



Recommendation ITU-R RS.2105-1
(12/2021)

**Typical technical and operational
characteristics of Earth exploration-satellite
service (active) systems using allocations
between 432 MHz and 238 GHz**

RS Series
Remote sensing systems

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Series	Title
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BS	Broadcasting service (sound)
BT	Broadcasting service (television)
F	Fixed service
M	Mobile, radiodetermination, amateur and related satellite services
P	Radiowave propagation
RA	Radio astronomy
RS	Remote sensing systems
S	Fixed-satellite service
SA	Space applications and meteorology
SF	Frequency sharing and coordination between fixed-satellite and fixed service systems
SM	Spectrum management
SNG	Satellite news gathering
TF	Time signals and frequency standards emissions
V	Vocabulary and related subjects

Note: This ITU-R Recommendation was approved in English under the procedure detailed in Resolution ITU-R 1.

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RECOMMENDATION ITU-R RS.2105-1

Typical technical and operational characteristics of Earth exploration-satellite service (active) systems using allocations between 432 MHz and 238 GHz

(2017-2021)

Scope

This Recommendation provides technical and operational characteristics of Earth exploration-satellite service (active) systems using allocations between 432 MHz and 238 GHz for utilisation in sharing and compatibility studies.

Keywords

EESS (active), Earth exploration-satellite service, remote sensing, synthetic aperture radar, altimeters, precipitation radar, scatterometers, cloud profile radar

Abbreviations/Glossary

ARNS	Aeronautical radionavigation service
CPR	Cloud profile radar
EESS	Earth exploration-satellite service
e.i.r.p.	Effective isotropically radiated power
FM	Frequency modulation
IFOV	Instantaneous field of view
LHCP	Left hand circular
LFM	Linear FM
LST	Local solar time
LRM	Low resolution mode
Non-GSO	Non-geostationary satellite orbit
NSS	Non-sun-synchronous
pdf	Power flux-density
PRF	Pulse Repetition Frequency
RF	Radio frequency
RHCP	Right hand circular
SRS	Space research service
SSO	Sun-synchronous
SAR	Synthetic aperture radars

The ITU Radiocommunication Assembly,

considering

- a) that Earth exploration-satellite service (EESS) (active) observations may receive emissions from active services;
- b) that EESS (active) is co-allocated with active services in certain bands;
- c) that studies considering protection for and from EESS (active) systems are taking place within ITU-R;
- d) that in order to perform compatibility and sharing studies with EESS (active) systems, the technical and operational characteristics of those systems must be known,

recognizing

- a) that Recommendation ITU-R RS.577 provides information on the bandwidths of active sensor systems envisaged to operate in the allocated bands between 432 MHz and 238 GHz;
- b) that several ITU-R Recommendations and Reports provide information on the current and future characteristics of EESS (active) systems operating in several frequency bands (see Annex, Table 2),

recommends

that the technical and operational parameters presented in the Annex of this Recommendation should be taken into account in studies considering EESS (active) systems using allocations between 432 MHz and 238 GHz.

Annex

Technical and operational parameters of EESS (active) systems using allocations between 432 MHz and 238 GHz

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1 Introduction

Active sensors are used in the remote sensing of the Earth and its atmosphere by Earth exploration and meteorological satellites in certain frequency bands allocated to the Earth exploration-satellite service (EESS) (active). The products of these active sensor operations are used extensively in meteorology, climatology, and other disciplines for operational and scientific purposes.

The technical and operational parameters presented in this Recommendation shall be used in studies considering EESS (active) systems using allocations between 432 MHz and 238 GHz. However, it should be noted that some of the EESS (active) systems are under development and the typical values for certain parameters provided should be considered preliminary as these still may change.

2 Active sensor types and typical characteristics

There are five active spaceborne sensor types addressed in this Recommendation:

- Type 1: Synthetic aperture radars (SAR) – Sensors looking to one side of the nadir track, collecting a phase and time history of the coherent radar echo from which a radar image of the Earth's surface from the returned echo or topography from interferometric returns can be produced.
- Type 2: Altimeters – Sensors looking at nadir, measuring the precise time between a transmit event and receive event, to extract the precise altitude of the Earth's ocean surface.
- Type 3: Scatterometers – Sensors pointing at various look angles relative to the sides of the nadir track, using the measurement of the return echo power variation with aspect angle to determine the roughness of land surface or to determine the wind direction and speed on the Earth's ocean surface.
- Type 4: Precipitation radars – Sensors scanning perpendicular to nadir track which measure the radar echo from rainfall in order to determine the rainfall rate over the Earth's surface and the three-dimensional structure of rainfall.
- Type 5: Cloud profile radars – Sensors looking at nadir which measure the radar echo return from clouds in order to determine the cloud reflectivity profile over the Earth's surface.

Some typical characteristics of spaceborne active sensors are shown below in Table 1. The actual characteristic values of the systems operating in the various frequency bands provided in § 7 of this Recommendation may vary considerably from these typical characteristic values reflected in Table 1.

TABLE 1

Typical characteristics of active spaceborne sensors

Characteristic	Sensor type				
	SAR	Altimeter	Scatterometer	Precipitation radars	Cloud profile radars
Service area	Land/coastal/ ocean	Ocean/ice/coastal/ Inland water	Ocean/ice/land/ coastal	Land/ocean	Land/ocean
Antenna beam	Fan beam	Pencil beam	– Fan beams – Pencil beams	Pencil beam	Pencil beam

TABLE 1 (end)

Characteristic	Sensor type				
	SAR	Altimeter	Scatterometer	Precipitation radars	Cloud profile radars
Viewing geometry	Side-looking at 10°-60° off nadir	– Nadir-looking – Multi incidence looking	– Three/six fan beams in azimuth – One or more conically scanning beams	Scanning across-track around Nadir	Nadir-looking
Footprint/dynamics	– Fixed to one side – ScanSAR – Spotlight	– Fixed at nadir – Multi incidence looking	– Fixed in azimuth – Multiple conically scanning beams	Scanning across nadir track	Fixed at nadir
RF bandwidth	20-1 200 MHz	320-500 MHz	5-80 kHz (ocean) or 1-4 MHz (land)	14 MHz	300 kHz
Transmit peak power (W)	1 500-16 000	20	100-5 000	600	1 000-1 500
Waveform	Linear FM pulses	Linear FM pulses	Interrupted CW or short pulses (ocean) or linear FM pulses (land)	Short pulses	Short pulses
Transmit duty cycle (%)	1-30	46	31 (ocean) or 10 (land)	0.9	1-14

3 Typical orbits

EESS (active) systems operate in non-geostationary satellite orbit (non-GSO). Orbits are typically circular with an altitude between 350 and 1 400 km. Some EESS (active) systems operate in a sun-synchronous orbit. Some sensors make measurements over the same area on the Earth every day, while others will repeat observations only after a longer (often more than two weeks) repeat period.

In certain circumstances, multiple satellites operate in formation. Formation flying EESS satellites allow the capability to measure different Earth system characteristics (land, ocean, atmosphere, cryosphere and solid Earth) using both multiple instruments and orientations. Measurements from multiple spacecraft will be separated within an amount of time shorter than the time constant of the phenomena being measured. Nominally, this separation is on the order of 5 to 15 min but can be as little as a few seconds.

4 Active sensors interference and performance criteria

The criteria for performance, interference and data availability are provided in Recommendation ITU-R RS.1166 for the various types of active spaceborne sensors. Performance criteria for active spaceborne sensors are needed in order to develop interference criteria. Interference criteria, in turn, can be used to assess the compatibility of other active services and active sensors operating in common frequency bands.

5 Sharing considerations for active sensors

5.1 Existing ITU-R Recommendations and Reports

The sharing considerations for sharing between spaceborne active sensors in the EESS (active) and other services are provided in the ITU-R Recommendations and Reports listed in Table 2. These Recommendations and Reports are concerned with specific frequency bands or ranges of frequencies and the other services operating in those bands.

The sharing considerations for spaceborne active sensors include the level of the power flux-density (pfd) and received interference power at the Earth's surface, the type of transmitted RF signal, the dynamics of the antenna coupling with systems of other services, and the types of systems in the other services.

TABLE 2

List of ITU-R documents with sharing considerations for active sensors

Recommendations	
ITU-R RS.1260	Feasibility of sharing between active spaceborne sensors and other services in the range 420-470 MHz
ITU-R RS.1261	Feasibility of sharing between spaceborne cloud radars and other services in the range of 92-95 GHz
ITU-R RS.1280	Selection of active spaceborne sensor emission characteristics to mitigate the potential for interference to terrestrial radars operating in frequency bands 1-10 GHz
ITU-R RS.1281	Protection of stations in the radiolocation service from emissions from active spaceborne sensors in the band 13.4-13.75 GHz
ITU-R RS.1282	Feasibility of sharing between wind profiler radars and active spaceborne sensors in the vicinity of 1 260 MHz
ITU-R RS.1347	Feasibility of sharing between radionavigation-satellite service receivers and the Earth exploration-satellite (active) and space research (active) services in the 1 215-1 260 MHz band
ITU-R RS.1628	Feasibility of sharing in the band 35.5-36 GHz between the Earth exploration-satellite service (active) and space research service (active), and other services allocated in this band
ITU-R RS.1632	Sharing in the band 5 250-5 350 MHz between the Earth exploration-satellite service (active) and wireless access systems (including radio local area networks) in the mobile service
ITU-R RS.1749	Mitigation technique to facilitate the use of the 1 215-1 300 MHz band by the Earth exploration-satellite service (active) and the space research service (active)
ITU-R RS.2043	Characteristics of synthetic aperture radars operating in the Earth exploration-satellite service (active) around 9 600 MHz
ITU-R RS.2065	Protection of space research service (SRS) space-to-earth links in the 8 400-8 450 MHz and 8 450-8 500 MHz bands from unwanted emissions of synthetic aperture radars operating in the earth exploration-satellite service (active) around 9 600 MHz
ITU-R RS.2066	Protection of the radio astronomy service in the frequency band 10.6-10.7 GHz from unwanted emissions of synthetic aperture radars operating in the Earth exploration-satellite service (active) around 9 600 MHz

TABLE 2 (*end*)

Reports	
ITU-R RS.2068	Current and future use of the band near 13.5 GHz by spaceborne active sensors
ITU-R RS.2094	Studies related to the compatibility between Earth exploration-satellite service (active) and the radiodetermination service in the 9 300-9 500 MHz and 9 800-10 000 MHz bands and between Earth exploration-satellite service (active) and the fixed service in the 9 800-10 000 MHz band
ITU-R RS.2178	The essential role and global importance of radio spectrum use for Earth observations and for related applications
ITU-R RS.2273	Potential interference from EESS (active) scatterometers into ARNS systems in the frequency band 1 215-1 300 MHz
ITU-R RS.2274	Spectrum requirements for spaceborne synthetic aperture radar applications planned in an extended allocation to the Earth exploration-satellite service around 9 600 MHz
ITU-R RS.2310	Worst-case interference levels from mainlobe-to-mainlobe antenna coupling of systems operating in the radiolocation service into active sensor receivers operating in the Earth exploration-satellite service (active) in the 35.5-36.0 GHz band
ITU-R RS.2311	Pulsed radio frequency signal impact measurements and possible mitigation techniques between Earth exploration-satellite service (active) systems and RNSS systems and networks in the band 1 215-1 300 MHz
ITU-R RS.2313	Sharing analyses of wideband Earth exploration-satellite service (active) transmissions with stations in the radio determination service operating in the frequency bands 8 700-9 300 MHz and 9 900-10 500 MHz
ITU-R RS.2314	Sharing analyses of wideband EESS SAR transmissions with stations in the fixed, mobile, amateur, and amateur-satellite services operating in the frequency bands 8 700-9 300 MHz and 9 900-10 500 MHz

5.2 Power flux-density levels due to active spaceborne sensors

The characteristics of the various types of active spaceborne sensors as shown in Table 1 indicate that the transmitted peak power and therefore the power levels received at the Earth's surface will vary significantly. Table 3 shows the active sensor pfd levels at the Earth's surface for some typical sensor configurations.

TABLE 3

Typical pfd levels at Earth's surface

Parameter	Sensor type				
	SAR	Altimeter	Scatterometer	Precipitation radars	Cloud profile radars
Transmit peak power (W)	1 500	20	100	578	630
Antenna gain (dBi)	36.4	43.3	34	47.7	63.4
Altitude (km)	695	1 344	1 145	350	400
pfd (dB(W/m ²))	-59.67	-77.25	-78.17	-46.55	-31.64

5.3 Dynamics of antenna coupling with systems of other services

The viewing geometry and footprint/dynamics of the active sensors are shown in Table 1. All five types of active sensors are mounted on spacecraft looking down at the Earth's surface.

The SARs have a look angle, which is the angle between nadir and the beam centre, of 10 degrees to 55 degrees. The scatterometers have a look angle of about 40 degrees from nadir.

The altimeters, precipitation radars and the cloud profile radars are nadir looking. Typical terrestrial search radars cover low elevation angles, therefore they do not have mainlobe-to-mainlobe coupling with altimeters, precipitation radars, or cloud profile radars.

The spaceborne sensor beams scan past the terrestrial systems as the spacecraft proceeds in its orbit. For a sensor beamwidth of 2 degrees, the beam scans past the terrestrial system in about 2-3 seconds. The SARs typically look down to the side of the nadir track either at a commanded look angle or at various look angles for ScanSAR modes. The scatterometers are either fixed at various azimuth angles or are conically scanned about nadir with one or more beams. For a sensor beamwidth of 2 degrees, the conically scanning beam scans past the terrestrial system in less than 25 milliseconds for a scan rate of 15 rpm. Typical terrestrial search radars also scan 360 degrees in azimuth at rates of 5 to 10 rpm so that the terrestrial radar beam with a 1-degree beamwidth scans past the spaceborne sensor in only 30 to 60 milliseconds. The precipitation radars typically are nadir looking and scan across the nadir track. For a sensor beamwidth of 0.7 degrees, the cross-track scanning beam of the precipitation radar scans past the terrestrial system in only 12.5 milliseconds at a scan rate of about 57 degrees/second. The altimeters and cloud profile radars are typically nadir looking.

6 Definition of parameters

This section provides definitions of the parameters used to characterize the operations of the active sensors provided in this Recommendation.

TABLE 4
Definitions of parameters

Parameter	Definition
Sensor type	One of the five types described in the Introduction of this Recommendation
Orbit parameters	
Type of orbit	Such as: circular or elliptical, sun-synchronous (SSO) or non-sun-synchronous (NSS)
Altitude (km)	The height above the mean sea level
Inclination (degrees)	Angle between the equator and the plane of the orbit
Ascending Node LST	The local solar time (LST) of the ascending node is that local solar time for which the ascending orbit of the spacecraft crosses the equator
Eccentricity	The ratio of the distance between the foci of the (elliptical) orbit to the length of the major axis
Repeat period (days)	The time for the footprint of the antenna beam to return to (approximately) the same geographic location.

TABLE 4 (continued)

Parameter	Definition
Sensor antenna parameters	
Antenna characteristics vary among sensors.	
Antenna type	Such as: Parabolic offset fed to active phased array, Passive waveguide to active phased array, Planar slotted waveguide array
Number of beams	The number of beams is the number of locations on Earth from which data are acquired at one time.
Antenna diameter (or size)	Diameter of the antenna reflector (when applicable), or length and width of the planar array (when applicable).
Antenna Peak (Transmit & Receive) Gain (dBi)	<p>The maximum (peak) antenna gain can be the measured value, or, if it is not known, it can be computed.</p> <p>For the case of parabolic reflectors, the maximum antenna gain can be estimated by using the antenna efficiency η and D diameter of the reflector (when applicable):</p> $\text{Maximum_antenna_gain} = \eta \left(\pi \frac{D}{\lambda} \right)^2$ <p>For the case of planar array antennas, the maximum gain can be estimated by using the length l and width w of the planar array (when applicable) with the formula:</p> $\text{Maximum_antenna_gain} = \eta 4\pi lw/\lambda^2$
Polarization	Specification of linear (H or V) or circular polarization (RHCP or LHCP). NOTE: where “HV” polarization is listed, “H” polarization is transmitted and “V” polarization is received and vice versa for “VH” polarization.
–3 dB beamwidth (degrees)	The –3 dB beamwidth (also called, half power beamwidth), $\theta_{3\text{dB}}$, is defined as the angle between the two directions in which the radiation intensity is one-half the maximum value.
Instantaneous field of view IFOV	<p>The instantaneous field of view (IFOV) is the area over which the measurement is made by the detector. By knowing the altitude of the satellite, the dimension of the IFOV can be calculated on the Earth’s surface at the nadir point: the IFOV is generally expressed in km × km. The IFOV is a measure of the size of the resolution element.</p> <p>In a scanning system the IFOV refers to the solid angle subtended by the detector when the scanning motion is stopped. For conical scan radars, two values are usually computed:</p> <ul style="list-style-type: none"> – along-track: in the direction of the platform motion (along the in-track direction); – cross-track: in the direction orthogonal to the motion of the sensor platform. <p>For nadir scan radars, such as that shown in Fig. 1, the nadir IFOV = $H\theta_{3\text{dB}}$, where H is the height of the satellite and $\theta_{3\text{dB}}$ is the half-power beamwidth.</p>
Antenna incidence angle at Earth (degrees)	The angle between the pointing direction and the normal to the Earth’s surface. It is the angle i as in Fig. 1 (in some cases, the off-nadir angle is provided).
Azimuth scan rate (rpm)	The azimuth scan rate is the number of 360 degrees revolutions per minute that the antenna scans in azimuth.

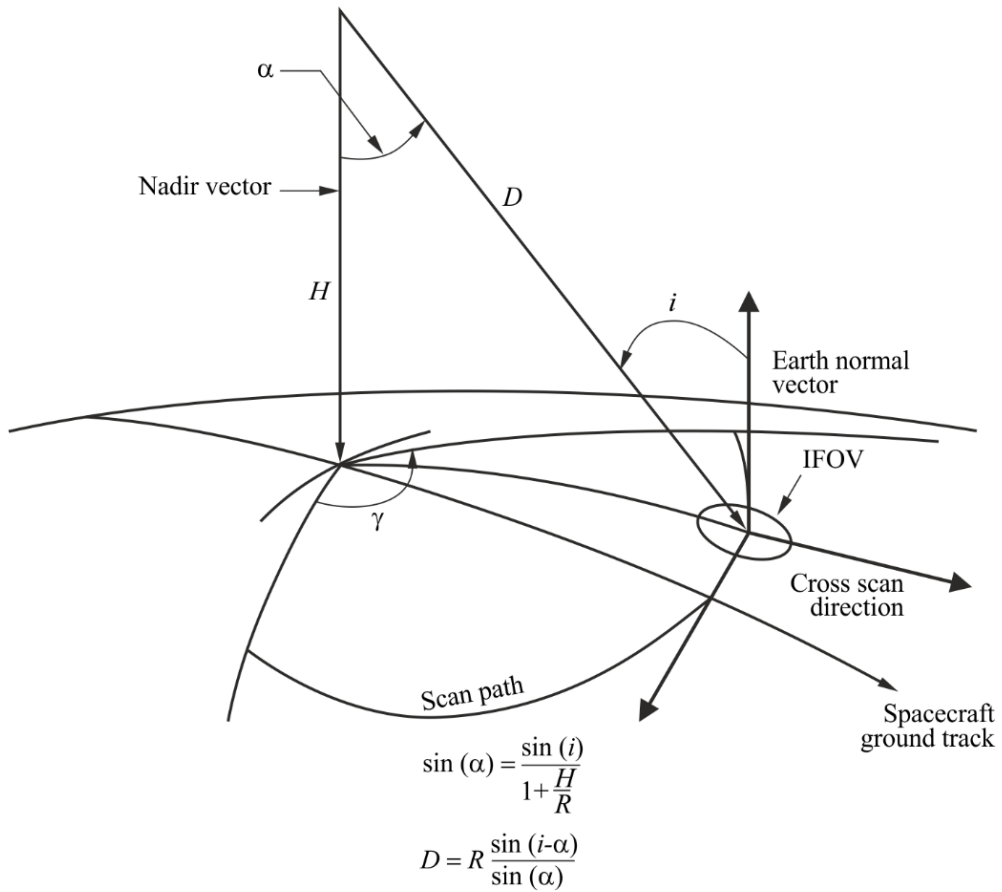
TABLE 4 (continued)

Parameter	Definition
Antenna beam look angle (degrees)	The antenna beam look angle, α , is the angle between the antenna boresight axis and nadir, sometimes called the off-nadir pointing angle. Some systems provide instead the information of the incident angle, i . They are the angle α and i , as shown in Fig. 1
Antenna beam azimuth angle (degrees)	The antenna beam azimuth angle is the angle between the antenna boresight axis and velocity vector in the plane defined by the velocity vector and the negative orbit normal vector (see Fig. 2)
Antenna elevation beamwidth (degrees)	The antenna elevation beamwidth is the angle in the elevation or cross-track direction between the -3 dB points of the beam
Antenna azimuth. beamwidth (degrees)	The antenna azimuth beamwidth is the angle in the azimuth or along-track direction between the -3 dB points of the beam
Swath width (km)	The swath width is defined as the linear ground distance covered in the cross-track direction.
Main beam efficiency (%)	The main beam area is defined as the angular size of a cone with an opening angle equal to 2.5 times the measured -3 dB beamwidth. The main beam efficiency is defined as the ratio of the energy received in the main beam to the energy received in the complete antenna pattern
Beam dynamics	The beam dynamics is defined as follows: <ul style="list-style-type: none"> – For conical scans, it is the rotating speed of the beam – For nadir scans, it is the number of scans per second
Sensor antenna pattern	Antenna gain as a function of off-axis angle
Transmitter characteristics	
RF centre frequency (MHz)	The RF centre frequency is that frequency about which the bandwidth of the transmitted signal is centred
RF bandwidth (MHz)	The RF bandwidth is the -3 dB bandwidth of the transmitted signal. For compatibility analysis, this is also typically used as the receiver bandwidth
Transmit Pk pwr (W)	The transmit peak power is the peak power of the envelope of the transmitted waveform
Transmit Ave. pwr (W)	The transmit average power is the product of the peak power of the envelope of the transmitted waveform times the transmit duty cycle
Pulsewidth (μ s)	The pulsewidth is the half power duration of the transmitted pulse
Pulse repetition frequency (PRF) (Hz)	The pulse repetition frequency is the frequency of the transmitted pulse waveforms
Chirp rate (MHz/ μ s)	The chirp rate for a linear FM (LFM) pulse is the ratio of the RF bandwidth in MHz and the pulsewidth in μ s
Transmit duty cycle (%)	The transmit duty cycle is the product of the transmitted pulsewidth and the pulse repetition frequency
Operational duty cycle (%)	The percentage of time that the transmitter is active per orbit (this may vary according to the operational mode)
e.i.r.p. ave (dBW)	The average effective isotropically radiated power (e.i.r.p.) is the amount of power that a theoretical isotropic antenna would radiate to produce the average power density observed in the direction of maximum antenna gain; the e.i.r.p. is the product of the transmit average power and the antenna peak gain in dBW

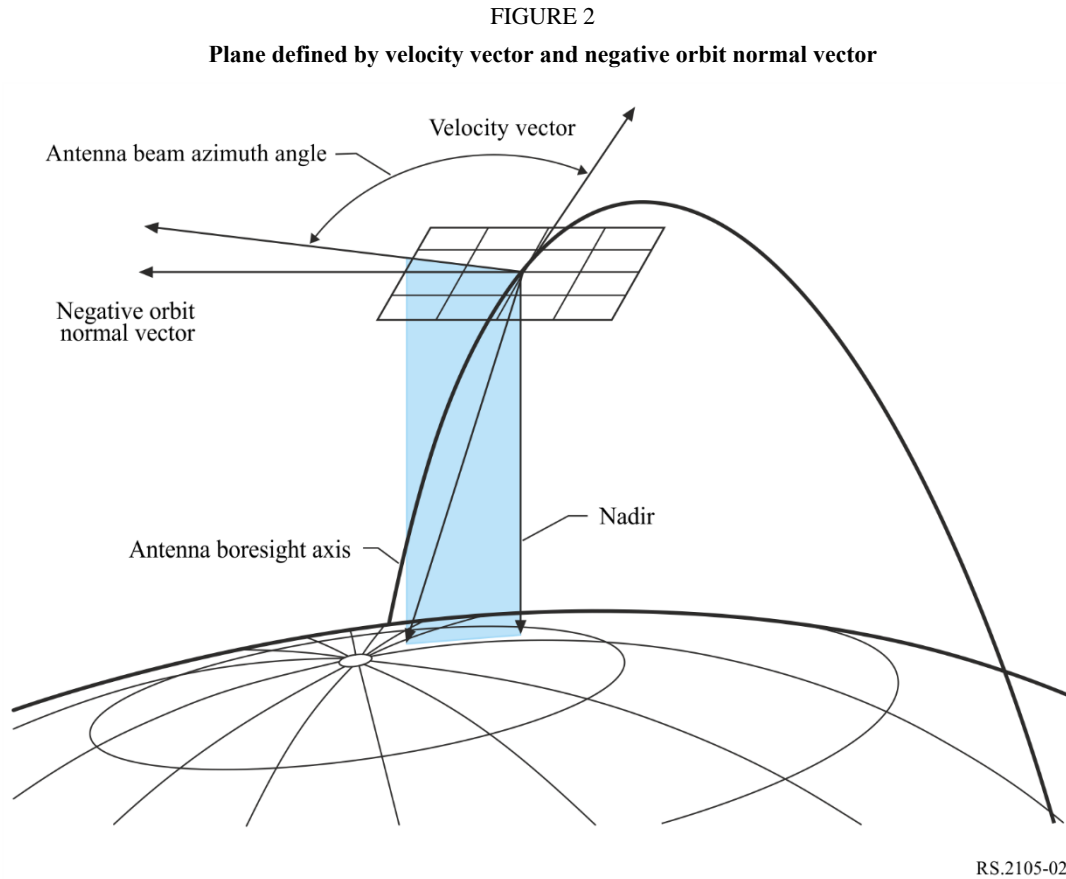
TABLE 4 (*end*)

Parameter	Definition
e.i.r.p. peak (dBW)	The peak effective isotropically radiated power (e.i.r.p.) is the amount of power that a theoretical isotropic antenna would radiate to produce the peak power density observed in the direction of maximum antenna gain; the peak e.i.r.p. is the product of the transmit peak power and the antenna peak gain in dBW
Sensor receiver parameters	
Sensor dwell time	The <i>sensor dwell time</i> corresponds to the period of time allocated for the echo measurement of the instantaneous area of observation by the detector of a sensor
Sensitivity (dBZ)	The sensitivity of a precipitation radar or cloud profile radar is the <i>minimum</i> detectable reflectivity Z (mm^6/m^3) of the precipitation or cloud profile radar in dBZ
System noise figure (dB) or System noise temperature (K)	The system noise figure is the ratio of the input signal-to-noise power ratio (S/N) _i to the output signal-to-noise power ratio (S/N) _o . The system noise temperature is effectively the antenna noise temperature plus the first stage receiver noise temperature; the other system noise temperature contributions can usually be neglected when the first stage receiver gain is greater than 16 dB.
Measurement spatial resolution	
Range resolution	The <i>spatial resolution</i> is often defined as the ability to distinguish between two closely spaced objects on an image. It is generally expressed in both range or horizontal (usually cross-track) and azimuth, or vertical (along-track) resolutions. (Note that “vertical”, in this sense, does not refer to altitude.)
Azimuth resolution	

FIGURE 1
Scanning configuration typical of conical scanning scatterometers



- i*: Incidence angle at footprint centre
- α : Angle off nadir
- γ : Total scan angle
- H*: Height above mean sea level
- D*: Distance to field of view centre
- R*: Radius of Earth (not shown in diagram)



7 Parameters of typical systems

This section provides typical parameters of active sensors for EESS (active) bands between 432 MHz and 238 GHz. A consistent set of parameters is used for each band to support worst-case static analyses and dynamic analyses.

7.1 Typical parameters of active sensors operating in the 432-438 MHz band

The 435 MHz SARs are active microwave sensors using the frequency band 432-438 MHz to achieve weather-independent and day and night land observation. The lower frequencies enable penetration of the vegetation canopies in order to provide global vegetation models to improve the quantification of the global terrestrial carbon cycle. Typical characteristics of 435 MHz SARs are shown in Table 5.

TABLE 5
Characteristics of EESS (active) missions in the 432-438 MHz band

Parameter	SAR-A1
Sensor type	SAR
Type of orbit	SSO
Altitude (km)	665
Inclination (degrees)	98.1
Ascending node LST	06:00
Repeat period (days)	17
Number of beams	1

TABLE 5 (*end*)

Parameter	SAR-A1
Antenna diameter (m)	12
Antenna Pk Xmt gain (dBi)	33.6
Antenna Pk Rcv gain (dBi)	33.6
Polarization	linear H, V
Azimuth scan rate (rpm)	0
Antenna beam look angle (degrees)	22.7, 25.9, 28.2
Antenna beam azimuth angle (degrees)	86.2-93.8
Antenna elevation beamwidth (degrees)	4.8
Antenna azimuth beamwidth (degrees)	3.2
RF centre frequency (MHz)	435
RF bandwidth (MHz)	6
Transmit peak pwr (W)	170
Transmit average pwr (W)	10
Pulsewidth (μ s)	38
Pulse repetition frequency max (Hz)	1 550
Chirp rate (MHz/ μ s)	0.200, 0.182, 0.1861
Transmit duty cycle (%)	5.9%
e.i.r.p. ave (dBW)	43.6
e.i.r.p. peak (dBW)	55.9
System noise figure (dB)	3

7.2 Typical parameters of active sensors operating in the 1 215-1 300 MHz band

The 1.25 GHz SARs are active microwave sensors using the frequency band 1 215-1 300 MHz to achieve weather-independent and day and night land observation. The SARs may have several modes, including fine resolution mapping modes, medium resolution mapping modes, and scanSAR modes. Typical characteristics of SARs operated in the 1 215-1 300 MHz band are shown in Table 6.

Table 6 shows the characteristics of the typical land scatterometer operated in the band 1 215-1 300 MHz.

TABLE 6

Characteristics of EESS (active) missions in the band 1 215-1 300 MHz

Parameter	SCAT-B1	SCAT-B2	SAR-B1	SAR-B2	SAR-B3
Sensor type	Scatterometer	Scatterometer	SAR	SAR	SAR
Type of orbit	Circular, SSO	Circular, SSO	Circular, SSO	Circular, SSO	Near circular, SSO
Altitude (km)	670	657	757	628	693
Inclination (degrees)	98	98	98	97.9	98.18
Ascending node LST	18:00	18:00	18:00	12:00*	18:00

TABLE 6 (continued)

Parameter	SCAT-B1	SCAT-B2	SAR-B1	SAR-B2	SAR-B3
Repeat period (days)	3	7	12	14	12
Antenna type	Offset parabolic reflector	Three-feed offset parabolic reflector	Linear array fed reflector	Planar phased array	Planar phased array
Number of beams	1	3	1	1	1
Antenna size/diameter	6 m	2.5 m	15 m	9.9 m × 2.9 m	11 m × 3.6 m
Antenna peak transmit gain (dBi)	36	28.1	35	34.7	33.5 (dual pol), 34.6 (quad pol), 39.5 (Wave mode) ⁽¹⁾
Antenna peak receive gain (dBi)	36	28.1	45	36.6	25.4
Polarization	Dual, linear H,V	Dual, linear H,V	Dual/quad, linear H,V	Dual/quad, circular, linear H,V	Single/dual/quad, linear H, V
Azimuth scan rate (rpm)	13.0-14.6	0	0	0	0
Antenna beam look angle (degrees)	34	25.9/33.9/40.3	30 (transmit), 20-40 (receive)	7.2-59	25.2-38.7
Antenna beam azimuth angle (degrees)	0-360	99.7/74.8/96.5	90	±90/±3.5	90
Antenna elev. beamwidth (degrees)	2.5	6.5/6.7/7.1	20.9	4.3 to 4.6	3.36 (transmit), 13.45 (receive)
Antenna az. beamwidth (degrees)	2.5	6.5/6.7/7.1	0.89	1.3 to 2.1	1.1 (transmit), 5.5 (receive)
RF centre frequency (MHz)	1 215-1 300	1 260	1 215-1 300	1 236.5/ 1 257.5	1 215-1 300
RF bandwidth (MHz)	1	4	25	14-78	40-85
Transmit Pk pwr (W)	200	200	3 200	3 944-6 120	9 000
Transmit Ave. pwr (W)	28	–	614.4	453-454	600 (dual pol), 720 (quad pol)
Pulsewidth (µs)	15	1 000	60	18-71	10-80

TABLE 6 (end)

Parameter	SCAT-B1	SCAT-B2	SAR-B1	SAR-B2	SAR-B3
Pulse repetition frequency (PRF) (Hz)	3 500	100	1 500-2 000	1 050-3 640	1 300-3 800
Chirp rate (MHz/ μ s)	0.067	0.004	0.42	0.21-1.95	0.15-0.93
Transmit duty cycle (%)	5.25	10	19.2	6.8-11.5	6.7-8 (2% for Wave mode) ⁽¹⁾
e.i.r.p. peak (dBW)	60	51.1	71.5	70.7-74.5	78
System noise figure (dB)	4.0	7.0	3.9	4.9	3.3

⁽¹⁾ Wave mode is used only over ocean.

7.3 Typical parameters of active sensors operating in the 3 100-3 300 MHz band

Typical characteristics of 3.1 GHz SAR are shown in Table 7.

TABLE 7

Characteristics of EESS (active) missions in the 3 100-3 300 MHz band

Parameter	SAR-C1	SAR-C2	SAR-C3
Sensor type	SAR	SAR	SAR
Type of orbit	Circular, SSO	Circular	Circular
Altitude (km)	500	503-536	503-536
Inclination (degrees)	97.3	97.4	97.4
Ascending node LST	06:00	09:00 \pm 1:00	10:00 \pm 1:00
Repeat cycle, days	31	16	16
Antenna type	–	Parabolic Dish	Parabolic Dish
Number of beams	9	–	–
Antenna diameter or size	–	6 m	6 m
Antenna peak gain (dBi)	37.6	42	44
Polarization	VV	H,V	H,V
Azimuth scan rate (rpm)	0	0	0
Antenna beam look angle (degrees)	25-47	25-55	20-55
Antenna beam azimuth angle (degrees)	90	90/–90	90/–90
Antenna elevation beamwidth (degrees)	2.5	1	1
Antenna azimuth beamwidth (degrees)	1	1	1
RF centre frequency (MHz)	3 200	3 200	3 200
RF bandwidth (MHz)	60	50/200	50/200
Transmit Pk pwr (W)	3 000	5 000	11 220
Transmit Ave. pwr (W)	300	–	–

TABLE 7 (*end*)

Parameter	SAR-C1	SAR-C2	SAR-C3
Pulsewidth (μs)	27	10	1-16
Chirp rate (MHz/ μs)	2.22	5/20	5/20
Transmit duty cycle (%)	10	Variable, max 20%	Variable, max 20%
System noise figure (dB)	2	3	3

7.4 Typical parameters of active sensors operating in the 5 250-5 570 MHz band

The typical characteristics of for several types of SAR sensors, altimeters and scatterometers operating in the 5 250-5 570 MHz band are shown in Tables 8, 9 and 10.

It should be noted that the service area for most of these active sensors is global, as it is the case for SAR-D4, SAR-D5, SAR-D6, and SAR-D1 (a two-satellite constellation).

TABLE 8

Characteristics of SAR sensors in the 5 250-5 570 MHz band

Mission	SAR-D1	SAR-D2	SAR-D3	SAR-D4	SAR-D5	SAR-D6	SAR-D7	SAR-D8
Sensor type	SAR	SAR	SAR	SAR	SAR	SAR	SAR	SAR
Type of orbit	Circular SSO	SSO, circular	SSO	Near circular	Near circular	Near circular	Near circular	Near circular
Altitude (km)	693	764	536	792-813	586.9-615.2	586.9-615.2	755	410-420
Inclination (degrees)	98.18	98.6	97	98.6	97.74	97.74	98.4	51.6
Ascending node LST	18:00/6:00 ⁽¹⁾	10:30	6:00	6:00	6:00	6:00 (TBC)	18:00	N/A
Repeat period (days)	12	35	13	24	12	12 (TBC)	29	–
Antenna type	Phase array	Phase array	Planar phased array	Planar phased array	Planar phased array	Planar phased array	Planar phased array	Phased array
Number of beams	1	1	1	1	1	1	1	1
Antenna size/diameter	12.3 m × 0.8 m	10 m × 1.3 m	10 m × 3 m	15 m × 1.5 m	6.88 m × .37 m	6.88 m × 1.37 m	15 m × 1.232 m	2.5 m × 1.2 m
Antenna Pk Xmt gain (dBi)	43.5 to 45.3	40 to 45	35	49 ⁽²⁾	45 ⁽³⁾	45 ⁽³⁾	48	38.7
Pk Rcv gain (dBi)	43.5 to 44.8	Antenna 40 to 45	35	49 ⁽³⁾	45 ⁽³⁾	45 ⁽³⁾	48	38.7
Polarization	V, H	H, V	Linear H, V	HH, HV, VH, VV	HH, VV, HV, VH, CH, CV	HH, VV, HV, VH, CH, CV	HH, HV, VH, VV	H, V
Antenna beam look angle (degrees)	20-47 ⁽³⁾	15-45	10-45	9-50	16-51	16-53	10-60	15-40
Antenna beam azimuth angle (degrees)	90	90	90	0	0	0	0	0/180
Antenna elev. beamwidth (degrees)	6 to 8	2.5	4.6	1.88 (for focused beam)	2.05 (for focused beam)	2.05 (for focused beam)	2.288	3.15
Antenna az. beamwidth (degrees)	0.3	0.3	1.4	0.19	0.42 (for focused beam)	0.42 (for focused beam)	0.188	1.6
Swath width (km)	20-410	10-405	10-225	18-500	20-500	20-500	10-650	40-400
RF centre frequency (MHz)	5 405	5 331	5 350	5 405	5 405	5 405	5 400	5 350
RF bandwidth (MHz)	100	16	18.75-75	11.6, 17.3, 30, 50, 100	14-100	14-300	2 -240	36.3

TABLE 8 (end)

Mission	SAR-D1	SAR-D2	SAR-D3	SAR-D4	SAR-D5	SAR-D6	SAR-D7	SAR-D8
Transmit Pk pwr (W)	4 140	2 500	4 000	2 400 or 3 700	1 490	1 990	15 360	5 000
Transmit Ave. pwr (W)	370	200	260	300	180	240	1 900	750
Pulsewidth (μ s)	5 to 53	16 to 41	2 0	21, 42	10 to 50	10 to 50	15 to 50	17.5 to 25.5
Pulse repetition frequency (Hz)	1 450-2 000	1 600-2 100	3 250	1 000-2 800	2 000-7 000	2 000-7 000	1 100 Hz ~ 4 500 Hz	6 000-8 560
Chirp rate (MHz/ μ s)	0.34-3.75	0.39	0.937-3.75	0.27 to 2.38	0.14 to 10	0.14 to 10	0.13 to 6.85	1.41 to 2.05
Transmit duty cycle (%)	0.5-9.0 depending on ops mode	8.61	6.5	Variable, max 8%	Variable, max 12%	Variable, max 12%	Variable, max 20%	Variable max 15%
e.i.r.p. ave (dBW)	70 (for 9% duty cycle)	68.0	68	Approx. 73 ⁽⁴⁾	67.67	69.0	Approx. 80.7	67.5
e.i.r.p. peak (dBW)	80	78.0	71.0	83.5 ⁽⁵⁾	76.7	78.0	89.8	75.7
System noise figure (dB)	3.2	4.5	5.8	6	6	6	4	4/6

⁽¹⁾ This system is a two-satellites constellation.

⁽²⁾ Lower gain can be used for the wider beams.

⁽³⁾ Antenna beam 'incident angles'.

⁽⁴⁾ Average e.i.r.p. over a pulse repetition interval.

⁽⁵⁾ Maximum e.i.r.p. during pulse transmission.

TABLE 9
Characteristics of altimeters in the 5 250-5 570 MHz band

Mission	ALT-D1	ALT-D2 ⁽¹⁾	ALT-D3	ALT-D4 ⁽¹⁾	ALT-D5	ALT-D6
Sensor type	Altimeter	Altimeter	Altimeter	Altimeter	Altimeter	Altimeter
Type of orbit	NSS	Circular, SSO	SSO	NSS	NSS	Circular, SSO
Altitude (km)	1 336	814	963	1 336	890	1 000
Inclination (degrees)	66	98.65	99.3	66	78	99.4
Ascending node LST	NSS	22:00	06:00	NSS	NSS	–
Repeat period (days)	10	27	14	10	21	14
Antenna type	Parabolic reflector	Parabolic reflector	Parabolic reflector	Parabolic reflector	Parabolic reflector	Parabolic reflector
Number of beams	1	1	1	1	1	1
Antenna size/diameter	1.2 m	1.2 m	1.4 m	1.2 m	1.2 m	1.5 m
Antenna Pk Xmt gain (dBi)	32	32	35	33.5	32.0	33.6
Antenna Pk Rcv gain (dBi)	32	32	43	33.5	32.0	33.6
Polarization	linear	linear	linear VV	linear	linear	linear
Azimuth scan rate (rpm)	0	0	0	0	0	0
Antenna beam look angle (degrees)	0	0	0	0	0	0
Antenna beam azimuth angle (degrees)	0	0	0	0	0	0
Antenna elev. beamwidth (degrees)	3.4	3.4	2.3	3.4	3.4	3
Antenna az. beamwidth (degrees)	3.4	3.4	2.3	3.4	3.4	3
Swath width (km)	79.4	48.4	38.7	97	52.9	51.4
RF centre frequency (MHz)	5 300	5 410	5 250	5 410	5 300	5 300
RF bandwidth (MHz)	100, 320	320	160	320	100, 320	100, 320
Transmit Pk pwr (W)	17	32	20	25	17	15.8
Transmit Ave. pwr (W)	0.51	0.4 (LRM), 0.25 (SAR)	8.2	< 2	0.51	0.51, 0.71
Pulsewidth (µs)	106.0	49	102.4	32	106.0	110.5
Pulse repetition frequency (Hz)	300	275 (LRM), 157 (SAR)	670	2 060-9 280	300	294, 412
Chirp rate (MHz/µs)	0.9, 3.0	6.5	1.56	9.69	0.9, 3.0	0.9, 2.9
Transmit duty cycle (%)	3.1	1.5 (LRM), 0.7 (SAR)	40.96	30	3.1	3.2, 4.5
e.i.r.p. ave (dBW)	29.5	30.8 (LRM), 28.4 (SAR)	44.1	36.51	29.2	30.7, 32.1
e.i.r.p. peak (dBW)	44.8	49.5	48	47.47	44.3	45.6
System noise figure (dB)	4.45	3.8	3.5	3.5	4.45	5.75

⁽¹⁾ Dual frequency radar altimeter (C/Ku Band) which performs measurements either in low resolution mode (LRM) or synthetic aperture radar mode (Nadir-SAR). LRM mode is the conventional altimeter pulse limited mode with interleaved C/Ku Band pulses, while Nadir-SAR mode is the high along track resolution mode based on SAR processing. The system is a two-satellite constellation.

TABLE 10
Characteristics of scatterometers in the 5 250-5 570 MHz band

Mission	SCAT-D1	SCAT-D2
Sensor type	Scatterometer	Scatterometer
Type of orbit	SSO	SSO
Altitude (km)	832	832
Inclination (degrees)	98.7	98.7
Ascending node LST	21:30	21:30
Repeat period (days)	29	29
Antenna type	Six fan beam-antennas (slotted WG arrays)	Six fan beam-antennas (slotted WG arrays)
Number of beams	6	6
Antenna size/diameter	2.251 m × 0.337 m (mid), 3.003 m × 0.253 m (side)	2.757 m × 0.315 m (mid), 3.02 m × 0.315 m (side)
Antenna Pk Xmt gain (dBi)	24-32	23-31 ⁽¹⁾
Antenna Pk Rcv gain (dBi)	24-32	23-31
Polarization	linear VV for all beams	linear VV for all 6 beams + VH/HV and linear HH for the 2 mid-beams
Azimuth scan rate (rpm)	0	0
Antenna beam look angle (degrees)	22-45.6 (mid beams) 29.5-53.4 (side beams)	17.5-45.5 (mid beams) 24-54 (side beams)
Antenna beam azimuth angle (degrees)	45, 90, 135, 225, 270, 315	45, 90, 135, 225, 270, 315
Antenna elev. beamwidth (degrees)	23.6 (mid beams) 23.9 (side beams)	28 (mid beams) 30 (side beams)
Antenna az. beamwidth (degrees)	1.5 (mid beams) 1.2 (side beams)	1.3
Swath width (km)	550 on each side of the orbit plane	665 on each side of the orbit plane
RF centre frequency (MHz)	5 255	5 355
RF bandwidth (MHz)	0.5	2
Transmit Pk pwr (W)	120	2 512
Transmit Ave. pwr (W)	29 (mid beams) 36.5 (side beams)	92
Pulsewidth (µs)	10 000	1 000
Pulse repetition frequency (PRF) Hz	28.259	32
Chirp rate (MHz/µs)	0.00002	0.00002
Transmit duty cycle (%)	28.29	3.68
e.i.r.p. ave (dBW)	39-47	42-50
e.i.r.p. peak (dBW)	53	57-65
System noise figure (dB)	3.0	3.5

⁽¹⁾ Antenna gain varies depending on antenna location (mid or side), and incident angle.

7.5 Typical parameters of active sensors operating in the 8 550-8 650 MHz band

The typical characteristics of 8.6 GHz SARs are shown in Table 11.

TABLE 11

Characteristics of EESS (active) missions in the 8 550-8 650 MHz band

Parameter	SAR-E1
Sensor type	SAR
Type of orbit	Circular, NSS
Altitude (km)	400
Inclination (degrees)	57
Repeat period (days)	3
Number of beams	1
Antenna type	Slotted waveguide
Antenna (Transmit and Receive) peak gain (dBi)	44.0
Polarization	Linear H,V
Azimuth scan rate (rpm)	0
Antenna beam look angle (degrees)	20-55
Antenna beam azimuth angle (degrees)	90
Antenna elevation beamwidth (degrees)	2.5
Antenna az. beamwidth (degrees)	0.4
RF centre frequency (MHz)	8 600
RF bandwidth (MHz)	10, 20
Transmit Pk pwr (W)	3 500
Transmit Ave. pwr (W)	243
Pulsewidth (μ s)	40
Pulse repetition frequency (PRF) (Hz)	1 395-1 736
Chirp rate (MHz/ μ s)	1.0, 0.5
Transmit duty cycle (%)	7
System noise figure (dB)	4.3

7.6 Typical parameters of active sensors operating in the 9 200-10 400 MHz band

The typical characteristics of SARs, operating in the 9 200-10 400 MHz band, are shown in Table 12. Additional information is contained in Recommendation ITU-R RS.2043.

TABLE 12

Characteristics of EESS (active) missions in 9 200-10 400 MHz band

Parameter	SAR-F1	SAR-F2	SAR-F3	SAR-F4	SAR-F5	SAR-F6	SAR-F7	SCAT-F8
Sensor type	SAR	SAR	SAR	SAR	SAR	SAR	SAR	Scatterometer
Type of orbit	Circular, SSO	Circular, SSO	SSO	SSO	SSO	Circular, SSO	Circular	Circular
Altitude (km)	514	620	512	620	514	514	650..850	835
Inclination (degrees)	97.4	97.8	97.9	97.8	97.44	97.4	97..99	98.85
Ascending node LST	18:00	06:00	06:00	06:00	18:00	18:00	N/A	19:30
Repeat period (days)	11	16	5	16	11	11	–	–
Antenna type	Active phased array	Planar array	Offset linear array fed reflector	Planar array	Active phased array	Active phased array	Phased array	Phased array
Number of beams	1	1	1	1	1	1	1	1
Antenna (Transmit and Receive) peak gain (dBi)	45.5	45.5	46	46.8	43.4	47	45.6	39.5/38.5
Polarization	Linear VV	Linear HH	Linear VV, VH	Linear HH	Linear HH, VV	Linear HH, VV	Linear HH, VV	Linear, VV
Azimuth scan rate (rpm)	0	0	0	0	0	0	0	0
Antenna beam look angle (degrees)	15-60	21-44	30-40	37.8	15-45	18-50	15-55	90
Antenna beam az. angle (degrees)	90	90	90	90	90	90	90	N/A
Antenna elev. beamwidth (degrees)	2.54	1.32	1.5	1.34	2.5	1.13	1-1.2	26
Antenna az. beamwidth (degrees)	0.37	0.32	0.5	0.32	0.4	0.53	0.4-0.45	0.13
RF centre frequency (MHz)	9 650	9 600	9 600	9 500	9 650	9 800	9 600	9 623.275
RF bandwidth (MHz)	150, 300	41-118	10	40-300	5-300	1 200	600	0.5
Transmit Pk pwr (W)	2 000	7 600	3 000	7 600	2 260	7 000	1 800	1 600
Transmit Ave. pwr (W)	400	836	270	836	452	2 100	–	–
Pulsewidth (μ s)	47	18-31	20-30	18-31	47	50	36	2
Pulse repetition frequency (Hz)	2 000-6 500	2 850-3 230	1 000-3 000	1 000-3 000	3 000-6 500	6 000	–	–
Chirp rate (MHz/ μ s)	3.2, 6.8	3.81	0.5-0.67	3.81-9.7	0.85-6.38	24	16.6	N/A
Transmit duty cycle (%)	20	7-11	2-9	7-11	20	30	Variable, max 15%	Variable, max 15%
System noise figure (dB)	2.9	1.0	3	1.0	5.0	3	4	4

TABLE 13 (end)

Mission	ALT-G1	ALT-G3	ALT-G4	ALT-G5	ALT-G6 (Note 1)	ALT-G7 (Note 1)	ALT-G8	ALT-G9
Antenna elev. beamwidth (degrees)	1.2	0.9	1.27	1.2	1.27	1.35	1.5	1
Antenna az. beamwidth (degrees)	1.2	0.9	1.27	1.1	1.27	1.35	1.5	1
RF centre frequency (MHz)	13 575	13 580	13 575	13 575	13 575	13 575	13.575	13 500
RF bandwidth (MHz)	320, 80, 20	320	320	320	350	320	320	500
Transmit Pk pwr (W)	60	20	25	25	7.1	8	5.6	21.7 ⁽²⁾ ; 24.4 ⁽³⁾
Transmit Ave. pwr (W)	2.16	8.2	5.41	2.22	0.66	<4	1.27	19.1 ⁽²⁾ ; 7.1 ⁽³⁾
Pulsewidth (µs)	20	102.4	106.0	50	49	32	110.5	49 ⁽²⁾ ; 18 ⁽³⁾
Pulse repetition frequency (Hz)	1 795.33	2 000	2 060	1 970 (LRM) 1818.1 (SAR mode)	1 924 (LRM) 1782.5 (SAR mode)	2 060-9 280	2 060	18 000 ⁽²⁾ ; 15 500 to 16 800 ⁽³⁾
Chirp rate (MHz/µs)	16, 4, 1	3.12	3.02	7.11	7.14	9.69	2.9	10.2 ⁽²⁾ ; 27.8 ⁽³⁾
Transmit duty cycle (%)	3.6	40.96	21.63	8.88	1.35-2.65, 9.31	30	22.7	88.2 ⁽²⁾ ; 29.1 ⁽³⁾
e.i.r.p. ave (dBW)	44.5	52.1	49.33	45.5	40.2	48.02	43.2	55.1 ⁽²⁾ ; 50.8 ⁽³⁾
e.i.r.p. peak (dBW)	59.0	56.0	56	60.0	50.5	51.03	49.7	55.7 ⁽²⁾ ; 56.2 ⁽³⁾
System noise figure (dB)	2.5, 3.0	2.8	2.6	1.9 ⁽⁴⁾	3.1	2.5	5.75	2.8

⁽¹⁾ 30-day subcycle.

⁽²⁾ Closed burst mode.

⁽³⁾ Open burst mode.

⁽⁴⁾ Receiver noise figure.

NOTE 1 – ALT-G5 and ALT-G6 are dual frequency radar altimeters (C/Ku Band) which performs measurements either in low resolution mode (LRM) or synthetic aperture radar mode (Nadir-SAR). LRM mode is the conventional altimeter pulse limited mode with interleaved C/Ku Band pulses, while Nadir-SAR mode is the high along track resolution mode based on SAR processing. The ALT-G6 system is in preparation and will be a two-satellite constellation with two satellites in the same orbit with 180 deg. phase difference.

TABLE 14

Characteristics of scatterometers in the 13.25-13.75 GHz band

Mission	SCAT-G1	SCAT-G2	SCAT-G3	SCAT-G4
Sensor type	Scatterometer	Scatterometer	Scatterometer	Scatterometer
Type of orbit	SSO	SSO	SSO	SSO
Altitude (km)	803	963	720	836
Inclination (degrees)	98.6	99.3	98.28	98.75
Ascending node LST	06:00	06:00	12:00 (desc node)	06:00
Repeat period (days)	4	14	2	5.5
Number of beams	2	2	2	4
Antenna diameter	1 m	1.3 m	1 m	3 m
Antenna Pk Xmt gain (dBi)	41	42	39.5	48
Antenna Pk Rcv gain (dBi)	41	42	39.5	48
Polarization	H (inner), V (outer)	HH, VV	HH, VV	HH, VV
Azimuth scan rate (rpm)	18	19.0	21.14	15
Antenna beam look angle (degrees)	40, 46	35, 41	43.63 (HH), 49.09 (VV)	36, 40
Antenna beam azimuth angle (degrees)	0-360	0-360	0-360	0-360
Antenna elev. beamwidth (degrees)	1.6	1	1.67	0.9
Antenna az. beamwidth (degrees)	1.6	1	1.47	0.3
RF centre frequency (MHz)	13 402	13 255.5	13 515	13 350
RF bandwidth (MHz)	0.53	3-6	0.4	2
Transmit Pk pwr (W)	100	120	100	1 000
Transmit Ave. pwr (W)	30.6	28.8	27	450
e.i.r.p. peak (dBW)	61.0	62.8	20	78.0
Pulsewidth (μ s)	1 700	650-1 200	1 350	1 500
Pulse repetition frequency (PRF) (Hz)	180	100-200	200	300
Chirp rate (MHz/ μ s)	0.000311765	0.005	0.0003	0.0013
Transmit duty cycle (%)	30.6	24	27.0	45
e.i.r.p. ave (dBW)	55.9	56.6	53.8	74.5
e.i.r.p. peak (dBW)	61.0	62.8	59.5	78.0
System noise figure (dB)	3.4	4.2	3.0	3.5

TABLE 15

Characteristics of precipitation radars in the 13.25-13.75 GHz band

Mission	PR-G1	PR-G2	PR-G3
Sensor type	Precip. Radar	Precip. Radar	Precip. Radar
Type of orbit	NSS	NSS	NSS
Altitude (km)	410	407	400
Inclination (degrees)	50	65	50
Repeat period (days)	11	82	6
Number of beams	2	1	4
Antenna diameter (m)	2	2.1 × 2.1	5.3
Antenna Pk (Xmt and Rcv) gain (dBi)	47	47.4	55
Polarization	HH	H	HH,HV
Azimuth scan rate (s/scan)	0.7	0.7	0.42
Antenna beam look angle (degrees)	±20	±17	±31
Antenna beam azimuth angle (degrees)	±90	±90	±90
Antenna elev. beamwidth (degrees)	0.7	0.7	0.28
Antenna az. beamwidth (degrees)	0.7	0.7	0.28
RF centre frequency (MHz)	13 647, 13 653	13 597, 13 603	13 626, 13 642, 13 658, 13 674
Number of beams	2	49	4
RF bandwidth (MHz)	0.6 × 2	0.6 + 0.6	8 × 4
Transmit Pk pwr (W)	1 000	1 000	2 000
Transmit Ave. pwr (W)	7.2	12.1	360
Pulsewidth (µs)	1.6	1.6	40
Pulse repetition frequency (PRF) (Hz)	4 500	4 485	4 500
Chirp rate (MHz/µs)	NA*	NA*	0.2
Transmit duty cycle (%)	0.72	1.21/0.67	18
e.i.r.p. ave (dBW)	55.6	55.7	80.6
e.i.r.p. peak (dBW)	77.0	77.4	88.0
System noise figure (dB)	5	5.1	3.5

* Unmodulated pulse.

7.8 Typical parameters of active sensors operating in the 17.2-17.3 GHz band

Typical characteristics of 17.25 GHz SAR radars are shown in Table 16.

TABLE 16

Characteristics of EESS (active) missions in the 17.2-17.3 GHz band

Parameter	SAR-H1
Sensor type	SAR
Type of orbit	Circular SSO
Altitude (km)	512
Inclination (degrees)	97.9
Ascending node LST	06:00
Repeat period (days)	5
Antenna type	Offset linear array fed reflector
Number of beams	1
Antenna (Transmit and Receive) peak gain (dBi)	49
Polarization	Linear VV, VH
Azimuth scan rate (rpm)	0
Antenna beam look angle (degrees)	30-40
Antenna beam azimuth angle (degrees)	90
Antenna elev. beamwidth (degrees)	0.9
Antenna az. beamwidth (degrees)	0.3
RF centre frequency (MHz)	17 250
RF bandwidth (MHz)	10
Transmit Pk pwr (W)	4 000
Transmit Ave. pwr (W)	360
Pulsewidth (μ s)	20-30
Pulse repetition frequency (PRF) (μ s)	1 000-3 000
Chirp rate (MHz/ μ s)	0.5-0.67
Transmit duty cycle (%)	2-9
System noise figure (dB)	5

7.9 Typical parameters of active sensors operating in the 24.05-24.25 GHz band

The typical characteristics of spaceborne radars operating in the 24.05-24.25 GHz band are shown in Table 17 with typical parameter values including the characteristics of the example radar. The spectrum is intended for use by precipitation radars and scatterometers.

TABLE 17

Characteristics of EESS (active) missions in the 24.05-24.25 GHz band

Parameter	SCAT-I1	PR-I1
Sensor type	Scatterometer	Precip. radar
Type of orbit	Circular, NSS	Circular, NSS
Altitude (km)	803	350
Inclination (degrees)	98.6	35
Repeat period (days)	4	46
Antenna type	0.56 m dia offset reflector	1.18 m Slotted waveguide array
Number of beams	2	1
Antenna (Transmit and Receive) peak gain, (dBi)	41	47.4
Polarization	H (inner), V (outer)	H
Azimuth scan rate, rpm or s/scan	18	0.6 s/scan
Antenna beam look angle (degrees)	40, 46	±17
Antenna beam azimuth angle (degrees)	0-360	±90
Antenna elev. beamwidth (degrees)	1.6	0.71
Antenna az. beamwidth (degrees)	1.6	0.71
RF centre frequency (MHz)	24 150	24 150
RF bandwidth (MHz)	0.53	0.6
Transmit Pk pwr (W)	100	578
Transmit Ave. pwr (W)	30.6	2.57
Pulsewidth (µs)	1 700	1.6
Pulse repetition frequency (PRF), (Hz)	180	2776
Chirp rate (MHz/µs)	0.0003118	NA
Transmit duty cycle (%)	30.6	0.44
System noise figure (dB)	5	7

7.10 Typical parameters of active sensors operating in the 35.5-36.0 GHz band

Typical characteristics of SAR, radar altimeters and precipitation radars operating in 35.5-36.0 GHz are shown in Table 18.

TABLE 18

Characteristics of EESS (active) missions in the 35.5-36 GHz band

Parameter	ALT-J1	ALT-J2 (Note 1)	ALT-J3	SAR-J1 (Note 2)	PR-J1	PR-J2	PR-J3	PR-J4
Sensor type	Altimeter	Altimeter	Altimeter	SAR	Precip. Radar	Precip. Radar	Precip. Radar	Precip. Radar
Type of orbit	SSO	NSS	NSS	SSO	SSO	NSS	NSS	NSS
Altitude (km)	800	970	714	780	650	407	410	600
Inclination (degrees)	98.53	78	92	98.6	98.2	65	50	50
Ascending node LST ⁽¹⁾	18:00	NA	NA	18:00	13:00	NA	NA	NA
Repeat period (days)	35	22	367	11	53	82	11	6
Antenna size/diameter	1.0 m	3.8 m × 4.17 m	1.4 m × 1.25 m	3 m × 0.6 m (xmt), 3 m × 2 m (rcv)	2.5 m × 5 m	0.8 × 0.81.6 m	1.2 m	2.1 m
Antenna Pk Xmt gain (dBi)	49.3	61.5	50.2	49.5	60.4	47.4	47	55
Antenna Pk Rcv gain (dBi)	49.3	61.5	50.2	55.0	60.4	47.4	47	55
Polarization	circular	H, V	Linear	H, V	H, V	H	HH	HH, HV
Azimuth scan rate (rpm)	0	0	0	0	0	0.7 s/scan ⁽²⁾	0.7 s/scan	0.42 s/scan
Antenna beam look angle (degrees)	0	0	0	30	±2.4	±17	±20	±31
Antenna beam azimuth angle (degrees)	0	0	0	90	90	90	±90	±90
Antenna elev. beamwidth (degrees)	0.6	0.13	0.4	2.9	0.2	0.7	0.7	0.28
Antenna az. beamwidth (degrees)	0.6	0.13	0.4	0.16	0.1	0.7	0.7	0.25
RF centre frequency (MHz)	35 750	35 600	35 750	35 750	35 600	35 547, 35 553	35 547, 35 553	35 526, 35 542, 35 558, 35 574
RF bandwidth (MHz)	480	200	500	40	2.5	0.6+0.6, 0.3+0.3	0.6 × 2	8 × 4
Transmit Pk pwr (W)	2	1 500	3.8 ⁽³⁾ ; 4.3 ⁽⁴⁾	3 000	1 500	140	150	300
Transmit Ave. pwr (W)	0.856	33.66	3.4 ⁽³⁾ ; 1.3 ⁽⁴⁾	300	19.3	2.56	27	54
Pulsewidth (µs)	107	5.1	49 ⁽³⁾ ; 18 ⁽⁴⁾	36.1	1.67	1.6, 3.2	1.6/10/20/40	40
Pulse repetition frequency (PRF) max (Hz)	4 000	4 400	18 000 ⁽³⁾ ; 15 500 to 16 800 ⁽⁴⁾	2 770	7 700	4 485	4 500	4 500

TABLE 18 (end)

Parameter	ALT-J1	ALT-J2 (Note 1)	ALT-J3	SAR-J1 (Note 2)	PR-J1	PR-J2	PR-J3	PR-J4
Chirp rate (MHz/ μ s)	4.49	39.22	10.2 ⁽³⁾ ; 27.8 ⁽⁴⁾	1.108	1.54	NA ⁽¹⁾	0.015-0.375	0.2
Transmit duty cycle (%)	42.8	2.24	88.2 ⁽³⁾ ; 29.1 ⁽⁴⁾	10.0	1.28	1.83	0.7-18	18
e.i.r.p. ave (dBW)	48.6	76.8	55.5 ⁽³⁾ ; 51.2 ⁽⁴⁾	84.3	73.3	47.1	61.4	72.4
e.i.r.p. peak (dBW)	52.3	93.3	56 ⁽³⁾ ; 56.6 ⁽⁴⁾	74.3	92.2	68.9	68.8	79.8
System noise figure (dB)	3.9	4	4.1	4.5	4	6.3	6	3.5

⁽¹⁾ Unmodulated pulse.

⁽²⁾ The azimuth scan rate in seconds per scan is the time needed to scan from side to side (across-track) during one cycle.

⁽³⁾ Closed burst mode.

⁽⁴⁾ Open burst mode.

NOTE 1 – This altimeter system is a Radar Interferometer instrument containing two Ka-band SAR antennas at opposite ends of a 10-metre boom with both antennas transmitting and receiving the emitted radar pulses along both sides of the orbital track. Look angles are limited to less than 4.5 degrees providing a 120-km wide swath.

The 200-MHz bandwidth achieves cross-track ground resolutions varying from about 10 m in the far swath to about 60 m in the near swath. A resolution of about 2 metres in the long track direction is derived by means of synthetic aperture processing.

NOTE 2 – Ka-Band SAR mission for single pass interferometry still in conceptual phase. Under consideration a single satellite with multiple antennas or two satellites in formation.

7.11 Typical parameters of active sensors operating in the 78-79 GHz band

The typical characteristics of spaceborne radars operating in the 78-79 GHz band are shown in Table 19 with typical parameter values including the characteristics of the example radar.

TABLE 19

Typical characteristics of EESS (active) missions in the 78-79 GHz band

Parameter	PR-K1
Sensor type	Precip. Radar
Type of orbit	Circular, NSS
Altitude (km)	400
Inclination (degrees)	60
Repeat period (days)	23
Antenna type	Parabolic reflector
Antenna (Transmit and Receive) peak gain (dBi)	61.7
Polarization	Linear H
Azimuth scan rate (rpm)	0.197
Antenna beam look angle (degrees)	0
Antenna beam azimuth angle (degrees)	±17
Antenna elevation beamwidth (degrees)	0.71
Antenna azimuth beamwidth (degrees)	0.71
RF centre frequency (MHz)	78.500
RF bandwidth (MHz)	0.8
Transmit Pk pwr (W)	1 000
Transmit Ave. pwr (W)	14
Pulsewidth (µsec)	3.33
Pulse repetition frequency (PRF), (Hz)	4 250
Chirp rate (MHz/µs)	N/A
Transmit duty cycle (%)	1.42
System noise figure (dB)	3

7.12 Typical parameters of active sensors operating in the 94-94.1 GHz band

Table 20 shows typical characteristics of the CPR operating in the 94-94.1 GHz band.

TABLE 20

Characteristics of EESS (active) missions in the 94-94.1 GHz band

Parameter	CPR-L1	CPR-L2
Sensor type	Cloud profiling radar	Cloud profiling radar
Type of orbit	SSO	SSO
Altitude (km)	705	393
Inclination (degrees)	98.2	97
Ascending Node LST	13:30	02:00
Repeat period (days)	16	25
Antenna type	Parabolic reflector to offset cassegrain antenna	Parabolic reflector
Antenna diameter (m)	1.85-2.5	2.5
Antenna (transmit and receive) peak gain (dBi)	63.1-65.2	66
Polarization	linear	LHC (transmit), RHC (receive)
Incidence angle at Earth (degrees)	0	0
Azimuth scan rate (rpm)	0	0
Antenna beam look angle (degrees)	0	0
Antenna beam azimuth angle (degrees)	0	0
Antenna elevation beamwidth (degrees)	0.12	0.095
Antenna azimuth beamwidth (degrees)	0.12	0.095
Beam width (degrees)	0.095-0.108	0.095
RF centre frequency (MHz)	94.050	94.050
RF bandwidth (MHz)	0.36	7
Transmit Pk pwr (W)	1 000	2 200
Transmit Ave. pwr (W)	21.31	44
Pulsewidth (μ s)	3.33	3.3
Pulse repetition frequency (PRF) (Hz)	4 300	1 800-7 500
Chirp rate (MHz/ μ s)	N/A ⁽¹⁾	2.1
Transmit duty cycle (%)	1.33	2
Minimum sensitivity (dBz)	-30 to -35	-30 to -35
Horizontal resolution	0.7-1.9 km	800 m
Vertical resolution (m)	250-500	500
Doppler range (m/s)	\pm 10	\pm 10
Doppler accuracy (m/s)	1	1
System noise figure (dB)	7	7

⁽¹⁾ The sensor uses an unmodulated pulse.

7.13 Typical parameters of active sensors operating in the 133.5-134 GHz band

Table 21 shows typical characteristics of a CPR with a centre frequency of 133.75 GHz. Very high frequencies are needed for sensitivity to small ice particles.

TABLE 21

Characteristics of EESS (active) missions in the 133.5-134 GHz band

Parameter	CPR-M1
Sensor type	Cloud profiling radar
Type of orbit	SSO
Altitude (km)	705
Inclination (degrees)	98.2
Ascending node LST	13:30
Repeat period (days)	16
Antenna diameter (m)	3
Antenna (transmit and receive) peak gain (dBi)	75
Polarization	linear
Azimuth scan rate (rpm)	0
Antenna beam look angle (degrees)	0
Antenna beam azimuth angle (degrees)	0
Antenna elevation beamwidth (degrees)	0.043
Antenna azimuth beamwidth (degrees)	0.043
RF centre frequency (GHz)	133.75
RF bandwidth (MHz)	0.65
Transmit Pk power (W)	300
Pulsewidth (μ s)	1.6
Pulse repetition frequency (PRF), (Hz)	4 000
Range resolution (m)	250
Horizontal resolution	0.2×0.7 km
System noise figure (dB)	8

7.14 Typical parameters of active sensors operating in the 237.9-238 GHz band

Table 22 shows typical characteristics of a CPR with a centre frequency of 237.95 GHz. Very high frequencies are needed for sensitivity to small ice particles.

TABLE 22

Characteristics of EESS (active) missions in the 237.9-238 GHz band

Parameter	CPR-N1
Sensor type	Cloud profiling radar
Type of orbit	SSO
Altitude (km)	705
Orbital inclination (degrees)	98.2
Ascending node LST	13:30
Repeat period (days)	16
Antenna diameter (m)	3
Antenna (Transmit and Receive) peak gain (dBi)	78
Polarization	Linear
Azimuth scan rate (rpm)	0
Antenna beam look angle (degrees)	0
Antenna beam azimuth angle (degrees)	0
Antenna elevation beamwidth (degrees)	0.024
Antenna azimuth beamwidth (degrees)	0.024
RF centre frequency (GHz)	237.95
RF bandwidth (MHz)	0.65
Transmit Pk power (W)	80
Pulsewidth (μ s)	1.6
Pulse repetition frequency (PRF) (Hz)	4 000
Range resolution (m)	250
Horizontal resolution	0.1×0.7 km
System noise figure (dB)	11