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| ITU Logo | INTERNATIONAL TELECOMMUNICATION UNION  **TELECOMMUNICATION STANDARDIZATION SECTOR**  STUDY PERIOD 2017-2020 | | FG-AI4H-M-018-A03 | |
| **ITU-T Focus Group on AI for Health** | |
| **Original: English** | |
| **WG(s):** | | Plenary | E-meeting, 28-30 September 2021 | |
| **DOCUMENT** | | | | |
| **Source:** | | TG-Outbreaks Topic Driver | | |
| **Title:** | | Att.3 – Presentation (TG-Outbreaks) | | |
| **Purpose:** | | Discussion | | |
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| **Abstract:** | This document contains a rendering of the live presentation delivered at Meeting M on the progress of TG-Outbreaks. |

# TG-Outbreaks, Meeting M[¶](#TG-Outbreaks,-Meeting-M)

In [1]:

from itertools import product

import matplotlib.pyplot as plt

import numpy as np

import pandas as pd

import seaborn as sns

from IPython.display import Image

from matplotlib.patches import Rectangle

from scipy.stats import multivariate\_normal, norm

from sklearn import metrics

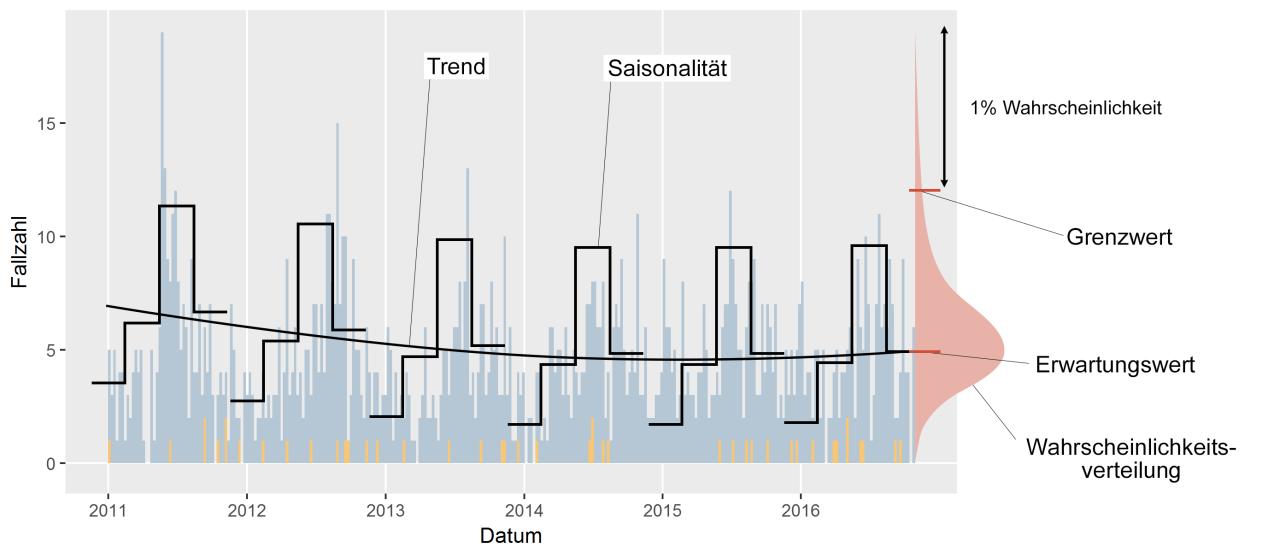
from scorer.scorer import EpiMetrics, Score

## Problem statement[¶](#Problem-statement)

In [2]:

Image("farrington.jpeg")

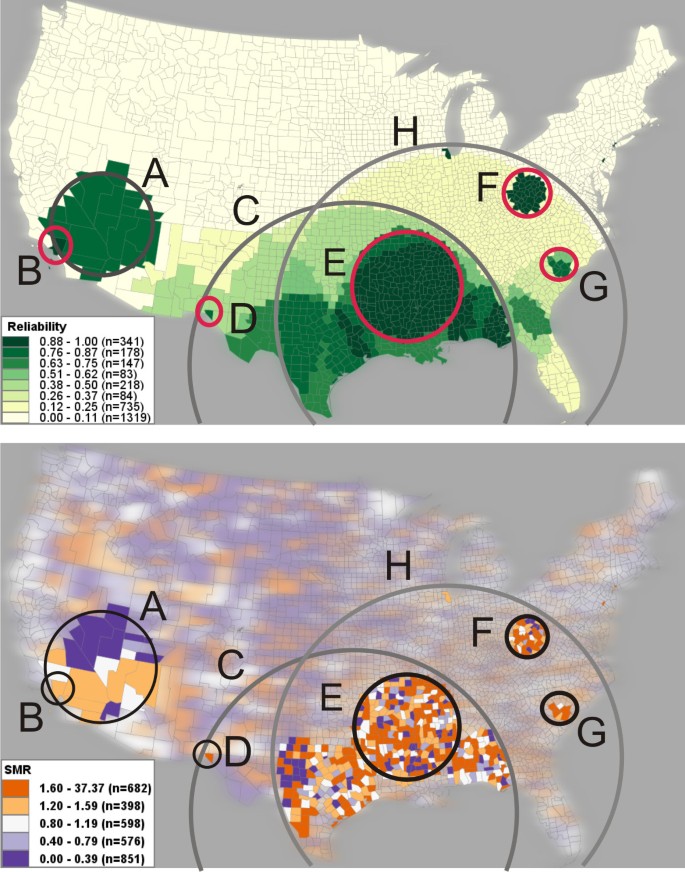
Out[2]:



In [3]:

Image("12942\_2008\_Article\_251\_Fig4\_HTML.jpg")

Out[3]:



## Our suggestions[¶](#Our-suggestions)

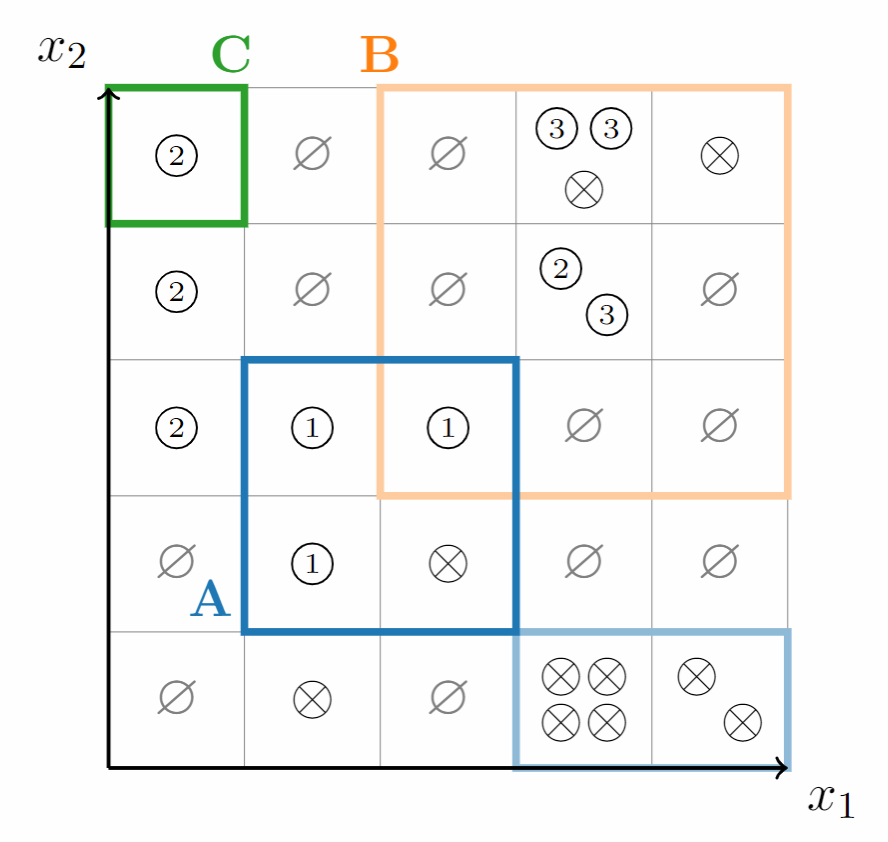
$$p(d\_i|x) = n(d\_i,x) / \sum\_{l} n(d\_l,x)$$$$\hat{p}(d\_i|x) = \sum\_j \hat{p}(d\_i|s\_j,x)\, \hat{p}(s\_j|x)$$

## Data[¶](#Data)

In [4]:

Image("base.PNG")

Out[4]:



In [5]:

cases = pd.read\_csv("tests/data/paper\_example/cases\_long.csv")

cases

Out[5]:

|  | **x1** | **x2** | **data\_label** | **value** |
| --- | --- | --- | --- | --- |
| **0** | 0.0 | 0.0 | one | 0 |
| **1** | 0.0 | 1.0 | one | 0 |
| **2** | 0.0 | 2.0 | one | 0 |
| **3** | 0.0 | 3.0 | one | 0 |
| **4** | 0.0 | 4.0 | one | 0 |
| **...** | ... | ... | ... | ... |
| **95** | 4.0 | 0.0 | endemic | 2 |
| **96** | 4.0 | 1.0 | endemic | 0 |
| **97** | 4.0 | 2.0 | endemic | 0 |
| **98** | 4.0 | 3.0 | endemic | 0 |
| **99** | 4.0 | 4.0 | endemic | 1 |

100 rows × 4 columns

In [6]:

signals = pd.read\_csv("tests/data/paper\_example/signals\_long.csv")

signals

Out[6]:

|  | **x1** | **x2** | **signal\_label** | **value** |
| --- | --- | --- | --- | --- |
| **0** | 0.0 | 0.0 | w\_A | 0.0 |
| **1** | 0.0 | 1.0 | w\_A | 0.0 |
| **2** | 0.0 | 2.0 | w\_A | 0.0 |
| **3** | 0.0 | 3.0 | w\_A | 0.0 |
| **4** | 0.0 | 4.0 | w\_A | 0.0 |
| **...** | ... | ... | ... | ... |
| **70** | 4.0 | 0.0 | w\_C | 0.0 |
| **71** | 4.0 | 1.0 | w\_C | 0.0 |
| **72** | 4.0 | 2.0 | w\_C | 0.0 |
| **73** | 4.0 | 3.0 | w\_C | 0.0 |
| **74** | 4.0 | 4.0 | w\_C | 0.0 |

75 rows × 4 columns

## Score[¶](#Score)

In [7]:

s = Score(cases, signals)

C:\Users\AbboodA\Documents\github\score-time\_series\_and\_scan\_statistics\scorer\scorer.py:128: UserWarning: w\_endemic is missing and is being imputed.

warn("w\_endemic is missing and is being imputed.")

C:\Users\AbboodA\Documents\github\score-time\_series\_and\_scan\_statistics\scorer\scorer.py:132: UserWarning: w\_non\_case is missing and is being imputed.

warn("w\_non\_case is missing and is being imputed.")

In [8]:

s.\_eval\_df()

Out[8]:

|  | **x1** | **x2** | **d\_i** | **p(d\_i)** | **p^(d\_i)** |
| --- | --- | --- | --- | --- | --- |
| **0** | 0.0 | 0.0 | one | 0.0 | 0.000000 |
| **1** | 0.0 | 1.0 | one | 0.0 | 0.000000 |
| **2** | 0.0 | 2.0 | one | 0.0 | 0.000000 |
| **3** | 0.0 | 3.0 | one | 0.0 | 0.000000 |
| **4** | 0.0 | 4.0 | one | 0.0 | 0.333333 |
| **...** | ... | ... | ... | ... | ... |
| **120** | 4.0 | 0.0 | non\_case | 0.0 | 0.000000 |
| **121** | 4.0 | 1.0 | non\_case | 1.0 | 1.000000 |
| **122** | 4.0 | 2.0 | non\_case | 1.0 | 0.500000 |
| **123** | 4.0 | 3.0 | non\_case | 1.0 | 0.500000 |
| **124** | 4.0 | 4.0 | non\_case | 0.0 | 0.000000 |

125 rows × 5 columns

In [9]:

def plot\_grid(series, title):

ax = sns.heatmap(

series.values.reshape(5, -1).T,

linewidth=2,

cmap="RdPu",

cbar=False,

annot=True,

)

ax.add\_patch(

Rectangle(

(0, 4),

1,

1,

fill=False,

lw=4,

color="green",

)

)

ax.add\_patch(

Rectangle(

(1, 1),

2,

2,

fill=False,

lw=4,

color="blue",

)

)

ax.add\_patch(

Rectangle(

(3, 0),

2,

1,

fill=False,

lw=4,

color="blue",

alpha=0.5,

)

)

ax.add\_patch(

Rectangle(

(2, 2),

3,

3,

fill=False,

lw=4,

color="orange",

alpha=0.5,

)

)

ax.set\_title(title)

ax.set\_ylim(0, 5)

ax.set\_xlim(0, 5)

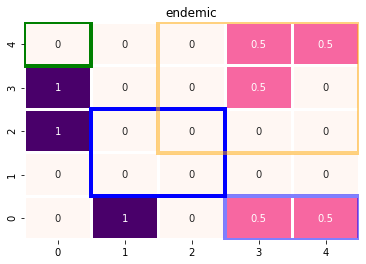
return ax

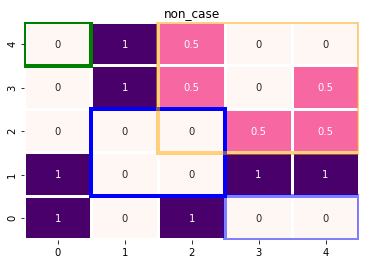
In [10]:

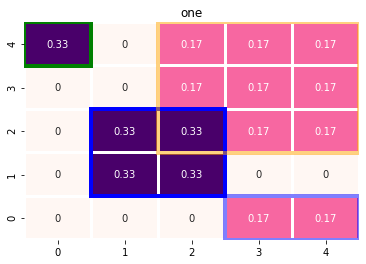
for datalabel in s.\_p\_hat\_di().d\_i.unique():

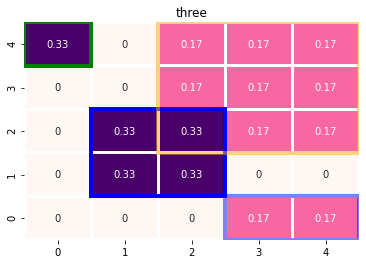
plot\_grid(s.\_p\_hat\_di().query("d\_i==@datalabel").loc[:, ["p^(d\_i)"]], datalabel)

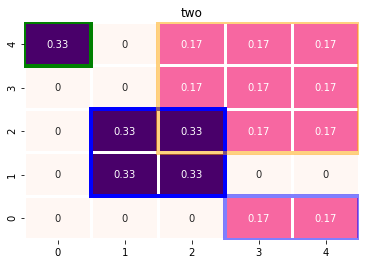
plt.show()











In [11]:

s.calc\_score(metrics.f1\_score)

Out[11]:

0.5175213675213676

In [12]:

s.calc\_score(metrics.f1\_score, weighted=True)

Out[12]:

0.7006081525312294

In [13]:

s.calc\_score(metrics.brier\_score\_loss)

Out[13]:

0.168

In [14]:

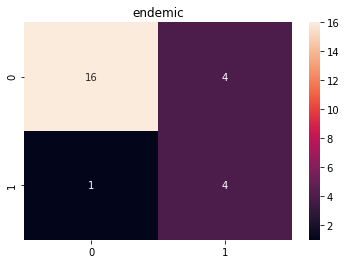
conf\_mats = s.class\_based\_conf\_mat()

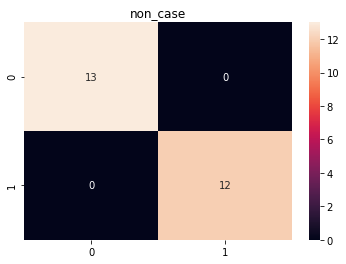
for k, v in conf\_mats.items():

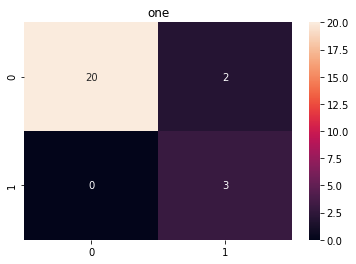
sns.heatmap(v, annot=True)

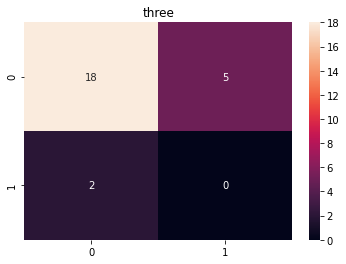
plt.title(k)

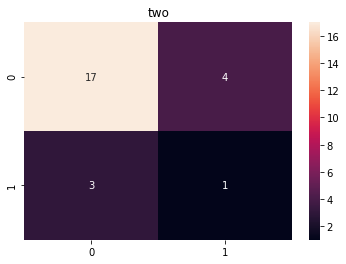
plt.show()











In [15]:

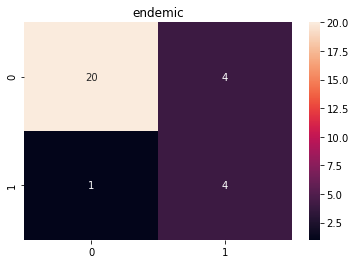
conf\_mats = s.class\_based\_conf\_mat(weighted=True)

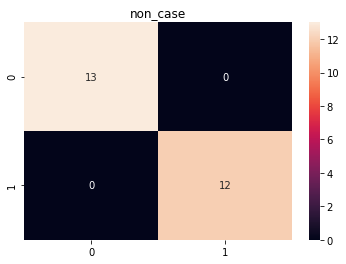
for k, v in conf\_mats.items():

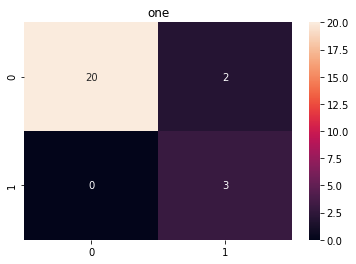
sns.heatmap(v, annot=True)

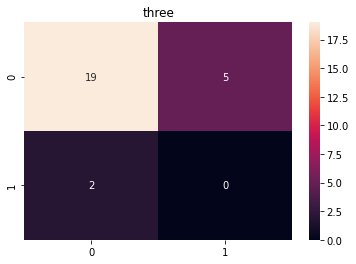
plt.title(k)

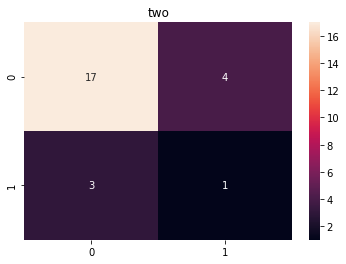
plt.show()











## Epidemiological metrics[¶](#Epidemiological-metrics)

* Timeliness
* Large cluster over small cluster
* Spatially precises over broad determination

In [16]:

e = EpiMetrics(cases, signals)

C:\Users\AbboodA\Documents\github\score-time\_series\_and\_scan\_statistics\scorer\scorer.py:128: UserWarning: w\_endemic is missing and is being imputed.

warn("w\_endemic is missing and is being imputed.")

C:\Users\AbboodA\Documents\github\score-time\_series\_and\_scan\_statistics\scorer\scorer.py:132: UserWarning: w\_non\_case is missing and is being imputed.

warn("w\_non\_case is missing and is being imputed.")

In [17]:

e.timeliness("x1", 2)

Out[17]:

data\_label

one 0.0

three 0.0

two 1.0

dtype: float64

In [18]:

e.timeliness("x2", 1)

Out[18]:

data\_label

one 0.0

three 0.0

two 0.0

dtype: float64

In [19]:

e.gauss\_weighting(["x1", "x2"])

Out[19]:

|  | **data\_label** | **weight** | **x1** | **x2** |
| --- | --- | --- | --- | --- |
| **0** | endemic | 0.111419 | 0 | 0 |
| **1** | endemic | 0.081214 | 0 | 1 |
| **2** | endemic | 0.026621 | 0 | 2 |
| **3** | endemic | 0.005112 | 0 | 3 |
| **4** | endemic | 0.002094 | 0 | 4 |
| **...** | ... | ... | ... | ... |
| **120** | two | 0.001080 | 4 | 0 |
| **121** | two | 0.013104 | 4 | 1 |
| **122** | two | 0.058643 | 4 | 2 |
| **123** | two | 0.096651 | 4 | 3 |
| **124** | two | 0.058643 | 4 | 4 |

125 rows × 4 columns

In [20]:

two\_d = multivariate\_normal([2, 2], [0.5, 0.5])

x, y = np.meshgrid(np.arange(0,5, 1), np.arange(0,5, 1))

two\_d2 = multivariate\_normal([3, 2], [0.5, 0.5])

x2, y2 = np.meshgrid(np.arange(0,5, 1), np.arange(0,5, 1))

two\_d3 = multivariate\_normal([4, 4], [0.5, 0.5])

x3, y3 = np.meshgrid(np.arange(0,5, 1), np.arange(0,5, 1))

pos = np.dstack((x, y))

pos2 = np.dstack((x2, y2))

pos3 = np.dstack((x3, y3))

z = np.zeros(np.shape(two\_d.pdf(pos)))

for p, pdf in zip([ pos3,pos, pos2,], [ two\_d3,two\_d, two\_d2,]):

tmp = pdf.pdf(p)

z += tmp

z = (z - np.min(z))/np.ptp(z) # Optional

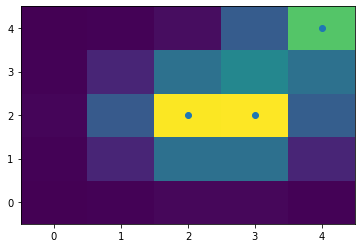
fig2 = plt.figure()

ax2 = fig2.add\_subplot(111)

ax2.pcolormesh(x, y, z, shading="auto")

plt.scatter([2, 3, 4], [2, 2, 4])

plt.show()



In [21]:

weights = []

for i in range(0,5):

weights.append(np.append(np.zeros(2), np.ones(3)))

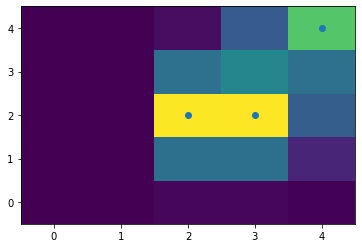
fig2 = plt.figure()

ax2 = fig2.add\_subplot(111)

ax2.pcolormesh(x, y, np.stack(weights, axis=0) \* z, shading="auto")

plt.scatter([2, 3, 4], [2, 2, 4])

plt.show()



In [22]:

mean = [2, 1, 2]

cov = [[2,0, 0], [0,2,0] , [0,0,2]]

three\_d = multivariate\_normal(mean, cov)

mean2 = [2, 1, 3]

three\_d2 = multivariate\_normal(mean2, cov)

mean3 = [2, 3, 3]

three\_d3 = multivariate\_normal(mean3, cov)

c = [three\_d.pdf(t) + three\_d2.pdf(t) + three\_d3.pdf(t) for t in product(range(5), repeat=3)]

x = [t[0] for t in product(range(5), repeat=3)]

y = [t[1] for t in product(range(5), repeat=3)]

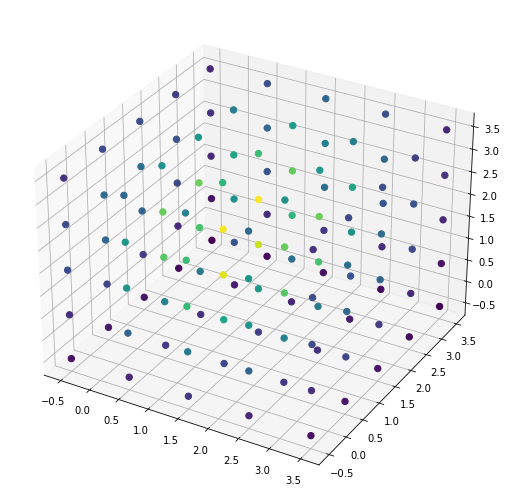
z = [t[2] for t in product(range(5), repeat=3)]

ax = plt.axes(projection='3d')

ax.scatter3D(np.array(x)-0.5, np.array(y)-0.5, np.array(z)-0.5, c=c, s=40, depthshade=False)

fig = plt.gcf()

fig.set\_size\_inches(9, 9);



In [23]:

cond = np.array([True if t[0]>=2 else False for t in product(range(5), repeat=3) ])

c = (c - np.min(c))/np.ptp(c)

ax = plt.axes(projection='3d')

ax.scatter3D(np.array(x), np.array(y), np.array(z), c=np.where(cond, c, 0), s=40, depthshade=False)

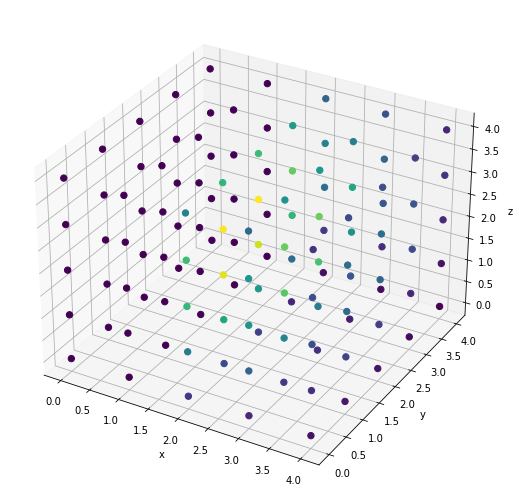
ax.set\_xlabel("x")

ax.set\_ylabel("y")

ax.set\_zlabel("z")

fig = plt.gcf()

fig.set\_size\_inches(9, 9);



In [ ]: