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	NITT Inc			
Legal Name	NTT, Inc.			
Contact for license a	ipplication:			
Name &	Rena Nakatsuji/ Licensing Group, Intellectual Property Center			
Department				
Address	9-11, Midori-cho 3-Chome Musashino-shi			
	Tokyo 180-8585 Japan			
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(*)Title	Parametric object-recognition-ratio-estimation model for remote monitoring of surveillance video delivered from autonomous vehicle			

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Place, Date	Tokyo, JAPAN, 1st October 2025	

FORM version: 2 November 2018