

# THE WAY TOWARDS AUTONOMOUS DRIVING

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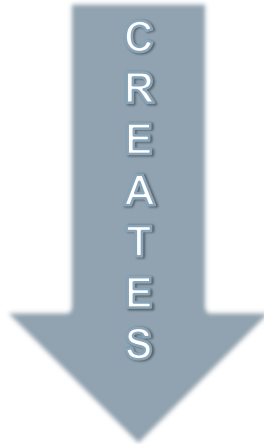
# MOTIVATION TO DEVELOP AUTOMATED FUNCTIONS I

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Mega Cities

Global  
Growth



From 1 billions cars today  
to 2-4 billion cars in our  
lifetime

The need for smarter vehicles which are

- Safer
- More efficient



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## MOTIVATION TO DEVELOP AUTOMATED FUNCTIONS II

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- Driver is the weak point
- Fatalities:
  - 38% caused by mental factors (sleep, drowsiness, medical)
  - 46% caused by misjudgement (safety distance, speed, weather, lane keeping, stationary objects)



Source: Auto Motor Sport 19, May 2010

# FORD FOCUS AVAILABLE DRIVER ASSISTANCE SYSTEMS



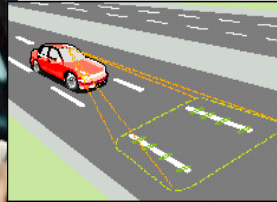
Blind Spot Information System



Low Speed Safety System



Driver Alert



Lane Keeping Aid



Lane Departure Warning



Active Park Assist / Parallel Parking



Traffic Sign Recognition



Power Child Locks



All Seat Beltminder Display



Adaptive Cruise Control



Auto High Beam

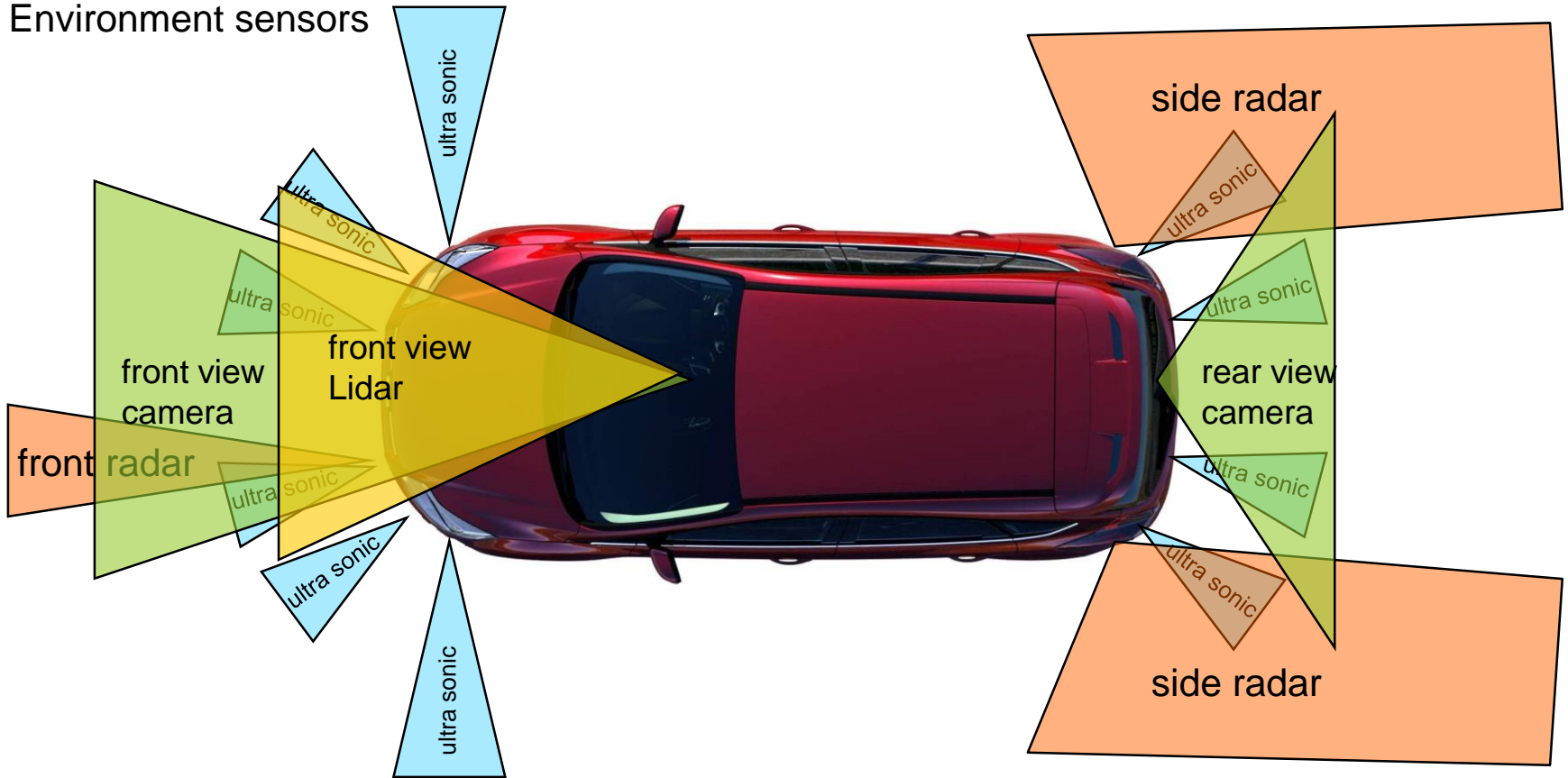


# SENSING DEVICES

Vehicle state sensors (e.g. wheel speeds, yaw rate)

Driver input sensors (e.g. steering wheel angle, brake & accelerator pedal, switches)

Environment sensors



# AUTOMATED DRIVING DEVELOPMENT – CRUISE CONTROL

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## Cruise Control

- Keep vehicle speed constant

## ACC (Adaptive Cruise Control)

- Maintains constant distance to vehicles in front

## ACC stop & go / full speed ACC

- Stops until stand still
- Automatically starts driving again

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## Traffic Jam Assist

- Automated steering control to stay in the current lane (until 50 km/h)
- The driver permanently monitors the system

## Automated high-way driving

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possible today

in future



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**Ford**  
**Traffic Jam Assist**



# AUTOMATED DRIVING DEVELOPMENT – PARKING

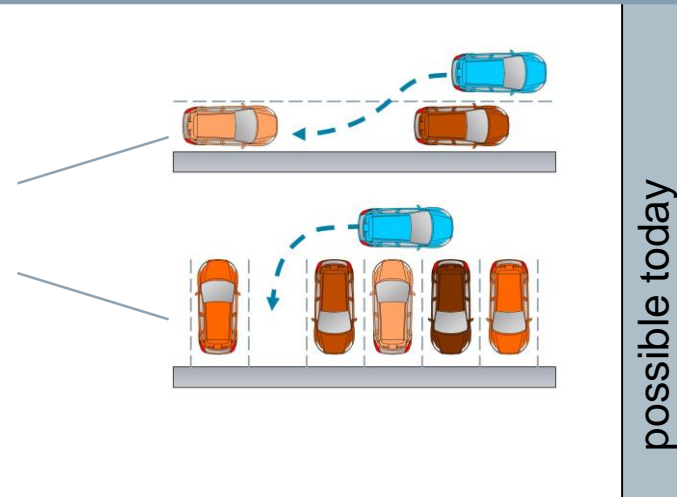
## Ultra-sonic parking sensors

- Warns the driver for obstacles

## Semi-automatic parallel parking

## Semi-automatic perpendicular parking

- Steering control
- The driver controls the speed of the car via accelerator and brake pedals



## Automatic parallel parking

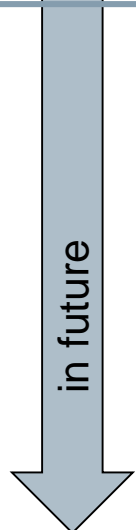
- Steering, brake and throttle control

## Smart phone parking

- Driver monitors vehicle from the outside during the parking manoeuvre

## Automatic valet parking

- Driver does not monitor the vehicle during the parking manoeuvre
- Separated parking deck without pedestrians required



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# AUTOMATED FUNCTIONS: FORD SELF-PARKING PROTOTYPE CAR

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# AUTOMATED FUNCTIONS – OBSTACLE AVOIDANCE

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# FORD'S STRATEGIES FOR AUTOMATED DRIVING RESEARCH

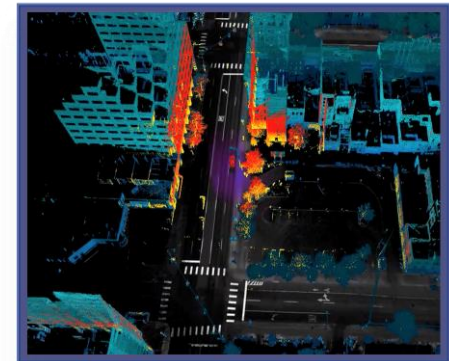
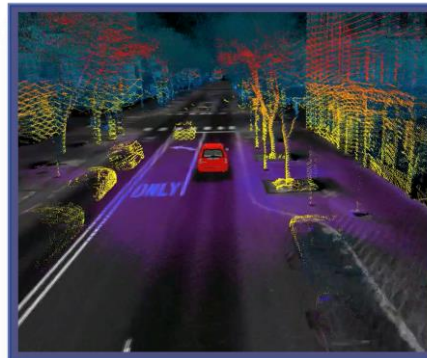
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- **Building Block**

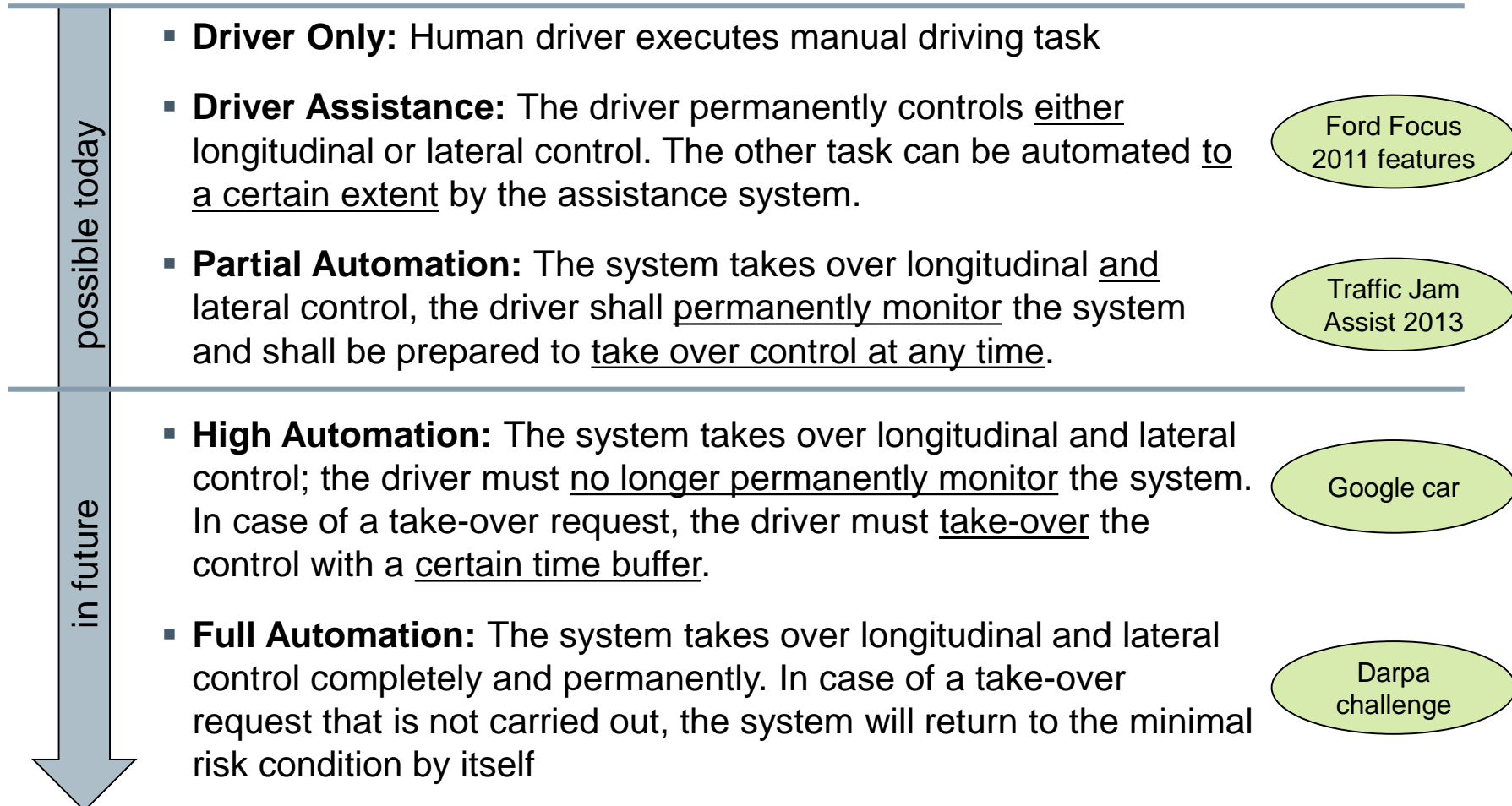
- Involves working with our current production suppliers to enhance and combine the existing sensors and algorithms to create new, more capable automated driving features

- **Top-Down**

- Involves creating a state-of-the-art Automated Driving platform to do leading edge research on what is possible in the absence of near-term production constraints



# VEHICLE AUTOMATISATION CLASSIFICATION



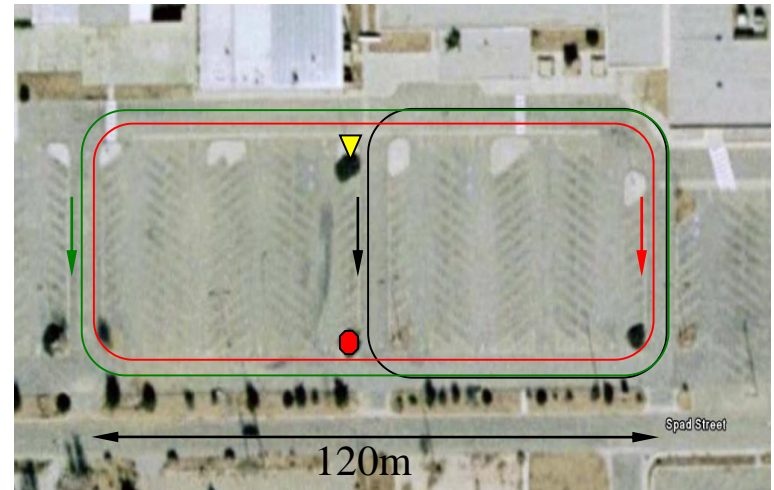
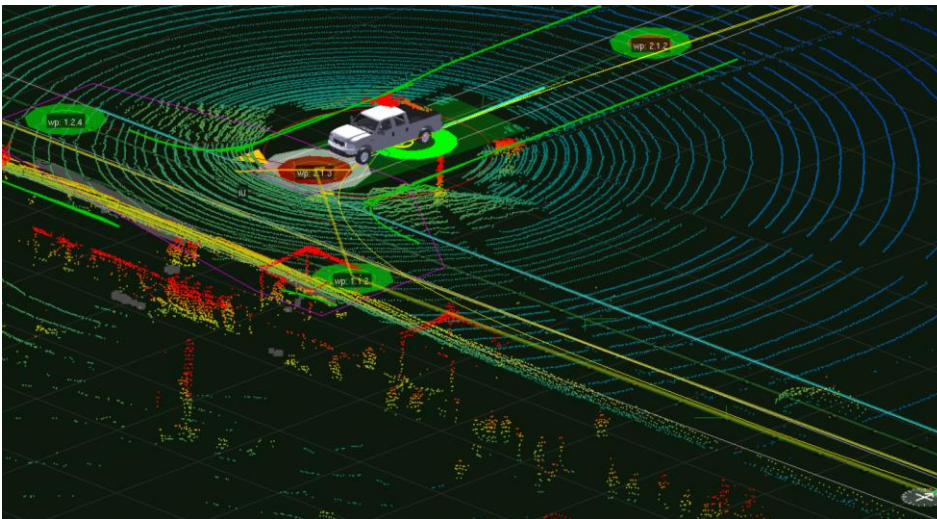
Source: German Federal Highway Research Institute (BASt - Bundesanstalt für Straßenwesen)

# DARPA URBAN CHALLENGE - AREA A

Ford was one of only 6 teams to have reached successive Finals of the event



Stopping, merging, and yielding across densely moving traffic



# FUSION HYBRID AUTOMATED RESEARCH VEHICLE

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# SUMMARY

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- Active Safety & Driver Assistance systems will significantly reduce the number of traffic accidents, injuries and fatalities
- Ford strategy is to make this systems available through our complete vehicle line-up and all geographical regions
- The next generation systems will have increased automated driving capability and take over some of the driving tasks under controlled condition
- Full vehicle automation is still in the research phase and the speed at which solutions take hold will be determined largely by customer acceptance of new technologies and how quickly cities develop enabling systems and infrastructure



# Q & A