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SERIES V: DATA COMMUNICATION OVER THE TELEPHONE NETWORK

Interworking with other networks

Support by an ISDN of data terminal equipment with V-Series type interfaces with provision for statistical multiplexing

ITU-T Recommendation V.120

(Previously CCITT Recommendation)

ITU-T V-SERIES RECOMMENDATIONS

DATA COMMUNICATION OVER THE TELEPHONE NETWORK

1 – General

2 – Interfaces and voiceband modems

3 – Wideband modems

4 – Error control

5 – Transmission quality and maintenance

6 – **Interworking with other networks**

For further details, please refer to ITU-T List of Recommendations.

FOREWORD

The ITU-T (Telecommunication Standardization Sector) is a permanent organ of the International Telecommunication Union (ITU). The ITU-T is responsible for studying technical, operating and tariff questions and issuing Recommendations on them with a view to standardizing telecommunications on a worldwide basis.

The World Telecommunication Standardization Conference (WTSC), which meets every four years, establishes the topics for study by the ITU-T Study Groups which, in their turn, produce Recommendations on these topics.

The approval of Recommendations by the Members of the ITU-T is covered by the procedure laid down in WTSC Resolution No. 1 (Helsinki, March 1-12, 1993).

ITU-T Recommendation V.120 was revised by ITU-T Study Group 14 (1993-1996) and was approved by the WTSC (Geneva, October 9-18, 1996).

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NOTE

1.   In this Recommendation, the expression "Administration" is used for conciseness to indicate both a telecommunication administration and a recognized operating agency.

2.   The status of annexes and appendices attached to the Series V Recommendations should be interpreted as follows:

–   an *annex* to a Recommendation forms an integral part of the Recommendation;

–   an *appendix* to a Recommendation does not form part of the Recommendation and only provides some complementary explanation or information specific to that Recommendation.

CONTENTS

Recommendation V.120

SUPPORT BY AN ISDN OF DATA TERMINAL EQUIPMENT WITH V-SERIES TYPE INTERFACES WITH PROVISION FOR STATISTICAL MULTIPLEXING

(Melbourne 1988, modified Geneva 1992 and 1996)

1 Scope

This Recommendation describes a protocol that can be used for adapting terminals with non-ISDN standard network interfaces to an ISDN. It is intended to be used between two Terminal Adaptor (TA) functional groups, between two ISDN terminal (TE1) functional groups, between a TA and a TE1, or between either a TA or TE1 and an interworking facility inside a public or private ISDN. It provides for operation:

a) over either circuit-mode or frame-mode connections;

b) using either demand or semi-permanent establishment of communications; and

c) over any of the following types of access channel:

  – for circuit-mode connections: B, H_0, H_{10} or H_{11};

  – for frame-mode connections: B, H_0, H_{10}, H_{11} or D.

This Recommendation also describes how this protocol is related to synchronous and asynchronous interface specifications using the interchange circuits defined in Recommendation V.24. It is not intended to be a functional specification for an implementation of any system containing a TE1 or TA functional group. Except as explicitly noted, it is restricted to the definition of the protocol at the user-network interface (reference points S, T or U) and the ISDN-side interface of the Interworking Function (IWF).

The terminal adaption protocol in this Recommendation may be used in support of three classes of non-ISDN-terminal protocols. These are:

1) Asynchronous (start/stop) protocols, supported using the protocol sensitive asynchronous mode;

2) Synchronous protocols using High-level Data Link Control procedure (HDLC) frame format, supported using the protocol sensitive synchronous mode;

3) Synchronous protocols, supported using the bit transparent mode.

The use of the bit transparent mode with frame mode connections is for further study.

2 Application

2.1 General

The protocols described in this Recommendation may be used by a TE1, TA or IWF, as illustrated in Figure 1. The formats and procedures contained in this Recommendation are defined in terms of their operation across interfaces at reference points S, T or U, or (in the case of an IWF) across interfaces that may be internal network interfaces. Where necessary to promote compatibility, the relationship between the terminal adaption protocol and existing protocols at the interface at reference point R (where present) are also described.

2.2   Connectivity

Two or more terminal adaption connections may be multiplexed across a circuit-mode bearer connection or frame-mode access connection. These connections are referred to in this Recommendation as "logical links". Logical links supporting different modes of the terminal adaption protocol may be multiplexed across the same circuit switched bearer connection or frame-mode access connection. Constraints on the number of logical links (up to the maximum number that can be coded in the Address field) and the combinations of modes supported by a circuit switched bearer connection or frame-mode access connection are implementation dependent and are beyond the scope of this Recommendation.

The protocol sensitive modes (1 and 2 above in clause 1) of this Recommendation may be used to support dissimilar rates (i.e. when used between two TAs, the data rates at the interfaces at reference point R may be different). The use of buffering, application of the flow control protocol in this Recommendation, use of flow control procedures at the R reference point, use of discarding and other strategies for support of dissimilar rates are implementation dependent.

Parameter exchange procedures may be defined to allow interworking between Terminal Adaptors (TAs) in an environment where multiple different TA protocols are used without requiring interworking functions within the network. Interworking between different types of TAs can be accomplished with Multiprotocol Terminal Adaptors (MTAs) that are capable of supporting more than one protocol. However, interworking functions may be used when TAs are not capable of supporting more than one protocol.
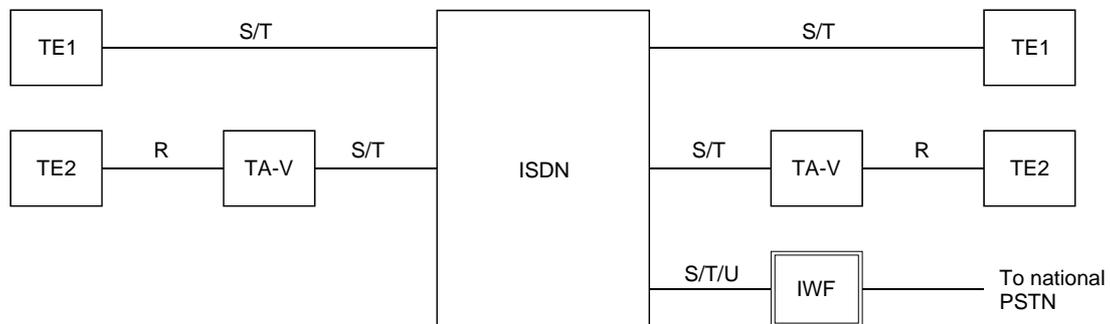
T1403160-97/d01

TE1   ISDN data terminal equipment
TE2   Terminal equipment (DTE with non-ISDN interfaces)
TA-V   V.120 terminal adapter supporting V-Series TE2s
IWF   Interworking function
S/T   S or T architectural reference points at which physical interfaces of concern may be implemented.
PSTN   Public Switched Telephone Network

FIGURE 1/V.120

ISDN connection scenarios

2.3 Protocol architecture

Figure 2 shows the protocol architecture of the U-plane, defined for the purposes of this Recommendation. The protocol defined in this Recommendation may be viewed as having the physical layer and three sublayers: the core sublayer, the data link control sublayer and the adaption sublayer. The core sublayer and the data link control sublayer are subdivisions of the data link layer (see Recommendation X.212). The adaption sublayer may also be considered a subdivision of the data link layer (though it may alternatively be viewed as a thin layer 3) This layering is in alignment with Recommendation I.233, "ISDN frame mode bearer services".

| Terminal adaptation sublayer |
| Data link control sublayer |
| Data link core sublayer |
| Physical layer |
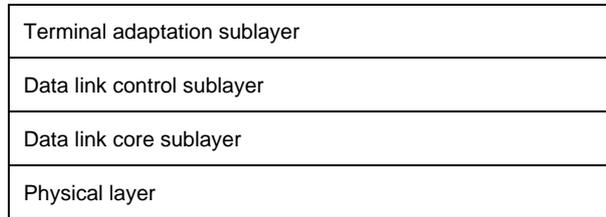
FIGURE 2/V.120

Protocol layers used in this Recommendation

Figure 3 shows how the layering of Figure 2 maps to the frame formats of this Recommendation.
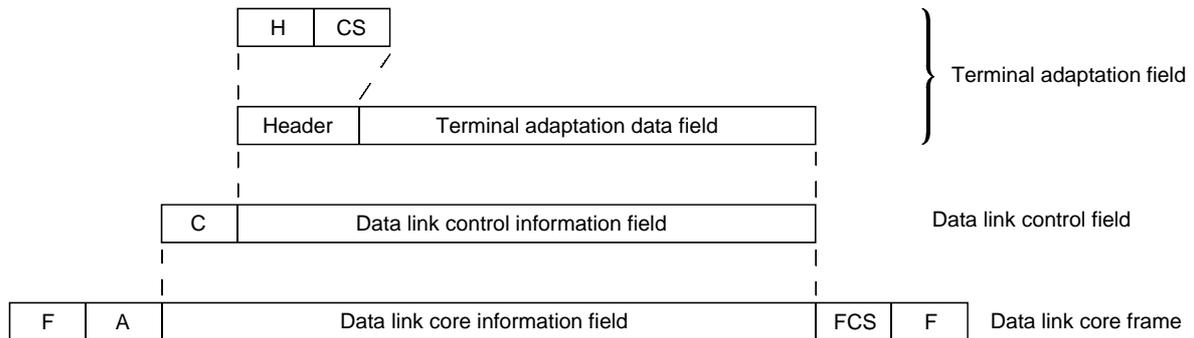
F   HDLC flag
A   Address
FCS   Frame Check sequence
C   Control (HDLC format)
H   Header octet (optional for bit transparent mode)
CS   Optional header extension for control state information

FIGURE 3/V.120

Relationship between layering and frame formats

2.3.1 Terminal adaption sublayer

The terminal adaption sublayer provides for transfer of data, provision for the detection of errors, and reassembly of segmented data between peer systems. It may also provide the following functions:

1) segmentation;

2) transport of notification of error conditions detected in external protocols (i.e. at the interface at reference point R);

3) transport of information related to the normal operation of external products (e.g. break for the protocol sensitive asynchronous mode, HDLC idle for the protocol sensitive synchronous mode);

4) support for operation with a network independent clock;

5) flow control;

6) transport of status information (which may be mapped to interchange circuits at the interface at reference point R; however, see Appendix II).

2.3.2 Data link control sublayer

The data link control sublayer provides the procedures and formats of fields for data link layer peer-to-peer communication. The elements of procedures define the commands and responses that are used for peer-to-peer communication.

For formats and the elements of procedures, see Recommendation Q.922.

2.3.3 Data link core sublayer

The data link core sublayer allows for the statistical multiplexing of core information flows.

The major core functions include:

– framing;

– transparency;

– multiplexing using the address field; and

– error detection.

The data link core protocol is defined in Annex A/Q.922. The data link core service is defined in Recommendation I.233.1.

The HDLC frame at the S or T interface is referred to hereafter as the terminal adaption frame (it includes the HDLC address and control fields, the terminal adaption header and user data).

2.4 Operation over restricted transport capabilities

Where a terminal adapter is used on an ISDN user interface for adaptation to a 64 kbit/s B-channel and the bearer capability provided by the ISDN is "restricted" 64 kbit/s, or the connection involves interworking with a 56 kbit/s network, the TA shall rate adapt to 56 kbit/s rate by using the first 7 bits of each B-channel octet and shall insert a binary ONE in the eighth bit of each B-channel octet as described in Recommendation I.464. The reverse process shall be used at a receiver. All of the procedures in this Recommendation are applicable to these transport capabilities as well as 64 kbit/s unrestricted transport capabilities.

NOTE – In frame mode applications, the limitation, if it exists, will be in the access capability only.

3 Terminal adaption protocol

This clause describes the terminal adaption protocol. This protocol depends upon the services of the data link control sublayer and, for the bit transparent mode, it also depends upon the services of the physical layer (clock).

There are two categories of terminal adaption defined in this Recommendation. Protocol sensitive operation requires that the TE1, TA or IWF be able to identify the beginning and end of characters or HDLC frames, removing any idle time fill. Bit transparent operation provides for the transport of isochronous data transparently without alignment (above the bit level) of information from the interface at the R reference point within the frame transport in the bearer channel. It is particularly suited to the adaption of protocols that are not covered by the protocol sensitive modes.

Two protocol sensitive modes are defined for the terminal adaption protocol. The asynchronous mode is intended to transport start/stop mode data. The synchronous mode is for the transport of HDLC framed data.

3.1 Formats

The terminal adaption header may contain one or two octets. The two are labelled the header (H) octet and the control state (CS) octet.

3.1.1 H-header octet

The H octet is mandatory for the protocol sensitive modes of operation, and is optional for the bit transparent mode. The format of the H octet is shown in Figure 4. Its presence in the bit transparent mode is negotiated during call setup for demand connections or by prior agreement for semi-permanent connections.

8	7	6	5	4	3	2	1	Bit
E	BR	res	res	C2	C1	B	F	

T1403180-97/d04

E   Extension bit
BR   Break/mark hold bit
C1, C2   Error control bits
B, F   Segmentation bits
res   Reserved for future standardization

FIGURE 4/V.120

Header octet format

3.1.1.1 E-extension bi (bit 8)

The E-bit is the header extension bit. It allows the extension of the header to provide additional control state information. A "0" bit indicates that a control state (CS) information octet follows (see 3.1.2).

3.1.1.2 BR asynchronous-break/HDLC-idle bit (bit 7)

In asynchronous applications, the break bit indicates the invocation of the BREAK function by the TE2. A "1" in this bit position indicates BREAK (see 3.2.1.1 and 7.2).

In protocol sensitive operation for synchronous HDLC applications, the BR bit is used to indicate whether an HDLC idle condition exists at the R reference point. A "1" in this position indicates that an HDLC idle condition (all binary 1s) exists. In bit transparent mode this bit is reserved and must be set to "0" on transmission and ignored on reception.

3.1.1.3 Bits 5 and 6

Bits 5 and 6 of the header octet are reserved and must be set to "0".

3.1.1.4 C1, C2 error control bits (bits 3 and 4)

Bit 3 and bit 4 of the header octet are defined as control 1 and control 2, respectively, and are used for TA error detection and transmission.

The meanings of the C1 and C2 bits are encoded as shown in Table 1.

TABLE 1/V.120

Coding of C1- and C2-bits

C1	C2	Synchronous	Asynchronous	Bit transparent
0	0	No error detected	No error detected	No error detected
0	1	FCS error (interface at R)	Stop-bit error	Not applicable
1	0	Abort	Parity error on the last character in frame	Not applicable
1	1	TA overrun (from interface at the R reference point)	Both Stop-bit and parity error	Not applicable

3.1.1.5   B, F segmentation bits (bit 2 and bit 1)

The B and F bits are used for segmenting and reassembly of user HDLC frames in synchronous mode applications. Setting the B bit to "1" indicates that the Terminal Adaptor (TA) frame contains an information portion signifying the start of a message. Setting the F bit to "1" indicates the TA frame contains the final portion of the user frame. If the entire message is contained within a single TA frame then both B and F bits shall be set to "1". A TA frame which is neither first nor last is termed a middle frame. For the asynchronous mode and the bit transparent mode these bits are set to "1". The meaning of the B and F bits is summarized in Table 2.

TABLE 2/V.120

Coding of B and F bits

B	F	Synchronous	Asynchronous	Bit transparent
1	0	Begin frame	Not applicable	Not applicable
0	0	Middle frame	Not applicable	Not applicable
0	1	Final frame	Not applicable	Not applicable
1	1	Single frame	Required	Required

3.1.2   CS-control state octet

The control state information is contained in the second octet of the header when present. The format of the control state information octet is shown in Figure 5. For TAs, this field may carry physical interface control information, (see 3.2.3 for procedures). When Unnumbered Information (UI) frames are used for data transfer, this field may be used to provide for flow control (see 3.2.4.1 for flow control). The CS octet should be expected any time the H-field is present and is extended to two octets. The following shows the format of the control state information octet. For an example of the mapping of the V.24 leads, see Appendix II. See 3.2.3 for the procedures and see 3.2.4.1 for the use of the RR bit for flow control.

3.1.2.1   E-extension bit (bit 8)

Because the control state information octet is the second and last octet in the Header, the E bit shall be set to "1". The receipt of a control state octet with the E bit set to "0" shall be considered an error.

3.1.2.2   Data Ready (DR) (bit 7)

This bit set to "1" indicates that the interface at the R reference point is activated (e.g. DTR ON).

8	7	6	5	4	3	2	1	Bit
E	DR	SR	RR	res	res	res	res	

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E   Extension bit
DR   Data Ready
SR   Send Ready
RR   Receive Ready
res   Reserved for future standardization

FIGURE 5/V.120

Control state information octet

3.1.2.3 Send Ready (SR) (bit 6)

This bit set to "1" indicates that the TE is ready to send data.

3.1.2.4 Receive Ready (RR) (bit 5)

This bit set to "1" indicates that the TE is ready to receive data.

3.1.2.5 Bits 4, 3, 2, 1

Bits 4, 3, 2, and 1 of the control state information octet are reserved and shall be set to "0".

3.1.3 Interframe time fill

Interframe time fill at the S-interface should normally be HDLC flags. For special non-D-channel applications it may be all "1s". On the D-channel of a basic access, the transmitted interframe time fill shall be all "1s".

3.2 Procedures

3.2.1 Operating modes – General

In order to ensure data integrity in the synchronous (HDLC) and asynchronous modes of operation, it is strongly recommended that, where practical, the multiple frame acknowledged information ("I") transfer procedure be used.

3.2.1.1 Protocol sensitive operation in the asynchronous mode

To send data to a peer terminal adaption protocol entity, characters shall be encapsulated in a TA frame. The parity bit, if present, may be encapsulated or omitted (except as noted in 7.2). The start and stop bits shall not be encapsulated. More than one character may be encapsulated in a TA frame. The decision to forward a TA frame is implementation dependent. The setting of the bits C1 and/or C2 to "1" shall indicate that the TA (or IWF) has detected a stop bit error and/or a parity bit error (R reference point), respectively. If either bit is set, the TA frame shall be transmitted without the encapsulation of additional characters. Similarly, the BR bit set to "1" by the terminal adaption protocol entity shall indicate a break. The TA frame shall be forwarded without encapsulating further characters. The BR bit set to "0" by the terminal adaption protocol entity shall indicate the end of a break.

When a terminal adaption protocol entity receives a frame, it may disassemble it into characters or accumulate it into units appropriate for internal use. Handling of stop bit errors, parity errors and break is implementation specific (except that additional procedures are noted in clause 7 and Appendix I for TA functional groups and TE1s, respectively).

3.2.1.2 Protocol sensitive operation in the synchronous (HDLC) mode

HDLC frames, including the address, control and information fields shall be encapsulated in one or (if segmentation[1]) and reassembly are used) more terminal adaption frames and forwarded to the peer terminal adaption protocol entity. In addition, if the unacknowledged mode of the data link control service is used, the FCS shall also be encapsulated. The C1 and/or C2 bits set according to Table 1 shall indicate that the TA functional group or IWF detected an FCS error, an HDLC abort, or an overrun (at the R interface or internal interface). When the C1 and/or C2 bits are set, the frame shall be forwarded. To indicate an HDLC idle condition (i.e. continuous marking), the terminal adaption protocol entity shall send a frame containing the BR bit set to "1". To indicate the end of an HDLC idle condition (i.e. resumption of sending of flags), the terminal adaption protocol entity shall send a frame containing the BR bit set to "0".

When a terminal adaption protocol entity receives a frame, reassembly of segments may be necessary. If either or both of the C1 and C2 bits is set to "1", the terminal adaption protocol entity may:

    a)   discard the frame and all previously received segments;

    b)   abort the HDLC frame being sent across the R interface or internal (virtual) interface; or

    c)   generate an incorrect FCS in the HDLC frame being sent across the R interface or internal interface.

         NOTE 1 – Support of non-octet-aligned frames is for further study.

         NOTE 2 – Alternatives b) and c) are not meaningful if the terminal adaptation protocol entity is in a TE1.

         NOTE 3 – When adapting 56 kbit/s HDLC terminals to 64 kbit/s B-channels, using unacknowledged data transfer, the value of N2120 should not exceed 64 bytes. A high probability of overflow in the direction of transmission towards the S or T interface side of a TA may occur if a large proportion of the frames are shorter than 64 bytes and there is no idle period between them. In such cases, restrictions, such as flow control of the TE2, may be necessary.

3.2.1.3 Bit transparent operation

Bits shall be encapsulated in frames and forwarded without modification. The maximum length of individual frames shall not be greater than N201, but otherwise is implementation dependent[2]. Longer frames will increase transit delay attributable to terminal adaption.

When a frame is received, the content of the data field is handled as a bit stream. A TA functional group or IWF shall not modify the bit stream.

Use of the unacknowledged mode of the Data Link Control service is preferred for bit transparent operation, as delay variance due to retransmission of I frames might result in underrun. Bit transparent operation is for further study.

3.2.2 Data field length

The maximum number of octets in a terminal adaption data field (N2120) must be equal N201 (see 5.9.3/Q.922) minus the length of the terminal adaption header (comprising the H and optionally the CS octets). Negotiation procedures for N201 are discussed in Appendix III/Q.922.

         NOTE – The resolution of a possible conflict between the use of XID exchanges for both data link layer parameter negotiation (Appendix III/Q.922) and unacknowledged mode link verification (4.2.2) is for further study.

3.2.3 CS information processing

This subclause describes the use of the control state variables and the processing of the CS information field, when present, defined in 3.1.2. Use of the CS information field is optional (see in § 6.3.2.4.5 octet 5b, bit 7 of low layer compatibility). The procedures described below in this subclause and in its subclauses only apply if the control state information field is used.

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[1] Segmentation and reassembly may reduce assembly delay associated with terminal adaption.

[2] As discussed in Appendix III, clock recovery at the receiver may depend upon frames being of uniform length and transmitted at uniform intervals.

The terminal adaptation protocol provides for six control state variables (to be maintained by the TA protocol entity) that are related to the DR, SR, and RR indicators as follows:

1) send variables DR(S), SR(S), and RR(S) – when a frame with DR, SR, and RR is transmitted, their transmitted values shall be equal to the current values of DR(S), SR(S), and RR(S), respectively;

2) receive variables DR(R), SR(R), and RR(R) – when a frame with DR, SR, and RR is received, the receive variables are set to the values of these indicators, respectively.

The control state information field may be included even if control state variables are not changed. The use of the control state information field with UI frames is not recommended except for flow control as mentioned in 3.1.2.

3.2.3.1 Control state information initialization

The first I or UI frame sent by each peer (after link initialization) shall contain the control state information octet. This exchange shall occur immediately following link verification. If the first frame does not contain the control state, the values of all of the bits should be assumed to be "1"; i.e. until a frame containing the CS bits is received, DR(R), SR(R) and RR(R) should be set to "1".

3.2.3.2 Sending a control state information field

A control state information field shall be sent whenever a send control state variable changes. The control state information field shall be sent in the last frame containing any of that previously queued data (received across the interface at the R reference point) prior to the control state variable change, or in a separate frame.

The contents of the control state information octet shall be set to the state of the corresponding send control state variables. DR is set to DR(S), SR is set to SR(S), and RR to RR(S).

3.2.3.3 Receiving a control state information field

Upon receipt of a control state information field, the control field indicators shall be compared with the receive control state variables: DR to DR(R), SR to SR(R), and RR to RR(R). The receive control state variables shall be set to their received indicator values.

If SR(R) was "0" and the SR indicator bit in the received control state information field is "1", then the state of RR(S) is set to state of SR(R) provided that the peer entity is not being flow controlled by use of the RR(S) state (see 3.2.4.1).

If SR(R) was "1", and the SR indicator bit in the received control state information field is "0", then the RR(S) state is set to SR(R).

NOTE 1 – Where the control state variables are used for control of the interface at the R reference point, the changes in the state of RR(S) should be consistent with one of the following:

1) if received data (from peer entity) does not remain to be forwarded, then the control actions can occur immediately;

2) if received data (from peer entity) is incomplete (e.g. in protocol sensitive mode the final frame was not received) and DR(R) is "1", then the incomplete message is forwarded (continued) until delivered on the interface at the reference point, at which time the control actions may occur;

3) if received data (from peer entity) is complete, then the received data is forwarded until delivery on the interface at the R reference point is complete, at which time the control actions should occur.

If DR(R) was "0" and the DR indicator bit in the received control state information field is "1", then DR(R) is set to 1.

If DR(R) was "1" and the DR bit in the received control state information field is "0", then DR(R) is set to "0".

NOTE 2 – Where the control states variables are used for control of the interface at the R reference point, the changes in the state of DR(R) should be consistent with the following:

1) If the received user frame from the peer entity is incomplete, it is discarded.

2) If the received user frame from the peer entity is a complete user frame, then it should be delivered prior to the control actions taking place.

3.2.4 Data flow control and buffering

Strategies for buffering, forwarding and flow control are implementation dependent. This subclause describes the mechanisms in the data link control and terminal adaption protocols for asserting flow control between peer terminal adaption protocol entities. The specific protocol mechanisms are dependent on the mode of operation.

3.2.4.1 Protocol sensitive asynchronous mode

When the multi-frame mode of the data link control protocol is used, flow control between peer terminal adaption protocol entities may be asserted by the data link control sublayer. The applicable data link control protocol mechanisms are: sending a receive not ready (RNR) frame, or withholding the update of the sequence state variable V(R).

When the unacknowledged mode is used, flow control between peer terminal adaption protocol entities may be asserted by setting the RR bit in the control state information octet (if available). Flow control is asserted by sending a control state information field with the RR bit set to "0". The flow control condition is removed by sending a control state information field with the RR bit set to "1". Frames containing only the H and C octets may be sent even if flow control has been asserted by the peer terminal adaption protocol entity. Use of the RR bit for this purpose may be mutually exclusive from its mapping to V.24 interchange circuits required for support of half-duplex operation (see Appendix II).

NOTE – In some applications, local flow control procedures (e.g. in the protocol used at the interface at reference point "R") may be used. The use of these procedures is implementation dependent. Examples of such procedures include signalling using V.24 interchange circuits and use of the "XOFF" and "XON" characters.

3.2.4.2 Protocol sensitive synchronous mode

In protocol sensitive synchronous mode, overrun and underrun conditions are possible in a TA functional group (i.e. at the interface at reference point "R") or IWF (i.e. at the interface at the non-ISDN side of the IWF). Procedures at the interface at reference point "R" are described in 7.3.

If, after transmitting one or more segments of a frame to the peer terminal adaption protocol entity, it becomes necessary to abort the transmission of the remainder of the frame, the "H" octet of the last segment to be sent shall have the B- and F-bits set to "final" (see Table 2) and the C1- and C2-bits set to "TA overrun" (see Table 1). Additional segments of the frame shall be discarded. (This procedure is intended for use by a TA functional group or IWF in the case of an overrun at the interface at reference point R, or at the interface at the non-ISDN side of the IWF, respectively. An underrun condition towards the R reference point may result in the sending of an abort or by forcing an FCS error.)

As flow control in HDLC involves elements of procedure not supported by the terminal adaption protocol, internal overflow conditions may be handled by discarding user frames. Recovery from lost frames will be between users (e.g. between TE2s).

3.2.4.3 Bit transparent mode

In bit transparent mode, overrun and underrun conditions may occur if buffers are inadequate and/or inappropriate clock recovery capabilities are provided. Dissimilar rates between users (e.g. TE2s) are not possible.

NOTE 1 – Underrun conditions may be treated as the equivalent of the mark hold condition (e.g. by sending continuous marks across the interface at reference point "R").

NOTE 2 – If a terminal adaptation protocol entity is unable to process data to be sent to its peer (e.g. because of buffer overflow) it may discard as much data as it is unable to process.

3.2.5 Parameter negotiation

Parameter negotiation during the bearer channel establishment is in accordance with the procedures described in Recommendation Q.931 for circuit mode operation and Recommendation Q.933 for frame mode operation. During logical link negotiation, a specific value for a parameter may be requested by including the low layer compatibility information element containing the desired parameters in the SETUP message. The receiving TA may accept the requested parameter values by responding with a CONNECT message. If the receiving TA does not accept the parameter values included in the SETUP message, it may negotiate by including the desired values in a low layer compatibility information element in the CONNECT message. The originating TA may refuse the parameters received in the CONNECT message by initiating clearing with the cause number 21 "call rejected".

4 Data link control protocol

The data link control protocol shall be according to Recommendation Q.922 for operation over either the Frame Mode Bearer service or the Circuit Mode Bearer service.

For operation over the Frame Relay Bearer service, use of the congestion control mechanisms of Appendix I/Q.922 are recommended.

4.1 Data link control modes of service

The data link control sublayer has two modes of service (for user information transfer):

1) The Unacknowledged service is provided by exchanging exchange identification (XID) command and response frames for the optional link verification procedures described below, and using UI command frames (see Recommendation Q.922).

2) The Multiframe service (which supports Acknowledged and Unacknowledged transfer) is provided by exchanging Set Asynchronous Balanced Mode Extended (SABME) and Unnumbered Acknowledgement (UA) frames for link verification, and using I and UI command frames (see Recommendation Q.922).

   NOTE – In order to ensure data integrity in the synchronous (HDLC) mode of operation, it is strongly recommended that, where practicable, the multiframe acknowledged information ("I") transfer procedure be used.

4.2 Data link connection verification procedures

Two modes of layer 2 operations are defined: multi-frame mode and UI-frame-only mode. This subclause describes connection or link verification procedures for these modes. Connection or link verification is the procedure used by each terminal adapter (associated with a TE2 or an IWF) or TE1 to determine the existence of an end-to-end transmission path and the existence of responding equipment at the opposite end.

In this subclause, "cut-through-indication" refers to the reception of CONNECT or CONNECT ACKNOWLEDGE message. In general, to assure proper verification of a connection or link, for either multiple-frame or UI-frame-only modes, no frames shall be transmitted or received prior to the reception of a cut-through-indication.

To reduce the possibility of transmitting to a TA that is not yet connected:

1) a TA that receives a CONNECT message from the network should always transmit a frame to initiate the connection; and

2) a TA that receives a CONNECT ACKNOWLEDGE message from the network should wait for T200 or until it receives a frame (whichever is earlier) before transmitting a frame.

   NOTE – These procedures are applicable to all logical links.

4.2.1 Multiframe mode link verification

In multiple frame mode, the exchange of SABME/UA as defined in Recommendation Q.922 is sufficient to verify the existence of the data link.

4.2.2 Unacknowledged mode (only) link verification

In UI-frame-only mode, after receiving a cut-through indication, the TA shall send an XID command and start timer TM20. A TA receiving the XID command shall respond with an XID response. Upon receiving the XID response, a TA must stop TM20 and may begin data transmission (link is established).

If TM20 expires before an XID response is received, the TA shall retransmit the XID command, increment the retransmission count NM20, and restart TM20.

If TM20 expires and the retransmission count is equal to the maximum allowable number of retransmissions, the TA may either begin data transmission or abandon the call.

The values of TM20 and NM20 should be determined by the same considerations as the values of T200 and N200, respectively (see Appendix III/Q.922). This link verification procedure does not specify the information field of the XID frames, any coding of the information is acceptable.

This procedure is not necessary in applications that do not require link verification.

4.2.3 Collision between multiframe mode and unacknowledged mode link verification

When a terminal adaptor (or TE1) that has sent an SABME receives an XID command, it shall send an XID response and remain in the same state. When a terminal adaptor or TE1 that has sent an XID command receives an SABME, it shall send either a disconnected mode (DM) response or a UA response.

5 Protocol specifications for operation over Frame Mode Bearer service

The terminal adaption protocol described in clause 3 may be supported by a Frame Mode Bearer service. Either frame mode case A or case B, as described in Recommendation Q.933, may be used.

5.1 Physical protocol

The physical layer protocol shall be as described in Recommendation I.430 or I.431. Frame mode access connections may operate over B-channels, H_0 channels, H_{10} channels, H_{11} channels or D-channels.

5.2 Data link protocol

5.2.1 Data link core protocol

The data link core protocol shall be as described in Annex A/Q.922. Use of the congestion control procedures described in I.2/Q.922 are recommended.

5.2.2 Data link protocol for frame switching

The data link protocol shall be as described in Recommendation Q.922.

5.3 Signalling protocol

For demand establishment of frame mode bearer connections, the signalling protocol shall be according to Recommendation Q.933. Either case A or case B apply.

In the low layer compatibility information element (see Recommendation Q.933), the user information layer 1 protocol (octet 5) shall be coded as "ITU-T standardized rate adaption V.120". This implies the presence of octets 5a and 5b, and, optionally, octets 5c and 5d of this information element. Coding of remaining fields and octet groups in this information element is dependent on the particular application of this Recommendation.

6 Protocol specifications for operation over Circuit Mode Bearer service

6.1 Physical protocol

For operation over a Circuit Mode Bearer service, the physical layer shall be as described in Recommendation I.430 or I.431. This protocol applies for operation over B-channels, H_0 channels, H_{10} channels or H_{11} channels. Establishment of the circuit switched bearer connection may be demand or semi-permanent.

6.2 Data link core protocol

6.2.1 General

The format of the data link core frame is as shown in Figure 3. The definition of the flag sequence, transparency, frame check sequence and format conventions shall be according to Recommendation Q.922.

6.2.2 Address field

6.2.2.1 LLI field

The format of the address field is shown in Figure 6. The LLI0 and LLI1 fields may be viewed as a single 13-bit logical link identifier (LLI) field or alternatively as two separate fields.

The LLI is considered to be the concatenation of the LLI0 field with the LLI1 field. The LLI can take on values in the range 0 to 8191. Table 3 indicates values that are reserved.
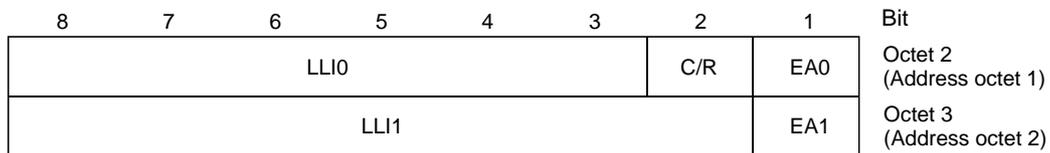
LLI0   High order 6 bits of LLI
LLI1   Low order 7 bits of LLI
C/R   Command/response bit
EA0   Octet 2 address extension bit – set to 0
EA1   Octet 3 address extension bit – set to 1
        (for a 2 octet address field)

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FIGURE 6/V.120

Address field format for circuit mode applications

TABLE 3/V.120

Reserved LLI values for circuit mode applications

LLI	Function
0	In-channel signalling
1-255	Reserved
256	Default LLI
257-2047	For LLI assignment
2048-8190	Reserved
8191	In-channel layer management

6.2.2.2 Address field extension bit (EA)

The address field range is extended by using bit 1, the first transmitted bit, of the address field octets to indicate the final octet of the address field. The presence of a "1" in bit 1 of an address field octet signals that it is the final octet of the address field.

6.2.2.3 Command/response field bit (C/R)

The C/R bit identifies a frame as either a command or a response. The C/R bit is employed symmetrically for the two directions of transmission, and is coded as shown in Table 4.

TABLE 4/V.120

Coding of C/R bit

C/R	Meaning
0	Command
1	Response

6.3 Signalling protocols

Signalling procedures are described in this subclause for the:

a) establishment and release of the underlying circuit-mode bearer connection; and

b) establishment and release of logical links, multiplexed within the circuit-mode bearer connection.

Procedures for establishment and release of circuit-mode bearer connections are required only for demand establishment of communication.

Procedures for establishment and release of logical links are used only for demand establishment of logical links. A procedure for semi-permanent establishment of logical links is also defined. Either procedure may be used over either demand or semi-permanent circuit mode bearer connections.

To differentiate the logical link establishment protocol from the protocols defined in Recommendation Q.931, a different protocol discriminator is used (see 6.3.2.4.1).

6.3.1 Establishment of underlying circuit-switched bearer connection

Demand establishment and release of circuit-switched bearer connections shall be done using the formats and procedures of Recommendation Q.931.

In the SETUP message, the Bearer capability information element shall be coded to indicate circuit mode unrestricted digital information.

The low layer compatibility information element shall be coded to indicate circuit mode, unrestricted digital information with ITU-T standardized rate adaption V.120. If Annex M/Q.931 is to be used, the negotiation indicator (octet 5a) shall be coded as "out-band negotiation possible". If the procedures of 6.3.2 are supported, LLI negotiation (octet 5b) shall be coded as "LLI negotiation"; otherwise, it shall be coded as default LLI = 256 only. Remaining fields in the Low layer compatibility (LLC) information element shall be coded to indicate the particular values to be used with the default LLI = 256.

6.3.2 Establishment of logical links

When an underlying circuit-switched bearer connection is established, a logical link identified by LLI = 256 is established at the same time. Additional Data Link Connection Identifiers (DLCIs) may be established by prior agreements between peer entities.

Logical link negotiation procedures may be carried out by means of user information messages in Q.931 call associated temporary signalling connection on the ISDN D-channel, or by means of logical link zero within the bearer channel using Q.931 elements of procedure (i.e. either UI or I frames). The choice of methods is a terminal equipment option and is partially determined by the availability of end-to-end ISDN signalling capability. The optional establishment of logical links between equipment that support different options may be possible.

The logical link establishment protocol operates over a logical link reserved for its use, identified by LLI = 0. This protocol uses either the multiframe mode (preferred) or unacknowledged mode of the Data Link Control service. No terminal adaption protocol header is used in support of this protocol.

Data link control entities shall be designated to be either "default assignee" or "default assignor". The default assignor shall normally assign LLIs. However, the default assignee may need to assume the role of assignor during negotiation. The assignor/assignee field (octet 5b) in the Low layer compatibility information element shall be used during establishment of logical links using this protocol.

6.3.2.1   Logical link establishment during circuit-switched bearer connection establishment

The first logical link established between the two data link control entities is the default LLI = 256. This is done using information provided in the LLC information element.

In connections where end-to-end notification of low layer compatibility is not supported, the data link control entity must rely on prior agreement to configure its options. Where no prior agreement exists, it may reject an offered call, assume a default and try to work with its peer, or it may choose to negotiate the values using SETUP with LLC parameters for LLI = 256 in-band on LLI = 0.

6.3.2.2   Logical link establishment on an active circuit-switched bearer connection

Protocol exchanges are carried in LLI = 0 in the bearer channel.

6.3.2.2.1   LLI assignee

If a data link control entity is determined to be assignee, it must set the assignor/assignee field in LLC information element contained in any additional SETUP messages to "0".

The assignee data link control entities request additional logical links by sending a SETUP message without the LLI information element. The data link control entity receiving this SETUP message assigns a LLI by including the LLI information element in the CONNECT message.

6.3.2.2.2   LLI assignor

If a data link control entity is determined to be assignor, it must set the assignor/assignee field in the low-layer compatibility information element contained in any additional SETUP messages to "1".

The assignor data link control entities set up additional logical links by sending SETUP messages that include the LLI information element. The receiving data link control entity responds with a CONNECT message and sets up a logical link using the information provided in the SETUP message.

6.3.2.2.3   Resolution of collisions when both peers are default assignee

The first data link control entity initiating a request for a logical link other than the default shall assume the assignee role. The data link control entity that receives that request shall assume the assignor role.

If both data link control entities simultaneously send SETUP message, the SETUP message containing the larger call reference (see Recommendation Q.931 for the definition of call reference) is accepted and treated in accordance with the above procedure. The response to the SETUP message with the lower call reference is a RELEASE COMPLETE message. If both SETUP messages contain the same call reference, they are both cleared with RELEASE COMPLETE messages, and the data link control entities select different call references and try again.

6.3.2.3 Messages used for logical link establishment and release

The following messages are used for establishing logical links within a bearer channel.

Call establishment:	SETUP
	CONNECT
Call clearing:	RELEASE
	RELEASE COMPLETE

6.3.2.3.1 SETUP

This message is sent by the signalling protocol entity associated with either TA to indicate that it desires to initiate a new logical link. It must contain protocol discriminator, call reference, and message type. A Low layer compatibility information element can optionally be included in the SETUP message. A Logical link identifier information element must be included in the SETUP message if the signalling protocol entity is assigning the LLI, and not included if requesting an LLI from the other signalling protocol entity. For applications where physical interface selection is desired (e.g. at the R reference point), the sub-address information element may be used. See Table 5 for the information elements that are used in the SETUP message.

TABLE 5/V.120

SETUP message content

Information element	Subclause	Type	Length
Protocol discriminator	6.3.2.4.1	M	1
Call reference	6.3.2.4.3	M	2
Message type	6.3.2.4.2	M	1
Logical link identifier	6.3.2.4.6	O (Note 1)	4
Called party sub-address	6.3.2.4.7	O (Note 2)	2-23
Calling party sub-address		(Note 3)	2-23
Low layer compatibility	6.3.2.4.5	O (Note 4)	2-13

M   Mandatory

O   Optional

NOTE 1 – Included if the calling user assigns LLI for that connection.

NOTE 2 – Included if the calling user wishes to select a specific physical interface (e.g. at the R reference point) associated with the terminal adaptor.

NOTE 3 – Included if it is desired to identify the specific physical interface (e.g. at the R reference point) associated with the terminal adaptor of the calling user.

NOTE 4 – Included when the calling user wants to pass low layer compatibility information to the caller user.

6.3.2.3.2 CONNECT

This message is sent by the signalling protocol entity associated with the TA that has received a SETUP message to indicate that the request for establishment of an additional logical link has been accepted. It must include protocol discriminator, call reference and message type information elements. The low layer compatibility information element can optionally be included in the CONNECT message. The logical link identifier information element must be included if not included in the SETUP message, and is not included otherwise. See Table 6 for the information elements that are used in the CONNECT message.

TABLE 6/V.120

CONNECT message content

Information element	Subclause	Type	Length
Protocol discriminator	6.3.2.4.1	M	1
Call reference	6.3.2.4.3	M	2
Message type	6.3.2.4.2	M	1
Logical link identifier	6.3.2.4.6	O (Note 1)	4
Low layer compatibility	6.3.2.4.5	O (Note 2)	2-13
M Mandatory			
O Optional			
NOTE 1 – Included if the called is assigning LLI.			
NOTE 2 – Included to allow the called user to negotiate low layer compatibility information with the calling user.			

6.3.2.3.3 RELEASE

The RELEASE message is used to indicate that the signalling protocol entity associated with the TA intends to release the call reference and the logical link, and that the signalling protocol entity receiving this message must release the logical link and prepare to release the call reference after sending a RELEASE COMPLETE. This message must contain protocol discriminator, call reference, message type, and optionally cause information elements. See Table 7 for the information elements that are used in the RELEASE message.

TABLE 7/V.120

RELEASE message content

Information element	Subclause	Type	Length
Protocol discriminator	6.3.2.4.1	M	1
Call reference	6.3.2.4.3	M	2
Message type	6.3.2.4.2	M	1
Cause	6.3.2.4.4	O	2-4
M Mandatory			
O Optional			

6.3.2.3.4 RELEASE COMPLETE

The RELEASE COMPLETE message is sent to acknowledge that the signalling protocol entity associated with the TA sending the message has released the logical link and call reference. This message must contain protocol discriminator, call reference, and message type and optionally cause information elements. See Table 8 for the information elements that are used in the RELEASE COMPLETE message.

TABLE 8/V.120

RELEASE COMPLETE message contents

Information element	Subclause	Type	Length
Protocol discriminator	6.3.2.4.1	M	1
Call reference	6.3.2.4.3	M	2
Message type	6.3.2.4.2	M	1
Cause	6.3.2.4.4	O	2-4
M Mandatory			
O Optional			

6.3.2.4 Information elements

This subclause provides the format of the information elements used by the logical link negotiation procedure, and it specifies the coding of particular octets within those information elements. All other octets shown in the format of these information elements should be coded in accordance with Recommendation Q.931.

6.3.2.4.1 Protocol discriminator

The protocol discriminator is defined in Recommendation Q.931. It shall be coded as follows:

Bits

8 7 6 5 4 3 2 1

0 0 0 0 0 1 1 1   V.120 rate adaption

This coding is in alignment with Recommendation Q.931.

6.3.2.4.2 Message type

The content of the message type shall be as defined in Recommendation Q.931.

6.3.2.4.3 Call reference

The call reference shall be as defined in Recommendation Q.931. The length of the call reference shall be two octets; i.e. the length of the call reference value shall be one octet. The dummy and global call references shall not be used.

6.3.2.4.4 Cause

The cause information element shall be as defined in Recommendation Q.931. The format of the cause information element is shown in Figure 7. Only the following cause values shall be used:

#16 Normal call clearing

#21 Call rejected

All other values are reserved. The optional diagnostic field may or may not be included.

6.3.2.4.5 Low layer compatibility

The low layer compatibility information element is used within the SETUP and CONNECT message to negotiate parameters. See Figure 8 for definition of the low layer compatibility information element.

Bits

8	7	6	5	4	3	2	1	Octet
			Cause					
0	0	0	0	1	0	0	0	1
			Information element identifier					
			Length of cause contents					2
1 ext.	0	0	0	0	0	0	0	3
1 ext.				Cause				4

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Cause values

16   Normal clearing
21   Call rejected

FIGURE 7/V.120

Cause information element

Bits

8	7	6	5	4	3	2	1	Octet
			Low layer compability					
0	1	1	1	1	1	0	0	1
			Information element identifier					
			Length of the LLC information element contents					2
1 ext.	Coding standard		Information transfer capability					3
0/1 ext.	Transfer mode		Information transfer rate					4
0/1 ext.	0 Layer 1 identifier	1	User information layer 1 protocol					5a)
0/1 ext.	Synchronous Asynchronous	Negotiation	User rate					5a a) (Note)
0/1 ext.	Hdr/ No Hdr	Multiframe	Mode	LLI Negotiation	Assignor Assignee	In-band/ Out-band	0 Spare	5b a) (Note)
0/1 ext.	Number of stop bits		Number of data bits		Parity			5c a) (Note)
1 ext.	Duplex mode	Modem type						5d a) (Note)
1 ext.	1 Layer 2 identifier	0	User information layer 2 protocol					6a)
1 ext.	1 Layer 3 identifier	1	User information layer 3 protocol					7a)

a) This field is optional.

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NOTE – This octet is present only if octet 5 indicates rate adaptation.

FIGURE 8/V.120

Low layer compatibility information element

The coding of the fields in the octets of the LLC information element is as follows:

Coding standard (octet 3)

Bits

7 6

0 0   ITU-T standardized coding as described below

Information transfer capability (octet 3)

Bits

5 4 3 2 1

0 1 0 0 0   Unrestricted digital information
0 1 0 0 1   Restricted digital information

Transfer mode (octet 4)

Bits

7 6

0 0   Reserved

Information transfer rate (octet 4)

Bits

5 4 3 2 1

0 0 0 0 0   Reserved

User information layer 1 protocol (octet 5)

Bits

5 4 3 2 1

0 1 0 0 0   Terminal adaption (this Recommendation)

This implies the presence of octets 5a, 5b, as defined below, and optionally octets 5c and 5d.

Synchronous/asynchronous (octet 5a)

Bit

7

0   Synchronous
1   Asynchronous

NOTE 1 – Octets 5c and 5d may be omitted in case of synchronous user rate except for half-duplex operation.

Negotiation (octet 5a)

Bit

6

0   Reserved

NOTE 2 – This field should be treated as reserved. It should be set to "0" on transmission and ignored on reception.

User rate (octet 5a)

Bits

5 4 3 2 1

0 0 0 0 0   Unspecified
0 0 0 0 1   0.6 kbit/s
0 0 0 1 0   1.2 kbit/s
0 0 0 1 1   2.4 kbit/s
0 0 1 0 0   3.6 kbit/s
0 0 1 0 1   4.8 kbit/s
0 0 1 1 0   7.2 kbit/s

```
0 0 1 1 1        8.0 kbit/s
0 1 0 0 0        9.6 kbit/s
0 1 0 0 1        14.4 kbit/s
0 1 0 1 0        16.0 kbit/s
0 1 0 1 1        19.2 kbit/s
0 1 1 0 0        32.0 kbit/s
0 1 1 0 1        38.4 kbit/s
0 1 1 1 0        48.0 kbit/s
0 1 1 1 1        56.0 kbit/s
1 0 1 1 0        0.100 kbit/s
1 0 1 1 1        0.075/1.2 kbit/s
1 1 0 0 0        1.2/0.075 kbit/s
1 1 0 0 1        0.050 kbit/s
1 1 0 1 0        0.075 kbit/s
1 1 0 1 1        0.110 kbit/s
1 1 1 0 0        0.150 kbit/s
1 1 1 0 1        0.200 kbit/s
1 1 1 1 0        0.300 kbit/s
1 1 1 1 1        12.0 kbit/s
```

Terminal adaption header/no header (octet 5b)

Bit

<u>7</u>

0   Terminal adaption header not included
1   Terminal adaption header included

Multiple frame establishment support in logical link (octet 5b)

Bit

<u>6</u>

0   Multiple frame establishment not supported, only UI frames allowed
1   Multiple frame establishment supported

Mode of operation (octet 5b)

Bit

<u>5</u>

0   Bit transparent mode of operation
1   Protocol sensitive mode of operation

Logical link identifier negotiation (octet 5b)

Bit

<u>4</u>

0   Default LLI = 256 only
1   Full LLI negotiation

Assignor/assignee (octet 5b)

Bit

<u>3</u>

0   Message originator is "default assignee"
1   Message originator is "assignor"

In-band/out-of-band negotiation (octet 5b)

Bit

<u>2</u>

1   Negotiation is done in-band using logical link zero

Number of stop bits (octet 5c)

Bits

<u>7 6</u>

0 0	Not used
0 1	1 bit
1 0	1.5 bits
1 1	2 bits

NOTE 3 – If bit 7 of octet 5a is "0", then these bits, when present, are set to "0" on transmission and ignored on reception.

Number of data bits excluding parity bit (octet 5c)

Bits

<u>5 4</u>

0 0	Not used
0 1	5 bits
1 0	7 bits
1 1	8 bits

NOTE 4 – The number of data bits refer to the number transmitted across the interface between peer terminal adaption protocol entities.

NOTE 5 – The character structure that may be transported between peer terminal adaption protocol entities may be no more than eight bits. Therefore, if this field is coded as "8 bits", the parity information field shall be coded as "None". This implies that for 8-bit character structures with parity, the parity bit shall be stripped by the sending terminal adaption protocol entity and regenerated by its peer.

NOTE 6 – Characters that have eight data bits and no parity should be coded in the same way.

NOTE 7 – If bit 7 of octet 5a is "0", then these bits, when present, are set to "0" on transmission and ignored on reception.

Parity information (octet 5c)

Bits

<u>3 2 1</u>

0 0 0	Odd
0 1 0	Even
0 1 1	None
1 0 0	Forced to 0
1 0 1	Forced to 1

NOTE 8 – The parity information refers to the interface at the S, T or U reference point.

NOTE 9 – If bit 7 of octet 5a is "0", than these bits, when present, are set to "0" on transmission and ignored on reception.

Duplex mode (octet 5d)

Bit

<u>7</u>

0	Half duplex
1	Full duplex

Modem type (octet 5d)

Bits 6-1 coded according to network specific rules.

User information layer 2 protocol (octet 6)

Bits

<u>5 4 3 2 1</u>

0 0 0 0 1	Basic mode ISO 1745
0 0 0 1 0	Rec. Q.921 (I.441)
0 0 1 1 0	Rec. X.25 link level
0 1 0 0 0	Extended LAPB for half-duplex operation (Rec. T.71)

0 1 0 0 1	HDLC ARM (ISO 4335)
0 1 0 1 0	HDLC NRM (ISO 4335)
0 1 1 0 0	HDLC ABM (ISO 4335)
0 1 1 0 0	LAN logical link control (ISO 8802-2)
0 1 1 0 1	X.75 single link procedure

User information layer 3 protocol (octet 7)

Bits

<u>5 4 3 2 1</u>

0 0 0 1 0	Rec. I.451/Q.931
0 0 1 1 0	X.25 packet level protocol
0 0 1 1 1	ISO 8208 (X.25 packet level protocol for DTE)
0 1 0 0 0	ISO 8308 (OSI connection oriented network service specific subset of ISO 8208 and Rec. X.25)
0 1 0 0 1	ISO 8473 (ISO connectionless service)
0 1 0 1 0	T.70 minimum network layer

6.3.2.4.6 Logical link identifier

The purpose of the logical link identifier information element is to identify a logical link within the bearer channel. The default length of this element is four octets. The logical link identifier information element is coded as shown in Figure 9.

6.3.2.4.7 Called party sub-address

The optional called party sub-address may be included for certain applications (e.g. to select a specific TE2 behind an interface at the R reference point). This optional information element may be included in a SETUP message to select a specific TE2 or interface at the R reference point behind a terminal adapter. The called party sub-address information element is coded as shown in Figure 10.

Type of subaddress (octet 3)

Bits

<u>7 6 5</u>

0 0 0	Network Service Acces Point (NSAP) (ITU-T Rec. X.213 | ISO/IEC 8348 AD2)
0 1 0	User specified

Odd/even indicator (octet 3)

Bit

<u>4</u>

0	Even number of address signals
1	Odd number of address signals

NOTE – The odd/even indicator is used when the type of sub-address is "user specified" and the coding is Binary Coded Decimal (BCD).

Subaddress information (octet 4, etc.)

The NSAP (ITU-T Rec. X.213 | ISO/IEC 8348 AD2) address, shall be formatted as specified by octet 4 which contains the Authority and Format Identifier (AFI). The encoding is made according to the "preferred binary encoding" as defined in ITU-T Rec. X.213 | ISO/IEC 8348 AD2.

For a user-specified sub-address, the field is encoded according to the user specification, subject to a maximum length of 20 octets. When interworking with X.25 networks, BCD coding should be applied.

6.3.2.5 Logical link control procedures

These optional procedures define the method for negotiating logical links other than the default (LLI = 256). For set-up and clearing of the bearer channel, the procedures described in Recommendation Q.931 must be followed.

Bits								
8	7	6	5	4	3	2	1	Octet
Logical link identifier								
0	0	0	1	1	0	0	1	1
Information element identifier								
Length of logical link identifier contents								
0	0	0	0	0	0	1	0	2
0	0 Spare	Logical link identifier (high order 6 bits)						3
1 ext.	Logical link identifier (low order 7 bits)							4

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FIGURE 9/V.120

Logical link identifier information element

Bits								
8	7	6	5	4	3	2	1	Octet
Called party sub-address								
0	1	1	1	0	0	0	1	1
Information element identifier								
Length of called party sub-address identifier								2
1 ext.	Type of sub-address		Odd/even	0	0	0		3
				Spare				
Sub-address information								4 etc.

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FIGURE 10/V.120

Called party sub-address information element

6.3.2.5.1 Logical link establishment

A logical link may be established by either signalling protocol entity by sending a SETUP message.

If the signalling protocol entity sending the SETUP message assigns the LLI, the SETUP message must also include the assigned LLI value for the logical link.

If the signalling protocol entity does not assign the LLI, it must not include the LLI information element in the SETUP message. In this case the LLI is assigned by the receiving TA by including an LLI information element in the CONNECT message.

A signalling protocol entity may request a logical link by sending a SETUP message, setting timer T303, and entering "call initiated" state.

If no response to the SETUP message is received before the first expiry of timer T303, the SETUP message must be retransmitted and timer T303 restarted. After the second expiry of timer T303, the "null" state is entered.

A signalling protocol entity receiving the SETUP message must send a CONNECT message and enter the "active" state if able; otherwise, it must send a RELEASE COMPLETE message and enter the "null" state.

When the initiating signalling protocol entity receives the CONNECT message, it must stop timer T303, and enter the "active" state.

6.3.2.5.2   Logical link release

Either signalling protocol entity may request clearance of a logical link by sending a RELEASE message, setting timer T308, and entering "release request" state.

When a signalling protocol entity receives a RELEASE message, it must release the logical link, send a RELEASE COMPLETE message, release the call reference, and enter the "null" state.

When the signalling protocol entity initiating a RELEASE receives RELEASE COMPLETE message, it must stop timer T308, release the logical link, release the call reference, and enter the "null" state.

If the signalling protocol entity initiating the RELEASE does not receive a RELEASE COMPLETE message before the first expiry of timer T308, the RELEASE message must be retransmitted and timer T308 restarted. If RELEASE COMPLETE message is not received before timer T308 expires for the second time, the TA must release the logical link, release the call reference, and enter the "null" state.

If both signalling protocol entities simultaneously request to clear the same logical link by sending RELEASE messages, both must stop timer T308, release the logical link, release the call reference, and enter the "null" state.

> NOTE – This procedure cannot be applied to the default logical link (LLI = 256), as this logical link has no call reference associated with it.

7   Application of terminal adaption protocol to terminal adaptor functions

This clause provides additional information concerning application of the protocol defined in clause 3 to a Terminal Adaptor Functional Group. This clause provides information required for interoperation between a terminal adaptor and a TE1, IWF or another TA. However, specific design details are implementation dependent.

7.1   Clock synchronization

The specific method for clock synchronization (circuit mode applications) is implementation dependent. See Appendix III for a discussion.

7.2   Asynchronous mode operation

The options to be used in this mode are specified and negotiated using octets 5b, 5c and 5d of the Low layer compatibility information element. See 6.3.2.4.5.

7.2.1   Processing of characters received from the TE2

When adapting character oriented data streams, a sequence of characters without start or stop bits shall be encapsulated in accordance with the following:

1)   parity, when used, is checked;

2)   the parity bit shall be removed if the code being used is an 8-bit code, otherwise passed as part of the octet;

3)   when codes using fewer than 8 bits (including parity) are used, the octet containing a character is padded with "0s" in the higher order bits. The low order bit of a character is the first bit of the octet containing it.

The resulting data is placed in data fields of frames, with the segmentation bits B and F set to "1". The data is placed in frames ordered so that it is transmitted to the peer entity in the order it was received.

Frames may be sent based on a timer, after a certain frame size, after a carriage return, etc. However, the forwarding mechanism used is an implementation issue and may vary.

If a BREAK is detected, a frame with the BR bit set in the header shall be transmitted in the same frame or after all queued characters have been sent. The C1 and C2 bits should be set to "0".

If a parity error is detected on a character of data being queued for encapsulation the C1 bit is set to "1", and the frame sent following any frames already queued for transmission. Thus, setting of the C1 bit to "1" indicates that the last character in the frame in which the C1 bit is set to "1" was received by the TA with a parity error. When a stop/start protocol is used at the interface at the R reference point, and a stop bit error is detected on a character of data being queued for encapsulation the C2 bit is set to "1", and the frame sent following any frames already queued for transmission. Thus, setting of the C2 bit to "1" indicates that a stop bit error was detected by the TA immediately following the last character contained in the frame in which the C2 bit was set to "1".

7.2.2   Processing of frames received from the peer terminal adaption protocol entity

The TA shall perform the following processing on frames received from peer terminal adaption protocol entity:

1) If the number of data bits in the character structure is less than 8, and the parity of characters received from the peer Terminal Adaption protocol entity is the same as that expected by the TE2, characters shall be sent to the TE2 without further processing.

2) If the character structure contains 8 data bits, or if the parity of characters received from the peer terminal adaption protocol entity is different from that expected by the TE2, a parity bit shall be calculated for each character and appended before sending to the TE2.

3) If a stop bit error is indicated in the H octet, the action of the TA is implementation dependent.

4) If a parity error is indicated in the H octet, the TA may force a parity error in the last character of the frame, or may take other implementation-dependent action.

5) If a break is indicated in the H octet, the TA shall, after sending all of the characters in the frame to the TE2, send a break to the TE2.

6) Characters to be transmitted shall be framed by the number of start bits and stop bits expected by the TE2.

7.3   Protocol sensitive synchronous mode operation

7.3.1   Processing of frames received from the TE2

Service data units (user frames) containing HDLC address, control, and information field when applicable (and FCS when UI frames are used for encapsulation) are segmented, if necessary, with each segment preceded by the header. Segmentation shall be such that no frame transmitted to the peer terminal adaption protocol entity (across the interface at the S, T, or U reference point) has an information field longer than N201 octets. The data is placed in frames ordered so that it is transmitted to the peer entity in the order it was received.

If only one segment is required, the header shall indicate both the beginning segment and the final segment in the "B" bit and the "F" bit. If more than one segment is required, the header of the first segment shall indicate the "begin" segment and the last segment of the message shall indicate the "final" segment. All intermediate segments shall have both "begin" and "final" segment indicators set to "0".

The C1 and C2 bits shall be used as follows:

1) C1 set to "0" and C2 set to "1" indicate that a bit error was detected in the HDLC message being transmitted in the sequence of segments;

2) C1 set to "1" and C2 set to "0" indicate that the user frame being transmitted in the sequence of segments has been aborted;

3) C1 and C2 set to "1" indicate that an overrun has occurred towards the interface at the S/T/U reference point as described above in 3.2.1.2.

If an HDLC idle condition (i.e. continuous marking) is received from the TE2, a frame with the BR bit in the H octet set to "1" shall be transmitted. The BR bit may be set to "1" in the last segment of a previous frame, or in a frame containing no user data. When the end of the HDLC idle condition is received, a frame with the BR bit of the H octet set to "0" shall be transmitted.

7.3.2   Processing of frames received from the peer terminal adaption protocol entity

The following processing shall be performed on the data received:

1) The header shall be checked as follows:

   a) if the "begin" segment bit is "1" and the previous segment did not have the "final" segment bit set to "1", then the previous user frame shall be aborted;

   b) if the "begin" segment bit is "0" and there is no user frame currently in progress, the segment will be discarded;

   c) if the C1 or C2 error bit is "1", then the segment will be discarded and the user frame in progress will be invalidated (e.g. aborted or sent with an incorrect FCS).

2) In the case when UI frames are used for encapsulation, the FCS received in the data stream may be examined and the appropriate action taken, if the FCS is not examined, it shall be passed on as the FCS of the reconstructed user frame.

If an underrun occurs toward the R reference point, then the frame being sent shall be treated as described in 3.2.1.2.

If the BR bit is "1", then an HDLC idle condition is generated after processing the received data. The HDLC idle condition shall be maintained until a frame is received with its BR bit set to "0".

7.4   Bit transparent mode operation

A synchronous data stream is broken into fixed size blocks and these blocks are sent to the peer terminal adaption protocol entity (over the interface at the S, T, or U reference point) in the same order that they were queued. The received data is removed from the frames and processed in the same order as received.

The terminal adaption header must be used in bit transparent mode if it is necessary to transmit the control state information. When the terminal adaption header is used in this mode, C1 and C2 bits must both be set to "0" (no error), B and F bits must both be set to "1", and the reserved bits and the BR bit must be set to "0".

If an underrun occurs toward the R reference point, then the procedures described in 3.2.1.3 shall be followed.

For unique applications, the contents of a frame received with an FCS error may be processed.

Annex A

List of variables

To be provided in the future.

Annex B

Alphabetical list of abbreviations used
in this Recommendation

AFI	Authority and Format Identifier
BCD	Binary Code Decimal
C/R	Command/response field bit

CD	Data channel receive signal line detector
CS	Control State
CTS	Ready for sending
DCE	Data Circuit-terminating Equipment
DLCI	Data Link Connection Identifier
DM	Disconnected Mode
DR	Data Ready
DSR	Data Set Ready
DTE	Data Terminal Equipment
DTR	Connect data set to line (108/1)
DTR	Data Terminal Ready (108/2)
EA	Address field extension bit
FCS	Frame Check Sequence
FDX	Full duplex
HDLC	High-level Data Link Control procedure
HDX	Half duplex
ISDN	Integrated Services Digital Network
IWF	Interworking Function
LLC	Low Layer Compatibility
LLI	Logical Link Identifier
MTA	Multiprotocol Terminal Adaptor
NSAP	Network Service Access Point
RC	Receiver signal element timing (DCE)
RD	Received Data
RI	Calling Indicator
RNR	Receive Not Ready
RR	Receive Ready
RTS	Request to Send
SABME	Set Asynchronous Balanced Mode Extended
SG	Signal Ground
SR	Send Ready
TA	Terminal Adaptor
TC	Transmitter signal element timing (DCE)
TD	Transmitted Data
UA	Unnumbered Acknowledgement
UI	Unnumbered Information
XID	Exchange identification

Annex C

Support of V.42 *bis* data compression

C.1   Introduction

This Annex describes additional procedures to allow negotiation of the use of V.42 *bis* data compression and its associated parameter values. In addition or as an alternative, it allows the negotiation of manufacturer-specific procedures and parameter values.

The support of these procedures in an implementation of V.120 is optional. When they are supported, the state of the protocol at the time a logical link is established shall be that V.42 *bis* or manufacturer-specific procedures are not in use.

In an implementation supporting multiple logical links, the use or not of V.42 *bis* or manufacturer-specific procedures may be negotiated individually for each logical link.

The extension to V.120 described in this Annex is applicable only to the protocol sensitive asynchronous mode of operation. In this Annex, it is mandatory that the data link layer shall operate using the multiple frame acknowledged information transfer procedure.

> NOTE – It is intended that any extension to V.42 *bis* (or a new Recommendation) that supports synchronous protocols using the HDLC frame format or specifies alternative compression algorithms should also apply to this Recommendation.

C.2   Negotiation/Indication of use of the V.42 *bis* procedure and its parameter values

C.2.1   General

In order to commence operation in V.42 *bis* data compression mode, a Terminal Adaptor (TA) shall initiate procedures using XID frames to negotiate/indicate the use of V.42 *bis* data compression and its associated parameter values with the remote TA. This procedure shall take place immediately after the error-corrected logical link has been set up using an SABME/UA exchange. The TA that initiates the SABME/UA exchange shall also initiate the XID exchange.

> NOTE – This is the TA that receives a CONNECT message when a logical link is set up (see 4.2). For operation over a circuit mode bearer service, the CONNECT message associated with the default logical link (LLI = 256) is the one received when the circuit mode bearer connection is established.

The subsequent use of an XID exchange to change the V.42 *bis* parameter values after data transmission has commenced is for further study.

Upon completion of the negotiation/indication process, the affected parameter values/procedure settings shall be recorded.

No sequence numbers are contained within the control field of an XID frame and the P/F bit is set to 0. The address field contains the LLI value for the logical link concerned.

In the following subclauses, the procedure at each TA is described in terms of passing L-SETPARM primitives between the data link control entity for a particular logical link and a control function which is associated with the management of the TA. The procedure commences with the control function at the initiating TA issuing an L-SETPARM request primitive.

C.2.2   Negotiation/indication procedure

Upon receipt of an L-SETPARM request primitive, the data link control entity shall transmit an XID command frame. The information field of this frame shall be used to convey the parameters/procedures to be negotiated/indicated to the remote data link control entity. Timer TM20 shall then be started and the retransmission counter reset.

On receipt of an XID command frame used for parameter/procedure negotiation/indication, the data link control entity shall issue an L-SETPARM indication primitive to its control function, passing it the contents of the information field.

On receipt of an L-SETPARM response primitive from its control function, a data link control entity shall return the indicated parameter values/procedure settings in the information field of an XID response frame.

On receipt of an XID response frame used for parameter/procedure negotiation/indication, the data link control entity shall stop timer TM20 and inform its control function by an L-SETPARM confirm primitive of the values contained in the information field.

C.2.3   Procedure on expiry of timer TM20

If timer TM20 expires before receipt of the XID response frame, the data link control entity shall:

- retransmit the XID command as above;

- restart timer TM20; and

- increment the retransmission counter.

Should the retransmission counter equal NM20 when the timer expires, the data link control entity shall notify the control function that the negotiation/indication procedure did not complete.

It should be noted that this situation can arise from three circumstances:

a) the recipient of the XID command frame does not implement the procedures described in this Annex and has ignored the request to operate with data compression;

b) the recipient of the XID command frame has processed it and transmitted an XID response frame, perhaps multiple times, with the responses being corrupted and discarded;

c) all the XID command frames have been corrupted and discarded.

There is no way in which the sender of the XID command frame can distinguish between these situations and there are two alternative courses of action:

a) Continue operation without data compression on the assumption that, because of the low error rate of the digital circuits used, the situation a) is much more likely than the others. This course of action carries with it the risk that if, in fact, frames were lost, the parameters of the peer V.42 *bis* data compression entities may be different, resulting in loss or corruption of user data.

b) Clear the connection and attempt to re-establish it but without attempting to negotiate V.42 *bis* data compression. This has the possible disadvantage that in the case of the default logical link (LLI = 256) operating over a circuit mode bearer service, the only way to clear the logical link is to clear the circuit mode bearer connection itself.

The value of TM20 is defined in C.3.1 and NM20 in C.3.2.

C.3   Parameters of the data link control entity

C.3.1   Acknowledgement timer (TM20)

The acknowledgement timer governs the amount of time that a data link control entity will wait for an acknowledgement before resorting to other action (e.g. transmitting a frame). The two error-correcting entities associated with an error-corrected connection may operate with a different value of TM20. Appendix III/Q.922 proposes a value of 2.5 seconds for an XID exchange.

C.3.2   Maximum number of retransmissions (NM20)

NM20 governs the maximum number of times that a data link control entity will re-attempt a procedure requiring a response. The two data link control entities associated with an error-corrected connection may operate with a different value of NM20. Appendix III/Q.922 proposes a value of 3 for an XID exchange.

C.4   Information fields in XID frames

C.4.1   General

The general structure of the information field of an XID frame is based on the encoding in ISO/IEC 8885 and is shown in Figure C.1 below. The information field is composed of a number of subfields. These subfields are a format identifier subfield, zero or more data link layer subfields and, possibly, a user data subfield.

When an octet encoding is shown for any of the subfields, it is shown with the right-most bit being the low-order bit and the bit transmitted first.

C.4.1.1 Format identifier subfield

The Format Identifier (FI) subfield is one octet in length and is the first octet of the information field of the XID frame. In general, the FI is encoded such that it can designate 128 different formats standardized by ISO and 128 different formats defined by users. Each ISO-standardized format is associated with a different FI value. The only such format defined at this time is the "general purpose" format.

C.4.1.2 Data link layer subfields

Data link layer subfields are used to specify various data link layer characteristics, such as operational parameters. In terms of Figure C.1, a data link layer subfield consists of a Group Identifier (GI) one octet in length, a Group Length (GL) two octets in length, and a parameter field (whose length is given by GL). The parameter field, in turn, is similarly decomposed into one or more sets of a Parameter Identifier (PI), a Parameter Length (PL), and a Parameter Value (PV) (the parameter length, however, is only one octet in length).

The data link layer subfields, if present, follow each other in ascending order of their GI values.

In this annex, a data link layer subfield is used to negotiate the use of the V.42bis protocol and the values of its parameters.

C.4.1.3 User data subfield

A GI has been defined to specify a user data subfield used in conjunction with the "general purpose" FI. This subfield, which, when present, follows all data link layer subfields, does not contain a GL. (See Figure C.1.) The subsequent information is bounded by the frame's FCS field.

In this Annex, the user data subfield is used to carry manufacturer-specific information. It is divided into sets of PIs, PLs, and PVs.
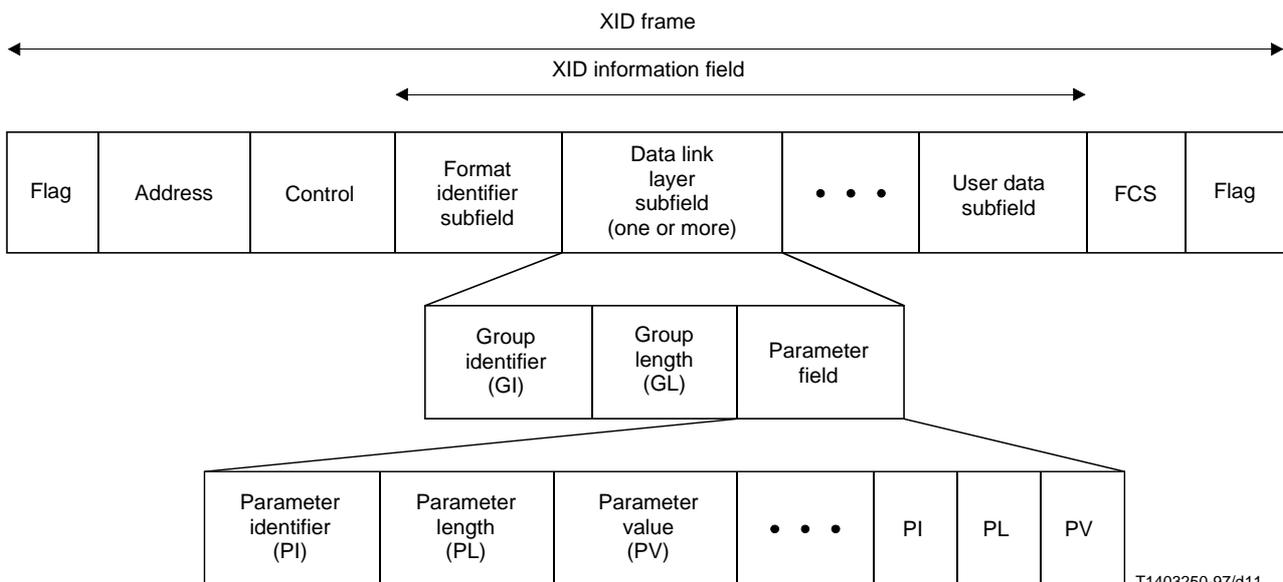

FIGURE C.1/V.120

General format of XID information field

C.4.2 Encoding for negotiation/indication of parameter values and optional procedures

The information field shall be encoded as specified below. Fields that are not recognized by the recipient are ignored.

Format identifier subfield

For negotiation/indication of parameter values and optional procedures, the FI subfield shall be encoded as "10000010" to indicate the ISO-standardized "general purpose" FI.

Data link layer subfields

Only one of the data link layer subfields specified in ISO/IEC 8885 shall be used in conjunction with this Annex. This is the "private parameter negotiation subfield" which has a GI value of "11110000".

The length of the subfields (GL) is dependent on the actual information to be transmitted.

Each item to be negotiated and/or indicated is identified by a PI. Table C.1 shows each item together with its PI and PL values.

User data subfield

The user data subfield may be present independently of whether negotiation and/or indication is performed. This subfield has a GI value of "11111111".

The only parameter within this subfield defined in this Annex is a "manufacturer ID". This parameter shall be identified by a PI value of "11111111". The encoding of the associated PV subfield is manufacturer-specific. The high-order bit of the first octet of the PV field is used as follows:

- bit = 0: Manufacturer IDs not assigned by ITU-T;

- bit = 1: ITU-T-assigned manufacturer IDs (the assignment of these identifiers is for further study).

When receiving a manufacturer ID that is not recognized, the manufacturer ID field is ignored.

> NOTE – An example of the use of this subfield would be to negotiate a manufacturer's proprietary data compression protocol.

C.5 Flow control and asynchronous-break handling

C.5.1 Flow control

In order to exploit fully the increase in throughput offered by the use of data compression, it is necessary to operate the terminal adaptor's user interface at a bit rate higher than that of the logical link. However, since the actual compression ratio will vary with the type of data, it is recommended that flow control as specified in 7.3.1/V.42 should be used at the user interface.

C.5.2 Asynchronous-break handling

In the normal operation of the protocol sensitive asynchronous mode, the terminal adaption header carries information concerning error conditions at the TA's user interface, together with optional flow control information (UI frame operation only). Breaks and data are handled in sequence as follows. When a break is detected, the BR bit in the TA header is set to 1 and the frame is forwarded without assembling further characters (3.2.1.1). When a frame with the BR bit set is received, the receiving entity outputs any data contained within the frame to the TE and then follows this with a break (7.2.2). In a similar way parity and stop-bit errors cause immediate forwarding of the frame, the C1 and C2 bits indicating that there is an error in the last character in the frame.

The addition of V.42 *bis* data compression introduces compression and decompression entities between the user interfaces and the frame assembly and disassembly processes, thus complicating the data and break sequencing. This leads to two methods of handling breaks and error conditions.

TABLE C.1/V.120

Parameter/procedures associated with the "private parameter negotiation" subfield

PI		PL	Parameter	Note(s)
Decimal	Binary			
0	00000000	4	Parameter set identification	1
1	00000001	1	V.42 *bis*: Data compression request (P0)	2
2	00000010	2	V.42 *bis*: Number of codewords (P1)	2, 3
3	00000011	1	V.42 *bis*: Maximum string length (P2)	2, 3

NOTE 1 – This parameter shall always be the first parameter present in the "private parameter negotiation" subfield. Its PV value shall be the octets "01010110", "00110001", "00110010", "00110000" (the IA5 characters for "V120").

NOTE 2 – Parameters P0, P1 and P2 operate together to specify whether data compression will be used and, if so, to specify the parameters associated with the procedure. The presence of P0 shall indicate a request for data compression for the direction(s) indicated. In a subsequent XID exchange, the absence of a parameter shall indicate that its previously negotiated value shall remain unchanged. This subsequent use is for further study.

For P0, its PV value indicates the direction for which data compression is requested; PV is encoded as "000000nn" where nn indicates:

  – 00: compression in neither direction (default);

  – 01: negotiation initiator-responder direction only;

  – 10: negotiation responder-initiator direction only;

  – 11: both directions.

NOTE 3 – Parameter values for these items shall be encoded in binary. Within an octet, the first bit transmitted shall be the lowest-order bit. Where multiple octets are needed to express a parameter value, the first octet transmitted shall contain the higher-order bits.

C.5.2.1 Break handling with sequence preservation

Following detection of a break, a C-FLUSH request primitive is sent to the compression entity. This causes string matching to terminate the dictionary to be updated and the FLUSH codeword (and any necessary padding bits) to be output (see 7.9/V.42 *bis*). All outstanding data is then passed to the frame assembly function, the BR bit is set in the TA header, and the frame transmitted.

At the receiver, the contents of the frame are processed according to clause 8/V.42 *bis* and after the last data character has been output, a break condition is output to the TE interface. Parity and stop-bit errors can be signalled in a similar manner using the FLUSH codeword in association with the C1 and C2 bits

C.5.2.2 Break handling without sequence preservation

Following detection of a break, the BR bit is set in the next frame which is transmitted according to the normal forwarding criteria. The receiver is therefore aware that a break has occurred but it is unable to place it accurately in the data sequence. The usefulness or otherwise of signalling parity and stop-bit errors using the C1 and C2 bits using this approach is for further study.

Reference

  – ISO/IEC 8885:1993, *Information Technology – Telecommunications and information exchange between systems – High-level Data Link Control (HDLC) procedures – General purpose XID frame information field content and format.*

Appendix I

TE1 application

The protocols and procedures defined in this Recommendation may be used for data transport by TE1s as well as Terminal Adaptor (TAs). In the TE1 case, the interface at the R reference point is effectively replaced by a virtual interface within the TE1 to a higher layer entity. This Appendix describes some aspects of the application of this Recommendation in TE1s.

I.1 Asynchronous mode operation

I.1.1 Transmission onto the ISDN channel

The B, F bits are set to "1", and the C1 and C2 bits in the header are set to "0". The data to be transmitted is segmented as required, and each segment is appended to the header before transmission.

If a BREAK is received from the next higher layer, a frame with the BR bit set to "1" in the header, shall be transmitted at the earliest opportunity following data queued for transmission.

I.1.2 Reception from the ISDN channel

Processing of received data is as follows, based on the values of the C1 and C2 bits in the header:

1) if the C1 bit and C2 bits are both set to "0", the received characters are forwarded to the next higher layer without error indication;

2) if the C1 bit is set to "1", then a parity error indication is forwarded to the next higher layer with the characters received; the parity error applies to the last character in the frame;

3) if the C2 bit is set to "1", then a stop-bit error is forwarded to the next higher layer with the characters received; the error occurred immediately following the last character in the frame.

If the BR bit is set to "1" in the header of the received frame, then a BREAK indication is forwarded to the next higher layer after all data queued has been forwarded.

I.2 Synchronous mode operation

In order to communicate properly with a TE2, as described in 3.2.1.2, the messages passed to and received from the higher layer should include the HDLC address and control field to be used over the remote TE2-to-TA HDLC connection, but do not include HDLC flags, FCS or inserted "0"s. The HDLC address and control field will be contained in the information field of the frames received and transmitted by the TE1. The procedures described are for the case in which acknowledged data transfer is used. The procedures for unacknowledged data transfer are not described.

I.2.1 Transmission on to the ISDN channel

The user frame length is compared with N2120 (see 3.2.2). The message is processed depending on its length as follows:

1) If the message length is less than or equal to N2120, then the entire message is appended behind the header and both the B and F bits are set to "1". The resulting segment is then transmitted.

2) If the message length is greater than N2120, the first N2120 octets are appended to the header, with the B bit set to "1" and the F bit set to "0". The resulting segment is then transmitted.

   a) If the remaining portion of the message is greater in length than N2120, the next N2120 octets are appended to the header with both the B and F bits set to "0". The resulting segment is then transmitted.

   b) If the length of the remaining portion of the message is less than or equal to N2120, then the remaining portion of the message is appended to the header with the F bit set to "1" and the B bit set to "0". The resulting segment is then transmitted.

The C1 and C2 bits are normally set to "0".

I.2.2 Reception from the ISDN channel

Any messages that were segmented at the transmit end are reassembled as indicated by the B and F header bits. The header of a received frame shall be checked for error conditions as follows:

1) If the "begin" segment bit is "1" and the previous segment did not have the "final" segment bit set to "1", then the previous user frame shall be aborted.

2) If the "begin" segment bit is "0" and there is no message currently in progress, the segment shall be discarded.

3) If the C1 or C2 error bit is "1" then the segment will be discarded and the message in progress will be discarded.

If a frame is received with the BR bit set to "1" in the header, then the TE1 management entity shall be notified of an HDLC idle condition sent from the far end. The TE1 management entity is not notified of termination of the HDLC idle condition until a frame is received with the BR bit in its header set to "0".

When a message has been reassembled, it is passed to the next higher layer.

I.3 Bit transparent mode operation

I.3.1 Transmission on to the ISDN channel

The transmitting entity accepts data from the process using its services, segments the data into segments of fixed length at most N2120, and transmits that data within data fields of frames to its peer entity. The length of transmitted interframe time fill is adjusted so that the average data transmission rate matches the rate selected during the call establishment.

I.3.2 Reception from the ISDN channel

The receiving entity, upon receiving a frame from its peer entity, checks the FCS and if the FCS is valid, passes any data contained in the frame to the process using its services. If the FCS is not valid, the entity may, on an application specific basis, discard the data contained in the errored frame or pass that data, with or without error indication, to the process using the services of the entity.

I.4 TE1 control state variable processing

This subclause describes the use of the control state variable and the processing of the control state information field, when present, defined in 3.2.3. Use of the control state information field is optional. The procedures described below in this subclause and in its subclauses only apply if the control state information field is used.

In TE1 applications, the six control state variable DR(S), SR(S), RR(S), DR(R), SR(R), and RR(R) have the following meanings:

1) For sending DR – DR(S) state variable: indicates that the sending TE1 is powered up and connected for communication.

2) For receiving DR – DR(R) state variable: indicates that the far end TE1 is powered up and connected for communication.

3) For sending SR – SR(S) state variable: indicates that the sending TE1 is ready to send frames.

4) For receiving SR – SR(R) state variable: indicates that the far end TE1 is ready to send frames.

5) For sending RR – RR(S) state variable: indicates that the TE1 is ready to receive frames.

6) For receiving RR – RR(R) state variable: indicates that the far end TE1 is ready to receive frames.

The following subclauses describe the procedure for control state variable processing in a TE1 using this Recommendation. Note that the control states in a TE1 as described above are essentially analogous to those in a TA as described in 3.1.2. Thus, the TE1 control state variables processing described below is completely compatible with that described in 3.2.3 for a TA.

I.4.1   Control state variable initialization

The first I or UI frame sent by each peer shall contain the control state information octet. This exchange shall occur immediately following link initialization.

I.4.2   Sending a control state information octet

A control state information Octet should be sent whenever a send control state variable changes. A Send control state variable shall change with a change to the state of the TE1 or a change to a Receive control state variable. A frame containing the control state information octet shall be sent following any queued data for the interface at the S or T reference point.

The control state information field is sent in the last frame assembled when the control state change occurs, or in a separate frame.

The contents of the control state information octet is set to the state of the corresponding send state variables. DR is set to DR(S), SR is set to SR(S) and RR is set to RR(S).

I.4.3   Receiving a control state information octet

Upon receipt of a control state information octet, the control field is checked with the receive control state variables: DR to DR(R), SR to SR(R) and RR to RR(R) if the peer entity is not being flow controlled by the use of the RR(R) state. Notification is made to the TE1 management entity.

If SR(R) was "1" and the SR bit in the Receive control state information octet is "0", then the RR(S) state is set to SR(R), consistent with one of the following:

1)   If received data (from the peer entity) does not remain to be forwarded (no message in progress), then the control actions can occur immediately.

2)   If received data (from the peer entity) is incomplete (e.g. in protocol sensitive mode the final frame was not received) and DR is "1", the incomplete message is forwarded with indication made to the TE1 management entity.

3)   If received data (from the peer entity) is complete, the message is forwarded and the notification of the TE1 management entity occurs.

If RR(R) and the RR bit in the received control field differ, notification is made to the TE1 management entity.

If DR(R) was "0" and the DR bit in the received control field is "1", notification is made to the TE1 management entity.

If DR(R) was "1" and the DR bit in the received control field is "0", then notification is made to the TE1 management entity consistent with the following:

1)   If received data from the peer entity is incomplete, it is discarded.

2)   If received data from the peer entity is a complete message, then it should be forwarded until completion prior to the control actions taking place.

Appendix II

Mapping of interface at R reference point circuits to control state information

The control of interface leads is not specified in this Recommendation. It is only necessary that the control provided conform to the requirements of the particular interface at the R reference point supported (e.g. as specified in Recommendation V.24 and ISO 2110). The following guidelines are provided to illustrate a suitable procedure.

II.1   Commonly supported interface leads

The V.24 interface leads that would be expected to be commonly supported are shown in Table II.1 as an example.

The leads that would be used to provide maintenance functionality are not listed because the associated functionality in this Recommendation is for further study.

TABLE II.1/V.120

Interface name abbreviation

Circuit function/Name	Abbreviation	Circuit number
Signal ground	SG	102
Transmitted data	TD	103
Received data	RD	104
Request to send	RTS	105
Ready for sending	CTS	106
Data set ready	DSR	107
Connect data set to line	DTR	108/1
Data terminal ready	DTR	108/2
Data channel receive signal line detector	CD	109
Transmitter signal element timing (DCE)	TC	114
Receiver signal element timing (DCE)	RC	115
Calling indicator	RI	125

II.2 Control procedures

For call origination, the response to DTR is a function of whether the TA is configured for manual or automatic call origination. Generally calls/links are not originated until DTR is ON. In response to DTR ON, DSR may be turned ON. However, it may be more consistent with the original intent of DSR to delay its ON condition until after an indication that a channel has been assigned (e.g. SETUP ACKNOWLEDGE) is received.

Generally calls/links are not accepted unless the called TA has at least one free port (interface at the R reference point or TE2) on which DTR (108/2) has been turned ON [however, it is permissible, where RI is implemented, for DTR (108/2) to be normally OFF but turned ON in response to calling indicator (RI) ON condition]. After receiving a cut-through indication, the TA must turn DSR ON if it is not yet turned ON.

II.2.1 TE2 operating in duplex (FDX) mode

The control state information octet is not used for control of interface leads with TE2s operating in the full duplex (FDX) mode. In the duplex mode, this field is used for providing flow control capability when UI frames are used to carry data as described in 3.2.4.

The TE2 may respond to DSR ON by turning ON RTS. After receiving a cut through indication and completing the link initialization, the TA may turn ON CD and unclamp RD (CTS, if implemented, may be turned ON at this point or any time afterwards). When RD is unclamped, the TA shall send the appropriate idle code (continuous marks or flags) to the TE2.

II.2.2 TE2 operating in half duplex (HDX) mode

For half duplex (HDX) operation of the TE2, the called TE2 may turn ON RTS at any time after the TA has turned ON DSR. This is analogous to the operations of half-duplex modems where the called DTE turns ON RTS. When a calling/called relationship cannot be established, a glare condition, due to both ends turning RTS ON, may occur. The resolution of glare in such cases is for further study.

In response to RTS ON, after completing connection or link initialization, the TA must transmit a control state information octet with SR bit set to "1". After having established the link, the TA that receives SR equal to "1", must turn ON CD, unclamp RD, send the appropriate idle code to the TE2, and send a control state information octet with RR bit set to "1" to the far-end TA. After having initialized the link, the TA that receives RR equal "1" must turn CTS ON.

Once a TE2 completes transmitting data, it drops RTS. In response, the TA drops CTS and transmits a control state information octet with SR bit set to "0". Upon receiving a control state information octet with SR bit set to "0", a TA that has CD ON drops CD and sends a control state octet with RR bit set to "0". When CD is dropped, the TE2 may turn RTS ON (see the previous paragraph for the procedure that follows).

Appendix III

Clock synchronization

Figure III.1 shows two DTE/DCE configurations and their respective clock synchronization.

In the first case, the TA is providing the clocks to the DTE or DCE. In the second case, the DCE provides the transmit clock to the TA for data to the DTE, and the TA at the DTE end provides the receive clock to the DTE for this same data.

There are three alternative strategies that can be used for clock tracking. The first is to use the data buffers as clock variance buffers by having buffers absorb the accumulating clock variance. In this case, no special clock tracking is performed. If the buffer is completely depleted, underrun occurs causing an error on the synchronous interface at the R reference point. Buffer space overrun can also happen, causing an error. However, the buffer accumulation or depletion to the point of overrun or underrun due to clock error is a slow process and is predictable in the worst case within the ITU-T clock tolerance of 100 parts per million. The second strategy is for the clocks at both ends to be synchronized to the network. This strategy solves the problem but is not applicable to case 2.

A third strategy is to monitor the buffer state as data is being received from the interface at the S/T reference point in the TA that is providing the receive clock to the DTE. This strategy monitors the rate of data flow at this interface by checking the buffer state when a new frame is received and adjusts the clock rate/phase accordingly. For a given logical link, the nominal frame size must be kept constant for the duration of the connection. Signals at the interface at the R reference point, including timing signals, must conform to the applicable synchronous signal quality requirements. These requirements limit the permitted jitter and the magnitude of phase adjustment steps required for clock rate adjustments.

For asynchronous application, the first strategy (no clock correction) should be sufficient. Clock tolerance is compensated for by stop-bit interval adjustment. For these applications a clock tolerance of +1% to −2.5% is permissible. Underrun is not possible and buffering in the TA should be sufficient to avoid overrun.

For synchronous mode application, appropriate buffer set-up and management using no clock correction should be sufficient. Any clock tolerance error should be compensated for through adjustments in interframe intervals.

For bit transparent mode applications, continuous data does not allow for buffer resynchronization. For case 2, the frames are read into a buffer at the receiving TA and are clocked out to the TE2 by a time source derived in the TA. If the data is clocked out at the rate transmitted, each frame should fill the receive buffer to precisely the same level. If the rate is low, the fill level should increase and provide an indication that the clock rate must be increased and vice versa.

In some implementations, the clock adjustments might be in the form of repeated small adjustments in the phase of the clock, which would be derived from the ISDN network clock. Where the TE2 is tolerant of large phase steps, the process may be simple.
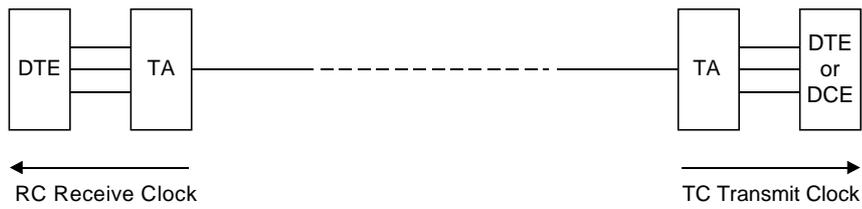
Case 1 – Receive clock tracks transmit clock via data or system synchronization.
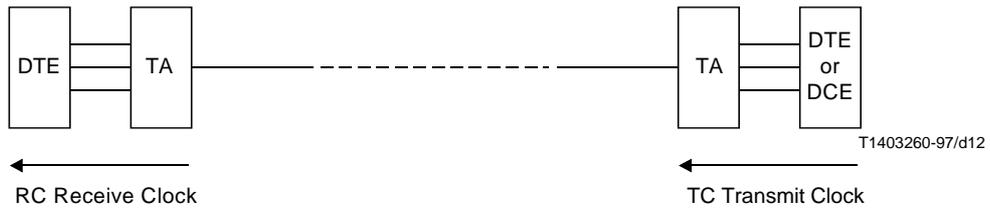
Case 2 – Receive clock tracks DCE receive clock via data.

FIGURE III.1/V.120

Clock tracking

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