

# CSAE standards and CAICV Activities Update

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Standard Engineer
2022.09



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01 Introduction of C-SAE and CAICV

02 | CAICV Activity and Research Project

03 CSAE Standards

# **C-SAE**

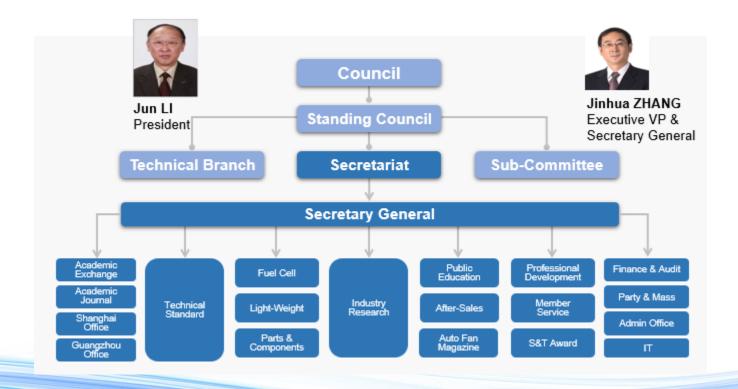


- China Society of Automotive Engineers (China-SAE or CSAE), a national academic organization, was founded in 1963, the secretariat is set up in Beijing.
- CSAE main services include academic communication, automotive policy research, collaborative innovation, talent training and technical standards establishment.

Individual members: 70,000+

Registered members: 110,000+

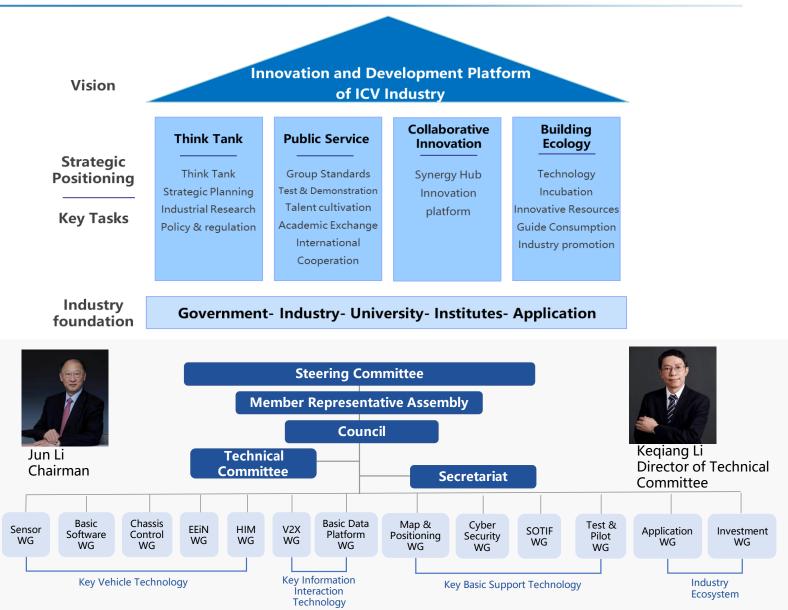
Unit members: 1,900+



# **CAICV**



- China Industry Innovation Alliance for the Intelligent and Connected Vehicles (CAICV) was initiated by China SAE and the China Association of Automobile Manufacturers (CAAM), with the support of MIIT on June 12, 2017.
- CAICV has more than 500 members, including companies, universities, and institutes from the automotive, telecommunication, transportation, and internet industries.
- CAICV has 13 working groups for different technical fields.





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# **CSAE Standards**

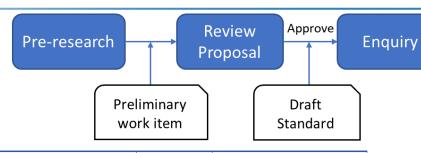


**Publish** 

Published

Standard

**CSAE** Standard Research Process



Nie	Curre		Current	Future Stage	
No	WG	Standard Name	Stage	Enquiry	Publish
7		Technical Requirement of Scenario Database and Simulation Testing for V2X Communication Application	Proposal Approved	2022/10	2023/01
8	Basic Data	T/CSAE 211-2021 Security Requirements for Data Sharing of Intelligent and Connected Vehicles	Published		
13	Basic Data	Technical Requirements of Regional Cloud Application of IOV Based on Public Communications Network	Standard Reviewed		
9	Platform	ICV Cloud Control System Part 1: System Composition and Infrastructure Platform Architecture	Proposal Approved	2022/07	2022/12
10	Platform	ICV Cloud Control System Part 2: Vehicle-Cloud Data Exchange Specification	Proposal Approved	2022/07	2022/12
11		ICV Cloud Control System Part 3: Road- Cloud Data Exchange Specification	Proposal Approved	2022/07	2022/12
12		ICV Cloud Control System Part 5: Platform Service Scenario Specification	Proposal Approved	2022/07	2022/12

Public

Notice

Standard

Under

Publication

Approve

Review

Standard

No	WG	Chandard Name	Current	Future Stage	
No		Standard Name	Stage	Enquiry	Publish
1	V2X	Cooperative Intelligent Transportation System—Vehicular Communication Application Layer Specification And Data Exchange Standard (Phase I)	Published	/	/
2	V2X	Cooperative Intelligent Transportation System—Vehicular Communication Application Layer Specification And Data Exchange Standard (Phase II)	Published	/	/
3	V2X	Data Exchange Standard For High Level Automated Driving Vehicle Based On Cooperative Intelligent Transportation System	Published	/	/
4	V2X	LTE-Based Vehicular Communication—Direct Communication System Roadside Unit Technical Requirements	Published	/	/
5	V2X	Test and Evaluation Methods For V2X System Warning Application Function of Intelligent And Connected Vehicles	Published	/	/
6	V2X	Collaborative Intelligent Transportation Systems—Application Layer Interaction Technical Requirements Part 1: Intention and Cooperation	Proposal Approved	2022/9	2023/01

# **CSAE Standards**



# ☐ Standards of Test & Pilot WG, Innovation & Application WG

No	WG Standard Name	Current	Future Stage		
No	WG	Standard Name	Stage	Enquiry	Publish
1	Test & Pilot	Cooperative Intelligent Transportation System—Technical Specifications of C- V2X Equipments Access to Vehicle-Road Collaborative Cloud Control System	Published	/	/
2	LIDCT X DIINT	Intelligent and Connected Vehicle — Test Field Design Technical Specification	Published	/	/
3	Test & Pilot	Technical specifications of intelligent and connected vehicles public road test supervision system	Published	/	/
4	Test & Pilot	Intelligent and Connected Vehicles—— Field Test Methods and Requirements for Automated Driving Functions in Special Scenarios	Proposal Approved	2022/9	2023/01
5	HECT X PHOT	Intelligent and Connected Automobile Products Evaluation Guidelines	Proposal Approved	2022/9	2022/12
6	Test & Pilot	Intelligent and Connected Vehicle— Technical Requirements and Test Methods for the Automatic Driving Systems on Highway	Proposal Approved	2022/6	2022/9
7	Test & Pilot	General Requirement of Roadside Infrastructure for Vehicle Infrastructure Cooperative System	Proposal Approved		
8	Test & Pilot	Intelligent And Connected Vehicle— Method and Requirements for Naturalistic Driving Scenario Extraction	Proposal Approved	2022/04	2022/07

No	WG	Standard Name	Current	Future stage	
No		Standard Name	Stage	Enquiry	Publish
12	Innovation & Application	Memory Parking System Technical Requirements	Proposal Approved	2022/9	2022/12
10	Innovation & Application	General Technical Requirements of Automated Valet Parking Systems	Published		
11	Innovation & Application	Automated Valet Parking —Field Test Methods and Requirements	Enquiry	2022/9	2022/12
13	&	Data exchange contents of communication between vehicle and parking lot of AVP system	Proposal Approved	2022/10	2023/02
14	X,	Automated valet parking—Technical requirements of parking lots (garage)	Proposal Approved	2022/12	2023/4
15		Functional unmanned vehicle — Part 1 Terms and definitions	Proposal Approved	2022/9	2023/2
16	Innovation & Application	Functional unmanned vehicle — Part 2 General technical requirements	Proposal Approved	2022/9	2023/2
17	&	Functional unmanned vehicle— Technical Requirement of Autonomous Driving Function Field Test	Proposal Approved	2022/9	2023/2
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# Cooperative intelligent transportation system Technical requirements for application layer interaction Part 1: intention sharing and cooperation



Purpose: Enhance the	12 scenarios	listed in T/CSAE	157-2020 (Phase II).
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□ Scope: This document specifies the technical requirements for application layer interaction in the intention and cooperation classification, including general requirements, scenario requirements, process requirements, data interaction requirements and message sets.

### 12 scenarios (T/CSAE 157-2020)

No	Application name
1	Sensor Data Sharing
2	Cooperative Lane Change
3	Cooperative Vehicle Merge
4	Cooperative Intersection Passing
5	Differential Data Service
6	Dynamic Lane Management
7	Cooperative High Priority Vehicle Passing
	7.1 Lane Reservation Scenario
	7.2 Lane Prohibition/Closure Scenario
	7.3 Cooperative Signal High Priority Passing Scenario
8	Guidance Service in Parking Area
9	Probe Data Collection
10	Vulnerable Road User
11	Cooperative Platooning Management
12	Road Tolling Service
	Noau Tolling Service

Scenario classification based on functional purpose (It is also the name of series standards)

Part 1:Intention and cooperation

Part 2:Perception data sharing

Part 3:Management

Part 4:Advanced information services

Part 5: Vulnerable road user

### 2 ways of cooperation

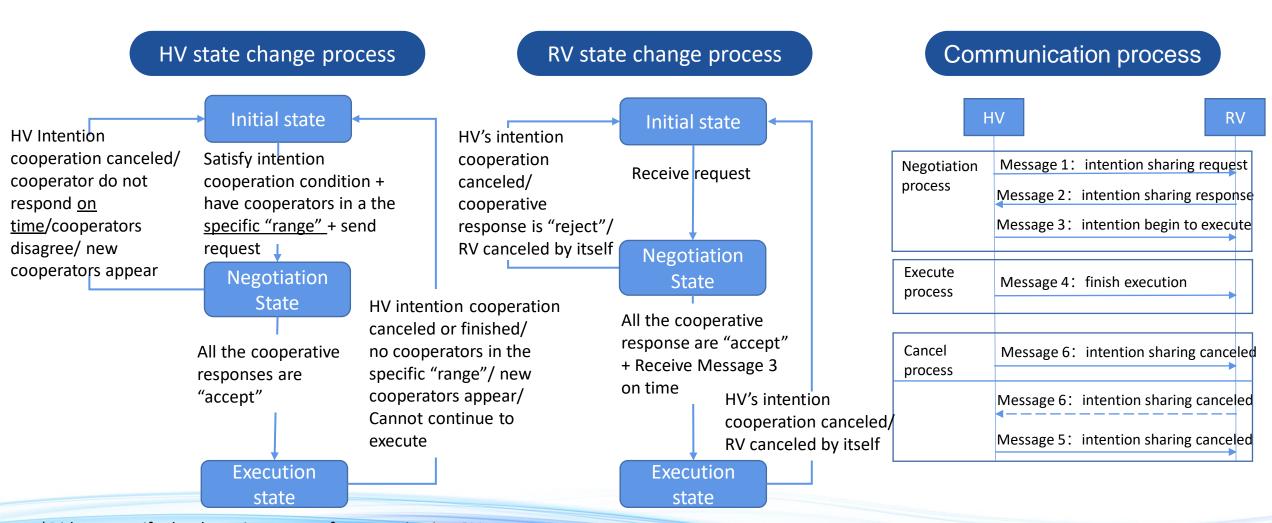
- HV who sending the intention cooperation request can achieve **vehicle-vehicle cooperation** by interacting with the collaborator RVs;
- HV can achieve vehicle-road cooperation by interacting with the roadside device.
- This standard does not prescribe which kind of interaction should be triggered in the scenario.

Scenarios	Road	V-V	V-I
Cooperative lane change	Highway, suburban area, closed park	٧	٧
Cooperative Vehicle Merge	Highway/city expressway entrance, service area exits, merging lanes	٧	٧
Cooperative Intersection Passing without signal	Intersection of urban road, suburban area, closed park	٧	٧
Cooperative Intersection Passing with signal	Intersection of urban road, suburban area, closed park		٧

# Cooperative intelligent transportation system Technical requirements for application layer interaction Part 1: intention sharing and cooperation



**Example: vehicle-vehicle collaboration** 



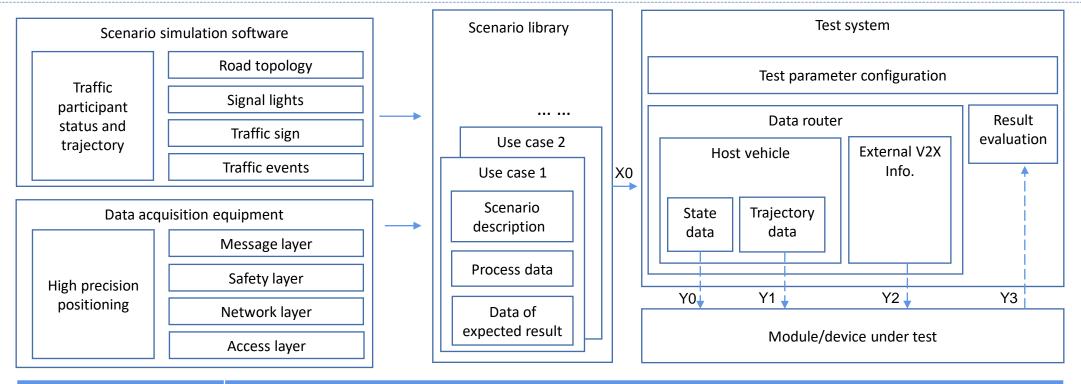
<sup>\*</sup>Did not specify the detection range of communication RVs at present

<sup>\*</sup>Did not specify the time range at present

# Technical requirement of scenario database and simulation testing for V2X communication application



□ Scope: This document specifies the V2X-based scenario library's data requirements, the architecture of the scenario data collection system, X-in-the-loop process and relevant interface requirements.



Element	Description	
Scenario description	Scenario type, road type, with/without map, stack protocol, DUT details	
Process data	A group of data frame based on time sequence, each frame includes current status of host vehicle and all	
	the external V2X messages	
Data of expected result	including the warning type, begin/end time of warning, priority etc.	
	(Refer to T/CSAE 246-2022)	



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# **Series of C-V2X Demonstration Activities**



□ CAICV and IMT2020 build a cross-industry collaborative testing and verification platform

# 2018 Three Cross-Industry • Modules • Terminals

**OEMs** 

# 2019 Four Cross-industry

- Modules
- Terminals
- OEMs
- Certificate Authority
- Open Road

# 2020 New Four Cross-industry

- HD Map & Positioning
- Cloud Control Platform
- Industrialization and enhanced scenario
- Closer to the actual travel scenario

# 2021 Pioneer Application Demonstration

- Multi-location scenario demonstration
- Integration of intelligence and connection
- Mass application

# 2022 Application Demonstration

- Vehicle mass production
- Best practice
- Innovation application

Fully verify LTE-V2X technology and related standards and further promote the industrialization of C-V2X in China.

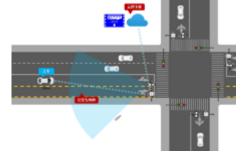
# **2022 Application Demonstration Details**



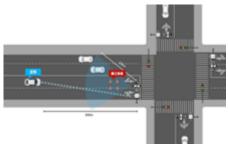
# **Test scenarios**



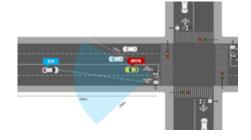
**Speed limit warning** 



**Bus lane warning** 



Road occupation for construction warning



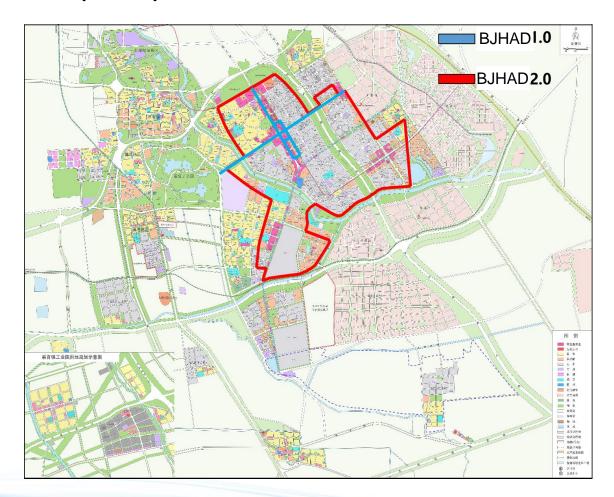
**Vehicle reversing warning** 



**Vehicle malfunction warning** 

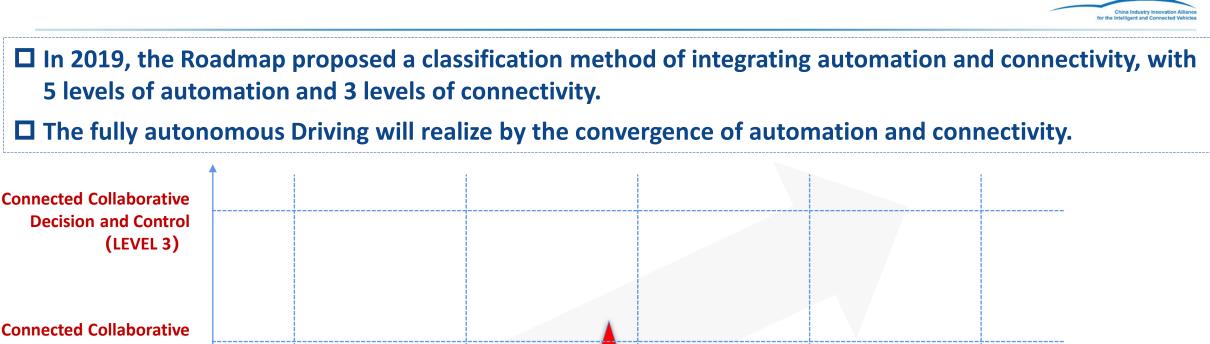


Beijing High-Level Autonomous Driving Demonstration Area (BJHAD) Construction Outcome



# Technology Roadmap for Intelligent & Connected Vehicles (Version 1 & 2)





Connected Collaborative
Perception
(LEVEL 2)

Connected Auxiliary
Information Interaction
(LEVEL 1)

Current vehicles are approaching automation level 3 (Conditional Automation) and connectivity level 2 (Connected Collaborative Perception).





Fully Automated
Driving
FA

# Roadmap for the convergence development of automation and connection based on C-V2X technology

- ☐ Provide guidelines of function development and application scenarios to enterprises.
- ☐ Promote cross-industry collaboration and facilitate policy implementation.

### Chapter 1 Current status

### **Chapter 2 Industrial development problems**

Chapter 3 Objective and timeline of convergence development

- 3.1 Long-term objectives
- 3.2 Medium-term objectives
- 3.3 Objectives for 2025

# **Chapter 4 Convergence scenarios**

Chapter 5 Main Task

- 5.1 Direction for technology development
- 5.2 Test and evaluation

Chapter 6 Recommendation for policy and regulation development

### Fieldwork on:

- The long tail problem of automation vehicle
- The current mass production application of connection function

### Research on:

- The connection use case which is suitable for industrialization
- The classification of connection functions



# Thanks





CSAE

http://www.sae-china.org/



**CICV** 

http://www.china-icv.cn/



CAICV Alliance

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