

What is embodied artificial intelligence and why it matters to ITU?

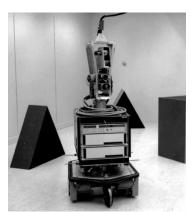
Kai WEI, Director of Artificial Intelligence Institute, CAICT 10 Oct 2025

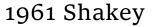


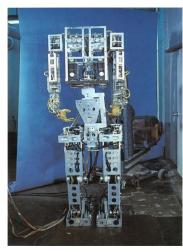
- 1. What is embodied AI?
- 2. Challenges of embodied AI
- 3. Standard gap and ITU-T's role

Embodied AI: beyond AI and robotics









1973 WABOT-1



1999 AIBO



2000 ASIMO

Smart Robot

Sensory & Execution







Embodied AI

- Sensory & Execution
- Cognition
- Collaborating
- Learning

Robot

Programmed

Humanoid Robot

- Robot with body, head and limbs
- looking and moving like a human

Embodied AI and (Non-embodied) AI



Embodied AI is a transformative shift in AI that integrates AI into physical systems, enabling them to interact with and learn from their environment through sensory inputs and actions.

| Aspect | (Non-embodied) AI (ChatGPT, Image Recognition program) | Embodied AI (Robots, Self-driving Cars) | |
|----------------------|--|--|--|
| Form of Existence | "A Brain in a Vat": Pure software, residing on servers. | "An Embodied Brain": Software integrated with a physical/virtual body. | |
| Primary Goal | Process information in a digital space; passively waits for input (e.g., a prompt). | Take action in a physical environment; acts proactively based on the situation. | |
| Input/Output | Data (text, images, speech)/Data (generated text, classification labels) | Perception (sensor data, cameras, LiDAR, touch)/Action (movement, manipulation) | |
| Learning Paradigm | Learns from static datasets: Trained by analyzing massive existing collections of images and text. | Learns through interaction & experience: Learns like an infant, through trial and error, touching, observing, and failing. | |

Embodied Al= Al + Physical Body(Action)

Embodied AI and robotics



Embodied AI enables robots from automation to autonomy, allowing them to performs behaviours or tasks independently, learn, and adapt to changing environments.

| Perspective | Robotics | Embodied AI | |
|--|--|---|--|
| 1. From "Programming" to "Learning" | All behaviors are based on explicit code written by programmers. | Abilities are acquired through real-time environmental interaction (trial-and-error). | |
| 2. From "Perception for Action" to "Perception-Cognition-Action" | Sensory data is used directly to execute predefined actions. e.g., verifying workpiece position, performing forcecontrolled assembly. | Sensory data is used to construct an internal model of the world, (e.g., "This is a messy room") and object properties, enabling actions driven by cognition. | |
| 3. From "Closed World" to "Open World" | The environment and all variables (e.g., object location, lighting, process) must be predictable and pre-defined.e.g., verifying workpiece position, performing force-controlled assembly. | Its purpose is to cope with environments, and must handle unseen objects, adapt to dynamic changes, and deal with ambiguity. | |

Embodied Al=Robots + Brain(Cognition)



Embodied AI refers to systems that integrate cognitive abilities with sensory and action capabilities, enabling machines to perceive, reason, and act autonomously in dynamic environments.

IEEE Systems, Man, and Cybernetics Society Announcement: Establishment of the Technical Committee on Embodied AI Systems Embodied AI refers to the integration of artificial intelligence into physical systems, enabling them to interact with the physical world. These systems can include general-purpose robots, humanoid robots, autonomous vehicles (AVs), and even factories and warehouse facilities.

NVIDIA Glossary https://www.nvidia.com/en-us/glossary/embodied-ai/ Robotics for tasks such as navigation, manipulation, and instruction following.....any tangible and intelligent machine that moves through space is a form of embodied AI, whether it is a self-driving car, a robot vacuum, or a robotic arm in the factory.

Searching for Computer Vision North Stars https://direct.mit.edu/daed/article/151/2/85/110602/Searching-for-Computer-Vision-North-Stars

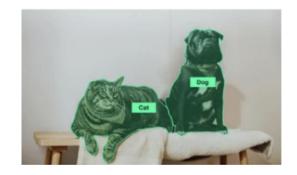
IEEE SMC

NVIDIA

Stanford Institute for HCAI

Key capabilities of embodied AI





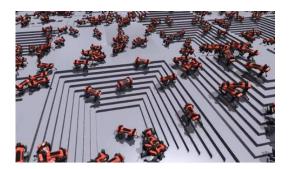
Recognition



1.Cognition



Programming



2.Learning



Isolated



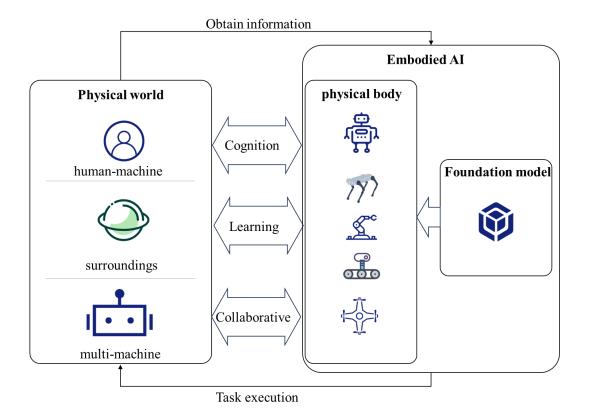


3.Collaborative

Embodied AI definition from ITU-T draft Rec.



Conceptual diagram and key features



Definition

Embodied artificial intelligence(EAI): Research, development, and implementation of artificial intelligence integrated into physical systems that interact autonomously with and adapt to the physical world.

ITU-T F.RF-EAI "Requirements and framework for embodied artificial intelligence systems"





EAI is a promising path to achieve AGI





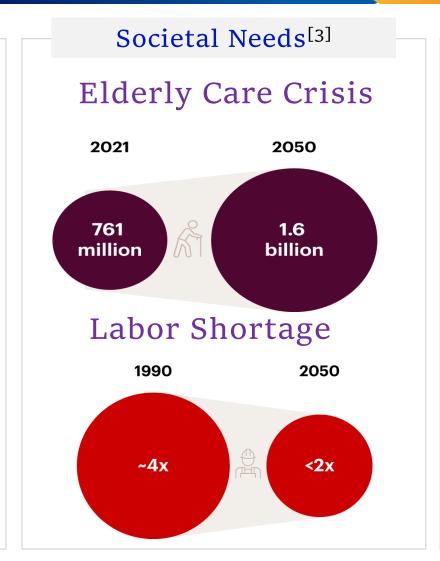
\$38 Billion

by 2035^[1]

1 Billion in Use

by 2050^[2]

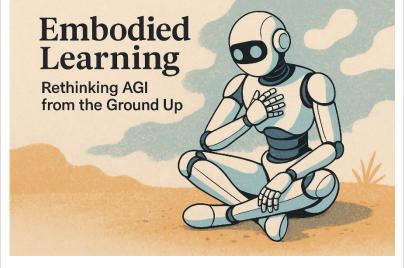
- only for humanoid robots



The way towards AGI

读万卷书, 行万里路

Read ten thousand books, travel ten thousand miles.



[1]Goldman Sachs, Jan, 2024, Global Automation: Humanoid Robots – The AI Accelerant [2]Morgan Stanley, May 2025, Humanoids: A \$5 Trillion Market [3]UN Department of Economic and Social Affairs & International Labor Organization



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Moravec's paradox is still validate for EAI



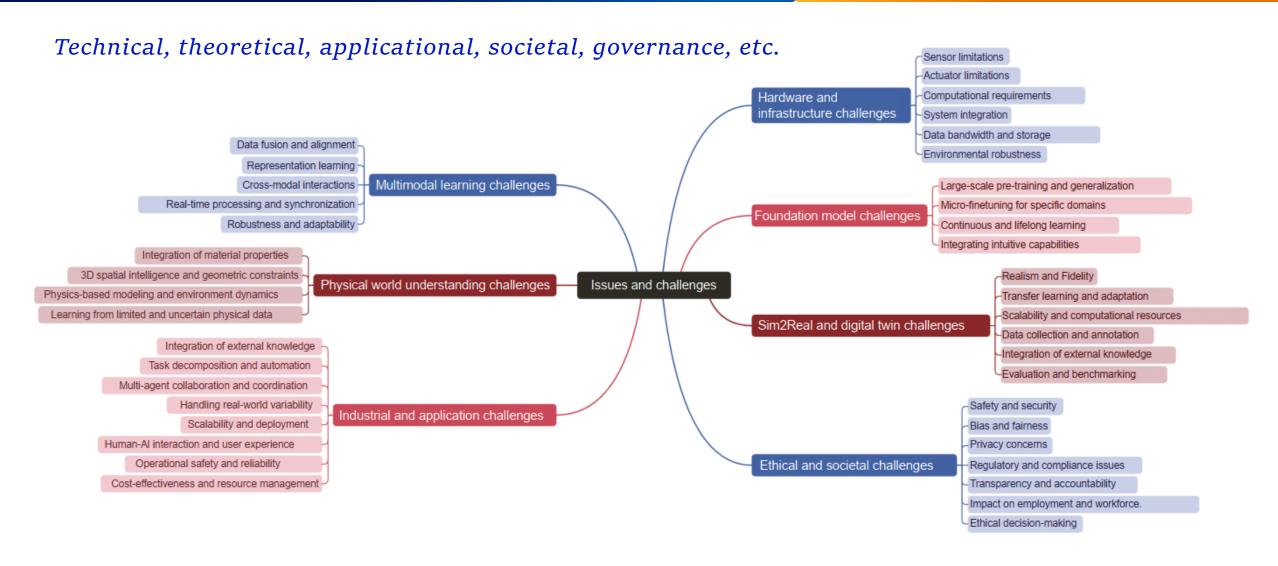
"It is comparatively easy to make computers exhibit adult level performance on intelligence tests or playing checkers, and difficult or impossible to give them the skills of a one-year-old when it comes to perception and mobility."

——Hans Moravec, 1988



There are many challenges ahead...





Sources: Sun F, Chen R, Ji T, et al. A comprehensive survey on embodied intelligence: Advancements, challenges, and future perspectives[J]. CAAI Artificial Intelligence Research, 2024, 3: 9150042.



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EAI standardization gap analysis

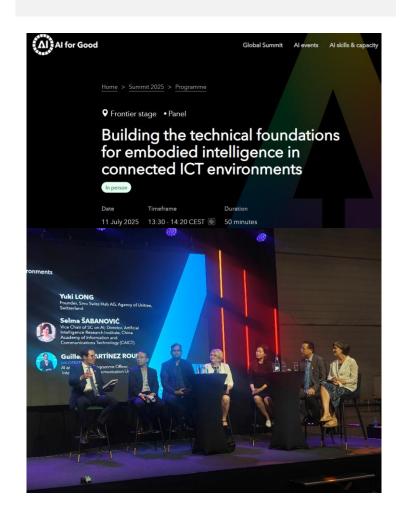


| Dimension | Key Challenges | Standardization Directions | |
|----------------------------|--|---|--|
| 1. Data & Perception | Heterogeneous multimodal and multimedia data Lack of high-quality, task-specific datasets | Format and quality standard for Multimodal training data Benchmark dataset & annotation specifications | |
| 2. Network & Collaboration | Complex task allocation across cloud-edge-device Lack of common multi-agent communication protocols | Unified interfaces for collaborative computingStandardized real-time agent interaction protocols | |
| 3. Model & Evaluation | No unified benchmarks for embodied models | Assessment criteria and metricsStandardized performance benchmarks | |
| 4. System Integration | High complexity in integrating heterogeneous components Hard interoperability between vendors | Modular development frameworks Plug-and-play component & middleware standards | |
| 5. Human-Robot Interaction | Lack of safety protocols for physical HRI Inconsistent user interfaces and experiences | Safety standards for physical interactionHuman-centered design guidelines | |
| 6. Safety & Security | Data privacy and protection risksLack of algorithmic transparency and explainability | End-to-end security & privacy frameworks Standards for explainable EAI & audit trails | |
| 7. Ethics & Governance | Ambiguity in accountability and liabilityRisk of value misalignment | Accountability & liability frameworksEthical guidelines & compliance standards | |

ITU's role on EAI development and standardization



COMMUNITY



USE CASE STUDY



STANDLIZATION

...standards are essential in translating the values we agree on as a global community into real-world systems.

Standards should not be construed as constraints on innovation.



Draf Rec. ITU-T F RF-EAI "Requirements and framework for embodied artificial intelligence systems, provides a unified framework for system capability building.

| application layer | application scenarios service interfaces, user/task-oriented services | | | | |
|-------------------|---|---|--|---|-------------------|
| functional layer | embodied perception multi-modal perception environment perception dynamic perception | embodied decision- making task planning decision optimization | embodied execution locomotion manipulation | human-machine interaction multi-machine collaboration | embodied learning |
| basic layer | foundation mo | odel | computing platform | | machine |

The way foreword for "EAI for Good"



- Embodied AI represents a promising pathway toward AGI that goes beyond the current domains of AI and robotics, with the potential to greatly benefit humanity.
- Moravec's paradox is still validate, EAI faces significant challenges, some of which can be effectively addressed through standardization.
- The ITU plays a key role in this effort, with its Study Group 21 serving as an open, collaborative platform actively advancing the field.

Looking foreword, we recommend continuing workshop discussions or to establishing a Focus Group in the future, to explore the opportunities for "EAI for Good", and to foster standardization studies, inclusively.

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Thanks

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