it.
- If it is a value procedure call then it is that of the procedure call in it.
- If it is a <u>value</u> built-in routine call that the CHILL definition or the implementation specifies to be intra-regional or extra-regional.

If it is a referenced location then it is that of the location in it.

If it is a receive expression then it is extra-regional.

If it is a conditional expression, then if one of the sub expression occurrences in it has regionality not nil, then it is that of that sub expression (it does not matter which choice is made, see section 5.3.2 static conditions); otherwise it is nil.

3. Procedure name

A <u>procedure</u> name is intra-regional if and only if it is defined inside a region or spec region and it is not critical (i.e. not granted by the region). Otherwise it is extra-regional.

4. Procedure call

A procedure call is intra-regional if it contains a <u>procedure</u> name which is intra-regional; otherwise it is extra-regional.

A value is regionally safe for a non-terminal (used only for location, procedure call and procedure name) if and only if:

- the non-terminal is extra-regional and the value is not intra-regional;
- the non-terminal is intra-regional and the value is not extra-regional;
- the non-terminal has regionality nil.

11.3 DELAYING OF A PROCESS

An active process may become delayed by executing (evaluating) one of the following actions (expressions):

- delay action (see section 6.16),
- delay case action (see section 6.17),
- receive expression (see section 5.3.9),
- receive signal case action (see section 6.19.2),
- receive buffer case action (see section 6.19.3),
- send buffer action (see section 6.18.3).

When a process becomes delayed while its control lies within a critical procedure, the associated region will be released. The dynamic context of the process is retained until it is re-activated. The process then attempts to lock the region again, which may cause it to be suspended.

11.4 RE-ACTIVATION OF A PROCESS

A delayed process may become re-activated if it is time supervised and a time interrupt occurs (see chapter 9). It may also become re-activated if another process executes (evaluates) one of the following actions (expressions):

- continue action (see section 6.15),
- send signal action (see section 6.18.2),
- send buffer action (see section 6.18.3),
- receive expression (see section 5.3.9),
- receive buffer case action (see section 6.19.3).

When a process, while having locked a region, re-activates another process, it remains active, i.e. it will not release the region at that point.

11.5 SIGNAL DEFINITION STATEMENTS

syntax:

semantics: A signal definition defines a composing and decomposing function for values to be transmitted between processes. If a signal is sent, the specified list of values is transmitted. If no process is waiting for the signal in a receive case action, the values are kept until a process receives the values.

static properties: A defining occurrence in a signal definition defines a signal name.

A signal name has the following properties:

- It has an optional list of modes attached, that are the modes mentioned in the signal definition.
- It has an optional process name attached that is the process name specified after TO.

static conditions: No mode in a signal definition may have the non-value property.

examples:

12 GENERAL SEMANTIC PROPERTIES

12.1 MODE RULES

12.1.1 Properties of modes and classes

12.1.1.1 Read-only property

Informal

A mode has the read-only property if it is a read-only mode or contains a component or a sub-component, etc. which is a read-only mode.

Definition

A mode has the read-only property if and only if it is:

- an array mode with an element mode that has the read-only property;
- a structure mode where at least one of its field modes has the read-only property, where the field is not a tag field with an implicit read-only mode of a parameterised structure mode;
- a read-only mode.

12.1.1.2 Parameterisable modes

Informal

A mode is parameterisable if it can be parameterised.

Definition

A mode is parameterisable if and only if it is

- a string mode;
- an array mode;
- a parameterisable variant structure mode.

12.1.1.3 Referencing property

Informal

A mode has the referencing property if it is a reference mode or contains a component or a sub-component, etc. which is a reference mode.

Definition

A mode has the referencing property if and only if it is:

- a reference mode;
- an array mode with an element mode that has the referencing property;
- a structure mode where at least one of its field modes has the referencing property.

12.1.1.4 Tagged parameterised property

Informal

A mode has the tagged parameterised property if it is a tagged parameterised structure mode or contains a component or a sub-component etc. which is a tagged parameterised structure mode.

Definition

A mode has the tagged parameterised property if and only if it is:

- an array mode with an element mode which has the tagged parameterised property;
- a structure mode where at least one of its field modes has the tagged parameterised property;
- a tagged parameterised structure mode.

12.1.1.5 Non-value property

Informal

A mode has the non-value property if no expression or primitive value denotation exists for the mode.

Definition

A mode has the non-value property if and only if it is:

- an event mode, a buffer mode, an access mode, an association mode or a text mode;
- an array mode with an element mode that has the non-value property;
- a structure mode where at least one of its field modes has the non-value property.

12.1.1.6 Root mode

Any mode M has a root mode defined as:

- M, if M is not a range mode;
- the parent mode of M, if M is a range mode.

Any M-value class or M-derived class has a root mode which is the root mode of M.

12.1.1.7 Resulting class

Given two compatible classes (see section 12.1.2.16), which are either the all class, an M-value class or an M-derived class, where M is either a discrete mode, a powerset mode or a string mode, the resulting class is defined in terms of the notion of resulting mode R of M and N and the root mode P of M.

Given two similar modes M and N, the resulting mode R is defined as:

- if the root mode of one is a fixed string mode and the other one is a varying string mode, then it is the root mode of the one (between M and N) whose root mode is a varying string mode;
- otherwise it is P.

The resulting class is defined as:

- the resulting class of the M-value class and the N-value class is the R-value class;
- the resulting class of the M-value class and the N-derived class or the all class is the P-value class;
- the resulting class of the M-derived class and the N-derived class;
- the resulting class of the M-derived class and the all class is the P-derived class;
- the resulting class of the all class and the all class is the all class.

Given a list C_i of pairwise compatible classes (i=1,...,n), the resulting class of the list of classes is recursively defined as the resulting class of the resulting class of the list C_i (i=1,...,n-1) and the class C_n if n > 1; otherwise as the resulting class of C_1 and C_1 .

12.1.2 Relations on modes and classes

12.1.2.1 General

In the following sections, the compatibility relations are defined between modes, between classes, and between modes and classes. These relations are used throughout the document to define static conditions.

The compatibility relations themselves are defined in terms of other relations which are mainly used in this chapter for the above mentioned purpose.

12.1.2.2 Equivalence relations on modes

Informal

The following equivalence relations play a role in the formulation of the compatibility relations:

- Two modes are similar if they are of the same kind; i.e. they have the same hereditary properties.
- Two modes are v-equivalent (value-equivalent) if they are similar and also have the same novelty.
- Two modes are equivalent if they are v-equivalent and also possible differences in value representation in storage or minimum storage size are taken into account.
- Two modes are l-equivalent (location-equivalent) if they are equivalent and also have the same readonly specification.
- Two modes are alike if they are indistinguishable; i.e. if all operations that can be applied to objects
 of one of the modes can be applied to the other one as well, provided that novelty is not taken into
 account.
- Two modes are novelty bound if they are alike and have equal novelty specification.

Definition

In the following sections, the equivalence relations on modes are given in the form of a (partial) set of relations. The full equivalence algorithms are obtained by taking the symmetric, reflexive and transitive closure of this set of relations. The modes mentioned in the relations may be virtually introduced or dynamic. In the latter case, the complete equivalence check can only be performed at run time. Check failure of the dynamic part will result in the RANGEFAIL or TAGFAIL exception (see appropriate sections).

Checking two recursive modes for any equivalence requires the checking of associated modes in the corresponding paths of the set of recursive modes by which they are defined. Equivalence between the modes holds if no contradiction is found. (As a consequence, a path of the checking algorithm stops successfully if two modes which have been compared before, are compared).

12.1.2.3 The relation similar

Two modes are similar if and only if:

- they are integer modes;
- they are boolean modes;
- they are character modes;
- they are set modes such that:
 - 1. they define the same number of values;
 - 2. for each set element name defined by one mode there is a set element name defined by the other mode which has the same name string and the same representation value;
 - 3. they both are numbered set modes or both are unnumbered set modes.
- they are range modes with similar parent modes;
- one is a range mode whose parent mode is similar to the other mode;
- they are powerset modes such that their member modes are equivalent;
- they are bound reference modes such that their referenced modes are equivalent;

- they are free reference modes:
- · they are row modes such that their referenced origin modes are equivalent;
- they are procedure modes such that:
 - 1. they have the same number of parameter specs and corresponding (by position) parameter specs have l-equivalent modes and the same parameter attributes, if present;
 - they both have or both do not have a result spec. If present, the result specs must have l-equivalent modes and the same attributes, if present;
 - 3. they have the same list of exception names;
 - 4. they have the same recursivity;
- they are instance modes;
- they are event modes such that they both have no event length or both have the same event length;
- they are buffer modes such that:
 - 1. they both have no buffer length or both have the same buffer length;
 - 2. they have l-equivalent buffer element modes;
- · they are association modes;
- they are access modes such that:
 - 1. they both have no index mode or both have index modes which are equivalent;
 - 2. at least one has no record mode, or both have record modes that are l-equivalent and that are both static record modes or both dynamic record modes;
- they are text modes such that:
 - 1. they have the same text length;
 - 2. they have I-equivalent text record modes;
 - 3. they have l-equivalent access modes;
- they are duration modes;
- they are absolute time modes;
- they are string modes such that they are both bit string modes or both are character string modes;
- they are array modes such that:
 - 1. their index modes are v-equivalent;
 - 2. their element modes are equivalent;
 - 3. their element layouts are equivalent;
 - 4. they have the same number of elements. This check is dynamic if one or both modes is (are) dynamic. Check failure will result in the RANGEFAIL exception;
- they are structure modes which are not parameterised structure modes such that:
 - 1. in the strict syntax, they have the same number of fields and corresponding (by position) fields are equivalent;
 - 2. if they are both parameterisable variant structure modes, their lists of classes must be compatible;
- they are parameterised structure modes such that:
 - 1. their origin variant structure modes are similar;
 - 2. their corresponding (by position) values are the same. This check is dynamic if one or both modes is (are) dynamic. Check failure will result in the TAGFAIL exception.

12.1.2.4 The relation v-equivalent

Two modes are v-equivalent if and only if they are similar and have the same novelty.

12.1.2.5 The relation equivalent

Two modes are equivalent if and only if they are v-equivalent and:

• if one is a range mode, the other must also be a range mode and both upper bounds must be equal and both lower bounds must be equal;

- if one is a fixed string mode, the other one must also be a fixed string mode, and they must have the same string length. This check is dynamic in the case that one or both modes is (are) dynamic. Check failure will result in the RANGEFAIL exception;
- if one is a varying string mode, the other one must also be a varying string mode, and they must have the same string length. This check is dynamic in the case that one or both modes is (are) dynamic. Check failure will result in the RANGEFAIL exception.

12.1.2.6 The relation l-equivalent

Two modes are l-equivalent if and only if they are equivalent and if one is a read-only mode, the other must also be a read-only mode, and:

- if they are bound reference modes, their referenced modes must be l-equivalent;
- if they are row modes, their referenced origin modes must be l-equivalent;
- if they are array modes, their element modes must be l-equivalent;
- if they are structure modes which are not parameterised structure modes, corresponding (by position) fields in the strict syntax must be l-equivalent; if they are parameterised structure modes, their origin variant structure modes must be l-equivalent.

12.1.2.7 The relations equivalent and l-equivalent for fields

Two fields (both fields in the context of two given structure modes) are 1. equivalent, 2. l-equivalent if and only if both fields are fixed fields which are 1. equivalent, 2. l-equivalent or both are alternative fields which are 1. equivalent, 2. l-equivalent.

The relations equivalent and l-equivalent are recursively defined for corresponding fixed fields, variant fields, alternative fields and variant alternatives, respectively, in the following way:

- Fixed fields and variant fields
 - 1. Both fixed fields or variant fields must have equivalent field layout.
 - 2. Both field modes must be 1. equivalent, 2. l-equivalent.
- · Alternative fields
 - 1. Both alternative fields have tag lists or both have no tag lists. In the former case, the tag lists must have the same number of tag field names and corresponding (by position) tag field names must denote corresponding fixed fields.
 - 2. Both must have the same number of variant alternatives and corresponding (by position) variant alternatives must be 1. equivalent, 2. l-equivalent.
 - 3. Both must have no **ELSE** specified or both must have **ELSE** specified. In the latter case, the same number of variant fields must follow and corresponding (by position) variant fields must be 1. equivalent, 2. l-equivalent.
- Variant alternatives
 - 1. Both variant alternatives must have the same number of case label lists and corresponding (by position) case label lists must either be both irrelevant, or both define the same set of values.
 - 2. Both variant alternatives must have the same number of variant fields and corresponding (by position) variant fields must be 1. equivalent, 2. l-equivalent.

12.1.2.8 The relation equivalent for layout

In the rest of the section, it will be assumed that each pos is of the form:

and that each step is of the form:

Section 3.12.5 gives the appropriate rules to bring pos or step in the required form.

· Field layout

Two field layouts are equivalent if they are both NOPACK, or both PACK, or both pos. In the latter case the one pos must be equivalent to the other one (see below).

Element layout

Two element layouts are equivalent if they are both NOPACK, both PACK, or both step. In the latter case the pos in the one step must be equivalent to the pos in the other one (see below) and step size must deliver the same values for the two element layouts.

Pos

A pos is equivalent to another pos if and only if both word occurrences deliver the same value, both start bit occurrences deliver the same value and both length occurrences deliver the same value.

12.1.2.9 The relation alike

Two modes are alike if and only if they both are or both are not read-only modes and they both have novelty nil or both have the same novelty and:

- they are integer modes;
- they are boolean modes;
- they are character modes;
- they are similar set modes;
- they are range modes with equal upper bounds and equal lower bounds;
- they are powerset modes such that their member modes are alike;
- they are bound reference modes such that their referenced modes are alike;
- they are free reference modes:
- they are row modes such that their referenced origin modes are alike;
- they are procedure modes such that:
 - 1. they have the same number of parameter specs and corresponding (by position) parameter specs have alike modes and the same parameter attributes, if present:
 - they both have or both do not have a result spec. If present, the result specs must have alike modes and the same attributes, if present;
 - 3. they have the same list of exception names;
 - 4. they have the same recursivity;
- they are instance modes;
- they are event modes such that they both have no event length or both have the same event length;
- they are buffer modes such that:
 - 1. they both have no buffer length or both have the same buffer length;
 - 2. they have buffer element modes which are alike;
- they are association modes;
- they are access modes such that:
 - 1. they both have no index mode or both have index modes that are alike;
 - at least one has no record mode or both have record modes that are alike and that are both static record modes or both dynamic record modes;
- they are text modes such that:
 - 1. they have the same text length;
 - 2. their text record modes are alike;
 - 3. their access modes are alike;
- they are duration modes:
- they are absolute time modes;

- they are string modes such that:
 - 1. they both are bit string modes or both are character string modes;
 - 2. they have the same string length;
 - 3. they both are fixed string modes or both are varying string modes;
- they are array modes such that:
 - 1. their index modes are alike;
 - 2. their element modes are alike;
 - 3. their element layouts are equivalent;
 - 4. they have the same number of elements;
- they are structure modes that are not parameterised structure modes such that:
 - 1. in the strict syntax they have the same number of fields and corresponding (by position) fields are alike;
 - 2. if they are both parameterisable variant structure modes, their lists of classes must be compatible;
- they are parameterised structure modes such that:
 - 1. their origin variant structure modes are alike;
 - 2. their corresponding (by position) values are the same.

12.1.2.10 The relation alike for fields

Two fields (both fields in the context of two given structure modes) are alike if and only if both fields are fixed fields which are alike or both are alternative fields which are alike.

The relation alike is recursively defined for corresponding fixed fields, variant fields, alternative fields and variant alternatives, respectively, in the following way:

- · Fixed fields and variant fields
 - 1. Both fixed fields or variant fields must have equivalent field layout.
 - 2. Both field modes must be alike.
 - 3. Both fixed fields or variant fields must have the same name string attached.
- · Alternative fields
 - 1. Both alternative fields have tag lists or both have no tag lists. In the former case, the tag lists must have the same number of tag field names and corresponding (by position) tag field names must denote corresponding fixed fields.
 - 2. Both must have the same number of variant alternatives and corresponding (by position) variant alternatives must be alike.
 - 3. Both must have no ELSE specified or both must have ELSE specified. In the latter case, the same number of variant fields must follow and corresponding (by position) variant fields must be alike.
- Variant alternatives
 - 1. Both variant alternatives must have the same number of case label lists and corresponding (by position) case label lists must either be both irrelevant, or both define the same set of values.
 - 2. Both variant alternatives must have the same number of variant fields and corresponding (by position) variant fields must be alike.

12.1.2.11 The relation novelty bound

Informal

In a program, each quasi newmode must represent at most one real newmode. This is established as follows: when a name string is bound to both a real and a quasi defining occurrence all the newmodes involved are paired. The relation novelty bound is then established between novelties.

Definition

The relation novelty paired applies between two modes and a reach. For each name string bound in a reach R to both a real and a quasi defining occurrence:

- if they are synonym names, then the root modes of their classes are novelty paired in R;
- if they are set element names, then the modes of the attached set modes are novelty paired in R;
- if they are location or loc-identity names, then their location modes are novelty paired in R;
- if they are procedure names, then the modes of the parameter specs and result spec, if present, are novelty paired in R;
- if they are process names, then the modes of the parameter specs are novelty paired in R;
- if they are signal names, then the modes in the list of modes are novelty paired in R.

If two modes are novelty paired in a reach R, then:

- if they are powerset modes, their member modes are novelty paired in R;
- if they are bound reference modes, their referenced modes are novelty paired in R;
- · if they are row modes, their referenced origin modes are novelty paired in R;
- if they are procedure modes, the modes of their parameter specs and result spec, if present, are novelty paired in R;
- if they are buffer modes, their buffer element modes are novelty paired in R;
- if they are access modes, their index modes, if present, and record modes, if present, are novelty paired in R;
- if they are text modes, their index modes, if present, are novelty paired in R;
- if they are array modes, their index modes and element modes are novelty paired in R;
- if they are structure modes, their field modes are novelty paired in R.

If two modes are novelty paired in a reach R and their novelties are not equal, then the real and quasi novelties of the modes are novelty bound to each other in R.

Two novelties are considered the same if they are:

- · the same real novelty, or
- a real novelty and a quasi novelty that are novelty bound.

12.1.2.12 The relation read-compatible

Informal

The relation read-compatible is relevant for equivalent modes. A mode M is said to be read-compatible with a mode N if it or its possible (sub-)components have equal or more restrictive read-only specifications and, if they are reference modes, refer to l-equivalent locations. This relation is therefore non-symmetric.

Example:

READ REF READ CHAR is read-compatible with REF READ CHAR

Definition

A mode M is said to be read-compatible with a mode N (a non-symmetric relation) if and only if M and N are equivalent and, if N is a read-only mode, then M must also be a read-only mode and further:

- if M and N are bound reference modes, the referenced mode of M must be l-equivalent with the referenced mode of N;
- if M and N are row modes, the referenced origin mode of M must be I-equivalent with the referenced origin mode of N;

- if M and N are array modes, the element mode of M must be read-compatible with the element mode of N;
- if M and N are structure modes which are not parameterised structure modes, any field mode of M must be read-compatible with the corresponding field mode of N. If M and N are parameterised structure modes, the origin variant structure mode of M must be read-compatible with the origin variant structure mode of N.

12.1.2.13 The relations dynamic equivalent and read-compatible

Informal

The relations 1. dynamic equivalent, 2. dynamic read-compatible, are relevant only for modes that can be dynamic, i.e. string, array and variant structure modes. A parameterisable mode M is said to be 1. dynamic equivalent, 2. dynamic read-compatible with a (possibly dynamic) mode N, if there exists a dynamically parameterised version of M which is 1. equivalent, 2. read-compatible with N.

Definition

A mode M is 1. dynamic equivalent to a mode N, 2. dynamic read-compatible with a mode N (a non-symmetric relation) if and only if one of the following holds:

- M and N are string modes such that M(p) is 1. equivalent, 2. read-compatible with N, where p is the (possibly dynamic) length of N. The value p must not be greater than the string length of M. This check is dynamic if N is a dynamic mode. Check failure will result in a RANGEFAIL exception;
- M and N are array modes such that M(p) is 1. equivalent, 2. read-compatible with N, where p is such that NUM (p) LOWER (M) + 1 is the (possibly dynamic) number of elements of N. The value p must not be greater than the upper bound of M. This check is dynamic if N is a dynamic mode. Check failure will result in a RANGEFAIL exception;
- M is a parameterisable variant structure mode and N is a parameterised structure mode such that $M(p_1, \ldots, p_n)$ is 1. equivalent, 2. read-compatible with N, where p_1, \ldots, p_n denote the list of values of N.

12.1.2.14 The relation restrictable

Informal

The relation restrictable is relevant for equivalent modes with the referencing property. A mode M is said to be restrictable to a mode N if it or its possible (sub-)components refer to locations with equal or more restrictive read-only specification than those referenced by N. This relation is therefore non-symmetric.

Example:

REF READ INT is restrictable to REF INT
STRUCT (P REF READ BOOL) is restrictable to STRUCT (Q REF BOOL)

Definition

A mode M is restrictable to a mode N (a non-symmetric relation) if and only if M and N are equivalent and further:

- if M and N are bound reference modes, the referenced mode of M must be read-compatible with the referenced mode of N;
- if M and N are row modes, the referenced origin mode of M must be read-compatible with the referenced origin mode of N;
- if M and N are array modes, the element mode of M must be restrictable to the element mode of N;
- if M and N are structure modes, each field mode of M must be restrictable to the corresponding field mode of N.

12.1.2.15 Compatibility between a mode and a class

- Any mode M is compatible with the all class.
- A mode M is compatible with the null class if and only if M is a reference mode or a procedure mode or an instance mode.
- A mode M is compatible with the N-reference class if and only if it is a reference mode and one of the following conditions is fulfilled:
 - 1. N is a static mode and M is a bound reference mode whose referenced mode is read-compatible with N;
 - 2. N is a static mode and M is a free reference mode;
 - 3. M is a row mode whose referenced origin mode is dynamic read-compatible with N.
- A mode M is compatible with the N-derived class if and only if M and N are similar.
- A mode M is compatible with the N-value class if and only if one of the following holds:
 - 1. if M does not have the referencing property, M and N must be v-equivalent;
 - 2. if M does have the referencing property, M must be restrictable to N.

12.1.2.16 Compatibility between classes

- Any class is compatible with itself.
- The all class is compatible with any other class.
- The null class is compatible with any M-reference class.
- The null class is compatible with the M-derived class or M-value class if and only if M is a reference mode, procedure mode or instance mode.
- The M-reference class is compatible with the N-reference class if and only if M and N are equivalent. If M and/or N is (are) a dynamic mode, the dynamic part of the equivalence check is ignored, i.e. no exceptions can occur.
- The M-reference class is compatible with the N-value class if and only if N is a reference mode and one of the following conditions is fulfilled:
 - 1. M is a static mode and N is a bound reference mode whose referenced mode is equivalent to M.
 - 2. M is a static mode and N is a free reference mode.
 - 3. N is a row mode whose referenced origin mode is dynamic equivalent with M;
- The M-derived class is compatible with the N-derived class or N-value class if and only if M and N are similar.
- The M-value class is compatible with the N-value class if and only if M and N are v-equivalent.

Two lists of classes are compatible if and only if both lists have the same number of classes and corresponding (by position) classes are compatible.

12.2 VISIBILITY AND NAME BINDING

The definition of visibility and name binding is based on the following terminology:

- name string: denotes a terminal string that has attached a canonical name string (see section 2.7) and visibility properties;
- name: denotes a simple name string associated with the defining occurrence that has created it (see section 10.1);
- name: denotes an applied occurrence of a name (with a possibly prefixed name string).

12.2.1 Degrees of visibility

The binding rules are based on the visibility of name strings in the reaches of a program. Within a reach, each name string has one of the following four degrees of visibility:

Visibility	Properties (informal)
directly strongly visible	Name string is visible by creation, granting or seizing or inheritance from spec to body
indirectly strongly visible	Name string is predefined or inherited via block nesting
weakly visible	Name string is implied by a strongly visible name string
invisible	Name string may not be applied

Table 1. Degrees of visibility

A name string is said to be strongly visible in a reach if it is either directly strongly visible or indirectly strongly visible in that reach. A name string is said to be visible if it is either weakly or strongly visible, in that reach. Otherwise the name string is said to be invisible in that reach. The program structuring statements and visibility statements determine uniquely to which visibility class each name string belongs.

When a name string is visible in a reach, it can be directly linked to another name string in another reach, or directly linked to a defining occurrence in the program. The rules for direct linkage are in section 12.2.3. Notice that any application of a rule introduces a new direct linkage for a name string.

Based on direct linkage, the notion of (not necessarily direct) linkage is defined as follows:

A name string N₁, visible in reach R₁, is said to be linked to name string N₂ in reach R₂ or to defining occurrence D, if and only if one of the following conditions holds:

- N_1 in R_1 is directly linked to N_2 in R_2 or to D. However, if N_1 is directly linked to more than one defining occurrence in R_1 , then all but one of these defining occurrences are superfluous, and N_1 is linked to an arbitrary one of them in R_1 .
- N₁ in R₁ is directly linked to some N in some R, and N in R is linked to N₂ in R₂ or to D.

12.2.2 Visibility conditions and name binding

In each reach of a program, the following conditions must be satisfied:

- If a name string is strongly visible in a reach and has more than one direct linkage, then:
 - it must be directly linked to defining occurrences only, and these defining occurrences must define the same set elements of set modes that are similar, or
 - it must be linked to exactly one real defining occurrence and one quasi defining occurrence.

A name string weakly visible in a reach, and linked as a weakly visible name string in that reach to defining occurrences that do not define the same set element of similar set modes, is said to have a weak clash in that reach.

A name string NS, visible in reach R, is said to be bound in R to several defining occurrences according to the following rules:

- If NS is strongly visible in R, NS is bound to the defining occurrences to which it is linked in R (as a strongly visible name string). If it is bound both to a quasi defining occurrence and a real defining occurrence, then the quasi one is redundant and does not participate further to visibility and name binding (i.e. it is not seized, granted, inherited and does not introduce implied names);
- else, if NS is weakly visible in R, it is bound to the defining occurrences to which it is linked in R (as a weakly visible name string), provided NS has no weak clash in R. (Weak clashes are allowed in a reach if no name with a name string with a weak clash exists in the reach);
- otherwise NS is not bound in R.

static condition: The name string attached to each name directly enclosed in a reach must be bound in that reach.

binding of names: A name N with attached name string NS in a reach R is bound to the defining occurrences to which NS is bound in R.

12.2.3 Visibility in reaches

12.2.3.1 General

A name string is directly strongly visible in a reach according to the following rules:

- the name string is seized into the reach (see 12.2.3.5);
- the name string is granted into the reach (see 12.2.3.4);
- there is a defining occurrence with that name string in the reach. In that case, the name string in the reach is directly linked to the defining occurrence. (Note that the name string may be directly linked to several defining occurrences in the reach.)
- The reach is a 1. module body, 2. region body and the name string is directly strongly visible in the reach of a corresponding 1. spec module, 2. spec region. The name string is directly linked to the name string in the corresponding reach.

A name string which is not directly strongly visible in a reach is indirectly strongly visible in it according to the following rules:

- The reach is a block, and the name string is strongly visible in the directly enclosing reach. The name string is said to be inherited by the block, and is directly linked to the same name string in the directly enclosing reach.
- The reach is not a block in which the name string is inherited and the name string is a language (see Appendix C.2) or implementation defined name string. The name string is considered to be directly linked to a defining occurrence in the reach of the imaginary outermost process definition for its predefined meaning.

A name string which is not strongly visible in a reach is weakly visible in it if it is implied by a name string which is strongly visible in the reach. The name string in the reach is directly linked to an implied defining occurrence (see section 12.2.4).

12.2.3.2 Visibility statements

syntax:

semantics: Visibility statements are only allowed in modulion reaches and control the visibility of the name strings mentioned in them and implicitly of their implied name strings.

static properties: A visibility statement has one or two origin reaches (see 10.2) and one or two destination reaches attached, defined as follows:

- If the visibility statement is a seize statement, its destination reach is the reach directly enclosing the seize statement, and its origin reaches are the reaches directly enclosing that reach.
- If the visibility statement is a grant statement, then its origin reach is the reach directly enclosing the grant statement, and its destination reaches are the reaches directly enclosing that reach.

12.2.3.3 Prefix rename clause

syntax:

$$<$$
old prefix $> ::=$ (2)

$$|$$
 (2.2)

$$< postfix > ::=$$
 (4)

$$\langle \text{seize postfix} \rangle \{ , \langle \text{seize postfix} \rangle \}^*$$
 (4.1)

$$| < grant postfix > \{ , < grant postfix > \}^*$$
 (4.2)

derived syntax: A prefix rename clause where the postfix consists of more than one seize postfix (grant postfix) is derived syntax for several prefix rename clauses, one for each seize postfix (grant postfix), separated by commas, with the same old prefix and new prefix.

For example:

GRANT
$$(p \rightarrow q) ! a, b;$$

is derived syntax for

GRANT
$$(p -> q) ! a , (p -> q) ! b ;$$

semantics: Prefix rename clauses are used in visibility statements to express change of prefix in prefixed name strings that are granted or seized. (Since prefix rename clauses can be used without prefix changes—when both the old prefix and the new prefix are empty—they are taken as the semantic base for visibility statements).

static properties: A prefix rename clause has one or two origin reaches attached, which are the origin reaches of the visibility statement in which it is written.

A prefix rename clause has one or two destination reaches attached, which are the destination reaches of the visibility statement in which it is written.

A postfix has a set of name strings attached, which is the set of name strings attached to its seize postfix or the set of name strings attached to its grant postfix. These name strings are the postfix name strings of the prefix rename clause.

A prefix rename clause has a set of old name strings and a set of new name strings attached. Each postfix name string attached to the prefix rename clause gives both an old name string and a new name string attached to the prefix rename clause, as follows: the new name string is obtained by prefixing the postfix name string with the new prefix; the old name string is obtained by prefixing the postfix name string with the old prefix.

When a new name string and an old name string are obtained from the same postfix name string, the old name string is said to be the source of the new name string.

visibility rules: The new name strings attached to a prefix rename clause are strongly visible in their destination reaches and are directly linked in those reaches to their sources in the origin reaches. If the prefix rename clause is part of a seize (grant) statement, those name strings are seized (granted) in their destination reach (reaches).

A name string NS is said to be seizable by modulion M directly enclosed in reach R if and only if it is strongly visible in R and it is neither linked in R to any name string in the reach of M nor directly linked to the defining occurrence of a predefined name string.

A name string NS is said to be grantable by modulion M directly enclosed in reach R if and only if it is strongly visible in the reach of M and it is neither linked in it to any name string in R nor directly linked in it to the defining occurrence of a predefined name string.

static conditions: If a prefix rename clause is in a seize statement directly enclosed in the reach of modulion M then each of its old name strings must be:

- bound in the reach directly enclosing the reach of M and
- seizable by M.

If a prefix rename clause is in a grant statement directly enclosed in the reach of modulion M then each of its old name strings must be:

- · bound in the reach of M and
- grantable by M.

A prefix rename clause that occurs in a grant (seize) statement must have a postfix that is a grant (seize) postfix.

examples:

12.2.3.4 Grant statement

syntax:

(2)

(4.1)

semantics: Grant statements are a means of extending the visibility of name strings in a modulion reach into the directly enclosing reaches. FORBID can be specified only for newmode names which are structure modes. It means that all locations and values of that mode have fields which may be selected only inside the granting modulion, not outside.

The following visibility rules apply:

<grant window> ::=

- If the grant statement contains prefix rename clause(s), the grant statement has the effect of its prefix rename clause(s) (see section 12.2.3.3).
- If the grant statement contains grant windows, it is shorthand notation for a set of grant statements with prefix rename clauses constructed as follows:
 - For each grant postfix in the grant window, there is a corresponding grant statement.
 - The old prefix in their prefix rename clause is empty.
 - The new prefix in their prefix rename clause is the prefix attached to the prefix clause in the grant statement, or it is empty if there is no prefix clause in the original grant statement.
 - The postfix in the prefix rename clause is the corresponding postfix in the grant
- The notation FORBID ALL is shorthand notation for forbidding all the field names of the newmode name (see section 12.2.5).
- If a prefix rename clause in a grant statement has a grant postfix which contains a prefix and ALL, then it is of the form:

$$(OP \rightarrow NP) ! P ! ALL$$

where OP and NP are the possibly empty old prefix and new prefix, respectively, and P is the prefix in the grant postfix. The prefix rename clause is then shorthand notation for a clause of the form:

$$(OP ! P \rightarrow NP ! P) ! ALL$$

static properties: A prefix clause has a prefix attached, defined as follows:

- If the prefix clause contains a prefix, then that prefix is attached.
- Otherwise the attached prefix is a simple prefix whose name string is determined as follows:
 - If the reach directly enclosing the prefix is a module or region, then the name string is the same as the one of the modulion name of that modulion.
 - If the reach directly enclosing the prefix is a spec region or spec module, then the name string is the name string in front of SPEC.

A grant postfix has a set of name strings attached, defined as follows:

- If it is a name string, or contains a <u>newmode</u> name string, then the set containing only that name string.
- Otherwise, let OP be the (possibly empty) old prefix of the prefix rename clause in which the grant postfix is placed, the set contains all name strings of the form OP! N (i.e. obtained by prefixing N with OP) for any name string N such that OP! N is strongly visible in the reach of the modulion in which the grant postfix is placed and grantable by this modulion.

static conditions: The <u>newmode</u> name string with forbid clause must be strongly visible in the reach R of the modulion in which the grant statement is placed. The <u>newmode</u> name string must be bound in R to the defining occurrence of a newmode which must be a structure mode, and each field name in the field name list must be a field name of that mode. The newmode defining occurrence must be directly enclosed in R. All field names in a forbid name list must have different name strings.

If the grant statement is placed in the reach of a region or spec region, it must not grant a name string which is bound in that reach to the defining occurrence of:

- a location name, or
- a loc-identity name, where the location in its declaration is intra-regional, or
- a synonym name whose value is intra-regional.

The prefix rename clause in a grant statement must have a grant postfix.

If a grant statement contains a prefix clause which does not contain a prefix, then its directly enclosing modulion must not be a context and,

- if its directly enclosing modulion is a module or region, then it must be named (i.e. it must be headed by a defining occurrence followed by a colon);
- if its directly enclosing modulion is a spec module or a spec region, then it must be headed by a simple name string.

examples:

12.2.3.5 Seize statement

syntax:

semantics: Seize statements are a means of extending the visibility of name strings in group reaches into the

reaches of directly enclosed modulions.

The following visibility rules apply:

- If the seize statement contains prefix rename clause(s), the seize statement has the effect of its prefix rename clause(s) (see section 12.2.3.3).
- If the seize statement contains a seize window, it is shorthand notation for a set of seize statements with prefix rename clauses constructed as follows:
 - For each seize postfix in the seize window, there is a corresponding seize statement.
 - The old prefix in their prefix rename clause is the prefix attached to the prefix clause in the seize statement, or is empty if there is no prefix clause in the original seize statement.
 - The new prefix in their prefix rename clause is empty.
 - The postfix in their prefix rename clause is the corresponding postfix of the seize window.
- If a prefix rename clause in a seize statement has a seize postfix which contains a prefix and ALL, then it is of the form:

$$(OP \rightarrow NP) ! P ! ALL$$

where OP and NP are the possibly empty old prefix and new prefix, respectively, and P is the prefix in the seize postfix. The prefix rename clause is then shorthand notation for a clause of the form:

$$(OP ! P \rightarrow NP ! P) ! ALL$$

static properties: A seize postfix has a set of name strings attached, defined as follows:

- If the seize postfix is a name string, the set containing only the name string.
- Else, if the seize postfix is ALL, let OP be the (possibly empty) old prefix of the prefix rename clause of which the seize postfix is part, the set contains all name strings of the form OP! S, for any name string S, such that OP! S is strongly visible in the reach directly enclosing the modulion in which the seize statement is placed and seizable by this modulion.

static conditions: The prefix rename clause in a seize statement must have a seize postfix.

If a seize statement contains a prefix clause which does not contain a prefix, then its directly enclosing modulion must not be a context and,

- if its directly enclosing modulion is a module or region, then it must be named (i.e. it must be headed by a defining occurrence followed by a colon);
- if its directly enclosing modulion is a spec module or a spec region, then it must be headed by a simple name string.

examples:

25.35 SEIZE (stack! int
$$\rightarrow$$
 stack)! ALL; (1.1)

12.2.4 Implied name strings

Each name string strongly visible in a reach R has a set of implied name strings, which may be weakly visible in R.

Each mode has a possibly empty set of implied defining occurrences attached in a reach, as listed in Table 2. Each name string NS, strongly visible in reach R, has a set of implied defining occurrences, defined as follows, where D is one of the defining occurrences to which NS is bound in R:

- If D defines an access name of mode M, the implied defining occurrences of NS in R are those implied in R by M.
- If D defines a mode name, the implied defining occurrences of NS in R are those implied in R by the defining mode of the mode name.

- If D defines a procedure name, the implied defining occurrences of NS in R are those implied in R by the modes of the parameter specs and the result spec of the procedure, if any.
- If D defines a process name, the implied defining occurrences of NS in R are those implied in R by the modes of the parameter specs, if any.
- If D defines a signal name, the implied defining occurrences of NS in R are all defining occurrences implied in R by all modes attached to the signal.
- · Otherwise the set is empty.

Modes	Set of implied defining occurrences
INT, BOOL, CHAR, RANGE () BIN (n), PTR, INSTANCE, EVENT, ASSOCIATION, TIME, DURATION, BOOLS (n), CHARS (n)	Empty
mode name	The set of defining occurrences implied in R by its defining mode
mode name () (parameterised)	The set of defining occurrences implied in R by mode name
M(m:n), REF M, ROW M, READ M POWERSET M, BUFFER M TEXT () M	The set of defining occurrences implied in R by M
SET ()	The set of set element defining occurrences in the mode
PROC $(M_1,\ldots,M_n)(M_{n+1})$	The union of the sets of the defining occurrences implied in R by M_1 through M_{n+1}
ARRAY (M) N, ACCESS (M) N	The union of the sets of the defining occurrences implied in R by M, and N
STRUCT $(N_1 \ M_1 \ , \ldots, N_n \ M_n \)$	The union of the sets of defining occurrences implied in R by M_i for fields that are visible in R. For variant structures it is the union of the defining occurrences implied in R by the fields of the variant structure that are visible in R

Table 2. Implied defining occurrences of modes in reach R

If a name string NS, strongly visible in a reach R, has implied defining occurrences, each of those defining occurrences specifies an implied name string for NS in R: let D be a defining occurrence implied by NS in R and let Ni be the name string of D. There are two cases:

- NS is a simple name string. Then Ni is an implied name string of NS.
- NS is of the form P!S, where S is a simple name string. Then P!Ni is an implied name string of NS.

examples:

12.2.5 Visibility of field names

Field names may occur only in the following contexts:

- · structure fields and value structure fields,
- labelled structure tuples,
- forbid clauses in grant statements.

In each of these cases, the name string of the field name can be bound to a field name defining occurrence in the mode M or in the defining mode of M, obtained as follows:

- M is the mode of the <u>structure</u> location or (strong) <u>structure</u> primitive value;
- M is the mode of the structure tuple;
- M is the mode of the defining occurrence to which the <u>newmode</u> name string is bound in the reach in which the forbid clause is placed.

However, if the novelty of M is a defining occurrence that defines a newmode name that has been granted by a grant statement in a modulion as a grant postfix with a forbid clause, then the field names mentioned in the forbid name list are only visible:

• in the group of the granting modulion,

<case label specification> ::=

(*)

<case label list> { , <case label list> }*

- if the novelty of M is novelty bound to a quasi novelty N, then in the group of the reach in which N is directly enclosed,
- if the modulion is a module spec or region spec, then in the reach of the corresponding modulion.

Outside these reaches the field names mentioned in the forbid name list are invisible and cannot be used.

12.3 CASE SELECTION

syntax:

(1)

(1.1)

(4.1)

semantics: Case selection is a means of selecting an alternative from a list of alternatives. The selection is based upon a specified list of selector values. Case selection may be applied to:

- alternative fields (see section 3.12.4), in which case a list of variant fields is selected,
- labelled array tuples (see section 5.2.5), in which case an array element value is selected,
- conditional expressions (see section 5.3.2), in which case an expression is selected,
- case action (see section 6.4), in which case an action statement list is selected.

In the first, third and fourth situations, each alternative is labelled with a case label specification; in the labelled array tuple, each value is labelled with a case label list. For ease of description, the case label list in the labelled array tuple will be considered in this section as a case label specification with only one case label list occurrence.

Case selection selects that alternative which is labelled by the case label specification which matches the list of selector values. (The number of selector values will always be the same as the number of case label list occurrences in the case label specification.) A list of values is said to match a case label specification if and only if each value matches the corresponding (by position) case label list in the case label specification.

A value is said to match a case label list if and only if:

- the case label list consists of case labels and the value is one of the values explicitly indicated by one of the case labels or implicitly indicated in the case of ELSE;
- the case label list consists of irrelevant.

The values explicitly indicated by a case label are the values delivered by any <u>discrete literal</u> expression, or defined by the <u>literal range</u> or <u>discrete mode name</u>. The values implicitly indicated by **ELSE** are all the possible selector values which are not explicitly indicated by any associated case label list (i.e. belonging to the same selector value) in any case label specification.

static properties:

- An alternative fields with case label specification, a labelled array tuple, a conditional expression, or a case action has a list of case label specifications attached, formed by taking the case label specification in front of each variant alternative, value or case alternative, respectively.
- A case label has a class attached, which is, if it is a <u>discrete literal</u> expression, the class of the <u>discrete literal</u> expression; if it is a <u>literal range</u>, the <u>resulting class</u> of the classes of each <u>discrete literal</u> expression in the <u>literal range</u>; if it is a <u>discrete mode</u> name, the <u>resulting</u> class of the M-value class where M is the <u>discrete mode name</u>; if it is **ELSE**, the <u>all class</u>.
- A case label list has a class attached, which is, if it is irrelevant, then the all class, otherwise the resulting class of the classes of each case label.
- A case label specification has a list of classes attached, which are the classes of the case label lists.
- A list of case label specifications has a resulting list of classes attached. This resulting list of classes is formed by constructing, for each position in the list, the resulting class of all the classes that have that position.

A list of case label specifications is complete if and only if for all lists of possible selector values, a case label specification is present, which matches the list of selector values. The set of all possible selector values is determined by the context as follows:

- For a tagged variant structure mode it is the set of values defined by the mode of the corresponding tag field.
- For a tag-less variant structure mode it is the set of values defined by the root mode of the corresponding resulting class (this class is never the all class, see section 3.12.4).
- For an array tuple, it is the set of values defined by the index mode of the mode of the array tuple.
- For a case action with a range list, it is the set of values defined by the corresponding discrete
 mode in the range list.
- For a case action without a range list, or a conditional expression it is the set of values defined by M where the class of the corresponding selector is the M-value class or the M-derived class.

static conditions: For each case label specification the number of case label list occurrences must be equal.

For any two case label specification occurrences, their lists of classes must be compatible.

The list of case label specification occurrences must be consistent, i.e. each list of possible selector values matches at most one case label specification.

examples:

12.4 DEFINITION AND SUMMARY OF SEMANTIC CATEGORIES

This section gives a summary of all semantic categories which are indicated in the syntax description by means of an underlined part. If these categories are not defined in the appropriate sections, the definition is given here, otherwise the appropriate section will be referenced.

12.4.1 Names

Mode names

absolute time mode name: a name defined to be an absolute time mode.

a name defined to be an access mode.

array mode name:

a name defined to be an array mode.

association mode name:

a name defined to be an association mode.

boolean mode name:

a name defined to be a boolean mode.

bound reference mode name: a name defined to be a bound reference mode.

a name defined to be a buffer mode. <u>buffer</u> mode name: character mode name: a name defined to be a character mode. discrete mode name: a name defined to be a discrete mode. duration mode name: a name defined to be a duration mode. event mode name: a name defined to be an event mode. free reference mode name: a name defined to be a free reference mode. instance mode name: a name defined to be an instance mode. integer mode name: a name defined to be an integer mode.

<u>mode</u> name: see section 3.2.1 <u>newmode</u> name: see section 3.2.3

parameterised array mode name: a name defined to be a parameterised array mode.

parameterised string mode name: a name defined to be a parameterised string mode.

parameterised structure mode name: a name defined to be a parameterised structure mode.

powerset mode name:

procedure mode name:

a name defined to be a procedure mode.

a name defined to be a procedure mode.

a name defined to be a range mode.

a name defined to be a row mode.

a name defined to be a set mode.

set mode name:

a name defined to be a set mode.

string mode name:

a name defined to be a string mode.

structure mode name:

a name defined to be a structure mode.

synmode name: see section 3.2.2

<u>variant structure mode</u> name: a name defined to be a variant structure mode.

Access names

 location name:
 see sections 4.1.2.

 location do-with name:
 see section 6.5.4.

 location enumeration name:
 see section 6.5.2.

 loc-identity name:
 see sections 4.1.3.

Value names

boolean literal name:see section 5.2.4.3.emptiness literal name:see section 5.2.4.6.synonym name:see section 5.1.value do-with name:see section 6.5.4.value enumeration name:see section 6.5.2.

value receive name: see sections 6.19.2, 6.19.3.

Miscellaneous names

bound reference location name:

built-in routine name:

a location name with a bound reference mode.

any CHILL or implementation defined name denoting a built-in

routine.

free reference location name:

general procedure name:

a location name with a free reference mode. a procedure name whose generality is general.

label name:

see sections 6.1, 10.6.

newmode name string:

a name string bound to the defining occurrence of a newmode

non-reserved name:

a name which is none of the reserved names mentioned in Ap-

pendix C.1.

see section 10.4.

procedure name:

process name: set element name:

see section 10.5. see section 3.4.5. signal name: see section 11.5.

tag field name: undefined synonym name:

see section 5.1.

see section 3.12.4.

12.4.2 Locations

access location:

array location:

association location:

character string location:

buffer location: discrete location: event location: instance location: static mode location:

string location: structure location: text location:

a location with an access mode.

a location with an array mode.

a location with an association mode.

a location with a character string mode.

a location with a buffer mode. a location with a discrete mode. a location with an event mode. a location with an instance mode.

a location with a static mode. a location with a string mode. a location with a structure mode.

a location with a text mode.

12.4.3 Expressions and values

absolute time primitive value:

a primitive value whose class is compatible with an absolute

array expression:

array primitive value: boolean expression:

bound reference primitive value:

an expression whose class is compatible with an array mode. a primitive value whose class is compatible with an array mode. an expression whose class is compatible with a boolean mode. a primitive value whose class is compatible with a bound refer-

character string expression:

an expression whose class is compatible with a character string mode.

constant value:

discrete expression:

discrete literal expression:

duration primitive value:

<u>free_reference</u> primitive value:

instance primitive value:

<u>integer</u> expression: <u>integer literal</u> expression:

powerset expression:

<u>procedure</u> primitive value:

reference primitive value:

row primitive value:
string expression:
string primitive value:
structure primitive value:

a value which is constant.

an expression whose class is compatible with a discrete mode.

a discrete expression which is literal.

a primitive value whose class is compatible with a duration

mode.

a primitive value whose class is compatible with a free reference

mode.

a primitive value whose class is compatible with an instance

mode.

an expression whose class is compatible with an integer mode.

an integer expression which is literal.

an expression whose class is compatible with a powerset mode. a primitive value whose class is compatible with a procedure

mode.

a primitive value whose class is compatible with either a bound

reference mode, a free reference mode or a row mode.

a primitive value whose class is compatible with a row mode. an expression whose class is compatible with a string mode. a primitive value whose class is compatible with a string mode. a primitive value whose class is compatible with a structure mode.

12.4.4 Miscellaneous semantic categories

array mode:

discrete mode:

<u>location</u> built-in routine call:

<u>location</u> procedure call:

non-reserved character:

non-special character:

string mode:

value built-in routine call:

value procedure call:

a mode in which the composite mode is an array mode.

a mode in which the non-composite mode is a discrete mode.

see section 6.7 see section 6.7

a character which is neither a quote (") nor a circumflex (^).

a character which is neither a circumflex (^) nor an open paren-

thesis (().

a mode in which the composite mode is a string mode.

see section 6.7 see section 6.7

13 IMPLEMENTATION OPTIONS

13.1 IMPLEMENTATION DEFINED BUILT-IN ROUTINES

semantics: An implementation may provide for a set of implementation defined built-in routines in addition to the set of language defined built-in routines.

The parameter passing mechanism is implementation defined.

predefined names: The name of an implementation defined built-in routine is predefined as a built-in routine name.

static properties: A built-in routine name may have a set of implementation defined exception names attached. A built-in routine call is a value (location) built-in routine call if and only if the implementation specifies that for a given choice of static properties of the parameters and the given static context of the call, the built-in routine call delivers a value (location).

The implementation specifies also the regionality of the value (location).

13.2 IMPLEMENTATION DEFINED INTEGER MODES

An implementation defines the upper bound and lower bound of the integer mode INT. An implementation may define integer modes other than the ones defined by INT; e.g. short integers, long integers, unsigned integers. These integer modes must be denoted by implementation defined integer mode names. These names are considered to be newmode names, similar to INT. Their value ranges are implementation defined. These integer modes may be defined as root modes of appropriate classes.

13.3 IMPLEMENTATION DEFINED PROCESS NAMES

An implementation may define a set of implementation defined process names; i.e. process names whose definition is not specified in CHILL. The definition is considered to be placed in the reach of the imaginary outermost process or in any context. Processes of this name may be started and instance values denoting such processes may be manipulated.

13.4 IMPLEMENTATION DEFINED HANDLERS

An implementation may specify that an implementation defined handler is appended to a process definition; such a handler may handle any exception.

13.5 IMPLEMENTATION DEFINED EXCEPTION NAMES

An implementation may define a set of exception names.

13.6 OTHER IMPLEMENTATION DEFINED FEATURES

- Static check of dynamic conditions (see section 2.1.2)
- implementation directive (see section 2.6)
- text reference name (see sections 2.7 and 10.10.1)
- default recursivity and generality (see sections 3.7 and 10.4)
- set of values of duration modes (see section 3.11.2)
- set of values of absolute time modes (see section 3.11.3)
- default element layout (see section 3.12.3)

- comparison of tag-less variant structure values (see section 3.12.4)
- number of bits in a word (see section 3.12.5)
- minimum bit occupancy (see section 3.12.5)
- additional referable (sub-)locations (see section 4.2.1)
- semantics of a <u>location do-with</u> name and <u>value do-with</u> name which is a variant field of a tag-less variant structure location (see sections 4.2.2 and 5.2.3)
- semantics of variant fields of tag-less variant structures (see section 4.2.10, 5.2.13 and 6.2)
- semantics of location conversion (see section 4.2.13)
- semantics of expression conversion and additional conditions (see section 5.2.11)
- additional actual parameters in a start expression (see section 5.2.14)
- ranges of values for literal and constant expressions (see section 5.3.1)
- scheduling algorithm (see sections 6.15, 6.18.2, 6.18.3, 6.19.2 and 6.19.3)
- releasing of storage in TERMINATE (see section 6.20.4)
- denotation for files (see section 7.1)
- operations on associations (see sections 7.1 and 7.2.1)
- non-exclusive associations (see section 7.1)
- additional attributes of association values (see section 7.2.2)
- semantics of associate parameters (see section 7.4.2)
- ASSOCIATEFAIL exception (see section 7.4.2)
- semantics of modify parameters (see section 7.4.5)
- CREATEFAIL, DELETEFAIL and MODIFYFAIL exception (see section 7.4.5)
- CONNECTFAIL exception (see section 7.4.6)
- semantics of reading of records that are not legal values according to the record mode (see section 7.4.9)
- additional timeoutable actions (see section 9.2)
- TIMERFAIL exception (see sections 9.3.1, 9.3.2 and 9.3.3)
- precision of duration values (see sections 9.4.1 and 9.4.2)
- indication of constant value in quasi synonym definitions (see section 10.10.3)
- regionality of built-in routines (see section 11.2.2).

APPENDIX A: CHARACTER SET FOR CHILL

The character set of CHILL is an extension of the CCITT Alphabet No. 5, International Reference Version, Recommendation V3. For the values whose representations are greater than 127, no graphical representation is defined.

The integer representation is the binary number formed by bits b₈ to b₁, where b₁ is the least significant bit.

	b7b6b5	000	001	010	011	100	101	110	111
b4b3b2b1		0	1	2	3	4	5	6	7
0000	0	NUL	TC ₇ (DLE)	SP	0	, (a)	Р		р
0001	1	TC ₁ (SOH)	DC_1	1	1	A	ď	a	q
0010	2	TC ₂ (STX)	DC_2	"	2	В	R	b	r
0011	3	TC ₃ (ETX)	DC ₃	#	3	C	S	С	s
0100	4	TC ₄ (EOT)	DC4	\$	4	D	Т	d	t
0101	5	TC ₅ (ENQ)	TC ₈ (NAK)	%	5	E	υ	е	u
0110	6	TC ₆ (ACK)	TC ₉ (SYN)	&	6	F	v	f	v
0111	7	BEL	TC ₁₀ (ETB)	,	7	G	w	g	w
1000	8	FE ₀ (BS)	CAN	(8	H	X	h	x
1001	9	FE ₁ (HT)	EM)	9	I	Y	i	у
1010	10	FE ₂ (LF)	SUB	*	:	J	Z	j	Z
1011	11	FE ₃ (VT)	ESC	+	;	K	[k	{
1100	12	FE ₄ (FF)	IS ₄ (FS)	,	<	L	١	1	_
1101	13	FE ₅ (CR)	IS ₃ (GS)		=	М]	m	}
1110	14	so	IS ₂ (RS)		>	N	-	n	~
1111	15	SI	IS ₁ (US)	/	?	0		0	DEL

APPENDIX B: SPECIAL SYMBOLS AND CHARACTER COMBINATIONS

	Name	Use
;	semicolon	terminator for statements etc.
,	comma	separator in various constructs
(left parenthesis	opening parenthesis of various constructs
)	right parenthesis	closing parenthesis of various constructs
l (left square bracket	opening bracket of a tuple
]	right square bracket	closing bracket of a tuple
(:	left tuple bracket	opening bracket of a tuple
() [] (;) ;	right tuple bracket	closing bracket of a tuple
:	colon	label indicator, range indicator
	dot	field selection symbol
:=	assignment symbol	assignment, initialisation
<	less than	relational operator
<=	less than or equal	relational operator
=	equal	relational operator, assignment,
		initialisation, definition indicator
/=	not equal	relational operator
>=	greater than or equal	relational operator
>	greater than	relational operator
+	plus	addition operator
-	minus	subtraction operator
*	asterisk	multiplication operator, undefined value,
		unnamed value, irrelevant symbol
/	solidus	division operator
//	double solidus	concatenation operator
->	arrow	referencing and dereferencing,
		prefix renaming
<>	diamond	start or end of a directive clause
/*	comment opening	bracket start of a comment
*/	comment closing	bracket end of a comment
,	apostrophe	start or end symbol in various literals
**	quote	start or end symbol in character string
		literals
27 27	double quote	quote within character string literals
1	prefixing operator	prefixing of names
B'	literal qualification	binary base for literal
D'	literal qualification	decimal base for literal
H'	literal qualification	hexadecimal base for literal
0'	literal qualification	octal base for literal
	line end	line end delimiter of in-line comments

APPENDIX C: SPECIAL SIMPLE NAME STRINGS

C.1 RESERVED SIMPLE NAME STRINGS

ACCESS AFTER ALL AND ANDIF ARRAY ASSERT AT	END ESAC EVENT EVER EXCEPTIONS EXIT	OD OF ON OR ORIF	SEND SET SIGNAL SIMPLE SPEC START STATIC STEP STOP
	FOR	,	STRUCT
BEGIN	FORBID		SYN
BIN		PACK	SYNMODE
BODY		POS	
BOOLS	GENERAL	POWERSET	-
BUFFER	GOTO	PREFIXED	TEXT
BY	GRANT	PRIORITY	THEN
	•	PROC	THIS
		PROCESS	TIMEOUT
CASE	\mathbf{IF}		TO
CAUSE	IN		
CHARS	INIT	RANGE	
CONTEXT	INLINE	READ	\mathbf{UP}
CONTINUE	INOUT	RECEIVE	
CYCLE		RECURSIVE	,
		REF	VARYING
	LOC	REGION	
DCL		REM	
DELAY		REMOTE	WHILE
DO	MOD	RESULT	WITH
DOWN	MODULE	RETURN .	
DYNAMIC		RETURNS	
		\mathbf{ROW}	XOR
	NEWMODE		
ELSE	NONREF		
ELSIF	NOPACK	SEIZE	

C.2 PREDEFINED SIMPLE NAME STRINGS

ABS ABSTIME ALLOCATE ASSOCIATE	FALSE FIRST GETASSOCIATION	MILLISECS MIN MINUTES MODIFY	SETTEXTACCESS SETTEXTINDEX SETTEXTRECORD
ASSOCIATION	GETASSOCIATION GETSTACK GETTEXTACCESS	MODIFY	SIZE SUCC
ROOT	GETTEXTINDEX	NULL	
BOOL	GETTEXTRECORD GETUSAGE	NUM	TERMINATE TIME
			TRUE
CARD		OUTOFFILE	
CHAR	HOURS		
CONNECT			UPPER
CREATE		PRED	USAGE
	INDEXABLE	PTR	
	INSTANCE		
DAYS	INT		VARIABLE
DELETE	INTTIME	READABLE	
DISCONNECT	ISASSOCIATED	READONLY	
DISSOCIATE		READRECORD	WAIT
DURATION		READTEXT	WHERE
	LAST	READWRITE	WRITEABLE
	LENGTH		WRITEONLY
EOLN	LOWER		WRITERECORD
EXISTING		SAME	WRITETEXT
EXPIRED		SECS	
	MAX	SEQUENCIBLE	

C.3 EXCEPTION NAMES

ALLOCATEFAIL NOTASSOCIATED ASSERTFAIL OVERFLOW ASSOCIATEFAIL RANGEFAIL CONNECTFAIL READFAIL CREATEFAIL SENDFAIL DELAYFAIL SPACEFAIL DELETEFAIL TAGFAIL EMPTYTEXTFAILMODIFYFAIL TIMERFAIL NOTCONNECTED WRITEFAIL

APPENDIX D: PROGRAM EXAMPLES

1. Operations on integers

```
integer_operations:
 2
    MODULE
 3
 4
        add:
 5
        PROC (i,j INT) RETURNS (INT) EXCEPTIONS (OVERFLOW);
 6
               RESULT i+i;
 7
        END add;
 8
 9
        mult:
10
        PROC (i,j INT) RETURNS (INT) EXCEPTIONS (OVERFLOW):
11
               RESULT i*j;
12
        END mult;
13
14
        GRANT add, mult;
15
        SYNMODE operand_mode=INT;
16
        GRANT operand_mode;
17
        SYN neutral_for_add=0,
18
             neutral_for_mult=1:
19
        GRANT neutral_for_add,
20
                neutral_for_mult;
21
22
    END integer_operations;
```

2. Same operations on fractions

```
1
    fraction_operations:
 2
    MODULE
 3
        NEWMODE fraction=STRUCT (num,denum INT);
 4
 5
 6
        PROC (f1,f2 fraction) RETURNS (fraction) EXCEPTIONS (OVERFLOW);
 7
                RETURN [f1.num*f2.denum+f2.num*f1.denum,f1.denum*f2.denum];
 8
        END add;
 9
10
        mult:
11
        PROC (f1,f2 fraction) RETURNS (fraction) EXCEPTIONS (OVERFLOW);
12
                RETURN [f1.num*f2.num,f2.denum*f1.denum];
13
        END mult;
14
15
        GRANT add, mult;
16
        SYNMODE operand_mode=fraction;
17
        GRANT operand_mode;
18
        SYN neutral_for_add fraction=[ 0,1 ],
             neutral_for_mult fraction=[ 1,1 ];
19
20
        GRANT neutral_for_add,
21
                 neutral_for_mult;
22
23
    END fraction_operations;
```

3. Same operations on complex numbers

```
complex_operations:
2
    MODULE
3
        NEWMODE complex=STRUCT (re,im INT);
4
5
        PROC (c1,c2 complex) RETURNS (complex) EXCEPTIONS (OVERFLOW);
6
               RETURN [c1.re+c2.re,c1.im+c2.im];
7
8
        END add;
 9
10
        mult:
        PROC (c1.c2 complex) RETURNS (complex) EXCEPTIONS (OVERFLOW);
11
                RETURN [c1.re*c2.re-c1.im*c2.im,c1.re*c2.im+c1.im*c2.re];
12
13
        END mult;
14
15
        GRANT add, mult;
16
        SYNMODE operand_mode=complex;
17
        GRANT operand_mode;
18
        SYN neutral_for_add=complex [ 0,0 ],
             neutral_for_mult=complex [ 1,0 ];
19
20
        GRANT neutral_for_add,
21
                 neutral_for_mult;
22
23
    END complex_operations;
```

4. General order arithmetic

```
general_order_arithmetic: /* from collected algorithms from CACM no. 93 */
2
    MODULE
3
        op:
        PROC (a INT INOUT, b,c,order INT)
4
5
                EXCEPTIONS (wrong_input) RECURSIVE;
6
            DCL d INT:
7
            ASSERT b>0 AND c>0 AND order>0
                ON (ASSERTFAIL):
8
9
                   CAUSE wrong_input;
10
                END:
11
            CASE order OF
12
                        a := b+c;
                (1):
13
                        RETURN;
14
                (2):
                        d := 0;
15
                (ELSE): d := 1;
16
            ESAC;
17
            DO FOR i := 1 TO c;
18
                op (a,b,d,order-1);
19
                d := a:
20
            OD;
21
            RETURN;
22
        END op;
23
24
        GRANT op;
25
26
    END general_order_arithmetic;
```

5. Adding bit by bit and checking the result

```
add_bit_by_bit:
 2
     MODULE
 3
         adder:
 4
         PROC (a STRUCT (a2,a1 BOOL) IN, b STRUCT (b2,b1 BOOL) IN)
 5
                 RETURNS (STRUCT (c4,c2,c1 BOOL));
 6
             DCL c STRUCT (c4,c2,c1 BOOL);
 7
             DCL k2,x,w,t,s,r BOOL;
 8
             DO WITH a,b,c;
 9
                 k2 := a1 \text{ AND } b1;
10
                 c1 := NOT k2 AND (a1 OR b1);
11
                 x := a2 \text{ AND } b2 \text{ AND } k2
12
                 w := a2 OR b2 OR k2;
13
                 t := b2 \text{ AND } k2;
14
                 s := a2 \text{ AND } k2;
15
                 r := a2 \text{ AND } b2;
16
                 c4 := r OR s OR t;
17
                 c2 := x \text{ OR } (w \text{ AND NOT } c4);
18
             OD.
19
             RETURN c;
20
         END adder;
21
         GRANT adder:
22
     END add_bit_by_bit;
23
24
     exhaustive_checker:
25
     MODULE
26
         SEIZE adder;
27
        DCL a STRUCT (a2,a1 BOOL),
28
              b STRUCT (b2,b1 BOOL):
29
         SYNMODE res=ARRAY (1:16) STRUCT (c4,c2,c1 BOOL);
30
         DCL r INT, results res;
31
        DO WITH a,b;
32
             r := 0;
33
             DO FOR a2 IN BOOL;
34
                DO FOR al IN BOOL;
35
                     DO FOR b2 IN BOOL;
36
                         DO FOR b1 IN BOOL:
37
                             r+ := 1;
38
                             results (r) := adder(a,b);
39
                         OD:
40
                     OD;
41
                 OD:
42
             OD;
43
         OD;
44
         ASSERT
45
             results=res [[FALSE,FALSE,FALSE],[FALSE,FALSE,TRUE],
46
                        [FALSE, TRUE, FALSE], [FALSE, TRUE, TRUE],
47
                        [FALSE, FALSE, TRUE], [FALSE, TRUE, FALSE],
48
                        [FALSE, TRUE, TRUE], [TRUE, FALSE, FALSE],
49
                        [FALSE,TRUE,FALSE], [FALSE,TRUE,TRUE],
50
                        [TRUE, FALSE, FALSE], [TRUE, FALSE, TRUE],
51
                        [FALSE,TRUE,TRUE],[TRUE,FALSE,FALSE],
52
                        [TRUE, FALSE, TRUE], [TRUE, TRUE, FALSE];
53
    END exhaustive_checker:
```

6. Playing with dates

```
1
    playing_with_dates:
2
    MODULE/* from collected algorithms from CACM no. 199 */
3
         SYNMODE month=SET (jan,feb,mar,apr,may,jun,
4
                     jul, aug, sep, oct, nov, dec);
5
        NEWMODE date=STRUCT (day INT (1:31), mo month, year INT);
6
7
         gregorian_date:
8
         PROC (julian_day_number INT) RETURNS (date);
9
             DCL j INT := julian_day_number,
10
                  d,m,y INT;
11
             j-:=1_{-}721_{-}119;
12
             y := (4 * j - 1) / 146_097;
13
             j := 4 * j - 1 - 146_097 * y;
14
             d := j / 4;
15
             j := (4 * d + 3) / 1_461;
16
             d := 4 * d + 3 - 1_461 * j;
17
             d := (d + 4) / 4;
18
             m := (5 * d - 3) / 153;
19
             d := 5 * d - 3 - 153 * m;
20
             d := (d + 5) / 5;
21
             y := 100 * y + j;
22
             IF m < 100 THEN m + := 3;
23
                       ELSE m \sim := 9;
24
                              y + := 1;
25
             FI:
26
             RETURN [d, month (m+1), y];
27
         END gregorian_date;
28
29
        julian_day_number:
30
         PROC (d date) RETURNS (INT);
31
             DCL c,y,m INT;
32
             DO WITH d;
33
                 m := NUM (mo)+1;
34
                 IF m>2 THEN m-:=3;
35
                         ELSE m + := 9;
36
                                year - := 1;
37
                 FI;
38
                 c := year/100;
39
                 y := year-100*c;
40
                 RETURN (146_-097*c)/4+(1_-461*y)/4
41
                            +(153+m+c)/5+day+1_721_119;
42
             OD:
43
         END julian_day_number;
         GRANT gregorian_date, julian_day_number;
44
45
     END playing_with_dates;
46
47
     test:
48
     MODULE
49
         SEIZE gregorian_date, julian_day_number;
50
         ASSERT julian_day_number ([ 10,dec,1979 ])=julian_day_number
51
                   (gregorian_date(julian_day_number([ 10,dec,1979 ])));
    END test:
52
```

7. Roman numerals

```
1
     Roman:
 2
     MODULE
 3
         SEIZE n,rn;
 4
         GRANT convert;
 5
         convert:
 6
         PROC () EXCEPTIONS (string_too_small);
 7
             DCL r INT := 0;
 8
             DO WHILE n>=1, 000;
 9
                 rn(r) := 'M';
10
                 n - := 1 - 000;
11
                 r + := 1;
12
             OD:
13
             IF n>500 THEN rn(r) := 'D';
14
                             n - := 500;
15
                             r + := 1;
16
             FI;
17
             DO WHILE n>=100:
18
                 rn(r) := C';
19
                 n - := 100;
20
                 r + := 1;
21
             OD;
22
             IF n > =50 THEN rn(r) := L';
23
                              n - := 50;
24
                              r + := 1;
25
             FI:
26
             DO WHILE n>=10;
27
                 rn(r) := 'X';
28
                 n - := 10;
29
                 r + := 1;
30
             OD:
31
             IF n>=5 THEN rn(r) := V';
32
                             n - := 5;
33
                            r + := 1;
34
             FI:
35
             DO WHILE n>=1;
36
                rn(r) := T';
37
                 n - := 1;
38
                r + := 1;
39
             OD;
40
             RETURN:
41
        END ON (RANGEFAIL): DO FOR i := 0 TO UPPER (rn);
42
                                     rn(i) := '.';
43
                                 OD;
44
                                 CAUSE string_too_small;
45
        END convert;
46
    END Roman;
47
    test:
48
    MODULE
49
        SEIZE convert;
50
        DCL n INT INIT := 1979;
51
        DCL rn CHARS (20) INIT := (20)';
52
        GRANT n,rn;
53
        convert ();
54
        ASSERT rn="MDCCCCLXXVIIII"//(6)';
55
    END test;
```

8. Counting letters in a character string of arbitrary length

```
letter_count:
    MODULE
2
3
        SEIZE max;
4
        DCL letter POWERSET CHAR INIT := ['A' : 'Z'];
5
        count:
6
        PROC (input ROW CHARS (max) IN, output ARRAY ('A':'Z') INT OUT);
7
            output := [(\mathbf{ELSE}) : 0];
8
            DO FOR i := 0 TO UPPER (input ->);
9
                IF input -> (i) IN letter
10
                    THEN
11
                        output (input \rightarrow (i)) + := 1;
12
                II.
13
            OD;
14
        END count;
15
        GRANT count;
16
    END letter_count;
17
    test:
18
    MODULE
19
        SYNMODE results=ARRAY ('A':'Z')INT;
20
        DCL c CHARS (10) INIT := "A-B < ZAA9K'.";
21
        DCL output results;
22
        SYN max=10_000;
23
        GRANT max;
24
        SEIZE count:
25
        count (-> c,output);
26
        ASSERT output=results [('A'):3,('B','K','Z'):1,(ELSE):0];
27
    END test;
```

9. Prime numbers

```
1
    prime:
2
    MODULE
 3
 4
        SYN max = H'7FFF;
5
        NEWMODE number_list =POWERSET INT (2:max);
6
        SYN empty = number_list [];
 7
        DCL sieve number_list INIT := [2:max],
8
              primes number_list INIT := empty;
9
        GRANT primes;
10
        DO WHILE sieve/=empty;
11
              primes OR := [MIN (sieve)];
12
              DO FOR j := MIN (sieve) BY MIN (sieve) TO max;
13
                 sieve - := [i];
14
              OD:
15
        OD;
16
    END prime;
```

10. Implementing stacks in two different ways, transparent to the user

```
1 stack: MODULE
2 NEWMODE element =STRUCT (a INT, b BOOL);
3 stacks_1:
4 MODULE
```

```
5
            SEIZE element;
 6
            SYN max=10_000,min=1;
 7
            DCL stack ARRAY (min: max) element,
 8
                  stackindex INT INIT := min;
 9
10
            push:
11
            PROC (e element) EXCEPTIONS (overflow);
12
                  IF stackindex=max
13
                      THEN CAUSE overflow;
14
                  FI;
15
                  stackindex + := 1;
16
                  stack (stackindex) := e;
17
                  RETURN:
18
             END push;
19
20
             pop:
21
             PROC () EXCEPTIONS (underflow);
22
                  IF stackindex=min
23
                      THEN CAUSE underflow;
24
                  FI;
25
                  stackindex - := 1;
26
                  RETURN;
27
             END pop;
28
29
             elem:
30
             PROC (i INT) RETURNS (element LOC) EXCEPTIONS (bounds);
31
                  IF i<min OR i>max
32
                       THEN CAUSE bounds;
33
                  FI:
34
                  RETURN stack (i);
35
             END elem;
36
             GRANT push, pop, elem;
37
         END stacks_1;
38
39
         stacks\_2:
40
         MODULE
41
             SEIZE element;
42
             NEWMODE cell=STRUCT (pred, succ REF cell, info element);
43
             DCL p,last,first REF cell INIT := NULL;
44
45
             push:
46
             PROC (e element) EXCEPTIONS (overflow);
47
                 p := ALLOCATE (cell) ON
48
                                       (ALLOCATEFAIL) : CAUSE overflow;
49
                                       END:
50
                 IF last=NULL
51
                     THEN first := p;
52
                            last := p;
53
                     ELSE last \rightarrow. succ := p;
54
                           p \rightarrow . pred := last;
55
                           last := p;
56
                 II:
57
                 last ->. info := e;
58
                 RETURN;
59
             END push;
60
61
             pop:
62
             PROC () EXCEPTIONS (underflow);
63
                 IF last=NULL
64
                      THEN CAUSE underflow;
65
                 FI.
```

```
66
                  p := last;
67
                  last := last \rightarrow pred;
68
                 IF last = NULL
69
                      THEN first := NULL;
70
                      ELSE last \rightarrow. succ := NULL;
71
                  FI;
72
                  TERMINATE(p);
73
                  RETURN:
74
             END pop;
75
76
             elem:
77
             PROC (i INT) RETURNS (element LOC) EXCEPTIONS (bounds);
78
                 IF first=NULL
79
                      THEN CAUSE bounds;
80
                 FI:
81
                 p := first;
82
                 DO FOR j := 2 TO i;
83
                     IF p ->. succ=NULL
84
                          THEN CAUSE bounds;
85
                     FI;
86
                     p := p \rightarrow succ;
87
                  OD:
88
                 RETURN p \rightarrow . info;
89
             END elem;
90
91
             /* GRANT push,pop,elem; */
92
         END stacks_2;
93
    END stack:
```

11. Fragment for playing chess

```
1
     chess_fragments:
 2
     MODULE
 3
         NEWMODE piece=STRUCT (color SET (white, black),
 4
                                          kind SET (pawn,rook,knight,bishop,queen,king));
 5
         NEWMODE column=SET (a,b,c,d,e,f,g,h);
 6
         NEWMODE line=INT (1:8);
 7
         NEWMODE square=STRUCT (status SET (occupied, free),
 8
                                           CASE status OF
 9
                                           (occupied): p piece,
10
                                           (free):
11
                                           ESAC);
12
         NEWMODE board=ARRAY (line) ARRAY (column) square;
13
         NEWMODE move=STRUCT (lin_1,lin_2 line,
14
                                          col_1,col_2 column);
15
16
         initialise:
17
         PROC (bd board INOUT);
18
              bd := [(1): [(a,h):
                                   [.status: occupied, .p : [white,rook]].
19
                           (b,g):
                                   [.status: occupied, .p : [white,knight]],
20
                           (c,f):
                                   [.status: occupied, .p : [white,bishop]],
21
                           (d):
                                   [.status: occupied, .p : [white,queen]],
22
                           (e):
                                   [.status: occupied, .p : [white,king]]],
23
                     (2): [(ELSE):[.status: occupied, .p : [white,pawn]]],
24
                     (3:6):[(ELSE):[.status: free]],
25
                     (7): [(ELSE):[.status: occupied, .p : [black,pawn]]],
26
                     (8): [(a,h):
                                 [.status: occupied, .p : [black,rook]],
27
                                   [.status: occupied, .p : [black,knight]],
                           (b,g):
```

```
28
                           (c,f):
                                    [.status: occupied, .p : [black,bishop]],
29
                           (d):
                                    [.status: occupied, .p : [black,queen]],
30
                           (e):
                                    [.status: occupied, .p : [black,king]]]
31
32
             RETURN;
33
         END initialise;
34
         register_ move:
35
         PROC (b board LOC, m move) EXCEPTIONS (illegal):
36
              DCL starting square LOC := b (m.lin_1)(m.col_1),
37
                    arriving square LOC := b (m.lin_2)(m.col_2);
38
              DO WITH m:
39
                  IF starting.status=free THEN CAUSE illegal; FI;
40
                  IF arriving.status/=free THEN
                     IF arriving.p.kind=king THEN CAUSE illegal; FI;
41
42
43
                  CASE starting.p.kind, starting.p.color OF
44
                       (pawn), (white):
45
                      IF col_1 = col_2 AND (arriving.status/=free
46
                          OR NOT (\lim_{z \to \lim_{z \to 0}} 1+1 \text{ OR } \lim_{z \to \lim_{z \to 0}} 1+2 \text{ AND } \lim_{z \to 2} 2=2))
47
                          OR (col_2=PRED (col_1) OR col_2=SUCC (col_1))
48
                          AND arriving.status=free THEN CAUSE illegal; FI;
49
                          IF arriving.status/=free THEN
50
                             IF arriving.p.color=white THEN CAUSE illegal; FI; FI;
51
                       (pawn),(black):
52
                       IF col_1=col_2 AND (arriving.status/=free
5.3
                          OR NOT (\lim_{z \to \lim_{z \to 0}} 1-1 \text{ OR } \lim_{z \to \lim_{z \to 0}} 1-2 \text{ AND } \lim_{z \to 0} 1=7))
                          OR (col_2=PRED (col_1) OR col_2=SUCC (col_1))
54
55
                          AND arriving.status=free THEN CAUSE illegal; FI;
56
                          IF arriving.status/=free THEN
57
                             IF arriving.p.color=black THEN CAUSE illegal; FI; FI;
58
                       (rook),(*):
                       IF NOT ok_rook (b,m)
59
60
                          THEN CAUSE illegal;
61
                       FI;
62
                       (bishop),(*):
63
                       IF NOT ok_bishop (b,m)
64
                          THEN CAUSE illegal;
65
                       FI:
66
                       (queen),(*):
67
                       IF NOT ok_rook (b,m) AND NOT ok_bishop (b,m)
68
                          THEN CAUSE illegal;
69
                       FI,
70
                       (knight),(*):
71
                       IF ABS (ABS (NUM (col_2)-NUM (col_1))
72
                                 -ABS (lin_2-lin_1)) /= 1
73
                          OR ABS (NUM (col_2)-NUM (col_1))
74
                               +ABS (lin_2-lin_1) =/3 THEN CAUSE illegal; FI;
75
                       IF arriving.status/=free THEN
76
                               IF arriving.p.color=starting.p.color THEN
77
                               CAUSE illegal; FI; FI;
78
                       (king),(*):
79
                       IF ABS (NUM (col_2)-NUM (col_1)) > 1
80
                          OR ABS (lin_2 - lin_1) > 1
81
                          OR lin_2=lin_1 AND col_2=col_1 THEN CAUSE illegal; FI;
82
                       IF arriving.status/=free THEN
                          IF arriving.p.color=starting.p.color THEN
83
84
                          CAUSE illegal; FI; FI; /* checking king moving to check not implemented */
85
                   ESAC;
86
              OD;
87
              arriving := starting;
              starting := [.status:free];
```

```
89
             RETURN;
90
         END register_move;
91
         ok_rook:
92
        PROC (b board, m move) RETURNS (BOOL);
             DCL starting square := b (m.lin_1)(m.col_1),
93
94
                   arriving square := b (m.lin_2)(m.col_2);
95
96
             DO WITH m;
97
                 IF NOT (col_2=col_1 OR lin_1=lin_2) THEN RETURN FALSE; FI;
98
                 IF arriving.status/=free THEN
99
                    IF arriving.p.color=starting.p.color THEN;
100
                    RETURN FALSE; FI; FI;
101
                 IF col_1=col_2
102
                    THEN IF lin_1<lin_2
103
                            THEN DO FOR \lim := \lim_{n \to \infty} 1+1 TO \lim_{n \to \infty} 2-1;
                                       IF b (lin)(col_1).status/=free
104
                                           THEN RETURN FALSE;
105
106
107
                                   OD;
108
                            ELSE DO FOR lin := lin_1 - 1 - 1 DOWN TO lin_2 + 1;
109
                                       IF b (lin)(col_1).status/=free
                                           THEN RETURN FALSE;
110
                                        FI:
111
                                   OD;
112
                                 FI:
113
                     ELSIF col_1<col_2
114
                            THEN DO FOR col := SUCC (col_1) TO PRED (col_2);
115
116
                                        IF b (lin_1)(col).status/=free
                                           THEN RETURN FALSE;
117
118
                                        FI:
119
                                    OD:
                            ELSE DO FOR col := SUCC (col_2) DOWN TO PRED (col_1);
120
121
                                        IF b (lin_1)(col).status/=free
                                           THEN RETURN FALSE;
122
123
                                        FI;
124
                                    OD;
125
                  FI:
126
                  RETURN TRUE;
127
              OD:
128
          END ok_rook;
129
          ok_bishop:
          PROC (b board, m move) RETURNS (BOOL);
130
              DCL starting square := b (m.lin_1)(m.col_1),
131
132
                    arriving square := b (m.lin_2)(m.col_2),
133
                    col column;
134
135
              DO WITH m;
136
                    CASE lin_2>lin_1,col_2>col_1 OF
                        (TRUE),(TRUE): col := col_1;
137
                                    DO FOR lin := lin_1 + 1 TO lin_2 - 2 - 1;
138
139
                                            col := SUCC (col);
140
                                            IF b (lin)(col).status/=free
                                                THEN RETURN FALSE;
141
142
                                            FI;
                                    OD:
143
144
                                    IF SUCC (col)/=col_2
                                            THEN RETURN FALSE;
145
146
                                    FI.
                        (TRUE), (FALSE): col := col_1;
147
148
                                    DO FOR lin := lin_{-}1+1 TO lin_{-}2-1;
                                            col := PRED (col);
149
```

```
150
                                           IF b (lin)(col).status/=free
151
                                               THEN RETURN FALSE;
152
                                           FI:
153
                                   OD;
154
                                   IF PRED (col)/=col_2
155
                                           THEN RETURN FALSE;
156
                                   FI;
157
                       (FALSE)_{*}(TRUE)_{*} col := col_{-}1_{*}
158
                                   DO FOR lin := lin_{-}1-1 DOWN TO lin_{-}2+1:
159
                                           col := SUCC (col);
160
                                           IF b (lin)(col).status/=free
161
                                               THEN RETURN FALSE;
162
                                           FI:
163
                                   OD:
164
                                   IF SUCC (col)/=col_2
165
                                           THEN RETURN FALSE;
166
                                   FI;
167
                       (FALSE), (FALSE): col := col_1;
168
                                   DO FOR lin := lin_1 - 1 DOWN TO lin_2 + 1;
169
                                           col := PRED (col);
170
                                           IF b (lin)(col).status/=free
171
                                               THEN RETURN FALSE:
172
                                           FI:
173
                                   OD:
174
                                   IF PRED (col)/=col_2
175
                                           THEN RETURN FALSE;
176
                                   FI;
177
                   ESAC:
178
                   IF arriving.status=free THEN RETURN TRUE;
179
                   ELSE RETURN arriving.p.color/=starting.p.color; FI;
180
              OD:
181
         END ok_bishop;
182
         END chess_fragments;
```

12. Building and manipulating a circularly linked list

```
circular_list:
 2
    MODULE
 3
         handle_list:
 4
         MODULE
 5
             GRANT insert, remove, node;
 6
             NEWMODE node=STRUCT (pred, suc REF node, value INT):
 7
             DCL pool ARRAY (1:1000) node;
 8
             DCL head node := (: NULL, NULL, 0:);
9
10
             insert: PROC (new node);
11
                 /* insert actions */
12
             END insert;
13
14
             remove: PROC ();
15
                 /* remove actions */
16
             END remove;
17
18
             initialize_list:
19
             BEGIN
20
                DCL last REF node := ->head;
21
                DO FOR new IN pool;
22
                     new.pred := last;
```

```
23
                      last->.suc := ->new;
24
                      last := -> new:
25
                      new.value := 0;
26
                  OD:
27
                  head.pred := last;
28
                  last->.suc := ->head;
29
             END initialize_list;
30
31
         END handle_list;
32
         manipulate:
33
         MODULE
34
              SEIZE node, remove, insert;
              DCL node_a node := (: NULL, NULL, 536 :);
35
36
              remove();
37
              remove();
38
              insert(node_a);
39
          END manipulate;
     END circular_list;
40
```

13. A region for managing competing accesses to a resource

```
1
    allocate_resources:
2
    REGION
3
        GRANT allocate, deallocate;
        NEWMODE resource_set = INT (0:9);
4
        DCL allocated ARRAY (resource_set)BOOL := (: (resource_set): FALSE :);
5
6
        DCL resource_ freed EVENT;
7
8
        allocate:
        PROC () RETURNS (resource_set);
9
10
             DO FOR EVER;
11
                 DO FOR i IN resource_set;
12
                     IF NOT allocated(i)
                         THEN
13
                             allocated(i) := TRUE;
14
                             RETURN i;
15
16
                     FI;
17
                 OD;
18
                 DELAY resource_freed;
19
             OD;
20
         END allocate;
21
22
         deallocate:
23
         PROC (i resource_set);
             allocated(i) := FALSE;
24
25
             CONTINUE resource_freed;
26
         END deallocate;
27
28
     END allocate_resources;
```

14. Queuing calls to a switchboard

```
    switchboard:
    MODULE
    /* This example illustrates a switchboard which queues incoming calls
    and feeds them to the operator at an even rate. Every time the
```

```
5
            operator is ready one and only one call is let through. This is
  6
            handled by a call distributor which lets calls through at fixed
  7
            intervals. If the operator is not ready or there are other calls
  8
            waiting, a new call must queue up to wait for its turn. */
  9
          DCL operator_is_ready,
10
               switch_is_closed EVENT;
11
12
          call_distributor:
13
         PROCESS ();
14
              wait:
15
              PROC (x INT);
16
                  /*some wait action*/
17
              END wait;
18
              DO FOR EVER;
19
                  wait(10 /*seconds*/);
20
                  CONTINUE operator_is_ready;
21
              OD;
22
         END call_distributor;
23
24
         call_process:
25
         PROCESS ();
26
             DELAY CASE
27
              (operator_is_ready): /* some actions */;
28
              (switch_is_closed): DO FOR i IN INT (1:100);
29
                                     CONTINUE operator_is_ready;
30
                                     /* empty the queue*/
31
                                OD;
32
             ESAC;
33
         END call_process;
34
35
         operator:
36
         PROCESS ();
37
             DCL time INT;
38
             DO FOR EVER:
39
                 IF time = 1700
40
                      THEN CONTINUE switch_is_closed;
41
                 FI;
42
             OD;
43
         END operator;
44
45
         START call_distributor();
46
         START operator();
47
         DO FOR i IN INT (1:100);
48
             START call_process();
49
         OD:
50
    END switchboard;
```

15. Allocating and deallocating a set of resources

```
1
    definitions:
2
   MODULE
3
   SIGNAL
4
        acquire,
5
        release=(INSTANCE),
6
        congested,
7
        ready,
8
        advance,
        readout=(INT);
```

```
10
         GRANT ALL.
11
     END definitions;
12
     counter_manager:
13
     MODULE
14
     /* To illustrate the use of signals and the receive case, (buffers
15
         might have been used instead) we will look at an example where an
16
         allocator manages a set of resources, in this case a set of
17
         counters. The module is part of a larger system where there are
18
         users, that can request the services of the counter_manager. The
19
         module is made to consist of two process definitions, one for the
20
         allocation and one for the counters. Initiate and terminate
21
         are internal signals sent from the allocator
22
         to the counters. All the other signals are external, being sent
23
         from or to the users. */
24
25
         SEIZE/* external signals */
26
             acquire, release, congested, ready, advance, readout;
27
         SIGNAL initiate = (INSTANCE),
28
                   terminate;
29
         allocator:
30
         PROCESS ();
31
             NEWMODE no_of_counters = INT (1:100);
32
         DCL counters ARRAY (no_of_counters)
33
                                 STRUCT (counter INSTANCE, status SET (busy, idle));
34
         DO FOR each IN counters;
35
             each := (: START counter(), idle :);
36
         OD:
37
         DO FOR EVER;
38
         BEGIN
39
             DCL user INSTANCE;
40
             await_signals:
41
             RECEIVE CASE SET user;
42
             (acquire):
43
                  DO FOR each IN counters;
44
                      DO WITH each;
45
                          IF status = idle
46
                               THEN
47
                                   status := busy;
48
                                   SEND initiate (user) TO counter;
49
                                   EXIT await_signals;
50
                          FI:
51
                      OD:
52
                  OD:
53
                  SEND congested TO user;
54
             (release IN this_counter):
55
                  SEND terminate TO this_counter;
56
                  find_counter:
57
                  DO FOR each IN counters;
58
                      DO WITH each;
59
                          IF this_counter = counter
60
                               THEN
61
                                   status := idle;
62
                                   EXIT find_counter;
63
                          FI:
64
                      OD:
65
                  OD find_counter;
66
             ESAC await_signals;
67
         END;
68
         OD:
         END allocator;
69
70
         counter:
```

```
71
        PROCESS ();
72
            DO FOR EVER;
73
            BEGIN
74
                DCL user INSTANCE,
75
                      count INT := 0;
76
                RECEIVE CASE
77
                    (initiate IN received_user):
78
                        SEND ready TO received_user;
79
                        user := received_user;
80
                ESAC:
81
                work_loop:
82
                DO FOR EVER;
83
                    RECEIVE CASE
84
                        (advance): count + := 1;
85
                        (terminate):
86
                            SEND readout(count) TO user;
87
                            EXIT work_loop;
88
                    ESAC;
89
                OD work_loop;
90
            END.
91
             OD;
92
        END counter;
93
        START allocator();
94
    END counter_manager;
```

16. Allocating and deallocating a set of resources using buffers

```
1
 2
 3
     user_world:
 4
     MODULE
 5
     /* This example is the same as no.15 except that buffers are
 6
          used for communication in stead of signals.
 7
          The main difference is that processes are now identified
 8
          by means of references to local message buffers rather than
 9
          by instance values. There is one message buffer declared
10
         local to each process. There is one set of message types
11
          for each process definition. When started each process must
12
          identify its buffer address to the starting process.
13
          The user_world module sketches some of the environment in
14
          which the counter_manager is used. */
15
16
     SEIZE allocator:
17
     GRANT user_buffers, user_messages,
18
               allocator_messages, allocator_buffers,
19
                counter_messages, counters_buffers;
20
     NEWMODE
21
          user_messages ==
22
              STRUCT (type SET (congested, ready,
23
                         readout, allocator_id),
24
                                      CASE type OF
25
                                          (congested):,
26
                                          (ready): counter REF counters_buffers,
27
                                          (readout): count INT,
28
                                          (allocator_id): allocator REF allocator_buffers
29
                                      ESAC),
30
          user_buffers = BUFFER (1) user_messages,
31
          allocator_messages =
```

```
32
             STRUCT (type SET (acquire, release, counter_id),
33
                        CASE type OF
34
                            (acquire): user REF user_buffers,
35
                            (release,
                            counter_id): counter REF counters_buffers
36
37
                        ESAC),
38
         allocator_buffers = BUFFER (1) allocator_messages,
39
         counter_messages =
40
             STRUCT (type SET (initiate, advance, terminate),
41
                        CASE type OF
42
                            (initiate): user REF user_buffers,
43
                            (advance,
44
                            terminate):
45
                        ESAC),
         counters_buffers = BUFFER (1) counter_messages;
46
47
     DCL user_buffer user_buffers,
48
          allocator_buf REF allocator_buffers,
49
          counter_buf REF counters_buffers;
50
     START allocator(->user_buffer);
51
     allocator_buf := (RECEIVE user_buffer).allocator;
52
     END user_world;
53
     counter_manager:
     MODULE
55
     SEIZE user_buffers, user_messages,
56
            allocator_messages, allocator_buffers,
57
            counter_messages, counters_buffers;
58
     GRANT allocator;
59
60
     allocator:
61
     PROCESS (starter REF user_buffers);
62
         DCL allocator_buffer allocator_buffers;
63
         NEWMODE no_of_counters = INT (1:10);
64
         DCL counters ARRAY (no_of_counters)
65
                                 STRUCT (counter REF counters_ buffers,
66
                                            status SET (busy, idle)),
67
               message allocator_messages;
68
         SEND starter->([allocator_id, ->allocator_buffer]);
69
         DO FOR each IN counters;
70
             START counter(->allocator_buffer);
71
             each := [(RECEIVE allocator_buffer).counter, idle];
72
         OD;
73
         DO FOR EVER;
74
              BEGIN
75
             DCL user REF user_buffers;
76
              message := RECEIVE allocator_buffer;
77
              handle_messages:
78
              CASE message.type OF
79
              (acquire):
80
                  user := message.user;
81
                  DO FOR each IN counters;
82
                      DO WITH each;
83
                          IF status= idle
84
                               THEN status := busy;
                                      SEND counter->([initiate, user]);
85
86
                                      EXIT handle_messages;
87
                          FI:
88
                      OD;
89
                  OD;
90
                  SEND user->([congested]);
91
92
                  SEND message.counter->([terminate]);
```

```
93
                     find_counter:
    94
                     DO FOR each IN counters:
    95
                         DO WITH each;
    96
                             IF message.counter = counter
    97
                                 THEN status := idle;
    98
                                        EXIT find_counter;
    99
                             FI;
   100
                         OD;
   101
                     OD find_counter;
   102
                 (counter_id): ;
   103
                 ESAC handle_messages;
   104
                 END:
   105
             OD:
   106
        END allocator;
   107
        counter:
   108
        PROCESS (starter REF allocator_buffers);
   109
            DCL counter_buffer counters_buffers;
   110
            SEND starter->([counter_id, ->counter_buffer]);
   111
            DO FOR EVER;
   112
                BEGIN
   113
                     DCL user REF user_buffers,
   114
                          count INT := 0,
   115
                          message counter_messages;
                     message := RECEIVE counter_buffer;
   116
   117
                     CASE message.type OF
   118
                         (initiate): user := message.user;
   119
                                  SEND user->([ready, ->counter_buffer]);
   120
                         ELSE/* some error action */
   121
                     ESAC;
   122
                work_loop:
   123
                DO FOR EVER;
   124
                     message := RECEIVE counter_buffer;
   125
                     CASE message.type OF
   126
                         (advance) : count + := 1;
  127
                         (terminate):SEND user->([readout, count]);
   128
                                   EXIT work_loop;
   129
                         ELSE/* some error action */
  130
                    ESAC;
  131
                OD work_loop;
  132
            END:
  133
            OD;
  134
        END counter;
  135
        END counter_manager;
17.
    String scanner1
    1
        string_scanner1: /* This program implements strings by means
    2
                           of packed arrays of characters. */
    3
        MODULE
    4
            SYN
    5
                blanks ARRAY (0:9)CHAR PACK = [(*):' '], linelength = 132;
    6
            SYNMODE
    7
                stringptr = ROW ARRAY (lineindex)CHAR PACK,
    8
                lineindex = INT (0:linelength-1);
    9
   10
        scanner:
   11
        PROC (string stringptr, scanstart lineindex INOUT,
   12
                scanstop lineindex, stopset POWERSET CHAR)
```

```
RETURNS (ARRAY (0:9)CHAR PACK);
13
14
        DCL count INT := 0,
              res ARRAY (0:9)CHAR PACK := blanks;
15
16
        DO
            FOR c IN string->(scanstart:scanstop)
17
            WHILE NOT (c IN stopset);
18
19
                count + := 1;
20
         OD;
21
        IF count>0
22
             THEN
23
                IF count>10
24
                     THEN
25
                         count := 10;
26
                 FI:
                 res(0:count-1) := string->(scanstart:scanstart+count-1);
27
28
         FI:
29
         RESULT res;
30
         IF scanstart+count < scanstop
31
             THEN
32
                 scanstart := scanstart+count+1;
33
         FI;
34
     END scanner;
35
36
     GRANT scanner;
37
38
     END string_scanner1;
```

18. String scanner2

```
string_scanner2: /* This example is the same as no.17 but it uses
1
                       character string instead of packed arrays */
2
3
    MODULE
4
        SYN
             blanks = (10)', linelength = 132;
5
6
        SYNMODE
            stringptr = ROW CHARS (linelength),
7
8
            lineindex = INT (0:linelength-1);
9
10
         scanner:
             PROC (string stringptr, scanstart lineindex INOUT,
11
                    scanstop lineindex, stopset POWERSET CHAR)
12
                    RETURNS (CHARS (10));
13
14
                 DCL count INT := 0;
15
                 DO FOR i := scanstart TO scanstop
                     WHILE NOT (string->(i) IN stopset);
16
                         count + := 1;
17
18
                 OD:
                 IF count > 0
19
20
                     THEN
21
                         IF count > = 10
22
                              THEN
                                  RESULT string->(scanstart UP 10);
23
24
                              ELSE
                                  RESULT string->(scanstart:scanstart+count-1)
25
                                            //blanks(count:9);
26
27
                         FI:
28
                     ELSE
                         RESULT blanks;
29
```

```
30
                  FI:
31
                 IF scanstart+count < scanstop
32
                      THEN
33
                          scanstart := scanstart + count + 1;
34
                  FI:
35
             END scanner;
36
37
         GRANT scanner;
38
39
     END string_scanner2;
```

19. Removing an item from a double linked list

```
1
     queue: MODULE
 2
         SYNMODE info=INT;
 3
         queue_removal:
 4
         MODULE
 5
             SEIZE info;
 6
             GRANT remove;
 7
 8
             PROC (p PTR) RETURNS (info) EXCEPTIONS (EMPTY);
 9
                     /* This procedure removes the item referred to
10
                       by p from a queue and returns the information
11
                       contents of that queue element */
12
                     SYNMODE element = STRUCT (
13
                                 i info POS (0,8:31),
14
                                  prev PTR POS (1,0:15),
15
                                  next PTR POS (1,16:31));
16
                    DCL x REF element LOC := element(p), prev, next PTR;
17
                     prev := x -> .prev;
18
                    next := x -> .next;
19
                     x->.prev, x->.next := NULL:
20
                     RESULT x \rightarrow i;
21
                    p := prev;
22
                     x->.next := next;
23
                    p := next;
24
                    x->.prev := prev;
25
             END remove;
^{26}
         END queue_removal;
27
    END queue;
```

20. Update a record of a file

```
read_modify_write:
 2
     MODULE
 3
 4
       /* this example indicates how the CHILL i/o concepts can be used */
 5
       /* to write an application where a record of a random accessible
 6
       /* file can be updated or added if not yet in use
 7
 8
       NEWMODE
 9
         index_set = INT (1:1000)
10
         record_type = STRUCT (
11
                                   free
                                         BOOL,
12
                                   count INT,
13
                                  name CHARS (20));
```

```
14
15
       DCL
16
         curindex
                           index_set,
                           ASSOCIATION,
17
         file_association
                           ACCESS (index_set) record_type,
18
         record_file
19
         record_buffer
                           record_type;
20
                                                                  /* create association */
21
       ASSOCIATE (file_association, "DSK:RECORDS.DAT");
22
       CONNECT (record_file,file_association,READWRITE);
                                                                  /* connect to file
23
                                                                  /* position record
                                                                                       */
       curindex := 123;
                                                                  /* read the record
24
       READRECORD (record_file,curindex,record_buffer);
                                                                  /* if record is free
25
          IF record_buffer.free
                                                                  /* the claim and
26
            THEN
              record_buffer.free := FALSE
27
                                                                  /* initialize it
28
              record_buffer.count := 0;
              record_buffer.name := "CHILL I/O concept";
29
30
          FI:
                                                                  /* increment its count/
31
       record_buffer.count + := 1;
32
       WRITERECORD (record_file, curindex, record_buffer);
                                                                  /* write the record */
                                                                  /* end the association*/
33
       DISSOCIATE (file_association);
34
35
     END read_modify_write;
```

21. Merge two sorted files

```
1
    merge_sorted_files:
2
    MODULE
3
4
       /* this example shows how two sorted files can be merged into one */
5
       /* new sorted file, where the field 'key' is used for sorting
       /* the old sorted files are deleted after the merging has been done */
6
7
8
       NEWMODE
          record_type = STRUCT (
9
                                    key INT,
10
                                    name CHARS (50));
11
12
13
       DCL
14
         flag
                    BOOL.
15
                    ARRAY (BOOL) ACCESS record_type,
         infiles
16
         outfile
                    ACCESS record_type,
17
                    ARRAY (BOOL) record_type,
         buffers
                    ARRAY (BOOL) CHARS (10) INIT := ["FILE.IN.1", "FILE.IN.2"],
18
         innames
                    CHARS (10) INIT := "FILE.OUT ",
19
         outname
                    ARRAY (BOOL) ASSOCIATION,
20
         inassocs
21
         outassoc
                    ASSOCIATION;
22
23
       /* associate both sorted input files, connect an access to them for input */
       /* and read their first record into a buffer
24
25
26
       \mathbf{D}\mathbf{O}
27
         FOR curfile IN infiles,
28
               curbuffer IN buffers,
29
               curassoc IN inassocs,
30
               curname IN innames;
31
            CONNECT (curfile, ASSOCIATE (curassoc, curname), READONLY);
32
            READRECORD (curfile, curbuffer);
33
       OD:
```

```
34
35
        /* associate the output file, create a file for the association */
36
        /* and connect an access to it for output
37
38
        ASSOCIATE (outassoc.outname):
39
        CREATE (outassoc);
40
        CONNECT (outfile, outassoc, WRITEONLY);
41
        merge_files:
42
          DO FOR EVER
43
44
            /* determine which file, if any at all, to process next*/
45
            /* 'flag' indicates the file
46
47
            CASE OUTOFFILE (infiles(FALSE)),OUTOFFILE (infiles(TRUE)) OF
48
              (TRUE),
                         (TRUE):
                                                            /* both files are empty */
49
                         EXIT merge_files;
50
              (TRUE),
                         (FALSE):
                                                            /* one file is empty
51
                         flag := TRUE;
52
              (FALSE), (TRUE):
                                                            /* one file is empty
53
                         flag := FALSE;
54
              (FALSE),
                         (FALSE):
                                                            /* no file is empty
55
                         flag := buffers(FALSE).key>buffers(TRUE).key;
56
            ESAC;
57
58
                /* output the buffer which currently contains a record with the */
59
                /* smallest value for 'key', fill the buffer with a new record
60
61
                WRITERECORD (outfile, buffers(flag));
62
                READRECORD (infiles(flag), buffers(flag));
63
       OD merge_files:
64
65
       /* delete the input files and close the output file */
66
67
       DO
68
         FOR curassoc IN inassocs;
69
            DELETE (curassoc);
                                                             /* delete the file
70
            DISSOCIATE (curassoc);
                                                             /* and terminate association
71
       OD;
72
       DISSOCIATE (outassoc);
                                                             /* disconnect and terminate
73
74
     END merge_sorted_files;
```

22. Read a file with variable length records

```
variable_length_records:
 2
     MODULE
 3
 4
       /* This example shows how a file which consists of variable length
 5
       /* records can be treated.
 6
       /* The file consists of a number of strings of varying length; the
 7
       /* algorithm will read a string, allocate an appropriate location
 8
       /* for it, and put the reference to this location into a push down list */
 9
10
       NEWMODE
11
          string = CHARS (80),
12
          link_record = STRUCT (
13
                                                   REF link_record,
                                     next_record
14
                                     string_row
                                                   ROW string);
```

```
15
16
       DCL
17
                        REF link\_record INIT := NULL,
         pushdownlist
18
                        INT (1:80),
         length
19
         temporaryrow ROW string,
20
         fileaccess
                        ACCESS string DYNAMIC,
21
                        ASSOCIATION;
         association
                        CHARS (20) VARYING INIT := "INPUT.DATA";
22
         filename
23
                                                               /* associate the input file
                                                                                            */
       ASSOCIATE (association, filename);
24
       CONNECT (fileaccess, association, READONLY);
                                                               /* connect access for input
25
       temporaryrow := READRECORD (fileaccess);
                                                               /* read the first record
26
                                                               /* while not end-of-file
       \mathbf{D}\mathbf{0}
27
         WHILE NOT(OUTOFFILE(fileaccess));
28
           pushdownlist := ALLOCATE (link_record,
                                                               /* get a new link record
                                                                                            */
29
                                 [pushdownlist, NULL]);
                                                               /* and initialize it
           length := 1 + UPPER (temporaryrow->);
30
                                                               /* determine length of string
31
           DO
                                                                                            */
32
              WITH pushdowlist->;
                                                               /* add new string to list
33
                string_row := ALLOCATE (CHARS (length),
                                                               /* allocate space for string
34
                                        temporaryrow->);
                                                               /* and fill it
35
            OD:
                                                               /* get next record in file
36
            temporaryrow := READRECORD (fileaccess);
37
                                                               /* end the association
38
       DISSOCIATE (association);
39
40
     END variable_length_records;
```

23. The use of spec modules

```
1
        /* The examples 23 and 24 are example 8 divided in two pieces. */
2
    letter_count:
3
    SPEC MODULE
4
        /* This is a spec module for the corresponding module in example 8. */
5
        SEIZE max;
6
        PROC (input ROW CHARS (max) IN, output ARRAY ('A':'Z') INT OUT) END;
8
        GRANT count;
9
    END letter_count;
10
    letter_count: REMOTE "example 24";
11
12
    MODULE
13
        /* This is the module 'test' from example 8.
14
        /* It can now be piecewise compiled together with
15
        /* the above spec module
16
        SYNMODE results = ARRAY ('A':'Z') INT;
        DCL c CHARS (10) INIT := "A-B < ZAA9K';
17
        DCL output results;
18
19
         SYN max = 10_{-}000;
20
         GRANT max;
21
         SEIZE count;
         count (-> c, output);
22
23
         ASSERT output = results [(A'):3,(B',K',Z'):1,(ELSE):0];
24
    END test;
```

24. Example of a context

```
CONTEXT
 1
 2
         /* This is a context for the module "letter_count" */
 3
         /* as used in example 23, allowing the piecewise
 4
         /* compilation of "letter_count"
 5
         SYN max = 10_{-}000;
 6
     FOR
 7
     letter_count:
 8
     MODULE
 9
         SEIZE max;
10
         DCL letter POWERSET CHAR INIT := ['A' : 'Z'];
11
         count:
12
         PROC (input ROW CHARS (max) IN, output ARRAY ('A':'Z') INT OUT);
13
             output := [(\mathbf{ELSE}) : 0];
14
             DO FOR i := 0 TO UPPER (input ->);
15
                 IF input -> (i) IN letter THEN
16
                     output (input \rightarrow (i)) + := 1;
17
                 FI;
18
             OD.
19
         END count:
20
         GRANT count;
21
    END letter_count;
```

25. The use of prefixing and remote modules

```
/* This example uses the module 'stack' from example 27 or 28. */
 2
         /* It shows how prefixes can be used to prevent name clashes.
 3
         /* It uses the remote construct to share the source code.
 4
     char_stack:
 5
     MODULE
 6
         SYNMODE element = CHAR;
 7
         GRANT (-> stack ! char) ! ALL;
 8
         stack: SPEC REMOTE "example 29";
 9
         stack: REMOTE
                                  "example 27 or 28";
10
     END char_stack;
11
12
    int_stack:
13
     MODULE
14
         SYNMODE element = INT;
15
         GRANT (-> stack ! int) ! ALL;
16
         stack: SPEC REMOTE "example 29";
17
         stack: REMOTE
                                  "example 27 or 28";
18
    END int_stack;
19
         /* Here 'push', 'pop' and 'element' are visible but
20
         /* with prefixes 'stack! char' and 'stack! int' for
21
         /* the implementations with element = CHAR and */
22
         /* element = INT, respectively.
23
         /* Below are some possibilities of using the granted */
24
         /* names inside modules.
25
    MODULE
26
         SEIZE ALL PREFIXED stack;
27
         DCL c CHAR;
28
         int ! push (123);
29
         char! push ('a');
30
         int ! pop ( );
31
         c = char ! elem (1);
```

```
32 END;
33
34 MODULE
35 SEIZE (stack! int -> stack)! ALL;
36 stack! push (345);
37 stack! pop();
38 END;
```

26. The use of text i/o

```
1
    textio:
2
    MODULE
3
4
        /* This example shows the use of the text i/o features. */
5
6
7
                    ASSOCIATION,
            outfile
8
                    TEXT (80) DYNAMIC,
            output
9
                     INT := 12345,
            size
10
            flag
                     BOOL := FALSE,
                     SET (a,b,c) := b,
11
            set
                     CHARS (5) := "CHILL",
12
            s1
                     CHARS (5) DYNAMIC := "text";
13
            s2
14
                                                         -- associate the output file
15
        ASSOCIATE (outfile,"OUTPUT.DATA");
16
        CREATE (outfile);
                                                         -- create it
        CONNECT (output, outfile, WRITEONLY);
                                                         -- then connect text location
17
                                                         -- 1010
        WRITETEXT (output, "%B%/",10);
18
         WRITETEXT (output, "%C%/", set);
                                                         --b
19
         WRITETEXT (output, "size = %C%/", size);
                                                         --size = 12345
20
         WRITETEXT (output, "%CL6%C i/o%/",s1,s2);
                                                         -- CHILL text i/o
21
         WRITETEXT (output,"flag = %X%C",flag);
                                                         -- flag = FALSE
22
         size := GETTEXTINDEX (output);
                                                         -- 12
23
24
         DISSOCIATE (outfile);
25
    END textio;
```

27. A generic stack

```
/* This example implements a generic stack. Please */
. 2
         /* note that the element mode has been left out.
         /* The element mode is defined in the surroundings. */
3
         /* The context is a virtually introduced context,
4
5
         /* and it has no source.
6
    CONTEXT REMOTE FOR
7
    stack:
8
    MODULE
9
         SEIZE element;
         NEWMODE cell = STRUCT (pred, succ REF cell, info element);
10
11
         DCL p, last, first REF cell INIT := NULL;
12
13
         push:
         PROC (e element) EXCEPTIONS (overflow)
14
             D := ALLOCATE (cell) ON (ALLOCATEFAIL): CAUSE overflow; END;
15
             IF last = NULL THEN
16
17
                 first := p;
18
                 last := p;
```

```
19
              ELSE
20
                  last -> .succ := p;
21
                  p \rightarrow .pred := last;
22
                  last := p;
23
             II.
24
             last \rightarrow .info := e;
25
             RETURN;
26
         END push;
27
28
         pop:
29
         PROC () EXCEPTIONS (underflow)
30
             IF last = NULL THEN
31
                  CAUSE underflow;
32
             II.
33
             p:=last;
34
             last := last -> .pred;
35
             IF last = NULL THEN
36
                 first := NULL;
37
             ELSE
38
                  last \rightarrow .succ := NULL;
39
             FI,
40
             TERMINATE (p);
41
             RETURN:
42
         END pop;
43
44
         elem:
45
         PROC (i INT) RETURNS (element LOC) EXCEPTIONS (bounds)
46
             IF first = NULL THEN
47
                  CAUSE bounds;
48
             FI.
49
             p := first;
50
             DO FOR j := 2 TO i;
51
                 IF p \rightarrow .succ = NULL THEN
52
                      CAUSE bounds;
53
                 FI;
54
                 p := p \rightarrow .succ;
55
             OD;
56
             RETURN p -> .info;
57
         END elem;
58
59
         GRANT push, pop, elem;
60
     END stack;
An abstract data type
 1
         /* This example implements the functionality of example 27 */
2
         /* demonstrating how an abstract data type can be
3
         /* implemented in two different ways in CHILL.
4
     CONTEXT REMOTE FOR
5
     stack:
6
     MODULE
7
         SEIZE element;
8
         SYN max = 10_{-}000, min = 1;
9
         DCL stack ARRAY (min: max) element,
```

10

11

12

13

push:

stackindex INT INIT := min-1;

PROC (e element) EXCEPTIONS (overflow)

IF stackindex = max THEN

```
14
                CAUSE overflow;
15
            FI:
16
            stackindex +:= 1;
17
            stack(stackindex) := e;
18
            RETURN;
19
        END push;
20
        pop:
        PROC () EXCEPTIONS (underflow)
21
22
            IF stackindex = min THEN
23
                CAUSE underflow;
24
            FI;
25
            stackindex-:= 1;
26
            RETURN;
        END pop;
27
28
29
        elem:
30
        PROC (i INT) RETURNS (element LOC) EXCEPTIONS (bounds)
31
            IF i < min \ OR \ i > max \ THEN
32
                CAUSE bounds;
33
            FI:
            RETURN stack(i);
34
35
        END elem;
36
37
        GRANT push, pop, elem;
38
    END stacks;
```

29. Example of a spec module

```
/*This SPEC MODULE defines the interface of example 27 and 28. */
stack: SPEC MODULE

SEIZE element;
push: PROC (e element) EXCEPTIONS (overflow) END;
pop: PROC () EXCEPTIONS (underflow) END;
elem: PROC (i INT) RETURNS (element LOC) EXCEPTIONS (bounds) END;
GRANT push,pop,elem;
END stack;
```

APPENDIX E: DECOMMITTED FEATURES

The features described in the following are not part of the present Recommendation Z200, but were part of the Recommendation Z200, 1984, Red Book, Volume VI — Fascicle VI.12. In the following a brief description is given; for a complete definition of them, refer to the relevant sections of the Z200 1984, that are hereafter mentioned. These features may be supported by an implementation.

1. Free directive (See section 2.6)

A free directive freed the reserved simple name strings specified in the <u>reserved</u> simple name string list so that they could be redefined.

2. Integer modes syntax (See section 3.4.2)

BIN was derived syntax for INT.

3. Set modes with holes (See section 3.4.5)

A set mode defined a set of named or unnamed values. A set mode was a set mode with holes, if and only if the number of its set element names was less than the number of values of the set mode.

4. Procedure modes syntax (See section 3.7)

A result spec without the optional reserved simple name string RETURNS was derived syntax for the result spec with RETURNS.

5. Array modes syntax (See section 3.11.3)

The reserved simple name string ARRAY was optional.

6. Level structure notation (See section 3.11.5)

A level structure mode was derived syntax for a nested structure mode. In the level structure notation the fields were preceded by a level number. If a structure contained fields that were themselves structures or arrays of structures, a hierarchy of structures was formed and a level number could be associated with each field. Instead of writing nested structure modes, it was allowed in the level structure mode to write the level number in the front of the field name.

7. Map reference names (See section 3.11.6)

Map reference names could be used to specify mapping in an implementation defined way.

8. Based declarations (See section 4.1.4)

A based declaration without a <u>bound or free reference location</u> name was derived syntax for a synmode definition statement. A based declaration with a <u>bound or free reference location</u> name defined one or more access names. These names served as an alternative way of accessing a location by dereferencing the reference value contained in the specified reference location. This dereferencing operation was performed each time and only when an access was made via a declared based name.

9. Character string literals (See section 5.2.4.6)

Character string literals were delimited by apostrophe characters. Apart from the printable representation, the hexadecimal representation could be used. Character string literals of length one served as character literals.

10. Addr notation (See section 5.3.8)

ADDR (<location>) was derived syntax for -> <location>.

11. Assignment syntax (See section 6.2)

The = symbol was derived syntax for the := symbol.

12. Case action syntax (See section 6.4)

The range list of a case action could be specified more generally by a <u>discrete</u> mode, and not only by a <u>discrete mode</u> name.

13. Do for action syntax (See section 6.5.2)

The range in the range enumeration of a do-for action could be specified more generally by a <u>discrete</u> mode, and not only by a <u>discrete mode</u> name.

14. Explicit loop counters (See section 6.5.2)

If an access name was visible in the reach where the do action was placed, which was equal to one of the names defined by a loop counters, then the loop counter was explicit; otherwise it was implicit. In the former case, the value of the loop counter was stored into the denoted location just prior to abnormal termination.

A distinction was made between normal and abnormal termination. Normal termination occurred if the evaluation of at least one of the loop counters indicated termination. Abnormal termination occurred if the evaluation of while condition delivered FALSE or if the do action was left by a transfer of control out of it.

15. Call action syntax (See section 6.7)

The reserved simple name string CALL was optional. A call action with CALL was derived from a call action without CALL.

16. RECURSEFAIL exception (See section 6.7)

The RECURSEFAIL exception was caused when a non-recursive procedure called itself recursively.

17. Start action syntax (See section 6.13)

The start action with the **SET** option was derived syntax for the single assignment action: <<u>instance</u> location> := <start expression>

18. Explicit value receive names (See section 6.19)

A receive signal case action and a receive buffer case action could introduce value receive names. If a name was visible in the reach where the receive signal case action was placed, which was equal to one of the names introduced after IN, then the value receive name was explicit; otherwise it was implicit. In the former case, the received value was stored into the denoted location immediately before the execution of the action statement list.

19. Blocks (See section 8.1)

The if action, case action, do action and delay case action were not defined to be blocks.

20. Entry statement (See section 8.4)

A procedure could have multiple entry points by means of entry statements. These statements were considered to be additional procedure definitions. The defining occurrence in the entry statement defined the name of the entry point in the procedure in which reach it was placed. The entry point was determined by the textual position of the entry statement.

21. Register names (See section 8.4)

Register specification could be given in the formal parameter of the procedure and in the result spec. In the pass by value case, it meant that the actual value was contained in the specified register; in the pass by location case, it meant that the (hidden) pointer to the actual location was contained in the specified register. If the specification was in the result spec it meant that the returned value or the (hidden) pointer to the returned location was contained in the specified register.

22. Weakly visible names and visibility statements (See section 10.2.4.3)

A name string NS weakly visible in reach R was said to be seizable by modulion M directly enclosed in R if NS was linked in R to a defining occurrence not surrounded by the reach of M. A name string NS weakly visible in reach R of modulion M was said to be grantable by M if NS was linked in R to a defining occurrence surrounded by R.

23. Seizing by modulion name (See section 10.2.4.5)

If a prefix rename clause in a seize statement had a seize postfix which contained a modulion name string and **ALL**, then the prefix rename clause was equivalent to a set of seize statements, for any name string that was strongly visible in the reach that directly enclosed the modulion in which the seize statement was placed and was seizable by this modulion, and was granted by the modulion attached to the <u>modulion</u> name in the reach directly enclosing the modulion in which the seize statement was placed.

24. Predefined simple name strings (See section C.2)

AND, NOT, OR, REM, MOD, THIS and XOR were predefined simple name strings.

APPENDIX F: COLLECTED SYNTAX

2 PRELIMINARIES

```
<simple name string> ::=
        <letter> { <letter> | <digit> | _ }*
<lr><letter> ::=
        A | B | C | D | E | F | G | H | I | J | K | L | M
       | \ N \ | \ O \ | \ P \ | \ Q \ | \ R \ | \ S \ | \ T \ | \ U \ | \ V \ | \ W \ | \ X \ | \ Y \ | \ Z
       | a | b | c | d | e | f | g | h | i | j | k | l | m
       | n | o | p | q | r | s | t | u | v | w | x | y | z
<digit> ::=
        0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9
<comment> ::=
        <br/>
<br/>
bracketed comment>
       | line-end comment>
<bracketed comment> ::=
        /* <character string> */
cline-end comment> ::=
        -- < character string > < end-of-line >
<character string> ::=
        { <character> }*
<directive clause> ::=
        <> <directive> { , <directive> }* <>
<directive> ::=
        <implementation directive>
<name> ::=
        <name string>
<name string> ::=
        <simple name string>
       | | prefixed name string>
cprefixed name string> ::=
        cprefix> ! <simple name string>
cprefix> ::=
        <simple prefix> { ! <simple prefix> }*
<simple prefix> ::=
        <simple name string>
<defining occurrence> ::=
        <simple name string>
<defining occurrence list> ::=
        <defining occurrence> { , <defining occurrence> }*
<field name> ::=
        <simple name string>
< field name defining occurrence> ::=
        <simple name string>
< field name defining occurrence list> ::=
        < field name defining occurrence> { , < field name defining occurrence> }*
<exception name> ::=
        <simple name string>
       <text reference name> ::=
        <simple name string>
```

3 MODES AND CLASSES

```
<mode definition> ::=
         <defining occurrence list> = <defining mode>
<defining mode> ::=
         <mode>
<synmode definition statement> ::=
        SYNMODE < mode definition > { , < mode definition > }*;
<newmode definition statement> ::=
        NEWMODE < mode definition > { , < mode definition > }*;
<mode> ::=
        [ READ ] < non-composite mode>
       | [ READ ] < composite mode>
<non-composite mode> ::=
        <discrete mode>
       | <powerset mode>
        <reference mode>
        procedure mode>
        <instance mode>
        <synchronisation mode>
        <input-output mode>
       | <timing mode>
<discrete mode> ::=
        <integer mode>
       | <boolean mode>
        <character mode>
        <set mode>
       | <range mode>
<integer mode> ::=
        < integer mode name>
<br/>
<br/>
boolean mode> ::=
        <<u>boolean mode</u> name>
<character mode> ::=
        < character mode name>
<set mode> ::=
        SET (\langle set \ list \rangle)
       <set mode name>
<set list> ::=
        <numbered set list>
       | <unnumbered set list>
<numbered set list> ::=
        <numbered set element> { , <numbered set element> }*
<numbered set element> ::=
        <defining occurrence> = <integer literal expression>
<unnumbered set list> ::=
        <set element> { , <set element> }*
<set element> ::=
        <defining occurrence>
<range mode> ::=
        < discrete mode name> ( < literal range> )
       | RANGE ( < literal range > )
       | BIN ( < integer literal expression> )
       < range mode name>
teral range> ::=
        lower bound> : <upper bound>
```

```
<lower bound> ::=
       < discrete literal expression>
<upper bound> ::=
       < discrete literal expression>
<powerset mode> ::=
       POWERSET < member mode>
      | < powerset mode name>
<member mode> ::=
       <discrete mode>
<reference mode> ::=
       <br/>
<br/>
bound reference mode>
      | <free reference mode>
      <re><row mode></re>
<bound reference mode> ::=
       REF < referenced mode>
      | < bound reference mode name>
<referenced mode> ::=
       <mode>
<free reference mode> ::=
        < free reference mode name>-
<row mode> ::=
       ROW < string mode>
       ROW < array mode>
       ROW < variant structure mode>
      <re> < row mode name>
cprocedure mode> ::=
        [EXCEPTIONS (<exception list>)][RECURSIVE]
      procedure mode name>
<parameter list> ::=
        <parameter spec> { , <parameter spec> }*
<parameter spec> ::=
        <mode> [ <parameter attribute> ]
<parameter attribute> ::=
       IN | OUT | INOUT | LOC [ DYNAMIC ]
<result spec> ::=
        RETURNS ( < mode> [ < result attribute> ] )
<result attribute>::=
        [NONREF] LOC [DYNAMIC]
<exception list> ::=
        <exception name> { , <exception name> }*
<instance mode> ::=
        <instance mode name>
<synchronisation mode> ::=
        <event mode>
       <buffer mode>
<event mode> ::=
        EVENT [ ( < event length > ) ]
       | < event mode name >
<event length> ::=
        < integer literal expression>
<buffer mode> ::=
        BUFFER [ ( < buffer length> ) ] < buffer element mode>
       < buffer mode name>
```

```
<br/>
<br/>
buffer length> ::=
         <integer literal expression>
<br/>
<br/>buffer element mode> ::=
        < mode >
<input-output mode> ::=
         <association mode>
        <access mode>
        <text mode>
<association mode> ::=
        <association mode name>
<access mode> ::=
        ACCESS [ ( <index mode> ) ] [ <record mode> [ DYNAMIC ] ]
       <access mode name>
<record mode> ::=
        <mode>
<index mode> ::=
        <discrete mode>
       literal range>
<text mode> ::=
        TEXT ( <text length> ) [ <index mode> ] [ DYNAMIC ] .
<text length> ::=
        < integer literal expression>
<timing mode> ::=
        <duration mode>
       | <absolute time mode>
<duration mode> ::=
        <<u>duration mode</u> name>
<absolute time mode> ::=
        <a href="mailto:absolute time mode">absolute time mode name></a>
<composite mode> ::=
        <string mode>
        <array mode>
        <structure mode>
<string mode> ::=
        <string type> ( <string length> ) [ VARYING ]
       parameterised string mode>
       <string mode name>
cparameterised string mode> ::=
        <origin string mode name> ( <string length> )
       parameterised string mode name>
<origin string mode name> ::=
        <string mode name>
<string type> ::=
        BOOLS
       CHARS
<string length> ::=
        < integer literal expression>
<array mode> ::=
        ARRAY ( <index mode> { , <index mode> }* )
        <element mode> { <element layout> }*
        <parameterised array mode>
      <array mode name>
<parameterised array mode> ::=
        <origin array mode name> ( <upper index> )
```

```
parameterised array mode name>
<origin array mode name> ::=
        <array mode name>
<upper index> ::=
        < discrete literal expression>
<element mode> ::=
        <mode>
<structure mode> ::=
        STRUCT ( < field > { , < field > }* )
       | <parameterised structure mode>
       <structure mode name>
<field> ::=
        <fixed field>
       | <alternative field>
<fixed field> ::=
        < field name defining occurrence list> < mode> [ < field layout> ]
<alternative field> ::=
         CASE [ < tag \ list > ] \ OF
         <variant alternative> { , <variant alternative> }*
        [ ELSE [ < variant field> { , < variant field> }* ] ] ESAC
<variant alternative> ::=
        [ <case label specification> ]: [ <variant field> { , <variant field> }* ]
<tag list> ::=
         < tag field name> \{ , < tag field name> \}*
<variant field> ::=
         < field name defining occurrence list> < mode> [ < field layout> ]
cparameterised structure mode> ::=
         <origin variant structure mode name> ( teral expression list> )
       | parameterised structure mode name>
<origin variant structure mode name> ::=
         <<u>variant structure mode</u> name>
literal expression list> ::=
         < <u>discrete literal</u> expression> { , < <u>discrete literal</u> expression> }*
<element layout> ::=
         PACK | NOPACK | <step>
<field layout> ::=
         PACK | NOPACK | <pos>
\langle step \rangle ::=
         STEP (<pos>[, <step size>])
<pos> ::=
         POS ( <word> , <start bit> , <length> )
       | POS ( < word> [ , < start bit> [ : < end bit> ] ] )
<word> ::=
         < integer literal expression>
<step size> ::=
         < integer literal expression>
<start bit> ::=
         < integer literal expression>
<end bit> ::=
         < integer literal expression>
< length> ::=
         < integer literal expression>
```

```
4 LOCATIONS AND THEIR ACCESSES
<declaration statement> ::=
         DCL < declaration > { , < declaration > }*;
<declaration> ::=
         <location declaration>
       | <loc-identity declaration>
<location declaration> ::=
         <defining occurrence list> <mode> [ STATIC ] [ <initialisation> ]
<initialisation> ::=
         <reach-bound initialisation>
       | < lifetime-bound initialisation >
<reach-bound initialisation> ::=
         <assignment symbol> <value> [ <handler> ]
lifetime-bound initialisation> ::=
        INIT <assignment symbol> < constant value>
<loc-identity declaration> ::=
         <defining occurrence list> <mode> LOC [ DYNAMIC ]
         <assignment symbol> <location> [ <handler> ]
<location> ::=
        <access name>
       <dereferenced bound reference>
       | <dereferenced free reference>
        <dereferenced row>
        <string element>
        <string slice>
        <array element>
        <array slice>
        <structure field>
        <location procedure call>
        <location built-in routine call>
       | <location conversion>
<access name> ::=
        <<u>location</u> name>
       < loc-identity name>
        < location enumeration name>
       < location do-with name>
<dereferenced bound reference> ::=
        < bound reference primitive value> -> [ < mode name> ]
<dereferenced free reference> ::=
        < free reference primitive value> -> < mode name>
<dereferenced row> ::=
        < row primitive value> ->
<string element> ::=
        < string location> ( < start element> )
<start element> ::=
        < integer expression>
<string slice> ::=
        <string location> ( <left element> : < right element> )
       | <string location> ( <start element> UP <slice size> )
<left element> ::=
        < integer expression>
<ri>definition </ri>
        <integer expression>
<slice size> ::=
        <integer expression>
```

```
<array element> ::=
        <array location> ( <expression list> )
<expression list> ::=
        <expression> { , <expression> }*
<array slice> ::=
        <array location> ( <lower element> : <upper element> )
       | <array location> ( <first element> UP <slice size> )
<lower element> ::=
        <expression>
<upre><upre>upper element> ::=
        <expression>
<first element> ::=
        <expression>
<structure field> ::=
        < structure location> . < field name>
<location procedure call> ::=
         < location procedure call>
<location built-in routine call> ::=
         < location built-in routine call>
clocation conversion> ::=
         < mode name > ( < static mode location > )
5 VALUES AND THEIR OPERATIONS
<synonym definition statement> ::=
        SYN <synonym definition> { , <synonym definition> }*;
<synonym definition> ::=
         <defining occurrence list> [ <mode> ] = <constant value>
cprimitive value> ::=
         clocation contents>
        <value name>
        teral>
        <tuple>
        <value string element>
        <value string slice>
        < value array element>
        <value array slice>
        <value structure field>
        <expression conversion>
        <value procedure call>
        < value built-in routine call>
        <start expression>
        <zero-adic operator>
        cparenthesised expression>
<location contents> ::=
         <location>
<value name> ::=
         <synonym name>
       | <<u>value enumeration</u> name>
       | <<u>value do-with</u> name>
       | <<u>value receive</u> name>
       <general procedure name>
< literal > ::=
         <integer literal>
       | <boolean literal>
       | <character literal>
```

```
| <set literal>
        | <emptiness literal>
        <character string literal>
       | <bit string literal>
<integer literal> ::=
         <decimal integer literal>
         <br/>
<br/>
dinary integer literal>
         <octal integer literal>
         <hexadecimal integer literal>
<decimal integer literal> ::=
         [ \{ D \mid d \} ' ] \{ < digit > | _ \}^+
<binary integer literal> ::=
         {B \mid b}'{0 \mid 1 \mid \_}^+
<octal integer literal> ::=
         \{O \mid o\}'\{\langle octal \ digit \rangle \mid \_\}^+
<hexadecimal integer literal> ::=
         \{H \mid h\} '\{ < hexadecimal digit> | _{-} \}^{+}
<hexadecimal digit> ::=
         <digit> | A | B | C | D | E | F | a | b | c | d | e | f
<octal digit> ::=
         0 | 1 | 2 | 3 | 4 | 5 | 6 | 7
<boolean literal> ::=
         <br/>
<br/>
boolean literal name>
<character literal> ::=
         '<character> | <control sequence> '
<set literal> ::=
         <set element name>
<emptiness literal> ::=
         <emptiness literal name>
<character string literal> ::=
         " { < non-reserved character> | < quote> | < control sequence> } "
<quote> ::=
<control sequence> ::=
          (<<u>integer literal</u> expression> { , <<u>integer literal</u> expression> }* )
       <br/>
<br/>
bit string literal> ::=
         <br/>
<br/>
dinary bit string literal>
       < < ctal bit string literal>
       | <hexadecimal bit string literal>
<binary bit string literal> ::=
         \{B \mid b\} ' \{0 \mid 1 \mid \_\}^* '
<octal bit string literal> ::=
         { O | o } '{ < octal digit> | _ }* '
<hexadecimal bit string literal> ::=
         { H | h } '{ < hexadecimal digit> | _ }* '
<tuple> ::=
         [ < mode name > ] (: { < powerset tuple > |
         <array tuple> | <structure tuple> } :)
<powerset tuple> ::=
         [{ <expression> | <range>} { , { <expression> | <range> } }*]
<range> ::=
         <expression> : <expression>
```

```
<array tuple> ::=
        <unlabelled array tuple>
       <labelled array tuple>
<unlabelled array tuple> ::=
        <value> { , < value> }*
<labelled array tuple> ::=
         <case label list> : <value> { , <case label list> : <value> }*
<structure tuple> ::=
         <unlabelled structure tuple>
       | <labelled structure tuple>
<unlabelled structure tuple> ::=
         <value> \{ , <value> \}*
<labelled structure tuple> ::=
         <field name list> : <value> { , <field name list> : <value> }*
<field name list> ::=
          <field name> { , . <field name> }*
< value string element> ::=
         <string primitive value> ( <start element> )
< value string slice> ::=
         < string primitive value> ( < left element> : < right element> )
       | <string primitive value> ( <start element> UP <slice size> )
<value array element> ::=
         <array primitive value> ( <expression list> )
<value array slice> ::=
         <array primitive value> ( <lower element> : <upper element> )
       <array primitive value> ( <first element> UP <slice size> )
<value structure field> ::=
         < structure primitive value> . < field name>
<expression conversion> ::=
         < mode name > ( < expression > )
<value procedure call> ::=
         <value procedure call>
<value built-in routine call> ::=
         < value built-in routine call>
<start expression> ::=
         START < process name > ( [ < actual parameter list > ] )
<zero-adic operator> ::=
         THIS
cparenthesised expression> ::=
         ( <expression> )
< value> ::=
         <expression>
       | <undefined value>
<undefined value> ::=
       | < undefined synonym name>
<expression> ::=
         <operand-0>
        | <conditional expression>
<conditional expression> ::=
       | IF < boolean expression > < then alternative >
         <else alternative> FI
        | CASE < case selector list > OF { < value case alternative > }+
         [ ELSE < sub expression> ] ESAC
```

```
<then alternative> ::=
        THEN <sub expression>
<else alternative> ::=
        ELSE < sub expression>
       ELSIF < boolean expression>
        <then alternative> <else alternative>
<sub expression> ::=
        <expression>
< value case alternative> ::=
        <case label specification> : <sub expression> ;
<operand-0> ::=
        <operand-1>
       | <sub operand-0> { OR | ORIF | XOR } < operand-1>
<sub operand-0> ::=
        <operand-0>
<operand-1> ::=
        <operand-2>
       | <sub operand-1> { AND | ANDIF } < operand-2>
<sub operand-1> ::=
        <operand-1>
<operand-2> ::=
        <operand-3>
       <sub operand-2> <operator-3> <operand-3>
<sub operand-2> ::=
        <operand-2>
<operator-3> ::=
        <relational operator>
       | < membership operator >
       powerset inclusion operator>
<relational operator> ::=
        = |/= | > | >= | < | <=
<membership operator> ::=
powerset inclusion operator> ::=
        <= |>= | < | >
<operand-3> ::=
        <operand-4>
       | <sub operand-3> <operator-4> <operand-4>
<sub operand-3> ::=
        <operand-3>
<operator-4> ::=
        <arithmetic additive operator>
       <string concatenation operator>
       | <powerset difference operator>
<arithmetic additive operator> ::=
        + |-
<string concatenation operator> ::=
cpowerset difference operator> ::=
<operand-4> ::=
        <operand-5>
      | <sub operand-4> <arithmetic multiplicative operator> <operand-5>
<sub operand-4> ::=
```

```
<operand-4>
<arithmetic multiplicative operator> ::=
        * | / | MOD | REM
<operand-5> ::=
        [ <monadic operator> ] <operand-6>
<monadic operator> ::=
        - NOT
      <string repetition operator>
<string repetition operator> ::=
        ( < integer literal expression > )
<operand-6> ::=
        <referenced location>
       < receive expression>
       | <pri>primitive value>
<referenced location> ::=
        -> < location>
<receive expression> ::=
        RECEIVE < buffer location>
6 ACTIONS
<action statement> ::=
        [ <defining occurrence> : ] <action> [ <handler> ] [ <simple name string> ];
       <module>
        <spec module>
       <context module>
<action> ::=
        <br/>bracketed action>
       <assignment action>
        <call action>
        <exit action>
        <return action>
        <result action>
         <goto action>
         <assert action>
         <empty action>
         <start action>
        <stop action>
        <delay action>
         <continue action>
         <send action>
        <cause action>
<bracketed action> ::=
         <if action>
         <case action>
         <do action>
         <br/>
<br/>
begin-end block>
         <delay case action>
        <receive case action>
        | <timing action>
 <assignment action> ::=
         <single assignment action>
        | <multiple assignment action>
 <single assignment action> ::=
         <location> <assignment symbol> <value>
        | <location> <assigning operator> <expression>
```

```
<multiple assignment action> ::=
         <location> { , <location> }+ <assignment symbol> <value>
 <assigning operator> ::=
         <closed dyadic operator> <assignment symbol>
 <closed dyadic operator> ::=
         OR | XOR | AND
        | <powerset difference operator>
         <arithmetic additive operator>
        <arithmetic multiplicative operator>
        <string concatenation operator>
<assignment symbol> ::=
<if action> ::=
         IF < boolean expression> < then clause> [ < else clause> ] FI
<then clause> ::=
         THEN <action statement list>
<else clause> ::=
         ELSE <action statement list>
       | ELSIF < boolean expression > < then clause > [ < else clause > ]
<case action> ::=
         CASE < case selector list > OF [ < range list > ; ] { < case alternative > } +
         [ ELSE <action statement list> ] ESAC
<case selector list> ::=
         < <u>discrete</u> expression> { , < <u>discrete</u> expression> }*
<range list> ::=
         < discrete mode name> { , < discrete mode name> }*
<case alternative> ::=
         <case label specification> : <action statement list>
<do action> ::=
        DO [ <control part> ; ] <action statement list> OD
<control part> ::=
         <for control> [ <while control> ]
       <while control>
       < with part>
<for control> ::=
        FOR { <iteration> { , <iteration> }* | EVER }
<iteration> ::=
         < value enumeration>
       | <location enumeration>
<value enumeration> ::=
        <step enumeration>
       <range enumeration>
       | powerset enumeration>
<step enumeration> ::=
        cloop counter> <assignment symbol>
         <start value> [ <step value> ] [ {f DOWN} ] <end value>
<loop counter> ::=
        <defining occurrence>
<start value> ::=
        <<u>discrete</u> expression>
<step value> ::=
        BY < integer expression>
<end value> ::=
        TO < <u>discrete</u> expression>
```

```
<range enumeration> ::=
        <loop counter> [ DOWN ] IN < discrete mode name>
cpowerset enumeration> ::=
        <loop counter> [ DOWN ] IN < powerset expression>
<location enumeration> ::=
        <loop counter> [ DOWN ] IN <composite object>
<composite object> ::=
        <array location>
        <array expression>
        <string location>
       <string expression>
<while control> ::=
        WHILE < boolean expression>
<with part> ::=
        WITH < with control> { , < with control> }*
<with control> ::=
        <structure location>
       | < structure primitive value>
<exit action> ::=
        EXIT < label name>
<call action> ::=
        call>
       | <built-in routine call>
call> ::=
        ([ <actual parameter list>])
<actual parameter list> ::=
        <actual parameter> { , <actual parameter> }*
<actual parameter> ::=
        < value>
       | <location>
<br/>
<br/>
built-in routine call> ::=
        < built-in routine name> ([ < built-in routine parameter list> ])
<br/>
<br/>
built-in routine parameter list> ::=
        <built-in routine parameter> { , <built-in routine parameter> }*
<br/>
<br/>
built-in routine parameter> ::=
        < value>
       | <location>
       | < non-reserved name > [ ( < built-in routine parameter list > ) ]
<return action> ::=
        RETURN [ < result> ]
<result action> ::=
        RESULT < result>
<result> ::=
        <value>
       | <location>
<goto action> ::=
        GOTO < label name>
<assert action> ::=
        ASSERT < boolean expression>
<empty action> ::=
        < empty >
< empty > ::=
```

```
<cause action> ::=
         CAUSE < exception name >
<start action> ::=
         <start expression>
<stop action> ::=
         STOP
<continue action> ::=
         CONTINUE < event location>
<delay action> ::=
         DELAY < <u>event</u> location> [ < priority> ]
<priority> ::=
         PRIORITY < integer literal expression>
<delay case action> ::=
         DELAY CASE [SET < instance location> [ < priority> ]; | < priority> ; ]
         { < delay alternative > }+
<delay alternative> ::=
         ( <event list> ): <action statement list>
<event list> ::=
         < <u>event</u> location> { , < <u>event</u> location> }*
<send action> ::=
         <send signal action>
       <send buffer action>
<send signal action> ::=
         SEND \leq ignal name> [ (\leq value> { , \leq value> }* )]
         [ TO < instance primitive value> | | < priority> |
<send buffer action> ::=
         SEND < buffer location> ( < value> ) [ < priority> ]
<receive case action> ::=
         <receive signal case action>
       <receive buffer case action>
<re>ceive signal case action> ::=
         RECEIVE CASE [ SET < instance location> ; ]
         { < signal receive alternative> }+
         [ ELSE <action statement list> ] ESAC
<signal receive alternative> ::=
         ( < signal name > [ IN < defining occurrence list > ] ) : < action statement list >
<re>ceive buffer case action> ::=
        RECEIVE CASE [ SET < instance location> ; ]
         { <buffer receive alternative> }+
         [ ELSE <action statement list> ]
        ESAC
<buffer receive alternative> ::=
         ( < buffer location > IN < defining occurrence > ) : < action statement list >
< CHILL built-in routine call> ::=
         < CHILL simple built-in routine call>
        < CHILL location built-in routine call>
       | <CHILL value built-in routine call>
< CHILL simple built-in routine call> ::=
         <terminate built-in routine call>
        <io simple built-in routine call>
       < timing simple built-in routine call>
< CHILL location built-in routine call> ::=
         <io location built-in routine call>
```

```
< CHILL value built-in routine call> ::=
        NUM ( < discrete expression > )
        PRED ( < discrete expression > )
        SUCC ( < discrete expression > )
        ABS ( <integer expression> )
        CARD ( < powerset expression > )
        MAX ( < powerset expression > )
        MIN ( < powerset expression > )
        SIZE ( { <location> | <mode argument> } )
        UPPER ( <upper lower argument> )
        LOWER ( <upper lower argument> )
        LENGTH ( < length argument> )
        <allocate built-in routine call>
        <io value built-in routine call>
       <time value built-in routine call>
<mode argument> ::=
         <<u>mode</u> name>
        <array mode name> ( <expression> )
        < string mode name > ( < integer expression > )
        <variant structure mode name> ( <expression list> )
<upper lower argument> ::=
         <array location>
        <array expression>
         <array mode name>
         <string location>
         <string expression>
         <string mode name>
         < discrete location>
        | < discrete expression>
        | < discrete mode name>
<length argument> ::=
         <string location>
       | < string expression>
<allocate built-in routine call> ::=
         GETSTACK ( < mode argument > [ , < value > ] )
        | ALLOCATE ( < mode argument > [ , < value > ] )
<terminate built-in routine call> ::=
         TERMINATE ( < reference primitive value > )
7 INPUT AND OUTPUT
<io value built-in routine call> ::=
         <association attr built-in routine call>
        <isassociated built-in routine call>
        | <access attr built-in routine call>
        | < readrecord built-in routine call>
        | <gettext built-in routine call>
<io simple built-in routine call> ::=
         <dissociate built-in routine call>
         <modification built-in routine call>
         <connect built-in routine call>
         <disconnect built-in routine call>
         <writerecord built-in routine call>
        <text built-in routine call>
        <settext built-in routine call>
 <io location built-in routine call> ::=
         <associate built-in routine call>
 <associate built-in routine call> ::=
```

```
ASSOCIATE ( < association location > [ , < associate parameter list > ] )
 <isassociated built-in routine call> ::=
         ISASSOCIATED (<association location>)
 <associate parameter list> ::=
         <associate parameter> { , <associate parameter> }*
<associate parameter> ::=
         <location>
        < value>
<dissociate built-in routine call> ::=
         DISSOCIATE ( < association location> )
<association attr built-in routine call> ::=
         EXISTING (<association location>)
         READABLE ( < association location > )
         WRITEABLE ( < association location > )
         INDEXABLE ( < association location > )
         SEQUENCIBLE ( < association location> )
        | VARIABLE ( < association location > )
<modification built-in routine call> ::=
         CREATE ( < association location> )
         DELETE ( < association location> )
        | MODIFY ( < association location > [ , < modify parameter list > ] )
<modify parameter list> ::=
         <modify parameter> { , <modify parameter> }*
<modify parameter> ::=
         < value>
       | <location>
<connect built-in routine call> ::=
         CONNECT ( <transfer location> , <association location> ,
         <usage expression> [ , <where expression> [ , <index expression> ] ] )
<transfer location> ::=
         <aecess location>
       | < text location>
<usage expression> ::=
         <expression>
<where expression> ::=
         <expression>
<index expression> ::=
         <expression>
<disconnect built-in routine call> ::=
         DISCONNECT ( < transfer location > )
<access attr built-in routine call> ::=
         GETASSOCIATION ( < transfer location > )
       | GETUSAGE ( < transfer location > )
        OUTOFFILE ( < transfer location > )
<readrecord built-in routine call> ::=
         READRECORD ( < access location > [ , < index expression > ]
        [, <store location>])
<writerecord built-in routine call> ::=
         WRITERECORD ( < access location > [ , < index expression > ] ,
         <write expression> )
<store location> ::=
        < static mode location>
<write expression> ::=
        <expression>
```

```
<text built-in routine call> ::=
        READTEXT ( < text io argument list> )
       WRITETEXT ( < text io argument list> )
<text io argument list> ::=
        <text argument> [ , <index expression> ] ,
        <format argument> [ , <io list> ]
<text argument> ::=
        < text location>
        < character string location>
        < character string expression>
<format argument> ::=
        < character string expression>
<io list> ::=
        <io list element> { , <io list element> }*
<io list element> ::=
        <value argument>
       | <location argument>
<location argument> ::=
        < discrete location>
       <string location>
< value argument> ::=
        < discrete expression>
       | <<u>string</u> expression>
<format control string> ::=
        [ <format text> ] { <format specification> [ <format text> ] }*
<format text> ::=
        { < non-percent character> | < percent> }
<percent> ::=
        % %
<format specification> ::=
        % [ <repetition factor> ] <format element>
<repetition factor> ::=
        { < digit > }^+
<format element> ::=
        <format clause>
       | <parenthesised clause>
<format clause> ::=
        <control code> [ % . ]
<control code> ::=
        <conversion clause>
        <editing clause>
       <io clause>
<parenthesised clause> ::=
        (<format control string> %)
<conversion clause> ::=
        <conversion code> { <conversion qualifier> }*
        [ <clause width> ]
<conversion code> ::=
        B \mid O \mid H \mid C
<conversion qualifier> ::=
        L | E | P < character >
<clause width> ::=
        { < digit > }^+ \mid V
<editing clause> ::=
```

```
<editing code> [ <clause width> ]
<editing code> ::=
         X \mid < \mid > \mid T
<io clause> ::=
         <io code>
<io code> ::=
         / | - | + | ? | ! | =
<gettext built-in routine call> ::=
         GETTEXTRECORD ( < text location > )
         GETTEXTINDEX ( < text location> )
         GETTEXTACCESS (\overline{\langle text | location \rangle})
       \mid EOLN (< \underline{text} \ location > )
<settext built-in routine call> ::=
         SETTEXTRECORD ( < text location> , < character string location> )
       | SETTEXTINDEX ( < text location > , < integer expression > )
       | SETTEXTACCESS ( < text location > , < access location > )
8 EXCEPTION HANDLING
<handler> ::=
         ON { <on-alternative> }* [ ELSE <action statement list> ] END
<on-alternative> ::=
         (<exception list>): <action statement list>
   TIME SUPERVISION
<timing action> ::=
         <relative timing action>
       | <absolute timing action>
       <cyclic timing action>
<relative timing action> ::=
         AFTER < duration primitive value> [ DELAY ] IN
         <action statement list> <timing handler> END
<timing handler> ::=
         TIMEOUT <action statement list>
<absolute timing action> ::=
         AT < absolute time primitive value > IN
         <action statement list> <timing handler> END
<cyclic timing action> ::=
         CYCLE < duration primitive value > IN
         <action statement list> END
<time value built-in routine call> ::=
        <duration built-in routine call>
       | <absolute time built-in routine call>
<duration built-in routine call> ::=
        MILLISECS ( < integer expression > )
       | SECS ( < integer expression> )
        MINUTES ( < integer expression > )
       | HOURS ( < integer expression > )
       | DAYS ( < integer expression > )
<absolute time built-in routine call> ::=
        ABSTIME ([[[[( < year expression>, ] < month expression>, ]
        <day expression> , ] <hour expression> , ]
        <minute expression> , ] <second expression> ] )
<year expression> ::=
```

```
<integer expression>
<month expression> ::=
        <integer expression>
<day expression> ::=
        < integer expression>
<hour expression> ::=
        <integer expression>
<minute expression> ::=
        <integer expression>
<second expression> ::=
        <integer expression>
<timing simple built-in routine call> ::=
        WAIT ()
       | EXPIRED ()
       INTTIME (<absolute time primitive value>, [ [ [ < year location>
        <month location>, ] <day location>, ]
        <hour location> , ] <minute location> , ]
        <second location> )
<year location> ::=
        <integer location>
<month location> ::=
        <integer location>
<day location> ::=
        < integer location>
<hour location> ::=
        <integer location>
<minute location> ::=
        < integer location>
<second location> ::=
        < integer location>
10 PROGRAM STRUCTURE
<begin-end body> ::=
        <data statement list> <action statement list>
c body> ::=
        <data statement list> <action statement list>
cess body> ::=
        <data statement list> <action statement list>
<module body> ::=
         { <data statement> | <visibility statement> | <region> |
         <spec region> }* <action statement list>
<region body> ::=
         { <data statement> | <visibility statement> }*
<spec module body> ::=
         { <quasi data statement> | < visibility statement> |
         <spec module> | <spec region> }*
<spec region body> ::=
         { <quasi data statement> | < visibility statement> }*
<context body> ::=
         { <quasi data statement> | <visibility statement> |
         <spec module> | <spec region> }*
 <action statement list> ::=
         { <action statement> }*
```

```
<data statement list> ::=
        { <data statement> }*
<data statement> ::=
        <declaration statement>
       <definition statement>
<definition statement> ::=
        <synmode definition statement>
        <newmode definition statement>
        <synonym definition statement>
        cedure definition statement>
        cess definition statement>
        <signal definition statement>
       |<empty>;
<br/>
<br/>
begin-end block> ::=
        BEGIN < begin-end body > END
cprocedure definition statement> ::=
        <defining occurrence> : cedure definition>
        [ <handler> ] [ <simple name string> ];
cedure definition> ::=
        PROC ([ <formal parameter list> ]) [ <result spec> ]
        c body> END
<formal parameter list> ::=
        <formal parameter> { , <formal parameter> }*
<formal parameter> ::=
        <defining occurrence list> < parameter spec>
cedure attribute list> ::=
        [ <generality> ] [ RECURSIVE ]
<generality> ::=
        GENERAL
        SIMPLE
       INLINE
cprocess definition statement> ::=
        <defining occurrence> : cess definition>
        [ <handler> ] [ <simple name string> ];
cess definition> ::=
       PROCESS ([ < formal parameter list> ]) < process body> END
<module> ::=
        [ <context list> ] [ <defining occurrence> : ]
        MODULE [ BODY ] < module body > END
       [ <handler> ] [ <simple name string> ];
      <remote modulion>
<region> ::=
        [ <context list> ] [ <defining occurrence> : ]
       REGION [BODY] < region body > END
       [ <handler> ] [ <simple name string> ];
      <remote modulion>
cprogram> ::=
       { < module > | < spec module > | < region > | < spec region > }+
<remote modulion> ::=
       [ <simple name string> : ] REMOTE < piece designator> ;
<remote spec> ::=
       [ <simple name string> : ] SPEC REMOTE <piece designator> ;
<re>mote context> ::=
       CONTEXT REMOTE < piece designator >
```

```
[ <context body> ] FOR
<context module> ::=
       CONTEXT MODULE REMOTE < piece designator > ;
<piece designator> ::=
        <character string literal>
       <text reference name>
      | <empty>
<spec module> ::=
        <simple spec module>
      | <module spec>
      | <remote spec>
<simple spec module> ::=
       [ <context list> ] [ <simple name string> : ] SPEC MODULE
        <spec module body> END [ <simple name string> ];
<module spec> ::=
        [ <context list> ] <simple name string> : MODULE SPEC
        <spec module body> END [ <simple name string> ];
<spec region> ::=
        <simple spec region>
       <region spec>
      | <remote spec>
<simple spec region> ::=
        [ <context list> ] [ <simple name string> : ] SPEC REGION
        <spec region body> END [ <simple name string> ];
<region spec> ::=
       [ <context list> ] <simple name string> : REGION SPEC
        <spec region body> END [ <simple name string> ];
<context list> ::=
        <context> { <context> }*
      <remote context>
<context> ::=
       CONTEXT < context body > FOR
<quasi data statement> ::=
        <quasi declaration statement>
      | <quasi definition statement>
<quasi declaration statement> ::=
       DCL < quasi declaration > { , < quasi declaration > }*;
<quasi declaration> ::=
        <quasi location declaration>
      | <quasi loc-identity declaration>
<quasi location declaration> ::=
        < defining occurrence list> < mode> [ STATIC ]
<quasi loc-identity declaration> ::=
        <defining occurrence list> < mode>
       LOC [NONREF] [DYNAMIC]
<quasi definition statement> ::=
        <synmode definition statement>
       <newmode definition statement>
       <synonym definition statement>
       <quasi synonym definition statement>
       <quasi procedure definition statement>
       <quasi process definition statement>
       <quasi signal definition statement>
       |<empty>;
<quasi synonym definition statement> ::=
```

```
SYN <quasi synonym definition> { , <quasi synonym definition> }*;
<quasi synonym definition> ::=
        <defining occurrence list> { <mode> = [ <constant value> ] |
        [ < mode > ] = < \underline{literal} \ expression >  }
<quasi procedure definition statement> ::=
        <defining occurrence> : PROC ([ <quasi formal parameter list> ] )
        [ <result spec> ] [ EXCEPTIONS ( <exception list> ) ]
        cedure attribute list> END [ <simple name string> ];
<quasi formal parameter list> ::=
        <quasi formal parameter> { , <quasi formal parameter> }*
<quasi formal parameter> ::=
        <simple name string> { , <simple name string> }* 
<quasi process definition statement> ::=
        <defining occurrence> : PROCESS ([ <quasi formal parameter list> ] )
        END [ <simple name string> ];
<quasi signal definition statement> ::=
        SIGNAL < quasi signal definition > { ,< quasi signal definition > }*;
<quasi signal definition> ::=
        <defining occurrence> [ = (<mode> { , <mode> }* ) ] [ TO ]
11 CONCURRENT EXECUTION
<signal definition statement> ::=
        SIGNAL < signal definition > { , < signal definition > }*;
<signal definition> ::=
        <defining occurrence> [ = (<mode> { , <mode> }* ) ] [ \mathbf{TO} <process name> ]
12 GENERAL SEMANTIC PROPERTIES
<visibility statement> ::=
        <grant statement>
      <seize statement>
cprefix rename clause> ::=
        ( <old prefix> -> <new prefix> )! <postfix>
<old prefix> ::=
        <prefix>
      <empty>
<new prefix> ::=
        <prefix>
      | <empty>
<postfix> ::=
        <seize postfix> { , <seize postfix> }*
      | <grant postfix> { , <grant postfix> }*
<grant statement> ::=
        GRANT prefix rename clause> { , <prefix rename clause> }* ;
      | GRANT < grant window > [ < prefix clause > ];
<grant window> ::=
        <grant postfix> { , <grant postfix> }*
<grant postfix> ::=
        <name string>
        < newmode name string> < forbid clause>
      |[<prefix>!] ALL
cprefix clause> ::=
        PREFIXED [ < prefix> ]
```

```
<forbid clause> ::=
          FORBID { < forbid name list> | ALL }
<forbid name list> ::=
          ( < field name > { , < field name > }* )
<seize statement> ::=
          \mathbf{SEIZE} < \! \mathsf{prefix} \ \mathsf{rename} \ \mathsf{clause} \! > \big\{ \ , < \! \mathsf{prefix} \ \mathsf{rename} \ \mathsf{clause} \! > \big\}^* \ ;
        | SEIZE < seize window > [ < prefix clause > ];
<seize window> ::=
          <seize postfix> { , <seize postfix> }*
<seize postfix> ::=
          <name string>
        | [ < prefix > ! ] ALL
<case label specification> ::=
          <case label list> { , <case label list> }*
<case label list> ::=
          ( <case label> \{ , <case label> \}^* )
        | <irrelevant>
<case label> ::=
          < discrete literal expression>
         | literal range>
         | < discrete mode name>
        | ELSE
<irrelevant> ::=
          (*)
```

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<arithmetic multiplicative="" operator=""></arithmetic>	5.3.7	72	72,76
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<array slice=""></array>	4.2.9	46	41
<array tuple=""></array>	5.2.5	56	56
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<pre><binary integer="" literal=""></binary></pre>	5.2.4.2	53	53
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<directive></directive>	2.2	8	8,53,113,114
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<pre><disconnect built-in="" call="" routine=""></disconnect></pre>	2.6	10	
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<else alternative=""></else>	5.3.2	67	67
<else clause=""></else>	6.3	77	77
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