

ROBORACE

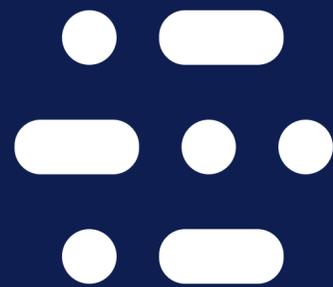


2019 DevBot 2.0

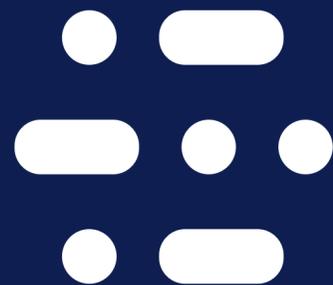
2018 Robocar

...beyond tradition



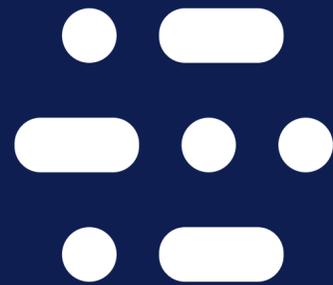


motorsport as #AlforGood



AUTONOMOUS
DRIVERS
ALLIANCE

Technology
Talent
Trust



Entertainment
Engagement
Exposure

Mission Zero 2050 = **Zero Road Deaths** + Zero CO₂ Emissions

Road traffic injuries are now the leading cause of death for children and young adults aged 5–29 years.

– Global Status Report on Road Safety 2018 - World Health Organisation

Road traffic **crashes** now represent the **eighth leading cause of death** globally. They claim more than **1.35 million lives** each year and cause up to **50 million injuries**. And the fact is...

– *Michael Bloomberg, WHO Global Ambassador for Noncommunicable Diseases and Injuries*

...**every one** of those **deaths** and **injuries** is **preventable**.

– *Michael Bloomberg, WHO Global Ambassador for Noncommunicable Diseases and Injuries*

When *AI* becomes our **driver, co-driver, guardian & instructor...**

...what should our **minimal performance** expectation be?

It starts with a **universal** assumption that all road users are;
“**aware, willing and able**” to avoid collisions

...including an **awareness** that **people** are **fallible** and often do
make **mistakes** on the road

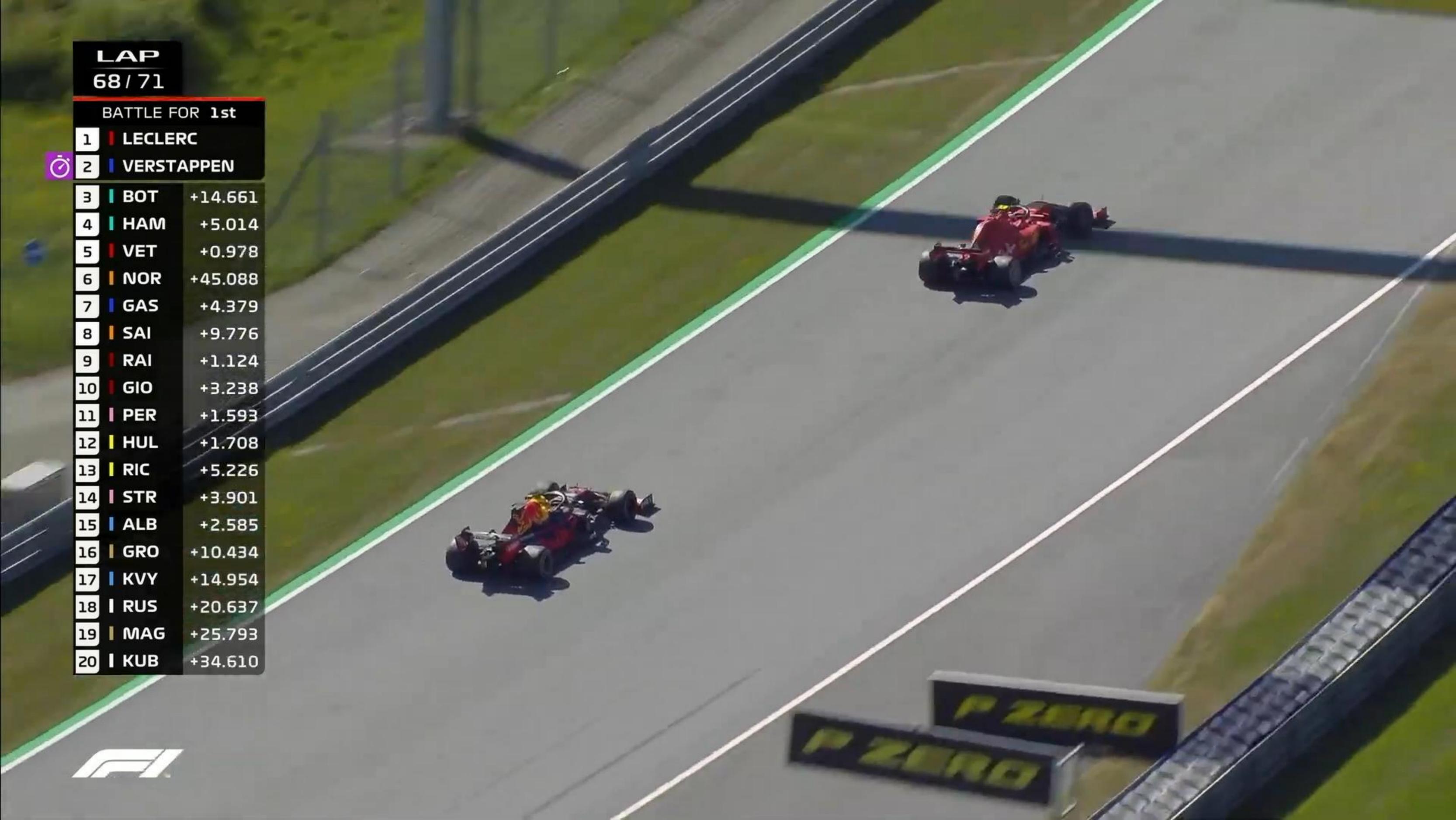


Race Control - Stewards

LAP
68 / 71

BATTLE FOR 1st

1	LECLERC	
2	VERSTAPPEN	
3	BOT	+14.661
4	HAM	+5.014
5	VET	+0.978
6	NOR	+45.088
7	GAS	+4.379
8	SAI	+9.776
9	RAI	+1.124
10	GIO	+3.238
11	PER	+1.593
12	HUL	+1.708
13	RIC	+5.226
14	STR	+3.901
15	ALB	+2.585
16	GRO	+10.434
17	KVY	+14.954
18	RUS	+20.637
19	MAG	+25.793
20	KUB	+34.610



PIRELLI

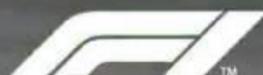
PIRE

LAP
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	Interval
1 LEC	
2 VER	+0.334
3 BOT	+14.290
4 HAM	+4.266
5 VET	+0.960
6 NOR	+46.033
7 GAS	+5.569
8 SAI	+9.408
9 RAI	+1.018
10 GIO	+2.643
11 PER	+1.545
12 HUL	+3.946
13 RIC	+2.321
14 STR	+5.049
15 ALB	+2.052
16 GRO	+10.990
17 KVY	+15.629
18 RUS	+20.943
19 MAG	+25.196
20 KUB	+37.428



P ZERO



1 LECLERC		DRS	299 KM/H	2 TURN	2 VERSTAPPEN	320 KM/H	DRS	
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Any driver **moving back towards the racing line**, having earlier defended his position off-line, should leave **at least one car width** between his own car and the edge of the track **on the approach to the corner.**

...manoeuvres liable to **hinder other drivers**, such as **deliberate crowding of a car beyond the edge of the track** or any other abnormal change of direction, are **strictly prohibited**.

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BATTLE FOR 1st

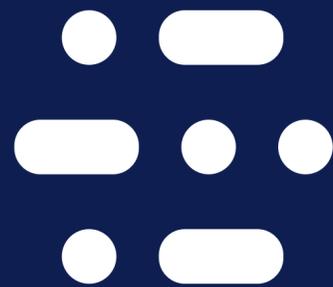
1	LECLERC	
2	VERSTAPPEN	
3	BOT	+14.846
4	HAM	+5.061
5	VET	+0.910
6	NOR	+45.080
7	GAS	+4.398
8	SAI	+9.812
9	RAI	+1.069
10	GIO	+3.159
11	PER	+1.634
12	HUL	+1.744
13	RIC	+4.989
14	STR	+3.905
15	ALB	+2.610
16	GRO	+10.434
17	KVY	+15.028
18	RUS	+20.877
19	MAG	+25.713
20	KUB	+34.573



LAP
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1	LEC	Interval
2	VER	+0.177
3	BOT	+14.461
4	HAM	+4.258
5	VET	+0.941
6	NOR	+45.990
7	GAS	+5.588
8	SAI	+9.534
9	RAI	+0.934
10	GIO	+2.604
11	PER	+1.545
12	HUL	+4.045
13	RIC	+2.093
14	STR	+5.095
15	ALB	+2.049
16	GRO	+10.990
17	KVY	+15.711
18	RUS	+21.152
19	MAG	+25.091
20	KUB	+37.300





How do we define **reckless**, **dangerous** or **careless** driving?

**Reckless driving: ...wilful or wanton disregard for the
safety of persons or property**

– USA Florida Statutes, Section 316.192

**Dangerous Driving: ...falls far below what would be expected of a
*competent and careful driver...***

– *UK Road Traffic Act 1988 c. 52 Part I Driving offences Section 2A*

Dangerous Driving: ...obvious to a *competent and careful driver* that driving in that way would be **dangerous**

– *UK Road Traffic Act 1988 c. 52 Part I Driving offences Section 2A*

Careless Driving: ...driving without **due care** and **attention** if (and only if) the way he drives **falls below** what would be **expected** of a ***competent and careful driver***

– *UK Road Traffic Act 1988 c. 52 Part I Driving offences Section 3ZA*

Should **AI** be held to same legal standards as **human** drivers?

Surely the **minimum** we should expect is that **AI Self-Driving Software** never engages in **reckless, dangerous or careless** driving?

Turing Test for Autonomous Driving
a global performance standard for AI on our roads

...it compares **AI** performance to that **expected** of a ***competent and careful driver*** (with humans as the starting baseline)

...it continually monitors the **AI's** self-reported
situational awareness and **situational risk assessment**

...to validate that the AI Self-Driving Software always remains
“**aware, willing and able**” to avoid collisions

let's start the journey to safer mobility today

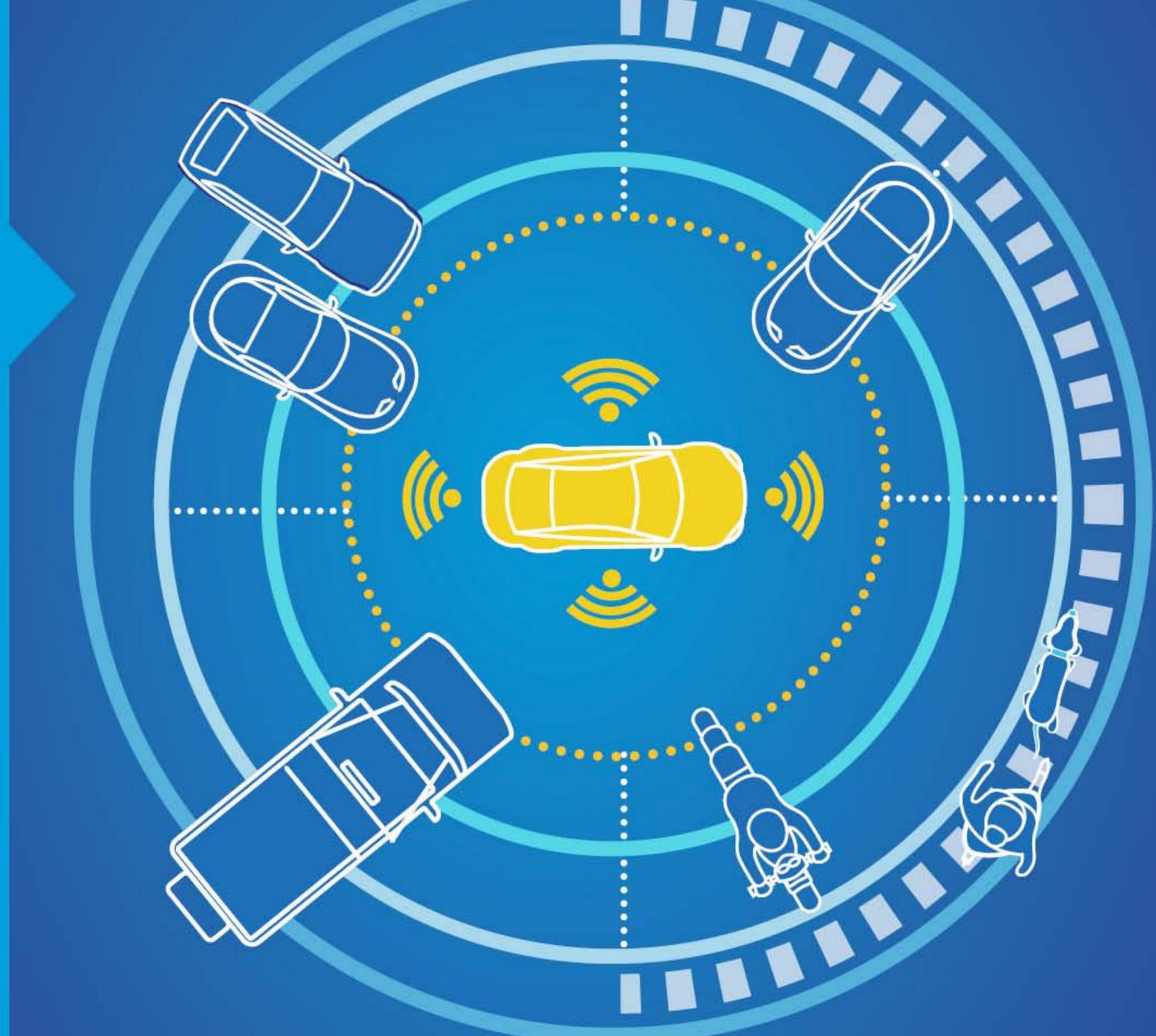
ITUEvents

One-day workshop

The Turing test for autonomous driving

*A global performance
standard for AI
on our roads*

10 September 2019
ITU Telecom World
Budapest, Hungary



Partner



AUTONOMOUS
DRIVERS
ALLIANCE

Organized by

