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The communication system for advanced automotive control applications

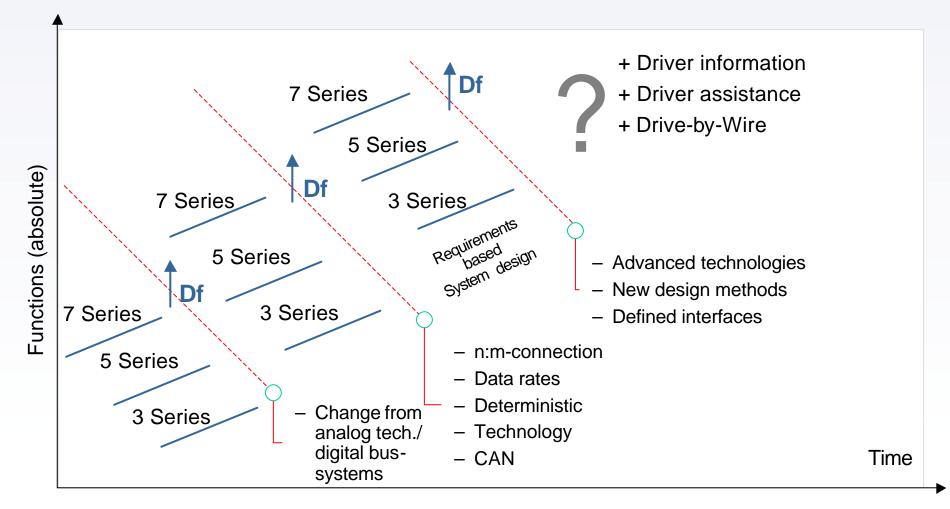
## FlexRay Enabler for Future Automotive System Architectures

3<sup>rd</sup> March 2005 Genf

Dr. Günter Reichart - BMW Group

## Requirements driven evolution of functions and systems - mapped on BMW car series

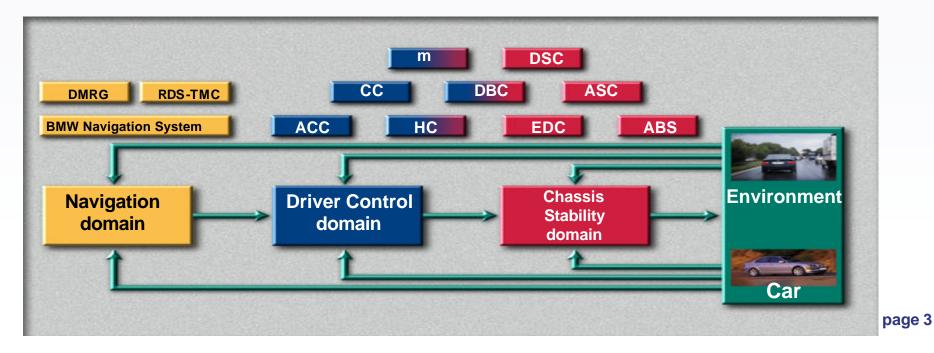
Flex<mark>Ray</mark>™





## Situation snapshot of in-car E/E systems and architectures

- Increasing requirements (legal, functional and safety) demand for further electric/electronic systems
- Mechatronic will replace mechanic (e.g. Drive-by-Wire)
- New functions (e.g. driver assistance) need higher data exchange between functional domains

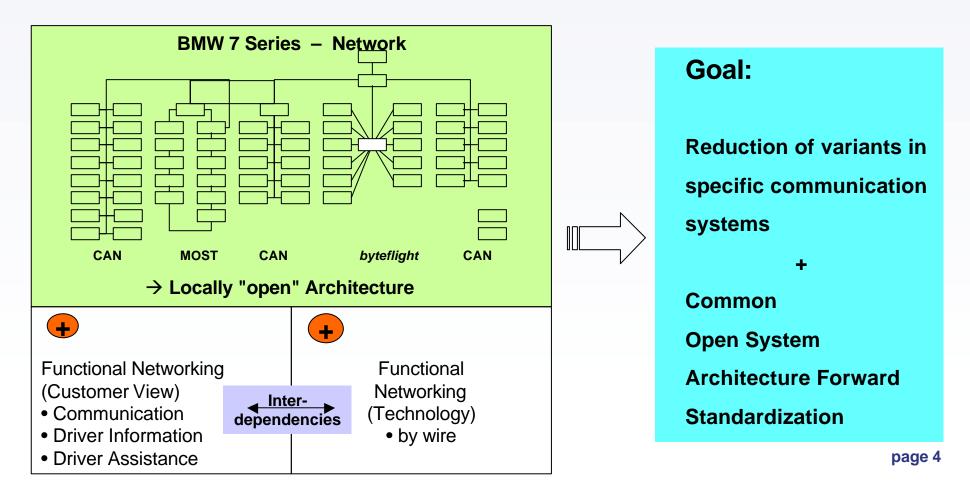




#### System Architecture - Complexity Management

Lessons learned ...

→ Complexity by introducing many communication systems in a single car platform



FlexRay™ **Requirements for a common communication system** mapped to the automotive application domains

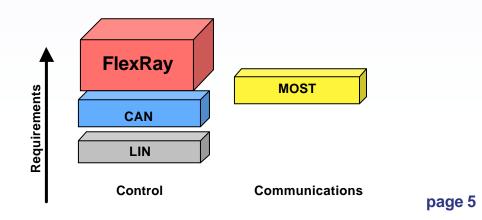
> • X-by-wire systems **→**

> > →

**>** 

- Chassis systems →
- Powertrain systems
- Future backbone for open systems architectures

- Dependability and fault containment
- Determinism
  - High bandwidth
    - Flexibility and high bandwidth



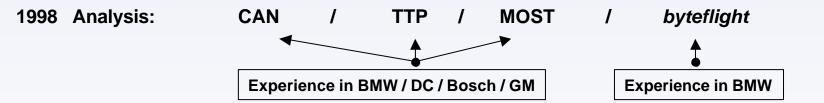


#### **Requirements for Open System Architecture**

- Displacement of functional modules beyond domain boundaries
- Strategy for reduction in technology variety is mandatory and it requires new feature integration
- Flexibility of hardware
- Approach must be based on future standards
- Standardized interfaces
- Support by development methods and tools



#### **FlexRay History**



Start of communication between BMW and DaimlerChrysler

	1999	Realization: Future requirements are not fulfilled by existing protocols
Since	1999	Consequences: Start of cooperation
	2000	FlexRay Consortium founded by BMW, DaimlerChrysler, Motorola, Philips
Since	2000	Realization of FlexRay System together with semiconductor industry
	10/2000	Bosch joins FlexRay Consortium
	09/2001	General Motors joins FlexRay Consortium
04/2002 -	10/2002	Ford Motor Company, Mazda and Fiat join as Premium Associate Members
	Q3/2003	Volkswagen joins the FlexRay Consortium
	Q4/2003	Toyota, Honda, Nissan join the FlexRay Consortium as PAMs
	06/2004	Release of FlexRay Specifications, SW & tools available to the general public
	Q3/2004	PSA, Renault join the FlexRay Consortium as Premium Associate Members



#### Scope of the Consortium

The scope of the Consortium is to develop jointly an innovative communications network of very high quality which consists of the complete communication infrastructure and includes inter alia the specifications for the serial communications protocol, the transceiver, the hardware and software interfaces and conformance/certification procedures. This will serve as the basis for the development, production and implementation of certain communications networks for automotive applications.

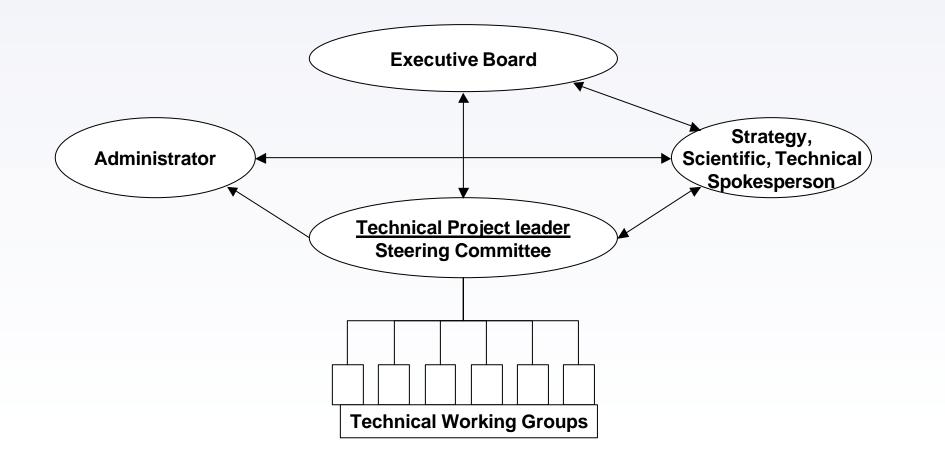
The ultimate objective of the Consortium is the factual industry-wide recognition of a new standard for a deterministic automotive network which shall be open to use and development by third parties.

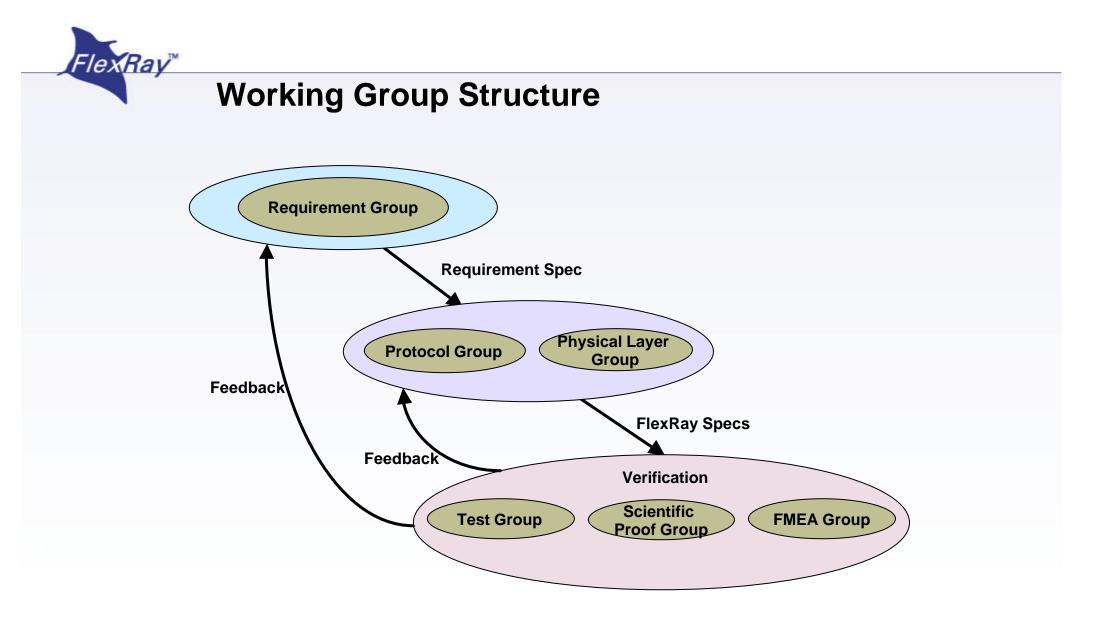


# **FlexRay** De-facto Automotive Standard

Core Members	Premium Associate Members	Associate Members	Development Members
BMW Group	ContiTeves Delphi	AMS ATMEL Avidyne Berata	Cadence CANway CapeWare
Bosch	Denso Fiat	EADS Elmos ESG	Cardec CRST
DaimlerChrysler	Ford Motor	Esterel Fujitsu Hella Hitachi	DECOMSYS dSpace ETAS
General Motors	Honda Mazda	Hyundai Infineon Mitsubishi NEC	IXXAT MicroSys National Instruments
<b>Freescale</b> (Motorola)	Nissan Peugeot Citroen	Nidec Pacifica Porsche Renesas	NSI 3SOFT Softing
Philips	Renault	RWTÜV SiemensVDO SP ST Micro	SystemA TecWings TZM
Volkswagen	Toyota Tyco Electronics	Subaru Sumitomo Texas Instruments ThyssenKrupp Automotive	Vector Informatik Volcano Weise GmbH
	Volvo	TRŴ Visteon Yazaki	









#### FlexRay - the communication system (1/3)

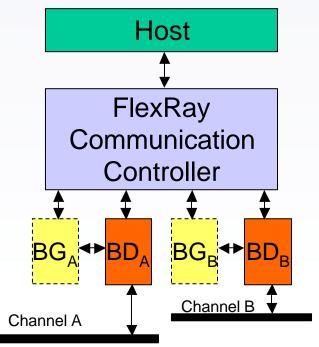
#### **Features**

- Forward-standardization an objective from the beginning
  - OEMs, TIER1s and semiconductor vendors are represented in the FlexRay consortium

#### • Bandwidth

- No limitation due to protocol mechanisms
- Current design focus: 10 Mbit/s
- Scalability
  - Single channel / Dual channel
  - Mixed configuration

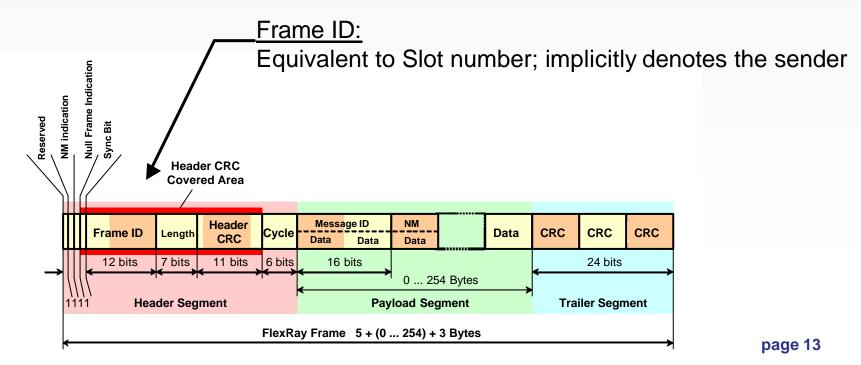
BD: Bus Driver BG: Bus Guardian (optional)





#### FlexRay - the communication system (2/3)

- Flexibility
  - Open to many network topologies
  - Electrical and optical Physical Layer
  - Dynamic and static segments in communication cycle
  - Frame ID





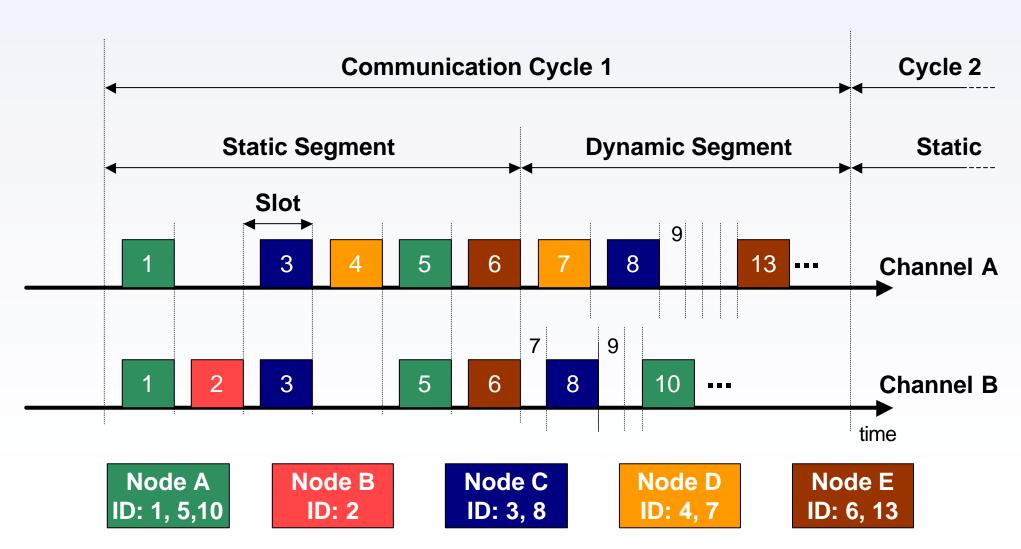
#### FlexRay - the communication system (3/3)

#### • Deterministic

- Stringent deterministic by TDMA media access (Time Division Multiple Access) in static segment
- Limited deterministic by FTDMA media access (Flexible Time Division Multiple Access) in dynamic segment
- Safety
  - Distributed Clock Synchronization
    - Offset and Rate Correction
  - Bus Guardian
  - CRC
    - Header CRC
    - Frame CRC
    - Hamming Distance of 6

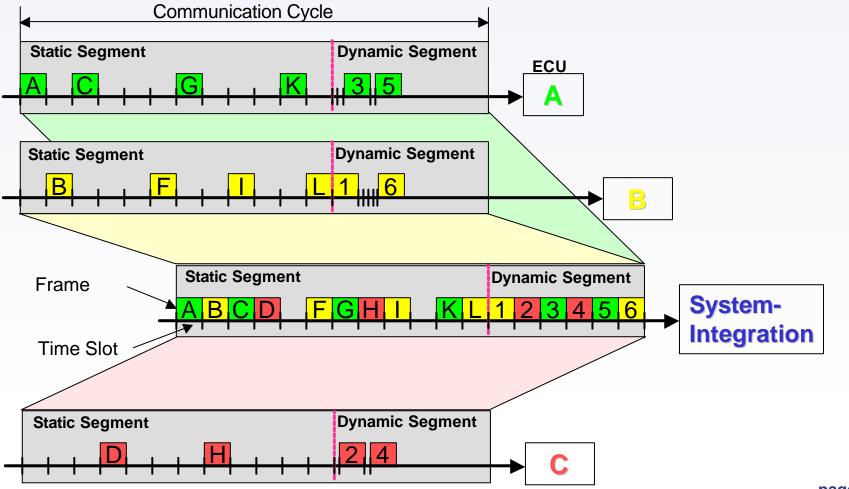
**FlexRay Bus Access Method** 

FlexRay<sup>™</sup>





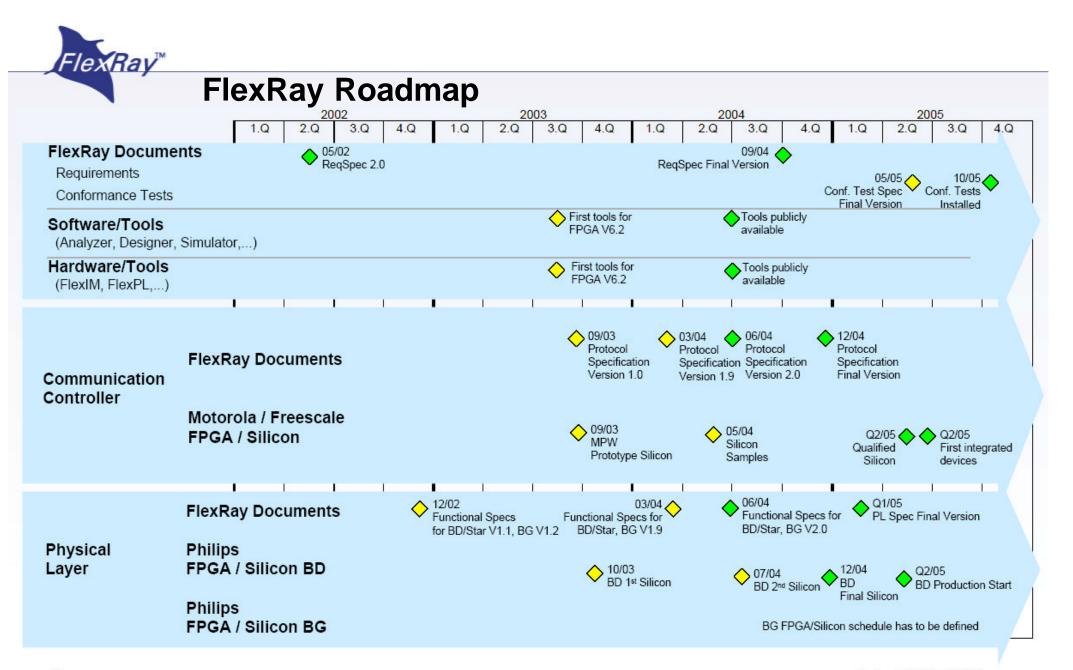
#### FlexRay Time Triggered Communication Composability in the Time Domain





#### **Benefits of the FlexRay Technology**

- Provide a communication infrastructure for future generation highspeed control applications in vehicles such as advanced powertrain, chassis, and by-wire systems.
- High bandwidth (net data rate 5 Mbps at gross 10 Mbps), flexible use of bandwidth
- Deterministic behavior (guaranteed transmission time for frames in the static segment)
- Synchronization of tasks in distributed control systems
- Cycle times < 2 ms
- Reliable data communication
- Facilitation of system integration
- Reserves for future functional extensions
- Possibility to implement future real Drive-by-Wire functions without mechanical back-up

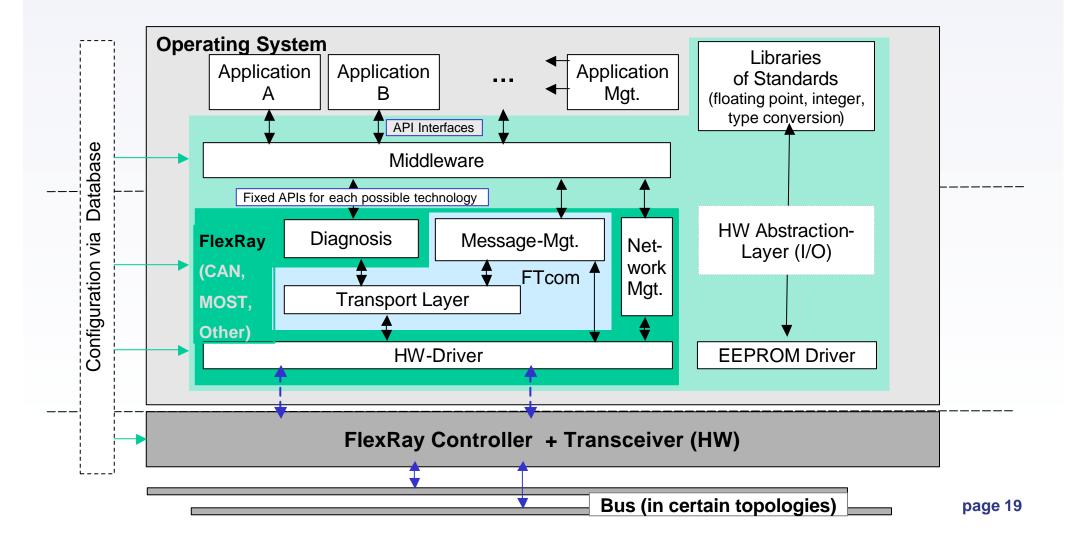


FlexRay Consortium (Motorola/Freescale, Philips FPGA/silicon products subject to bilateral agreement) General Public (Motorola/Freescale, Philips FPGA/silicon products subject to bilateral agreement)

#### Date: 2004-08-04



## Standard-Structure model with FlexRay as underlying Communication Layer





#### Activities around the FlexRay protocol

- Physical Layer development proceeding in parallel
- HW features to support future network management concepts
  - ie. Network Management Indication Bit and Network Management Vector
- OSEKtime
  - OSEK enhancement for time triggered operation
- FTcom: Fault Tolerant communication layer for OSEK architecture
  - specification and pilot-implementations available
- FIBEX (Fleld Bus EXchange format)
  - XML-exchange format based on a generic bus model enables interoperability between databases and development tools



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#### Summary

- FlexRay is a communication system targeted at high-speed control applications in vehicles such as advanced powertrain, chassis, and by-wire systems.
- FlexRay supports these applications by providing architectural flexibility through scalability and functional alternatives.
- FlexRay is expected to be the de-facto communication standard for high-speed automotive control applications.

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#### Thank you for your attention!

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